

### AT32F435/437 Firmware BSP&Pack

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## Introduction

This application note is written to give a quick guideline on how to apply AT32F435/437 BSP (Board Support Package) and install AT32 Pack.

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## 1 Overview

In order to allow users to use Artery MCU in an efficiently and quickly manner, we provide a complete set of BSP & Pack tools for the sake of application development. They include peripheral driver library, core-related documents and application cases as well as Pack documents supporting a variety of development environments, such as Keil\_v5, Keil\_v4, IAR\_v6, IAR\_v7 and IAR\_v8.

This application note gives a detailed account of how to use BSP and Pack.

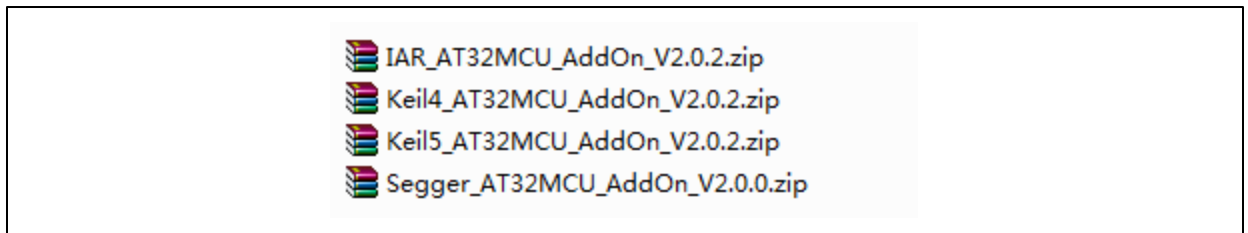
## 2 How to install Pack

ArteryTek provides a complete set of Pack documents that support various development environments such as Keil\_v5, Keil\_v4, IAR\_v6, IAR\_v7 and IAR\_v8. Double-click on the corresponding Pack to finish one-stop installation.

*Note:* This section takes AT32F403A as an example, and other AT32 MCUs have similar Pack installation methods.

The pack installation documents are as follows (the specific version information is subject to the actual conditions):

Figure 1. Pack kit

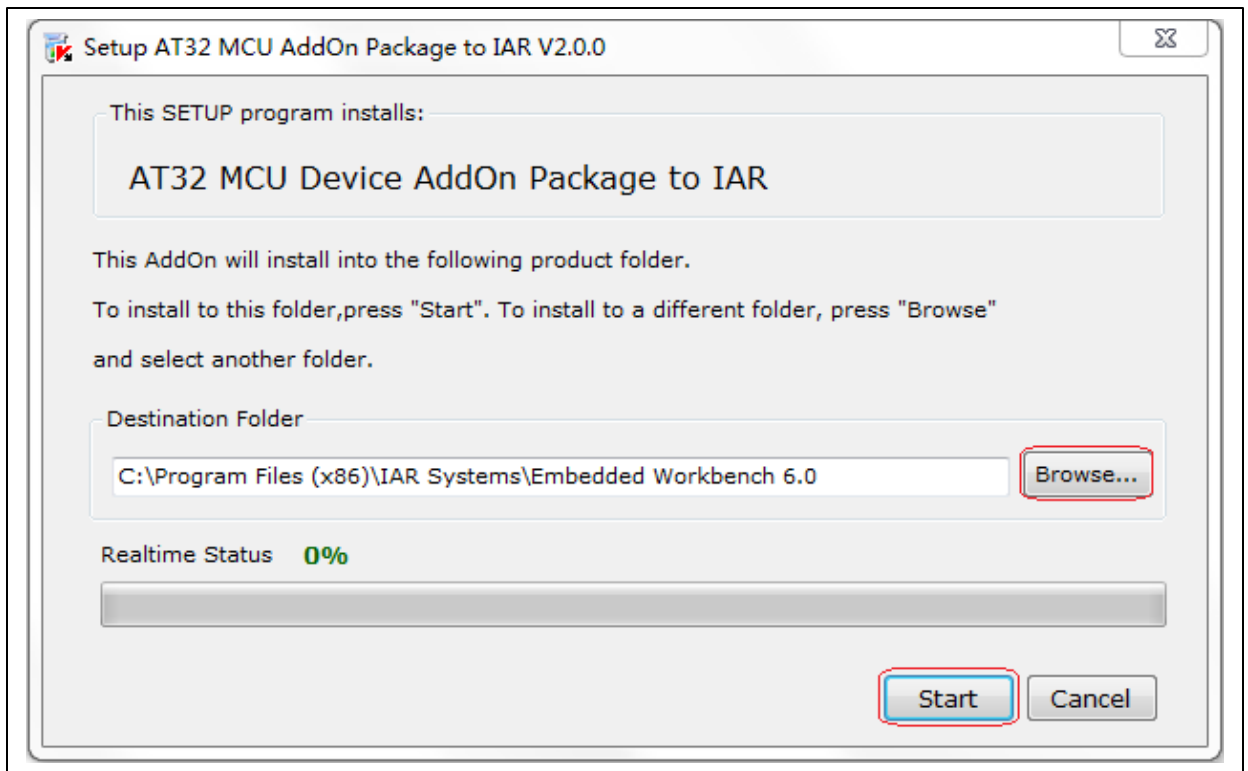


### 2.1 IAR Pack installation

**IAR\_AT32MCU\_AddOn.zip:** This is a zip file supporting IAR\_V6, IAR\_V7 and IAR\_V8. Follow the steps below to install:

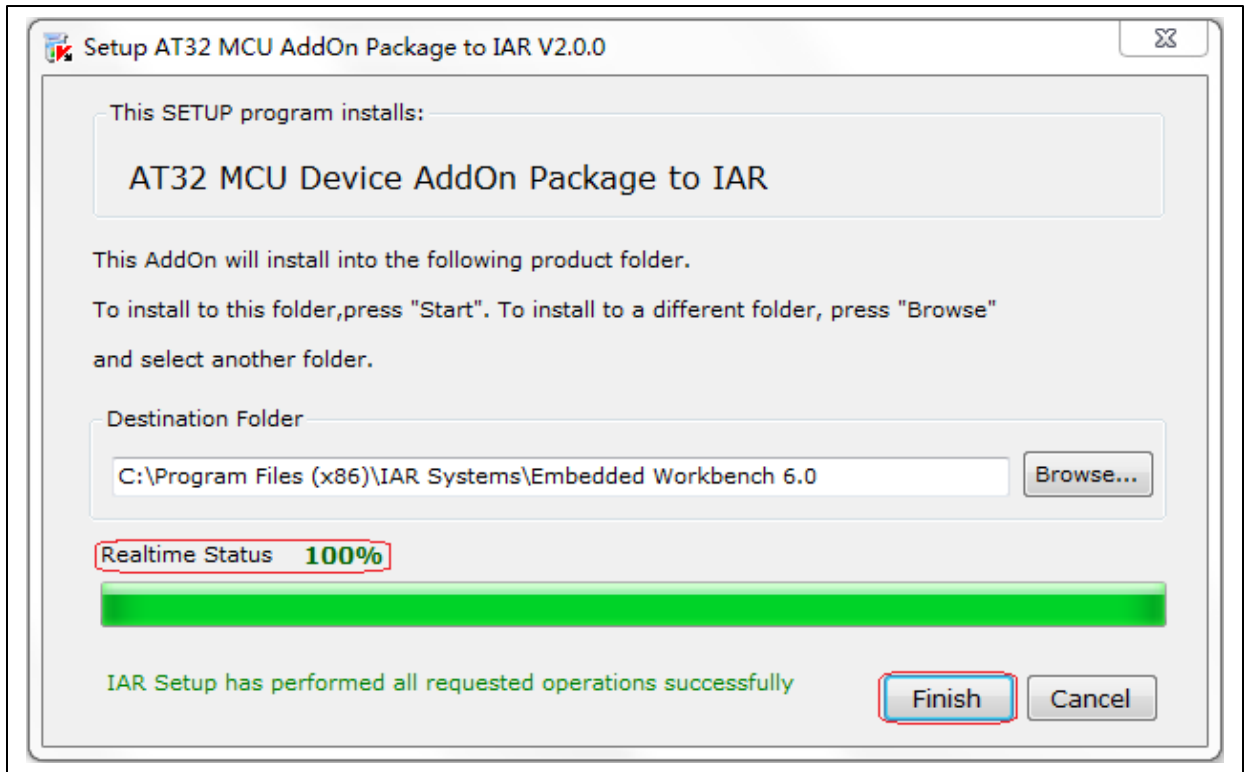
- ① Unzip *IAR\_AT32MCU\_AddOn.zip*
- ② Double click on *IAR\_AT32MCU\_AddOn.exe*, and a dialogue box pops up (the specific version information is subject to the actual conditions).

Figure 2. IAR Pack installation window



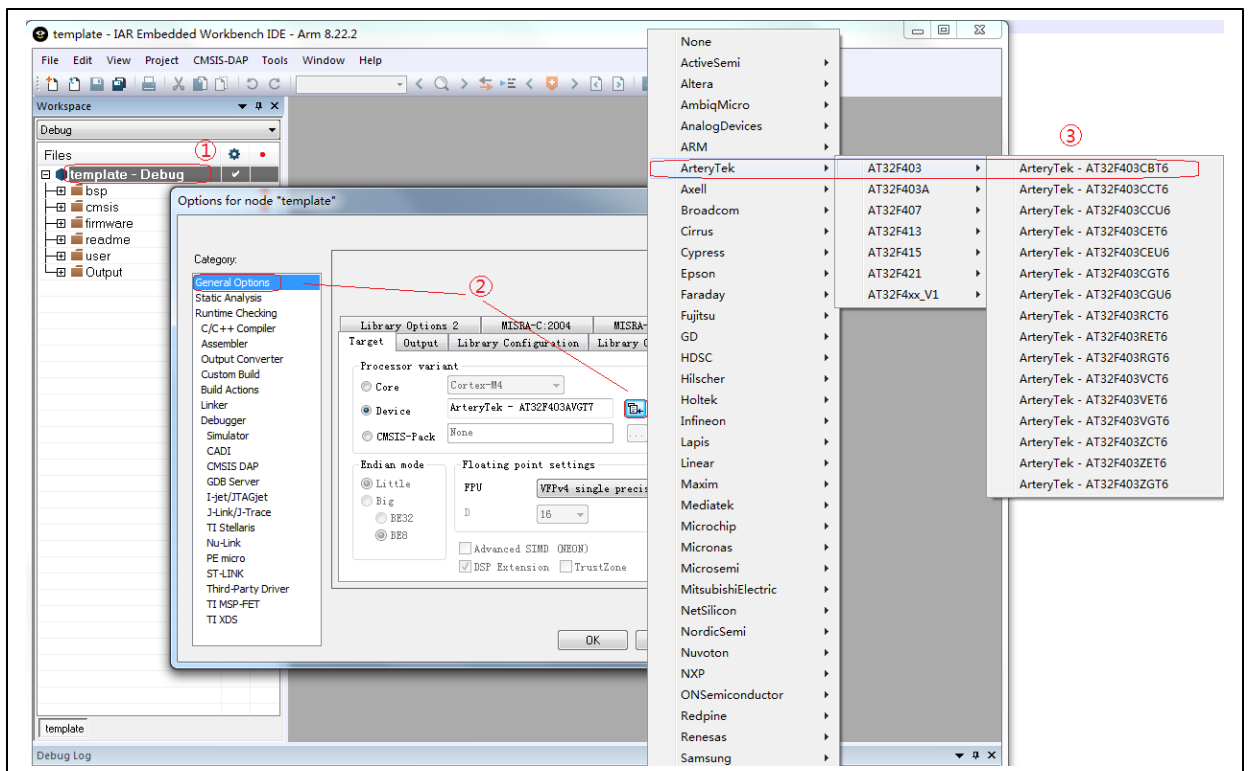
*Note:* If the installation path of IAR does not match the Destination Folder, click on "Browse" to select a correct path, then click on "Start", as shown below.

Figure 3. IAR Pack installation



- ③ Click on “Finish”
- ④ To check whether the IAR Pack is installed successfully or not, open an IAR project and follow the steps below:
  - Right click on a project name, and select “Options...”
  - Select “General Options”, and click on the check box
  - Click on “ArteryTek” and view AT32 MCU-related information.

Figure 4. View IAR Pack installation status



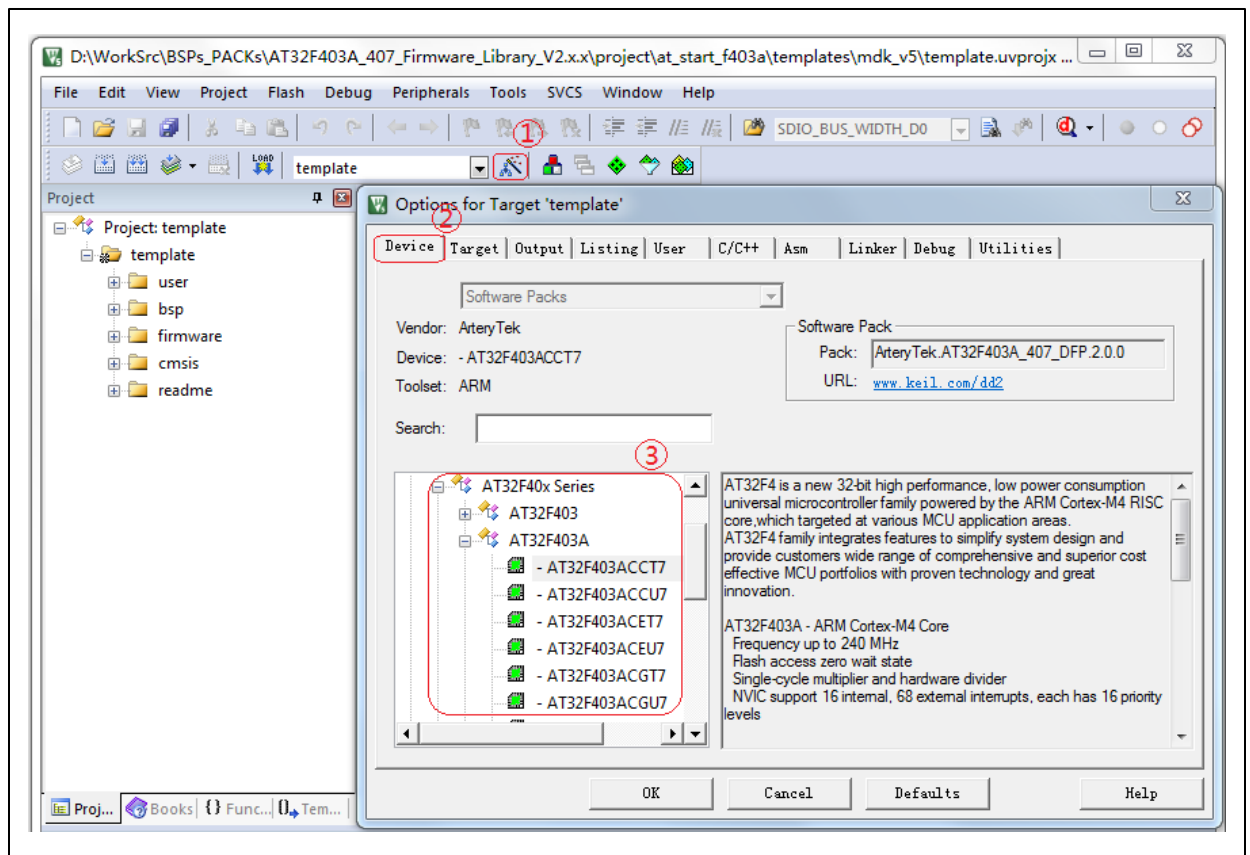


## 2.2 Keil\_v5 Pack installation

**Keil5\_AT32MCU\_AddOn.zip:** This is a zip file supporting Keil\_v5. Follow the steps below to install:

- ① Unzip *Keil5\_AT32MCU\_AddOn.zip*. This zip file includes all Keil5 packs supported, all of which are standard Keil\_v5 DFP installation files.
- ② Select the desired Pack, and double click on *ArteryTek.AT32xxx\_DFP.2.x.x.pack* to get one-stop installation.
- ⑤ To check whether the Keil\_v5 Pack is installed successfully or not, follow the steps below:
  - Click on wand
  - Select "Device"
  - View AT32 MCU-related information

**Figure 5. View Keil\_v5 Pack installation status**

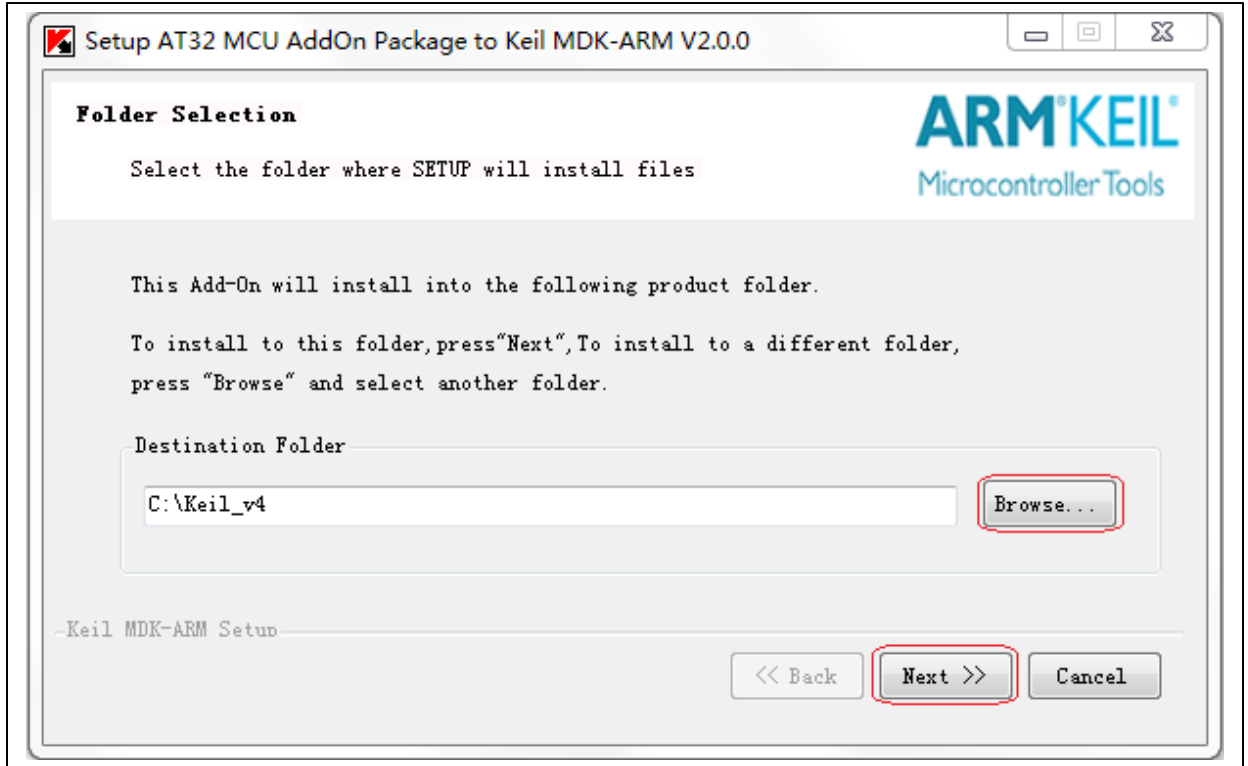


## 2.3 Keil\_v4 Pack installation

**Keil4\_AT32MCU\_AddOn.zip:** This is a zip file supporting Keil\_v4. Follow the steps below to finish installation.

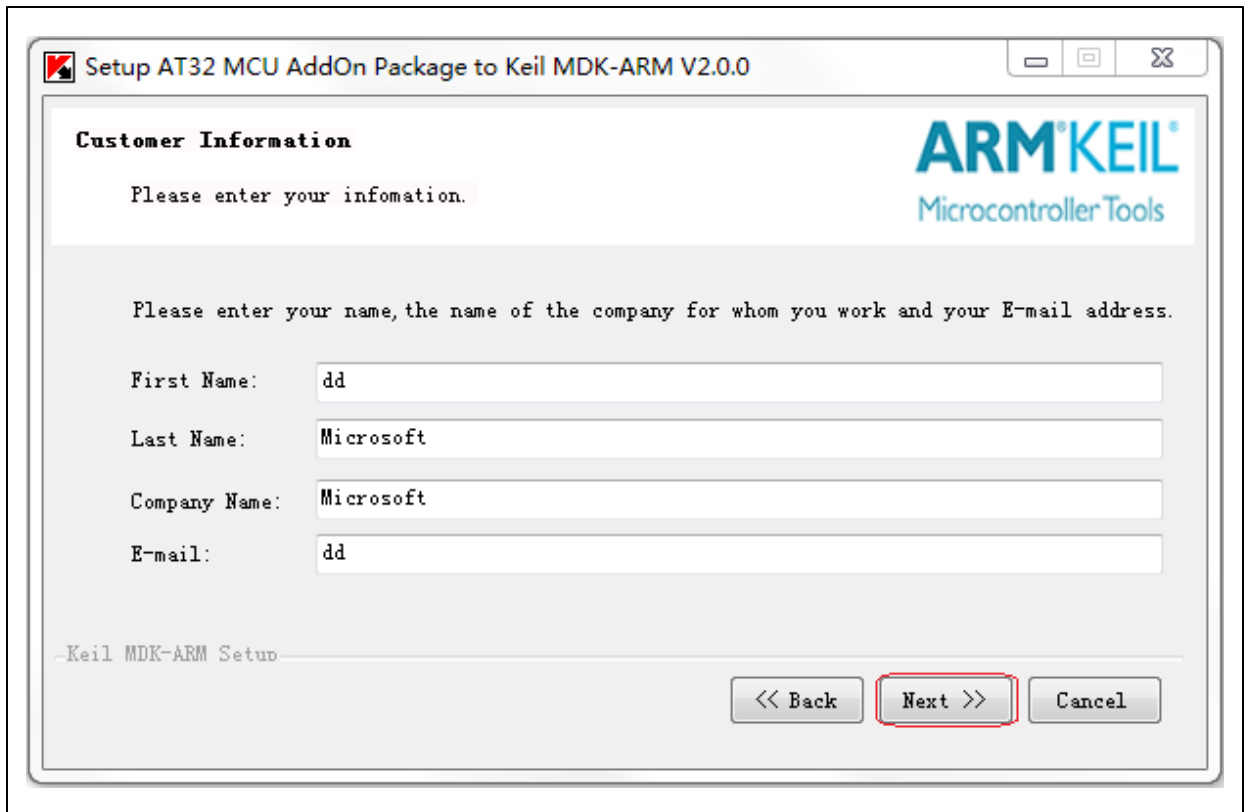
- ① Unzip *Keil4\_AT32MCU\_AddOn.zip*
- ② Double click on *Keil4\_AT32MCU\_AddOn.exe*, and a dialog box pops up below (the specific version information is subject to the actual conditions).

Figure 6. Keil\_v4 Pack installation window



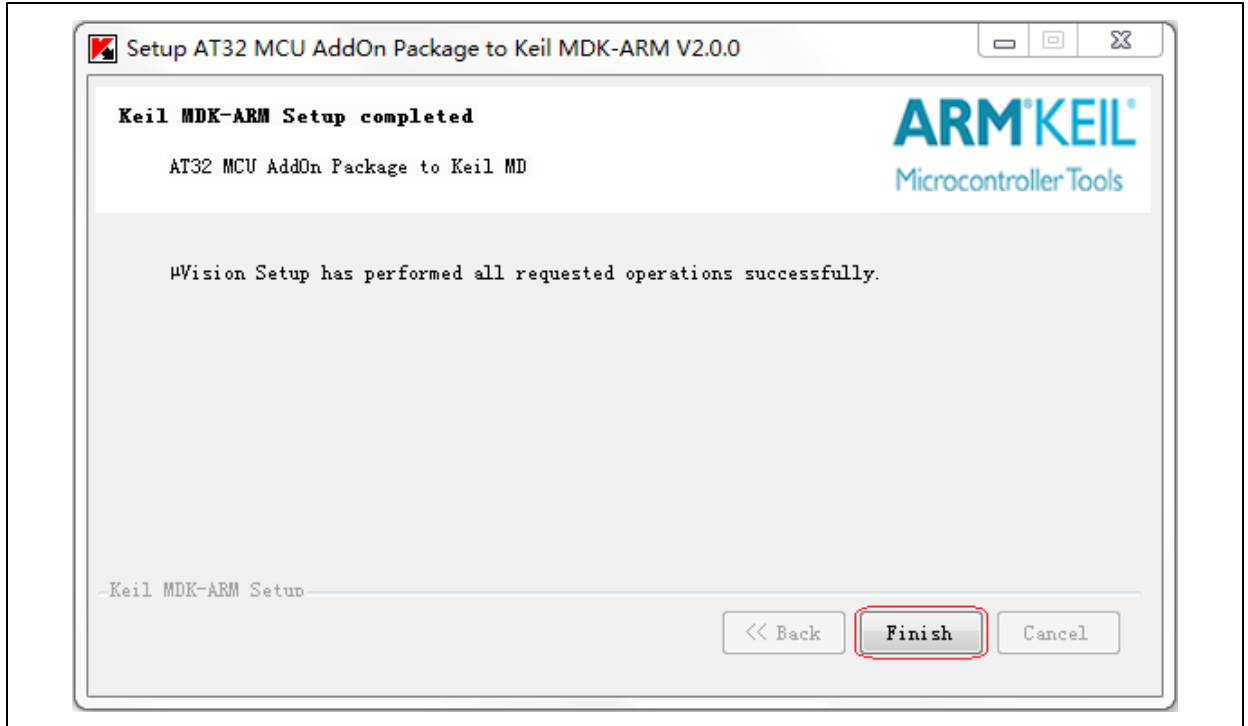
- ③ If the installation path of Keil\_v4 does not match the “Destination Folder”, click on “Browse” to select the actual correct path, then click on “Next”, as shown below.

Figure 7. Keil\_v4 Pack installation process



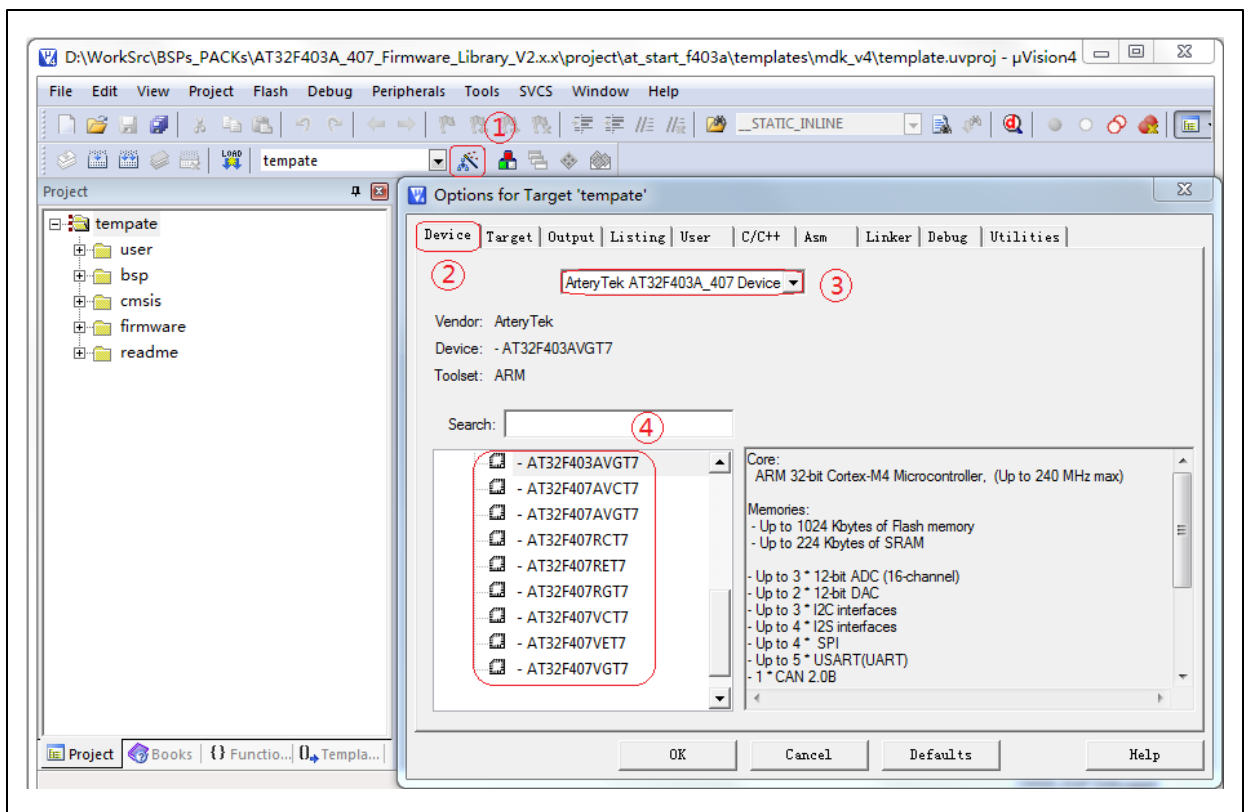
- ④ In the above “Customer Information” window, you can make some changes, but usually it is unnecessary. Then click on “Next” to start installation. The installation result is as follows.

Figure 8. Keil\_v4 Pack installation complete



- ⑤ Click on “Finish”. To check whether Keil\_v4 Pack is installed successfully or not, follow the below steps:
- Click on wand
  - Select “Device”
  - Select the desired pack file
  - View ArteryTek-related information

Figure 9. View Keil\_v4 Pack installation status

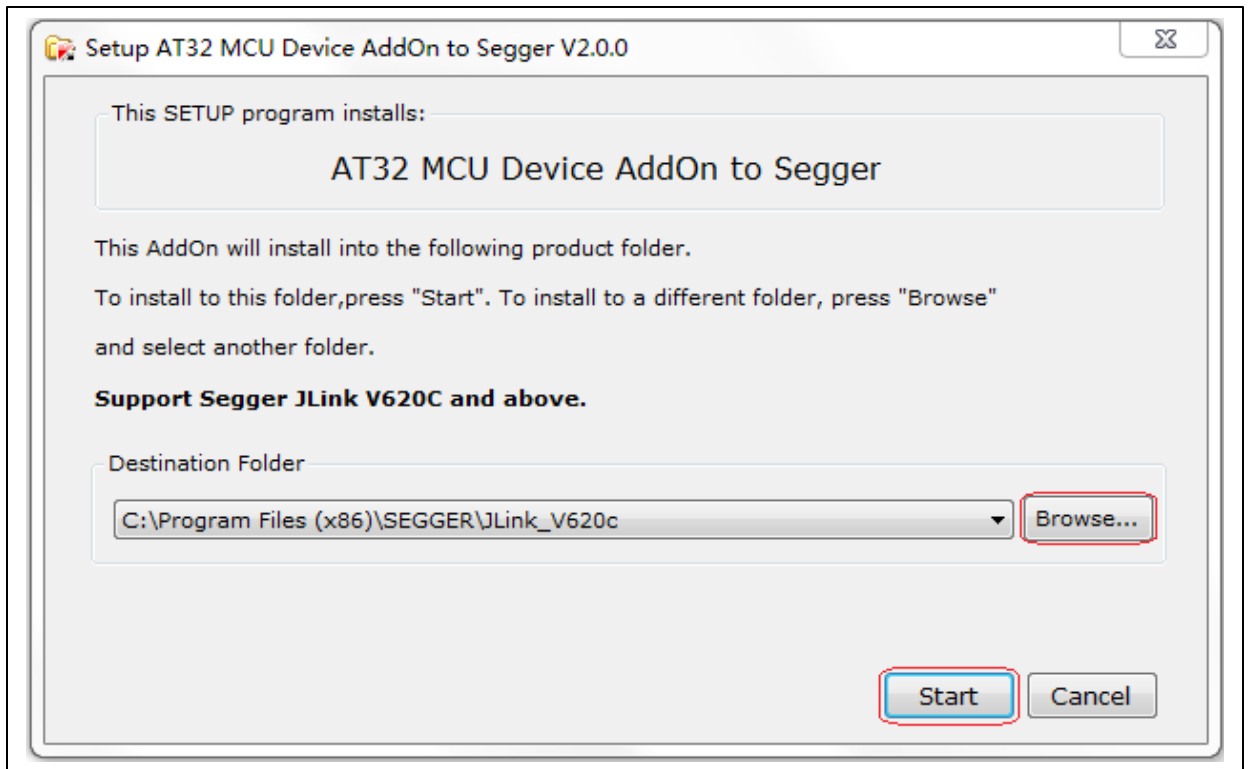


## 2.4 Segger Pack installation

**Segger\_AT32MCU\_AddOn.zip:** This is used to download J-Flash. Follow the steps below to install.

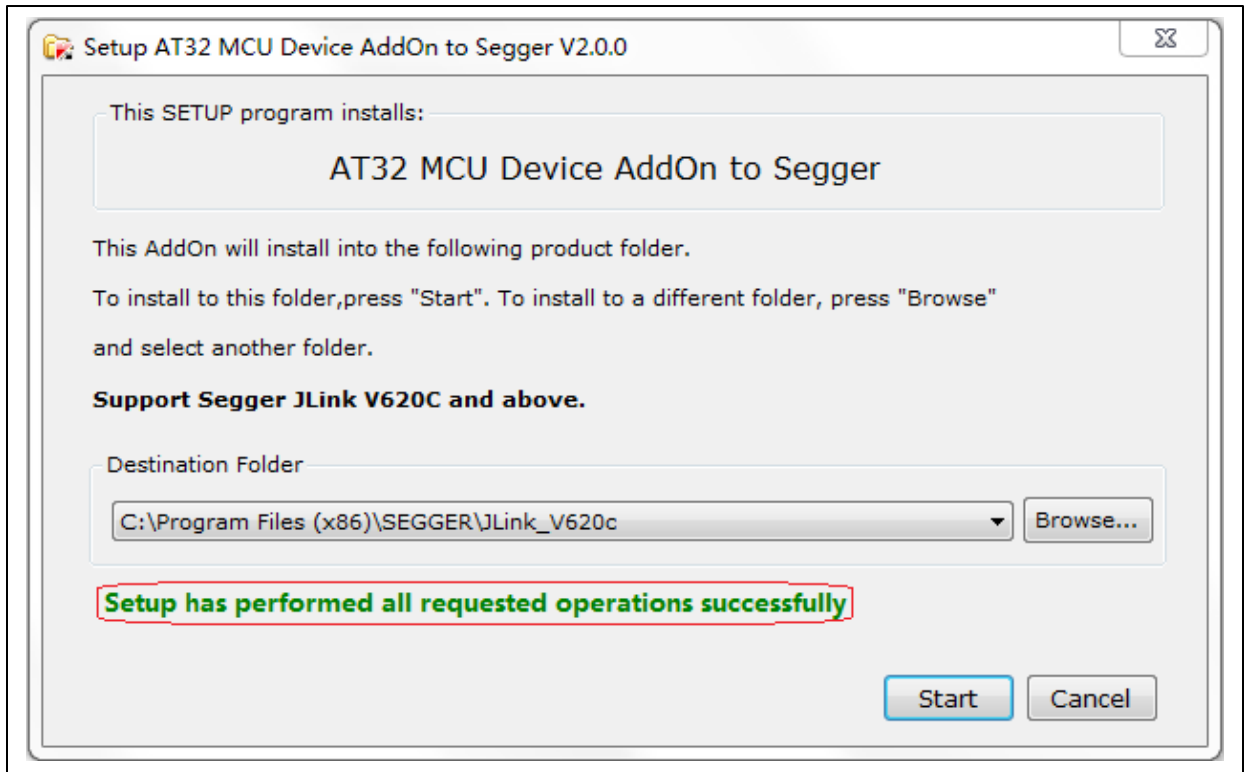
- ① Unzip Segger\_AT32MCU\_AddOn.zip
- ② Double click on Segger\_AT32MCU\_AddOn.exe, and a dialog box pops up below (the specific version information is subject to the actual conditions)

Figure 10. Segger pack installation window



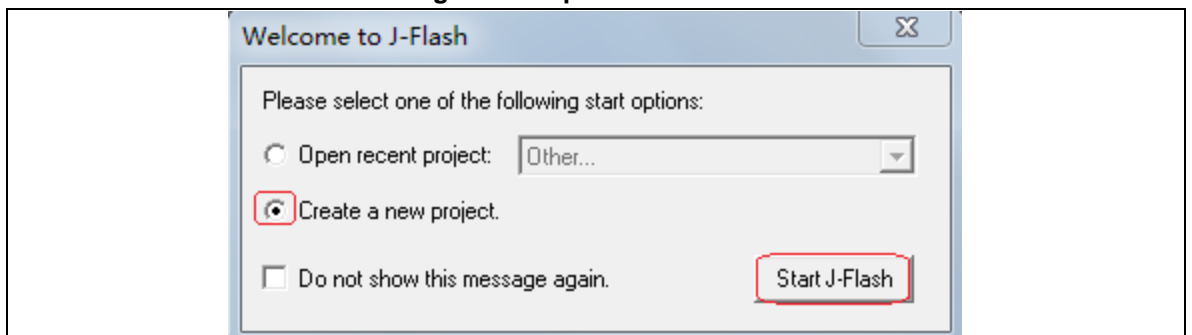
*Note:* If the installation path of Segger does not match the “Destination Folder”, click on “Browse” to select a correct path, then click on “Start”, as shown below.

Figure 11. Segger pack installation process



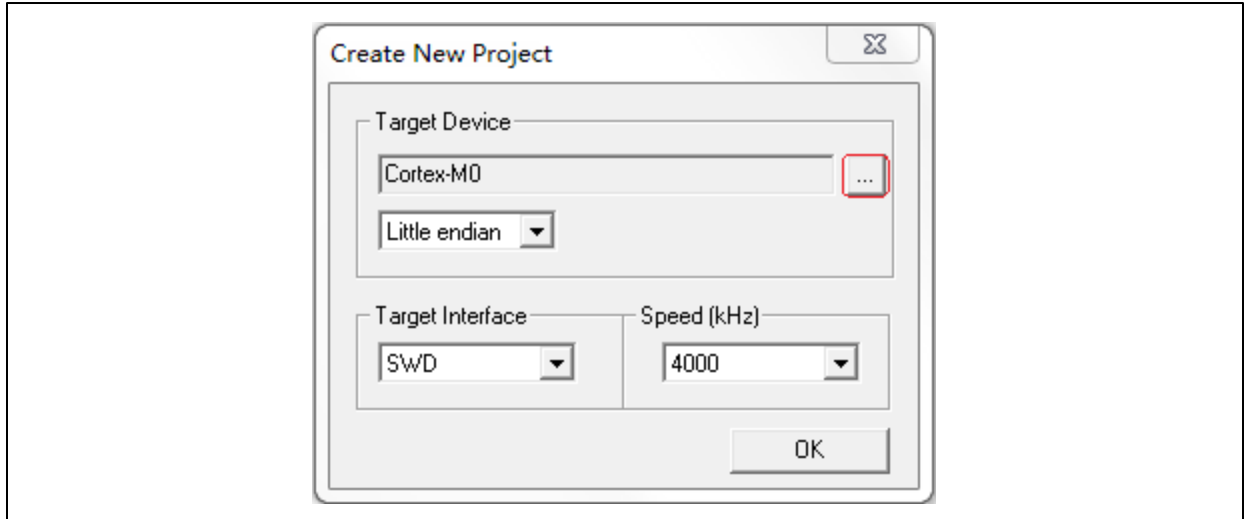
- ③ If the “Setup has performed all requested operations successfully” appears, it indicates successful installation. To check whether the installation is successful or not, follow the steps below:
  - Open J-Flash.exe, a dialog box appears, tick “Create a new project” and click on “Start J-Flash”:

Figure 12. Open J-Flash



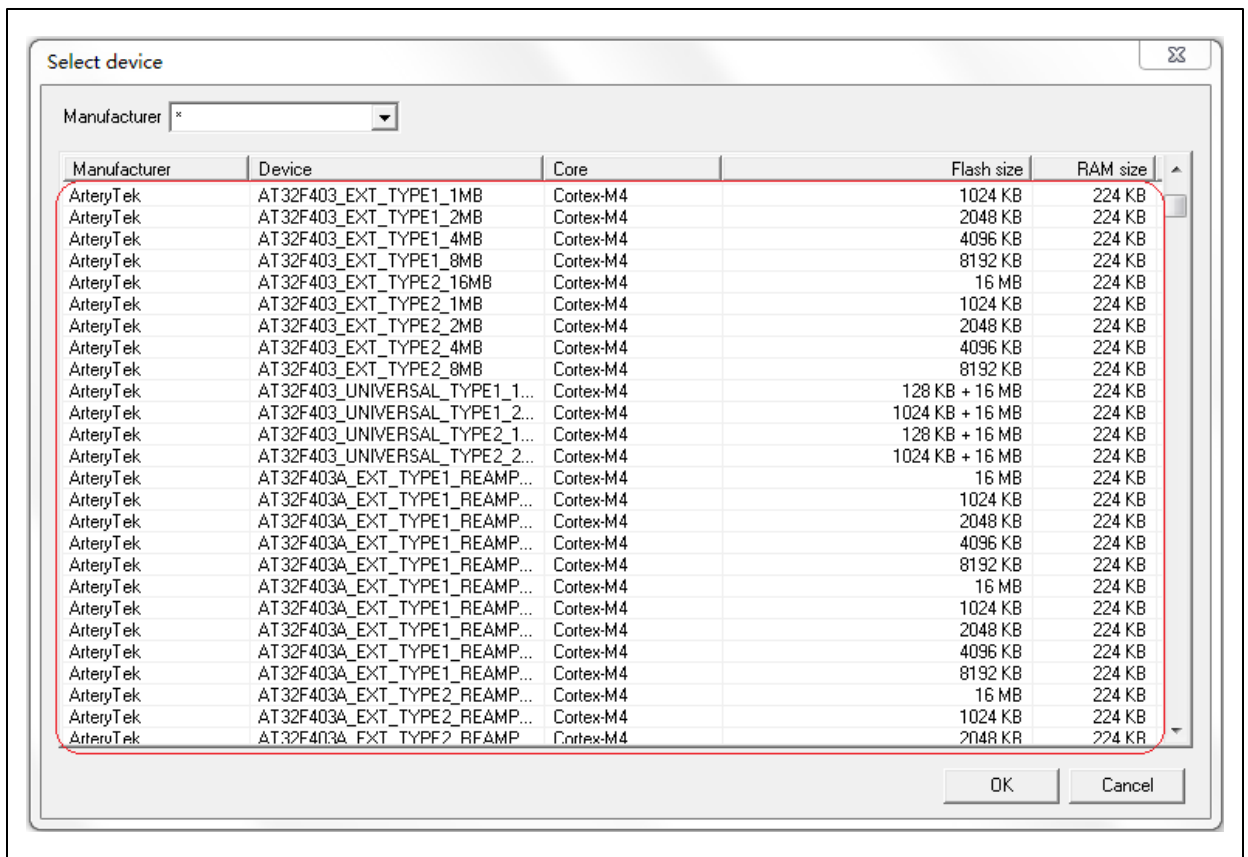
- After “Start J-Flash”, click on the check box under “Target Device”:

Figure 13. Create a new project using J-Flash



- Drag the scroll bar up and down in the check box. If the ArteryTek-related information and algorithm documents can be found, the installation is successful, as shown below:

Figure 14. View Device information



## 3 Flash algorithm file

Flash algorithm files are included in the Pack for online download through IDE tools such as KEIL/IAR. This section describes how to use Flash algorithm files.

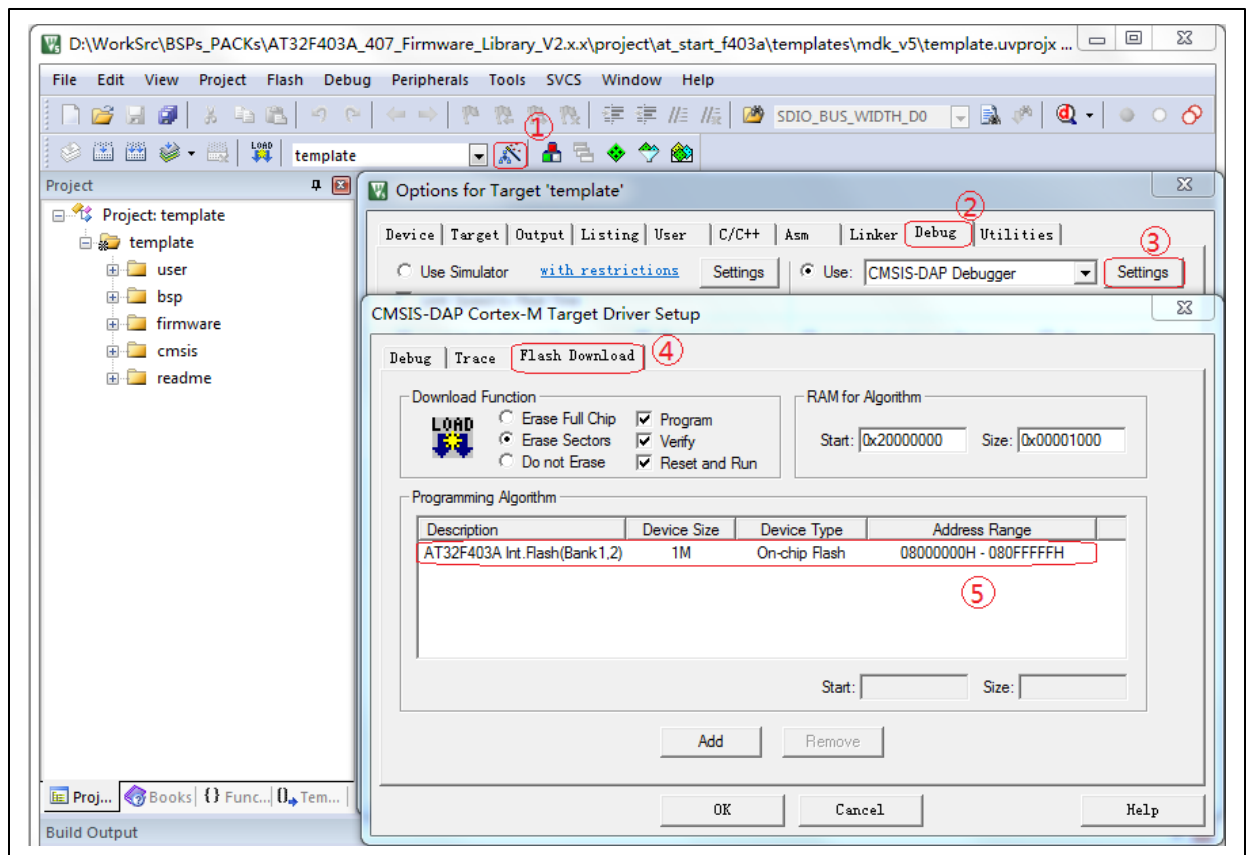
*Note: AT32 MUCs have similar Flash algorithms, and this section uses AT32F403A as an example.*

### 3.1 How to use Keil algorithm file

Common IDE tools such as Keil\_v4 and Keil\_v5 adopt a similar method to select and use the algorithm files. Here we take Keil\_v5 as an example.

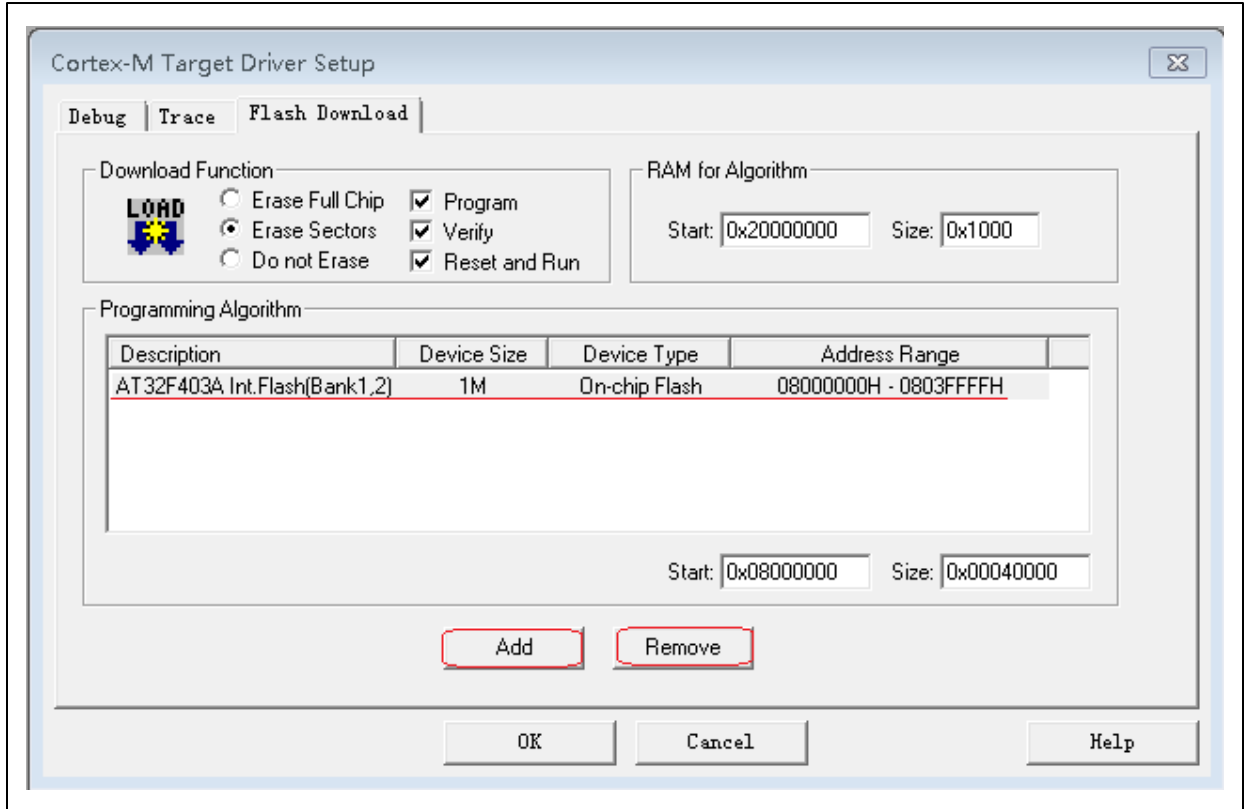
After creating a Keil IDE development tool project, the user can start Debug configuration and select the Flash algorithms. Go to *wand*—>*Debug*—>*Settings*—>*Flash Download*, as shown below:

**Figure 15. Keil algorithm file settings**



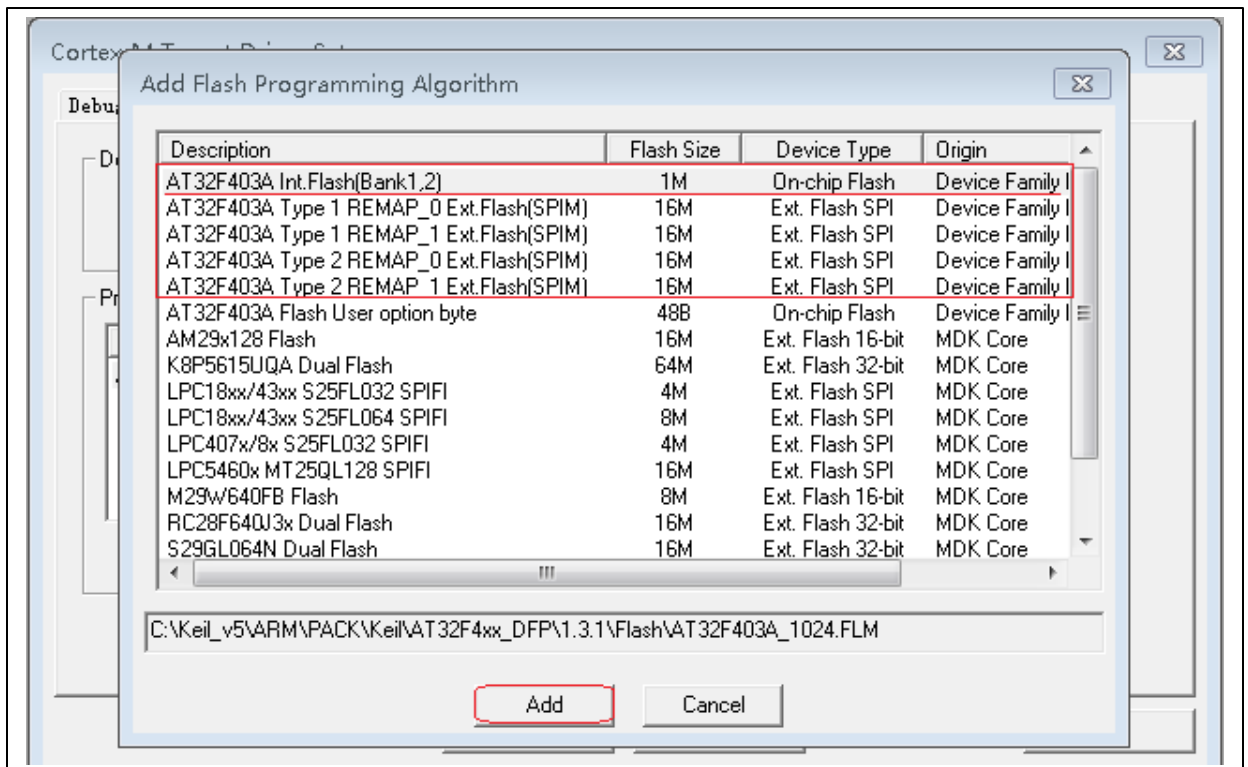
In this example, the selected Flash algorithm file is the default one. To change or remove it, click on this algorithm file, then click on *Add* or *Remove*. If the selected algorithm does not match the MCU, please follow the method below to modify.

Figure 16. Keil algorithm file configuration



Click on *Remove* to remove the existing algorithm from the configuration, then click on *Add* to view the algorithm files associated with a MCU model and select them, as shown below:

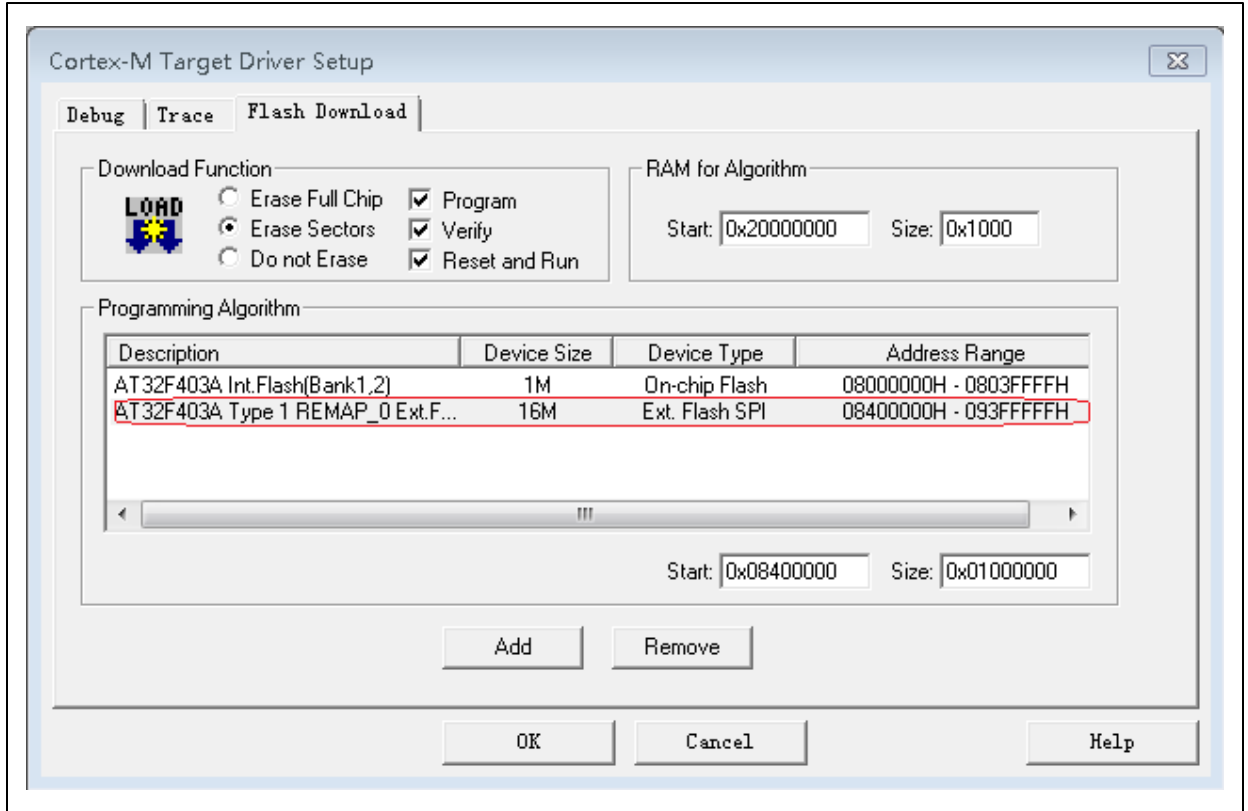
Figure 17. Select algorithm files using Keil



After selection, click on *Add* to add the selected algorithm files into the current configuration. For example, a new SPIM algorithm is added into the project.



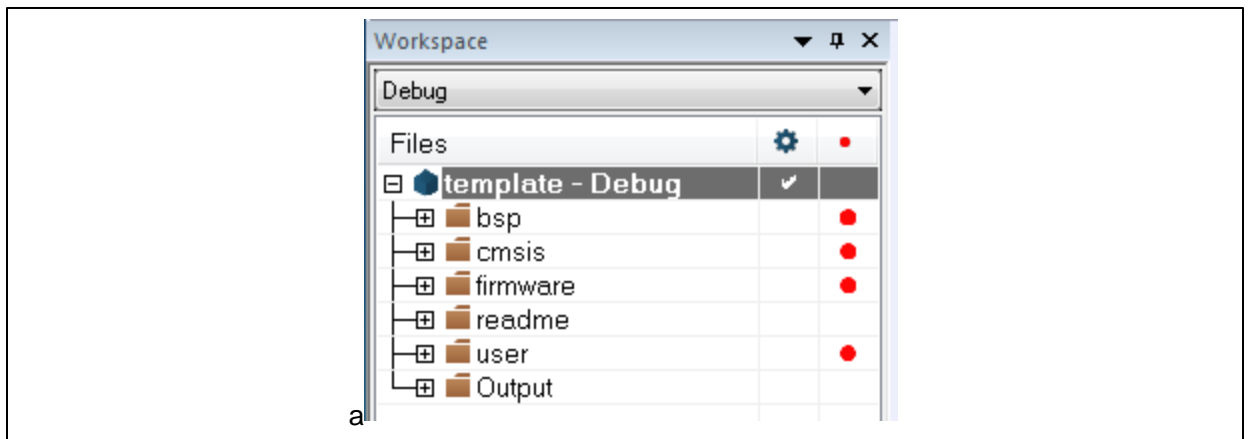
Figure 18. Add algorithm files using Keil



## 3.2 How to use IAR algorithm files

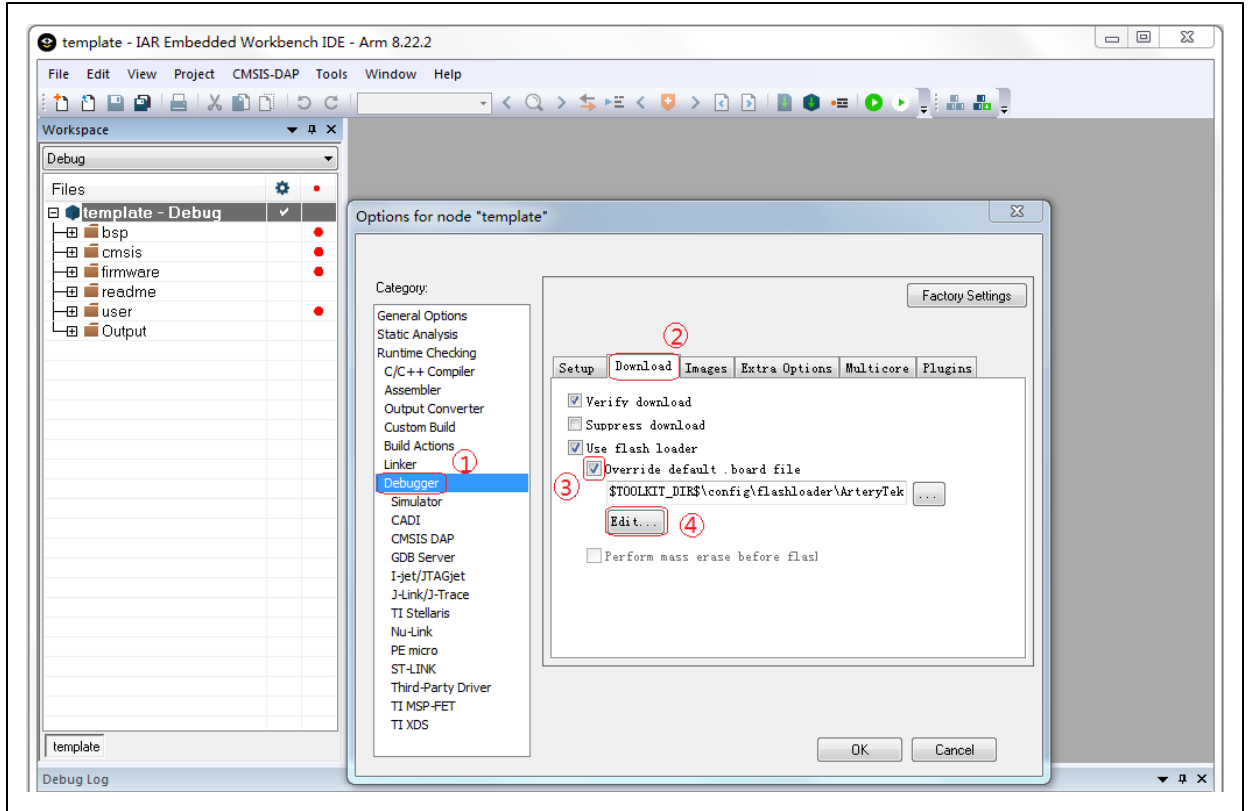
In IAR environment, the Flash algorithm files are automatically selected according to the selected MCU model during a new project configuration. To configure/modify an algorithm file manually, right-click on the file name (after an IAR project is created) in the following gray box:

Figure 19. IAR project name



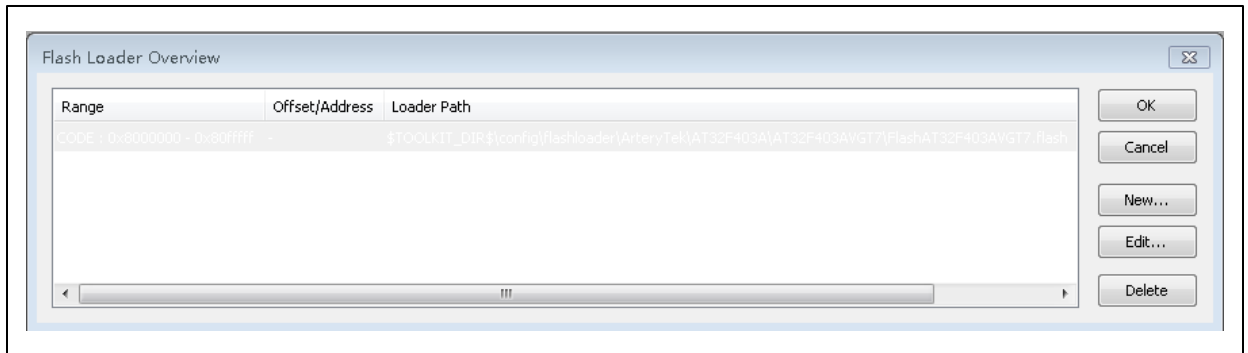
Go to *Options*—>*Debugger*—>*Download*—>Tick *Override default .board file*—>Click on *Edit*, as shown below:

Figure 20. IAR algorithm file configuration



Then the following window will be displayed.

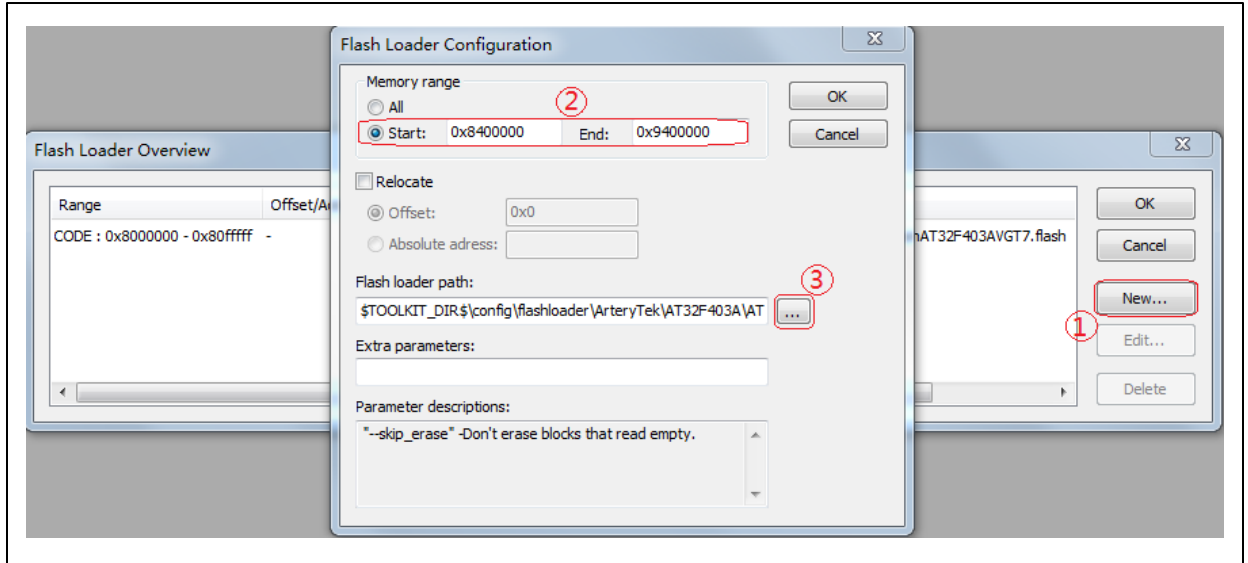
Figure 21. IAR Flash Loader Overview



Flash algorithm configuration is designated by default after selecting a MCU part number. To modify it, click on New/Edit/Delete.

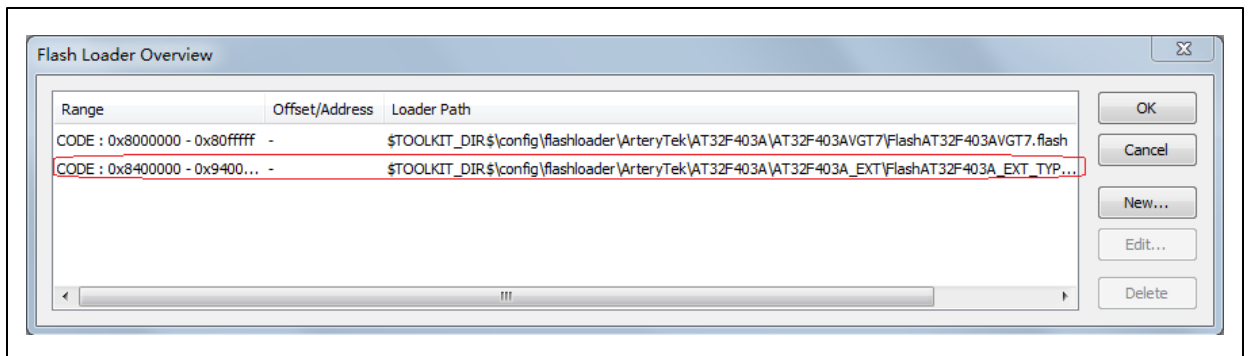
For example, click on *New*—>2. *Memory range*—>3. Select a Flash algorithm file, as shown below:

Figure 22. IAR Flash Loader configuration



This example shows how to add a SPIM Flash algorithm file. The user needs to select the corresponding MCU part number and a correct Flash algorithm file. The selected Flash algorithm configuration file is installed into IAR development environment using IAR\_AT32MCU\_AddOn tool. After a successful configuration, a new SPIM Flash algorithm is shown below.

Figure 23. IAR Flash Loader configuration success



## 1. Description of SPIM algorithms

Some Artery MCUs support Bank3 (refer to the Reference Manual or Datasheet on Artery official website for details), which can be used as an expansion of Flash memory in case of insufficient internal Flash or special application requirements. When the compiling addresses of some code or data are stored in the SPIM, these algorithm files are used for external Flash programming during online IDE tool download.

Naming rules of Artery SPIM algorithm file: AT32F4xxTypeNREMAP\_P Ext.Flash

N=1,2

P=0,1

**TYPEN:** External SPI Flash. Select it according to the external Flash type and part number. Refer to the FLASH\_SELECT register section of the corresponding MCU Reference Manual.

**REMAP\_P:** Select multiplex-function MCU SPIM PIN. Select it according to the connection method of pins connected to external Flash. Refer to the external SPIF remapping section in the corresponding MCU reference manual.

REMAP0: EXT\_SPIF\_GRMP=000

REMAP1: EXT\_SPIF\_GRMP=001

## 4 BSP introduction

### 4.1 Quick start

#### 4.1.1 Template project

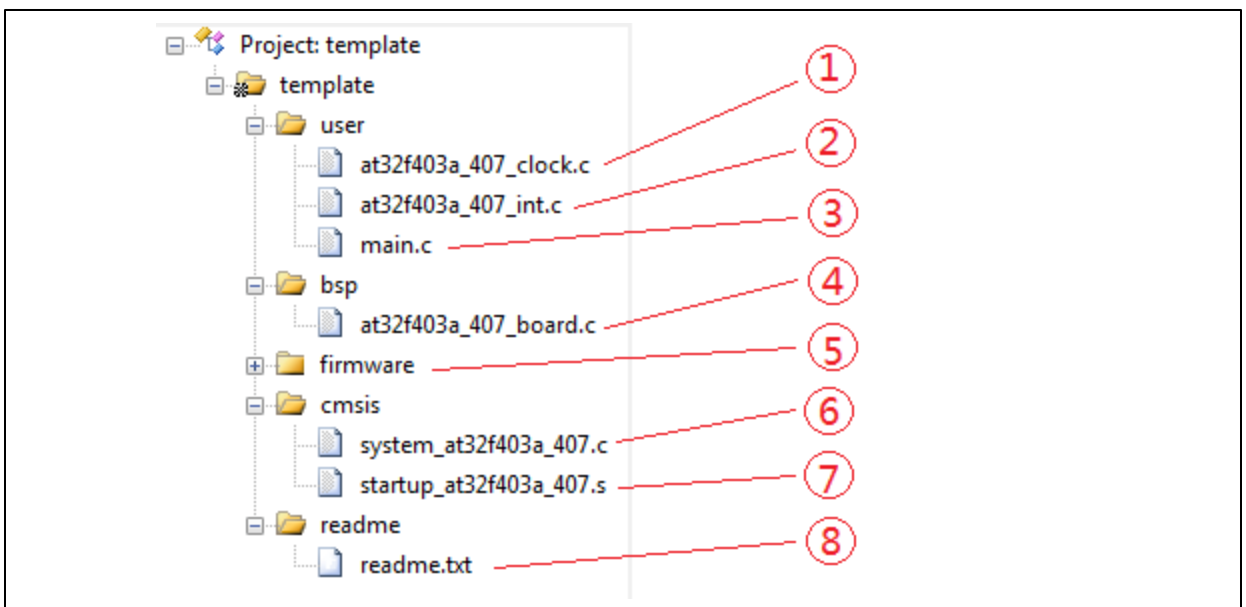
Artery firmware library BSP comes with a series of template projects built around Keil and IAR. For example, the template project of AT32F403A/407 series is located in *AT32F403A\_407\_Firmware\_Library\_V2.x.x/project/at\_start\_xxx/templates*.

**Figure 24. Template content**

|            |                |        |
|------------|----------------|--------|
| iar_v6.10  | 21/05/24 16:03 | 文件夹    |
| iar_v7.4   | 21/05/24 16:03 | 文件夹    |
| iar_v8.2   | 21/05/24 16:03 | 文件夹    |
| inc        | 21/05/24 16:03 | 文件夹    |
| mdk_v4     | 21/05/24 16:03 | 文件夹    |
| mdk_v5     | 21/05/24 16:03 | 文件夹    |
| src        | 21/05/24 16:03 | 文件夹    |
| readme.txt | 21/05/21 11:15 | TXT 文件 |

The above template project includes various versions such as Keil\_v5, Keil\_v4, IAR\_6.10, IAR\_7.4 and IAR\_8.2. Of those, “inc” and “src” folders contain header files and source code files. Open a corresponding folder and click on the corresponding file to open an IDE project. Figure 25 presents an example of Keil\_v5 template project (its details and version are subject to the actual firmware library).

**Figure 25. Keil\_v5 template project example**



The contents in a project include: (using AT32F403A/407 as an example, other products are similar)

- ① at32f403a\_407\_clock.c (clock configuration file) defines the default clock frequency and clock paths
- ② at32f403a\_407\_int.c (interrupt file) contains some interrupt handling codes
- ③ main.c contains the main code files

- ④ at32f403a\_407\_board.c (board configuration file) contains common hardware configurations such as buttons and LEDs on the AT-START-Evaluation Board
- ⑤ at32f403a\_407\_xx.c under firmware folder contains driver files of on-chip peripherals
- ⑥ system\_at32f403a\_407.c is the system initialization file
- ⑦ startup\_at32f403a\_407.s is a startup file
- ⑧ readme.txt is a readme file, containing functional description and configuration information

*Note: AT32 MUCs share similar BSP usage method, and this section uses AT32F403A as an example.*

## 4.1.2 BSP macro definitions

- ① To create a project, it is necessary to enable a startup code (startup\_at32f403a\_407.s) and open the appropriate macro definitions according to MCU part number before compiling code. Table 1 presents the correspondence between the MCUs and their macro definitions.

**Table 1. Summary of macro definitions**

| MCU part numbers | Macro definitions | PINs | Flash size (KB) |
|------------------|-------------------|------|-----------------|
| AT32F403ACCT7    | AT32F403ACCT7     | 48   | 256             |
| AT32F403ACET7    | AT32F403ACET7     | 48   | 512             |
| AT32F403ACGT7    | AT32F403ACGT7     | 48   | 1024            |
| AT32F403ACCU7    | AT32F403ACCU7     | 48   | 256             |
| AT32F403ACEU7    | AT32F403ACEU7     | 48   | 512             |
| AT32F403ACGU7    | AT32F403ACGU7     | 48   | 1024            |
| AT32F403ARCT7    | AT32F403ARCT7     | 64   | 256             |
| AT32F403ARET7    | AT32F403ARET7     | 64   | 512             |
| AT32F403ARGT7    | AT32F403ARGT7     | 64   | 1024            |
| AT32F403AVCT7    | AT32F403AVCT7     | 100  | 256             |
| AT32F403AVET7    | AT32F403AVET7     | 100  | 512             |
| AT32F403AVGT7    | AT32F403AVGT7     | 100  | 1024            |
| AT32F407RCT7     | AT32F407RCT7      | 64   | 256             |
| AT32F407RET7     | AT32F407RET7      | 64   | 512             |
| AT32F407RGT7     | AT32F407RGT7      | 64   | 1024            |
| AT32F407VCT7     | AT32F407VCT7      | 100  | 256             |
| AT32F407VET7     | AT32F407VET7      | 100  | 512             |
| AT32F407VGT7     | AT32F407VGT7      | 100  | 1024            |
| AT32F407AVCT7    | AT32F407AVCT7     | 100  | 256             |
| AT32F407AVGT7    | AT32F407AVGT7     | 100  | 1024            |

- ② In the header file (at32f403a\_407.h), USE\_STDPERIPH\_DRIVER (macro definition) is used to determine whether the Keil RTE feature is used or not. Enabling this definition while Keil RTE is unused can prevent some versions of Keil-MDK from opening \_RTE\_ accidentally.
- ③ The configuration header file (at32f403a\_407\_conf.h) defines macro definitions that enable peripherals. The file can be used to control the use of peripherals. The peripherals can be disabled simply by masking \_MODULE\_ENABLED pertaining to peripherals, as shown below:

Figure 26. Peripheral enable macro definitions

```
#define CRM_MODULE_ENABLED
#define TMR_MODULE_ENABLED
#define RTC_MODULE_ENABLED
#define BPR_MODULE_ENABLED
#define GPIO_MODULE_ENABLED
#define I2C_MODULE_ENABLED
#define USART_MODULE_ENABLED
#define PWC_MODULE_ENABLED
#define CAN_MODULE_ENABLED
#define ADC_MODULE_ENABLED
#define DAC_MODULE_ENABLED
#define SPI_MODULE_ENABLED
#define DMA_MODULE_ENABLED
#define DEBUG_MODULE_ENABLED
#define FLASH_MODULE_ENABLED
#define CRC_MODULE_ENABLED
#define WWDT_MODULE_ENABLED
#define WDT_MODULE_ENABLED
#define EXINT_MODULE_ENABLED
#define SDIO_MODULE_ENABLED
#define XMC_MODULE_ENABLED
#define USB_MODULE_ENABLED
#define ACC_MODULE_ENABLED
#define MISC_MODULE_ENABLED
#define EMAC_MODULE_ENABLED
```

at32f403a\_407\_conf.h also defines the HEXT\_VALUE (high-speed external clock value), which should be modified accordingly when changing an external high-speed crystal oscillator.

- ④ The system clock configuration file (at32f403a\_407\_clock.c/h) defines the default system clock frequency and clock paths. The user, if needed, can customize the frequency multiplication process and factors, or generate corresponding clock configuration files using the clock configuration host of ArteryTek.

## 4.2 BSP specifications

The subsequent sections give a description of BSP specifications.

### 4.2.1 List of abbreviations for peripherals

**Table 2. List of abbreviations for peripherals**

| Abbreviations | Description   |
|---------------|---|
| ADC           | Analog-to-digital converter                             |
| BPR           | Battery powered register                                |
| CAN           | Controller area network                                 |
| CRC           | CRC calculation unit                                    |
| CRM           | Clock and reset manage                                  |
| DAC           | Digital-to-analog converter                             |
| DMA           | Direct memory access                                    |
| DEBUG         | Debug   |
| EXINT         | External interrupt/event controller                     |
| GPIO          | General-purpose I/Os                                    |
| IOMUX         | Multiplexed I/Os  |
| I2C           | Inter-integrated circuit interface                      |
| NVIC          | Nested vectored interrupt controller                    |
| PWC           | Power controller  |
| RTC           | Real-time clock   |
| SPI           | Serial peripheral interface                             |
| I2S           | Inter-IC Sound  |
| SysTick       | System tick timer                                       |
| TMR           | Timer   |
| USART         | Universal synchronous asynchronous receiver transmitter |
| WDT           | Watchdog timer  |
| WWDT          | Window watchdog timer                                   |
| XMC           | External memory controller                              |

## 4.2.2 Naming rules

The naming rules for BSP are described as follows:

“ip” indicates an abbreviation of a peripheral, for example, ADC, TMR, GPIO, etc., regardless of upper and lower case letters, such as adc, tmr, gpio.

- **Source code file**

The file name starts with “at32fxxx\_ip.c”, for example, at32f403a\_407\_adc.c.

- **Header file**

The file name starts with “at32fxxx\_ip.h”, for example, at32f403a\_407\_adc.h.

- **Constant**

If it is used in a single one file, the constant is then defined in this file; if it is used in multiple files, the constant is defined in corresponding header file.

All constants are in written in English capital letters.

- **Variable**

If it is used in a single one file, the variable is then defined in this file; if it is used in multiple files, the variable is declared with “extern” in the corresponding header file.

- **Naming rules for functions**

The peripheral functions are named based on the rule of “**peripheral abbreviation\_attribute\_action**” or “**peripheral abbreviation\_action**”.

The commonly used functions are as follows:

| Function type                             | Naming rule          | Example               |
|---|----------------------|-----------------------|
| Peripheral reset                          | ip_reset             | adc_reset             |
| Peripheral enable                         | ip_enable            | adc_enable            |
| Peripheral structure parameter initialize | ip_default_para_init | spi_default_para_init |
| Peripheral initialize                     | ip_init              | spi_init              |
| Peripheral interrupt enable               | ip_interrupt_enable  | adc_interrupt_enable  |
| Peripheral flag get                       | ip_flag_get          | adc_flag_get          |
| Peripheral flag clear                     | ip_flag_clear        | adc_flag_clear        |



### 4.2.3 Encoding rules

This section describes the encoding rules related to firmware function library.

Type of variables:

```
typedef int32_t INT32;
```

```
typedef int16_t INT16;
```

```
typedef int8_t INT8;
```

```
typedef uint32_t UINT32;
```

```
typedef uint16_t UINT16;
```

```
typedef uint8_t UINT8;
```

```
typedef int32_t s32;
```

```
typedef int16_t s16;
```

```
typedef int8_t s8;
```

```
typedef const int32_t sc32; /*!< read only */
```

```
typedef const int16_t sc16; /*!< read only */
```

```
typedef const int8_t sc8; /*!< read only */
```

```
typedef __IO int32_t vs32;
```

```
typedef __IO int16_t vs16;
```

```
typedef __IO int8_t vs8;
```

```
typedef __I int32_t vsc32; /*!< read only */
```

```
typedef __I int16_t vsc16; /*!< read only */
```

```
typedef __I int8_t vsc8; /*!< read only */
```

```
typedef uint32_t u32;
```

```
typedef uint16_t u16;
```

```
typedef uint8_t u8;
```

```
typedef const uint32_t uc32; /*!< read only */
```

```
typedef const uint16_t uc16; /*!< read only */
```

```
typedef const uint8_t uc8; /*!< read only */
```

```
typedef __IO uint32_t vu32;
```

```
typedef __IO uint16_t vu16;
```

```
typedef __IO uint8_t vu8;
```

```
typedef __I uint32_t vuc32; /*!< read only */
```

```
typedef __I uint16_t vuc16; /*!< read only */
```

```
typedef __I uint8_t vuc8; /*!< read only */
```

### 4.2.3.1 Flag type

```
typedef enum {RESET = 0, SET = !RESET} flag_status;
```

### 4.2.3.2 Function status type

```
typedef enum {FALSE = 0, TRUE = !FALSE} confirm_state;
```

### 4.2.3.3 Error status type

```
typedef enum {ERROR = 0, SUCCESS = !ERROR} error_status;
```

### 4.2.3.4 Peripheral type

① Peripherals

Define the base address of peripheral in the at32fxxx\_ip.h, for example, in the at32f403a\_407.h:

```
#define ADC1_BASE (APB2PERIPH_BASE + 0x2400)
#define ADC2_BASE (APB2PERIPH_BASE + 0x2800)
```

Define the type of a peripheral in the at32fxxx\_ip.h, for example, in the at32f403a\_407\_adc.h:

```
#define ADC1 ((adc_type *) ADC1_BASE)
#define ADC2 ((adc_type *) ADC2_BASE)
```

② Peripheral registers and bits

Define the type of a peripheral in the at32fxxx\_ip.h, for example, in the at32f403a\_407\_adc.h

```
/**
 * @brief type define adc register all
 */
typedef struct
{
    /**
     * @brief adc sts register, offset:0x00
     */
    union
    {
        __IO uint32_t sts;
        struct
        {
            __IO uint32_t vmor : 1; /* [0] */
            __IO uint32_t tcce : 1; /* [1] */
            __IO uint32_t pcce : 1; /* [2] */
            __IO uint32_t pccs : 1; /* [3] */
            __IO uint32_t toccs : 1; /* [4] */
            __IO uint32_t reserved1 : 27; /* [31:5] */
        } sts_bit;
    };
} ...
```

```
...
...
/**
 * @brief adc odt register, offset:0x4C
 */
union
{
  __IO uint32_t odt;
  struct
  {
    __IO uint32_t odt                : 16; /* [15:0] */
    __IO uint32_t adc2odt            : 16; /* [31:16] */
  } odt_bit;
};

} adc_type;
```

③ Examples of peripheral register access

|                                    |   |
|------------------------------------|---|
| Read peripheral                    | <code>i = ADC1-&gt; ctrl1;</code>                 |
| Write peripheral                   | <code>ADC1-&gt; ctrl1 = i;</code>                 |
| Read bit 5 in bit-field mode       | <code>i = ADC1-&gt; ctrl1.cceien;</code>          |
| Write 1 to bit 5 in bit-field mode | <code>ADC1-&gt; ctrl1.cceien = TRUE;</code>       |
| Write 1 to bit 5                   | <code>ADC1-&gt; ctrl1  = 1&lt;&lt;5;</code>       |
| Write 0 to bit 5                   | <code>ADC1-&gt; ctrl1&amp;= ~(1&lt;&lt;5);</code> |

## 4.3 BSP structure

### 4.3.1 BSP folder structure

BSP (Board Support Package) structure is shown in Figure 27.

Figure 27. BSP folder structure

|   |                |     |
|---|----------------|-----|
|  document    | 21/05/18 10:32 | 文件夹 |
|  libraries   | 21/05/18 10:32 | 文件夹 |
|  middlewares | 21/05/18 10:32 | 文件夹 |
|  project     | 21/05/18 10:32 | 文件夹 |
|  utilities   | 21/05/14 11:35 | 文件夹 |

**document:**

- AT32Fxxx firmware library BSP&Pack user guide.pdf: refer to BSP/Pack user manual
- ReleaseNotes\_AT32F403A\_407\_Firmware\_Library.pdf: document revision history

**libraries:**

- **drivers:** driver library for peripherals  
src folder: low-level driver source file for peripherals, such as at32fxxx\_ip.c  
inc folder: low-level driver header file for peripherals, such as at32fxxx\_ip.h
- **cmsis:** core-related files  
cm4 folder: core-related files, including cortex-m4 library, system initialization file, startup file, etc.  
dsp folder: dsp-related files

**middlewares:**

Third-party software or public protocols, including USB protocol layer driver, network protocol driver, operating system source code, etc.

**project:**

examples: demo  
templates: template project, including Keil4, keil5, IAR6, IAR7, IAR8 and eclipse\_gcc

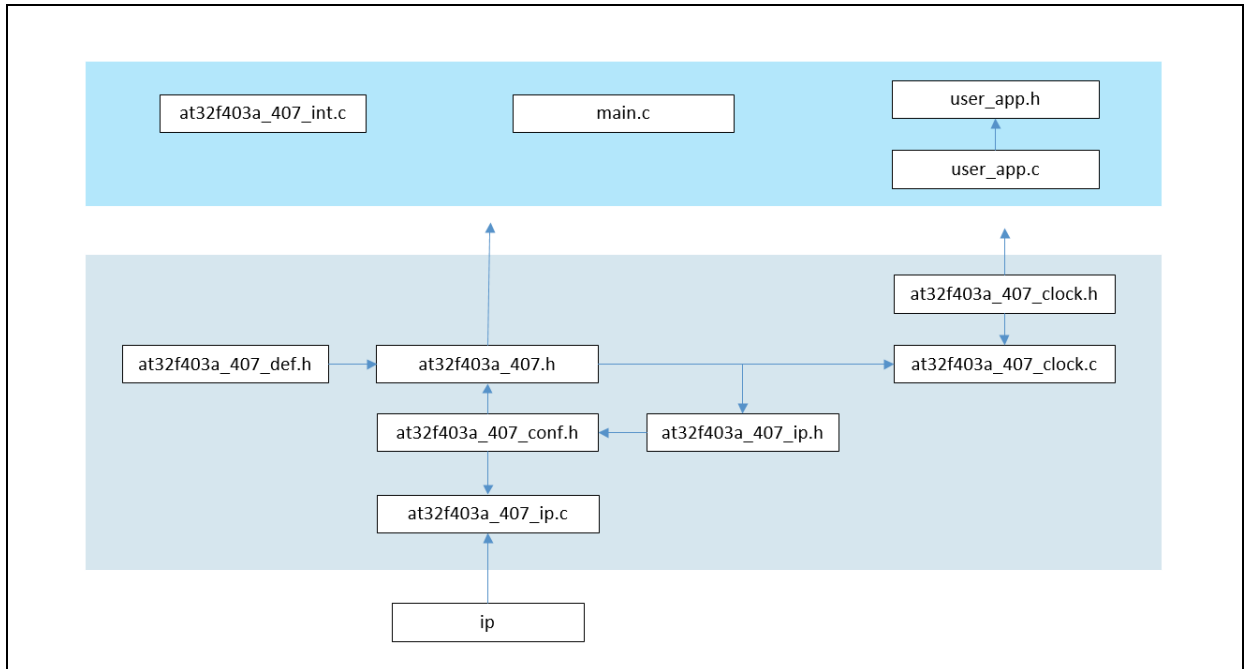
**utilities:**

Store application cases

## 4.3.2 BSP function library structure

Figure 28 shows the architecture of BSP function library.

**Figure 28. BSP function library structure**



BSP function library files are described in Table 3.

**Table 3. Summary of BSP function library files**

| File name               | Description   |
|-------------------------|---|
| at32f403a_407_conf.h    | Macro definition for peripheral enable, and external high-speed clock HEXT_VALUE  |
| main.c                  | Main function   |
| at32f403a_407_ip.c      | Driver source file for a peripheral, for example, at32f403a_407_adc.c   |
| at32f403a_407_ip.h      | Driver header file for a peripheral, for example, at32f403a_407_adc.h   |
| at32f403a_407.h         | In the header file (at32f403a_407.h), the definition USE_STDPERIPH_DRIVER is used to determine whether the Keil RTE is used or not. Enabling the definition while Keil RTE is unused can prevent Keil-MDK from enabling _RTE_ accidentally. |
| at32f403a_407_clock.c   | This is a clock configuration file used to configure default clock frequency and clock path.  |
| at32f403a_407_clock.h   | This is a clock configure header file.  |
| at32f403a_407_int.c     | This is a source file for interrupt functions that programs interrupt handling code.  |
| at32f403a_407_int.h     | This is a header file for interrupt functions.  |
| at32f403a_407_misc.c    | This is a source file for other configurations, such as, nvic configuration function, systick clock source selection.   |
| at32f403a_407_misc.h    | This is a header file for other configurations.   |
| startup_at32f403a_407.s | This is a startup file.   |

### 4.3.3 Initialization and configuration for peripherals

This section describes how to initialize and configure peripherals using GPIO as an example.

#### GPIO initialization

Step 1: Define the `gpio_init_type`, for example, `gpio_init_type gpio_init_struct;`

Step 2: Enable GPIO clock using the function `crm_periph_clock_enable;`

Step 3: De-initialize the structure `gpio_init_struct` to allow the values of other members (mostly default values) to be correctly written, for example, `gpio_default_para_init(&gpio_init_struct);`

Step 4: Configure member of the structure, and write structure parameters into GPIO registers through the `gpio_init`, for example,

```
gpio_init_struct.gpio_pins = GPIO_PINS_2 | GPIO_PINS_3;
```

```
gpio_init_struct.gpio_mode = GPIO_MODE_OUTPUT;
```

```
gpio_init_struct.gpio_out_type = GPIO_OUTPUT_PUSH_PULL;
```

```
gpio_init_struct.gpio_pull = GPIO_PULL_NONE;
```

```
gpio_init_struct.gpio_drive_strength = GPIO_DRIVE_STRENGTH_STRONGER;
```

```
gpio_init(GPIOA, &gpio_init_struct);
```

For more information on peripheral initialization procedure, refer to the section of peripherals of the Reference Manual, and the section of peripherals of the `AT32Fxxx_Firmware_Library_V2.x.x.zip\project\at_start_fxx\examples`.

### 4.3.4 Peripheral functions format description

**Table 4. Function format description for peripherals**

| Name                   | Description                                       |
|------------------------|---|
| Function name          | The name of a peripheral function.                |
| Function prototype     | Prototype declaration                             |
| Function description   | Brief description of how the function is executed |
| Input parameter (n)    | Description of the input parameters               |
| Output parameter (n)   | Description of the output parameters              |
| Return value           | Value returned by the function                    |
| Required preconditions | Requirements before calling the function          |
| Called functions       | Other library functions called                    |

## 5 AT32F435/437 peripheral library functions

### 5.1 HICK automatic clock calibration (ACC)

The ACC register structure `acc_type` is defined in the “`at32f435_437_acc.h`”.

```
/**
 * @brief type define acc register all
 */
typedef struct
{
    .....
} acc_type;
```

The table below gives a list of the ACC registers.

**Table 5. Summary of ACC registers**

| Register               | Description            |
|------------------------|------------------------|
| <code>acc_sts</code>   | ACC status register    |
| <code>acc_ctrl1</code> | ACC control register 1 |
| <code>acc_ctrl2</code> | ACC control register 2 |
| <code>acc_c1</code>    | ACC compare value 1    |
| <code>acc_c2</code>    | ACC compare value 2    |
| <code>acc_c3</code>    | ACC compare value 3    |

The table below gives a list of the ACC library functions.

**Table 6. Summary of ACC library functions**

| Function name                            | Description                           |
|--|---------------------------------------|
| <code>acc_calibration_mode_enable</code> | ACC calibration mode enable           |
| <code>acc_step_set</code>                | Configure ACC calibration step length |
| <code>acc_interrupt_enable</code>        | ACC interrupt enable                  |
| <code>acc_hicktrim_get</code>            | Get ACC trimming calibration value    |
| <code>acc_hickcal_get</code>             | Get ACC coarse calibration value      |
| <code>acc_write_c1</code>                | Write ACC C1 register value           |
| <code>acc_write_c2</code>                | Write ACC C2 register value           |
| <code>acc_write_c3</code>                | Write ACC C3 register value           |
| <code>acc_read_c1</code>                 | Read ACC C1 register value            |
| <code>acc_read_c2</code>                 | Read ACC C2 register value            |
| <code>acc_read_c3</code>                 | Read ACC C3 register value            |
| <code>acc_flag_get</code>                | Get ACC interrupt flag                |
| <code>acc_flag_clear</code>              | Clear ACC interrupt flag              |

### 5.1.1 acc\_calibration\_mode\_enable function

The table below describes the function acc\_calibration\_mode\_enable.

**Table 7. acc\_calibration\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | acc_calibration_mode_enable   |
| Function prototype     | void acc_calibration_mode_enable(uint16_t acc_trim, confirm_state new_state); |
| Function description   | ACC calibration mode enable   |
| Input parameter 1      | acc_trim: calibration mode selection<br>ACC_CAL_HICKCAL or ACC_CAL_HICKTRIM   |
| Input parameter 2      | new_state: Enable or disable ACC  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### acc\_trim

Calibration mode selection

ACC\_CAL\_HICKCAL: Coarse calibration mode

ACC\_CAL\_HICKTRIM: Fine calibration mode

#### new\_state

Enable or disable ACC

FALSE: Disabled

TRUE: Enabled

#### Example:

```
/* open acc calibration */
acc_calibration_mode_enable(ACC_CAL_HICKTRIM, TRUE);
```

### 5.1.2 acc\_step\_set function

The table below describes the function acc\_step\_set.

**Table 8. acc\_step\_set function**

| Name                   | Description                            |
|------------------------|--|
| Function name          | acc_step_set                           |
| Function prototype     | void acc_step_set(uint8_t step_value); |
| Function description   | Configure ACC calibration step length  |
| Input parameter 1      | step_value: step value for calibration |
| Output parameter       | NA                                     |
| Return value           | NA                                     |
| Required preconditions | NA                                     |
| Called functions       | NA                                     |

#### step\_value

This 4-bit field defines the value to be changed for each calibration.

Note: To obtain better calibration accuracy, it is recommended to set the step value to 1.

When ENTRIM=0, only HICKCAL is calibrated. If the step value is incremented or decremented



by one, the corresponding HICKCAL follows the change rule (increased or decreased by one), and the HICK frequency will increase or decrease by 40 KHz (design value), meaning a positive correlation between them.

When ENTRIM=1, only the HICKTRIM is calibrated. If the step value is incremented or decremented by one, the corresponding HICKTRIM follows the change rule (increased or decreased by one), and the HICK will increase or decrease by 20 KHz(design value), meaning a positive correlation between them.

**Example:**

```
/* set acc step value */
acc_step_set(0x1);
```

### 5.1.3 acc\_interrupt\_enable function

The table below describes the function acc\_interrupt\_enable.

**Table 9. acc\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dma_interrupt_enable  |
| Function prototype     | void acc_interrupt_enable(uint16_t acc_int, confirm_state new_state); |
| Function description   | Enable acc interrupts   |
| Input parameter 1      | acc_int: interrupt source selection                                   |
| Input parameter 2      | new_state: enable or disable interrupts                               |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**acc\_int**

Interrupt source selection

ACC\_CALRDYIEN\_INT: Calibration complete interrupt

ACC\_EIEN\_INT: Reference signal lost interrupt

**new\_state**

Enable or disable interrupts

FALSE: Interrupt disabled

TRUE: Interrupt enabled

**Example:**

```
/* enable the acc reference signal lost interrupt */
acc_interrupt_enable(ACC_EIEN_INT, TRUE);
```

### 5.1.4 acc\_hicktrim\_get function

The table below describes the function acc\_hicktrim\_get.

**Table 10. acc\_hicktrim\_get function**

| Name                   | Description                           |
|------------------------|---------------------------------------|
| Function name          | acc_hicktrim_get                      |
| Function prototype     | uint8_t acc_hicktrim_get(void);       |
| Function description   | Get acc trimming calibration value    |
| Input parameter        | NA                                    |
| Output parameter       | NA                                    |
| Return value           | Return acc trimming calibration value |
| Required preconditions | NA                                    |
| Called functions       | NA                                    |

**Example:**

```

/* get trim value*/
uint8_t trim_value;
trim_value = acc_hicktrim_get();
    
```

### 5.1.5 acc\_hickcal\_get function

The table below describes the function acc\_hickcal\_get.

**Table 11. acc\_hickcal\_get function**

| Name                   | Description                         |
|------------------------|-------------------------------------|
| Function name          | acc_hickcal_get                     |
| Function prototype     | uint8_t acc_hickcal_get(void);      |
| Function description   | Get acc coarse calibration value    |
| Input parameter        | NA                                  |
| Output parameter       | NA                                  |
| Return value           | Return acc coarse calibration value |
| Required preconditions | NA                                  |
| Called functions       | NA                                  |

**Example:**

```

/* get cal value*/
uint8_t cal_value;
cal_value = acc_hickcal_get();
    
```

### 5.1.6 acc\_write\_c1 function

The table below describes the function acc\_write\_c1.

**Table 12. acc\_write\_c1 function**

| Name                   | Description  |
|------------------------|--|
| Function name          | acc_write_c1   |
| Function prototype     | void acc_write_c1(uint16_t acc_c1_value);                |
| Function description   | Write ACC C1 register value                              |
| Input parameter        | acc_c1_value: the value to be written in ACC C1 register |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* update the c1 value */
acc_c2_value = 8000;
acc_write_c1(acc_c2_value - 10);
```

### 5.1.7 acc\_write\_c2 function

The table below describes the function acc\_write\_c2.

**Table 13. acc\_write\_c2 function**

| Name                   | Description  |
|------------------------|--|
| Function name          | acc_write_c2   |
| Function prototype     | void acc_write_c2(uint16_t acc_c2_value);                |
| Function description   | Write ACC C2 register value                              |
| Input parameter        | acc_c2_value: the value to be written in ACC C2 register |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* update the c2 value */
acc_c2_value = 8000;
acc_write_c2(acc_c2_value - 10);
```

### 5.1.8 acc\_write\_c3 function

The table below describes the function acc\_write\_c3.

**Table 14. acc\_write\_c3 function**

| Name                   | Description  |
|------------------------|--|
| Function name          | acc_write_c3   |
| Function prototype     | void acc_write_c3(uint16_t acc_c3_value);                |
| Function description   | Write ACC C3 register value                              |
| Input parameter        | acc_c3_value: the value to be written in ACC C3 register |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* update the c3 value */
acc_c2_value = 8000;
acc_write_c3(acc_c2_value - 10);
```

### 5.1.9 acc\_read\_c1 function

The table below describes the function acc\_read\_c1.

**Table 15. acc\_read\_c1 function**

| Name                   | Description                 |
|------------------------|-----------------------------|
| Function name          | acc_read_c1                 |
| Function prototype     | uint16_t acc_read_c1(void); |
| Function description   | Read ACC C1 register value  |
| Input parameter        | NA                          |
| Output parameter       | NA                          |
| Return value           | ACC C1 register value       |
| Required preconditions | NA                          |
| Called functions       | NA                          |

**Example:**

```
/* get the c1 value */
uint16_t acc_c1_value;
acc_c1_value = acc_read_c1();
```

### 5.1.10 acc\_read\_c2 function

The table below describes the function acc\_read\_c2.

**Table 16. acc\_read\_c2 function**

| Name                   | Description                 |
|------------------------|-----------------------------|
| Function name          | acc_read_c2                 |
| Function prototype     | uint16_t acc_read_c2(void); |
| Function description   | Read ACC C2 register value  |
| Input parameter        | NA                          |
| Output parameter       | NA                          |
| Return value           | ACC C2 register value       |
| Required preconditions | NA                          |
| Called functions       | NA                          |

**Example:**

```
/* get the c2 value */
uint16_t acc_c2_value;
acc_c2_value = acc_read_c2();
```

### 5.1.11 acc\_read\_c3 function

The table below describes the function acc\_read\_c3.

**Table 17. acc\_read\_c3 function**

| Name                   | Description                 |
|------------------------|-----------------------------|
| Function name          | acc_read_c3                 |
| Function prototype     | uint16_t acc_read_c3(void); |
| Function description   | Read ACC C3 register value  |
| Input parameter        | NA                          |
| Output parameter       | NA                          |
| Return value           | ACC C3 register value       |
| Required preconditions | NA                          |
| Called functions       | NA                          |

**Example:**

```
/* get the c3 value */
uint16_t acc_c3_value;
acc_c3_value = acc_read_c3();
```

### 5.1.12 acc\_flag\_get function

The table below describes the function acc\_flag\_get.

**Table 18. acc\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | acc_flag_get  |
| Function prototype     | flag_status acc_flag_get(uint16_t acc_flag);                |
| Function description   | Get acc flag status   |
| Input parameter 1      | acc_flag: ACC flag selection                                |
| Output parameter       | NA  |
| Return value           | flag_status: indicates whether or not the flag has been set |
| Required preconditions | NA  |
| Called functions       | NA  |

#### acc\_flag

The acc\_flag is used for flag selection, including:

ACC\_RSLOST\_FLAG: Reference signal lost interrupt

ACC\_CALRDY\_FLAG: Calibration complete interrupt

#### flag\_status

RESET: Corresponding flag bit is not set

SET: Corresponding flag bit is set

#### Example:

```

if(acc_flag_get(ACC_CALRDY_FLAG) != RESET)
{
    at32_led_toggle(LED2);
    /* clear acc calibration readyflag */
    acc_flag_clear(ACC_CALRDY_FLAG);
}
    
```

### 5.1.13 acc\_flag\_clear function

The table below describes the function acc\_flag\_clear.

**Table 19. acc\_flag\_clear function**

| Name                   | Description                             |
|------------------------|---|
| Function name          | acc_flag_clear                          |
| Function prototype     | void acc_flag_clear(uint16_t acc_flag); |
| Function description   | Clear acc flag                          |
| Input parameter 1      | acc_flag: ACC flag selection            |
| Output parameter       | NA                                      |
| Return value           | NA                                      |
| Required preconditions | NA                                      |
| Called functions       | NA                                      |

#### acc\_flag

The acc\_flag is used for flag selection, including:

ACC\_RSLOST\_FLAG: Reference signal lost interrupt

ACC\_CALRDY\_FLAG: Calibration complete interrupt

**Example:**

```

if(acc_flag_get(ACC_CALRDY_FLAG) != RESET)
{
    at32_led_toggle(LED2);
    /* clear acc calibration readyflag */
    acc_flag_clear(ACC_CALRDY_FLAG);
}
    
```

## 5.2 Analog-to-digital converter (ADC)

ADC register structure `adc_type` is defined in the “at32f435\_437\_adc.h”.

```

/**
 * @brief type define adc register all
 */
typedef struct
{
    .....
} adc_type;
    
```

The table below gives a list of the ADC registers.

**Table 20. Summary of ADC registers**

| Register | Description                                  |
|----------|--|
| sts      | ADC status register                          |
| ctrl1    | ADC control register 1                       |
| ctrl2    | ADC control register 2                       |
| spt1     | ADC sample time register 1                   |
| spt2     | ADC sample time register 2                   |
| pcdto1   | ADC preempted channel data offset register 1 |
| pcdto2   | ADC preempted channel data offset register 2 |
| pcdto3   | ADC preempted channel data offset register 3 |
| pcdto4   | ADC preempted channel data offset register 4 |
| vmhb     | ADC voltage monitor high boundary register   |
| vmhb     | ADC voltage monitor low boundary register    |
| osq1     | ADC ordinary sequence register 1             |
| osq2     | ADC ordinary sequence register 2             |
| osq3     | ADC ordinary sequence register 3             |
| psq      | ADC preempted sequence register              |
| pdt1     | ADC preempted data register 1                |
| pdt2     | ADC preempted data register 2                |
| pdt3     | ADC preempted data register 3                |
| pdt4     | ADC preempted data register 4                |
| odt      | ADC ordinary data register                   |
| ovsp     | ADC oversampling register                    |
| calval   | ADC valibration value register               |
| csts     | ADC common status register                   |

| Register | Description                       |
|----------|-----------------------------------|
| cctrl    | ADC common control register       |
| codt     | ADC common ordinary data register |

The table below gives a list of ADC library functions.

**Table 21. Summary of ADC library functions**

| Function name                             | Description   |
|---|---|
| adc_reset                                 | Reset all ADC registers to their reset values   |
| adc_enable                                | Enable A/D converter  |
| adc_base_default_para_init                | Define an initial value for adc_base_struct   |
| adc_base_config                           | Configure ADC registers with the initialized parameters of the adc_base_struct                          |
| adc_common_default_para_init              | Define an initial value for adc_common_struct   |
| adc_common_config                         | Configure ADC common register with the initialized parameters of the adc_common_struct                  |
| adc_resolution_set                        | Set ADC conversion resolution   |
| adc_voltage_battery_enable                | VBAT enable   |
| adc_dma_mode_enable                       | Enable DMA transfer for ordinary group  |
| adc_dma_request_repeat_enable             | Enable DMA request repetition mode for ordinary group conversion  |
| adc_interrupt_enable                      | Enable the selected ADC event interrupt   |
| adc_calibration_value_set                 | Set calibration value by software   |
| adc_calibration_init                      | Initialization calibration  |
| adc_calibration_init_status_get           | Get initialization calibration status   |
| adc_calibration_start                     | Start calibration   |
| adc_calibration_status_get                | Get calibration status  |
| adc_voltage_monitor_enable                | Enable voltage monitoring for ordinary/preempted channels and a single channel                          |
| adc_voltage_monitor_threshold_value_set   | Set the threshold of voltage monitoring   |
| adc_voltage_monitor_single_channel_select | Select a single channel for voltage monitoring  |
| adc_ordinary_channel_set                  | Configure ordinary channels, including channel selection, conversion sequence number and sampling time  |
| adc_preempt_channel_length_set            | Configure the length of preempted group conversion sequence   |
| adc_preempt_channel_set                   | Configure preempted channels, including channel selection, conversion sequence number and sampling time |
| adc_ordinary_conversion_trigger_set       | Enable trigger mode and trigger event selection for ordinary conversion                                 |
| adc_preempt_conversion_trigger_set        | Enable trigger mode and trigger event selection for preempted conversion                                |
| adc_preempt_offset_value_set              | Set data offset for preempted conversion  |
| adc_ordinary_part_count_set               | Set the number of ordinary channels for each triggered conversion in partition mode                     |
| adc_ordinary_part_mode_enable             | Enable partition mode for ordinary channels   |
| adc_preempt_part_mode_enable              | Enable partition mode for preempted channels  |



| Function name                            | Description   |
|--|---|
| adc_preempt_auto_mode_enable             | Enable auto conversion of preempted group at the end of ordinary conversion |
| adc_conversion_stop                      | Stop on-going ADC conversion  |
| adc_conversion_stop_status_get           | Get the status of stop conversion command                                   |
| adc_occe_each_conversion_enable          | Enable OCCE flag for each ordinary channel conversion                       |
| adc_ordinary_software_trigger_enable     | Software trigger ordinary group conversion                                  |
| adc_ordinary_software_trigger_status_get | Get the status of ordinary group conversion triggered by software           |
| adc_preempt_software_trigger_enable      | Software trigger preempted group conversion                                 |
| adc_preempt_software_trigger_status_get  | Get the status of preempted group conversion triggered by software          |
| adc_ordinary_conversion_data_get         | Get data of ordinary group conversion in non-master-slave mode              |
| adc_combine_ordinary_conversion_data_get | Get data of ordinary group conversion in master-slave mode                  |
| adc_preempt_conversion_data_get          | Get the converted data of preempted group                                   |
| adc_flag_get                             | Get the status of flag bits   |
| adc_flag_clear                           | Clear flag bits   |
| adc_ordinary_oversample_enable           | Enable oversampling of ordinary group                                       |
| adc_preempt_oversample_enable            | Enable oversampling of preempted group                                      |
| adc_oversample_ratio_shift_set           | Set oversampling ratio and its shift length                                 |
| adc_ordinary_oversample_trig_enable      | Enable oversampling trigger mode of ordinary group                          |
| adc_ordinary_oversample_restart_set      | Enable oversampling restart mode of ordinary group                          |

### 5.2.1 adc\_reset function

The table below describes the function `adc_reset`.

**Table 22. adc\_reset function**

| Name                   | Description                                   |
|------------------------|---|
| Function name          | <code>adc_reset</code>                        |
| Function prototype     | <code>void adc_reset(adc_type *adc_x)</code>  |
| Function description   | Reset all ADC registers to their reset values |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | <code>crm_periph_reset()</code>               |

**Example:**

```
/* deinitialize adc1 */
adc_reset();
```

## 5.2.2 adc\_enable function

The table below describes the function `adc_enable`.

**Table 23. adc\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_enable</code>   |
| Function prototype     | <code>void adc_enable(adc_type *adc_x, confirm_state new_state)</code>  |
| Function description   | Enable/disable A/D converter  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.                          |
| Input parameter 2      | <code>new_state</code> : indicates the pre-configured status of A/D converter<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable adc1 */
adc_enable(ADC1, TRUE);
```

## 5.2.3 adc\_base\_default\_para\_init function

The table below describes the function `adc_base_default_para_init`.

**Table 24. adc\_base\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_base_default_para_init</code>   |
| Function prototype     | <code>void adc_base_default_para_init(adc_base_config_type *adc_base_struct)</code> |
| Function description   | Set the initial value for the <code>adc_base_struct</code>                          |
| Input parameter        | <code>adc_base_struct</code> : <code>adc_base_config_type</code> pointer            |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The default values of members in the `adc_base_struct`:

```
sequence_mode:      FALSE
repeat_mode:        FALSE
data_align:         ADC_RIGHT_ALIGNMENT
ordinary_channel_length: 1
```

**Example:**

```
/* initialize a adc_base_config_type structure */
adc_base_config_type adc_base_struct;
adc_base_default_para_init(&adc_base_struct);
```

## 5.2.4 adc\_base\_config function

The table below describes the function `adc_base_config`.

**Table 25. adc\_base\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_base_config</code>  |
| Function prototype     | <code>void adc_base_config(adc_type *adc_x, adc_base_config_type *adc_base_struct);</code>              |
| Function description   | Initialize ADC registers with the specified parameters in the <code>adc_base_struct</code>              |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC peripheral<br>This parameter can be ADC1, ADC2 or ADC3. |
| Input parameter 2      | <code>adc_base_struct</code> : <code>adc_base_config_type</code> pointer                                |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### adc\_base\_config\_type structure

The `adc_base_config_type` is defined in the `at32f435_437_adc.h`:

typedef struct

```
{
    confirm_state          sequence_mode;
    confirm_state          repeat_mode;
    adc_data_align_type    data_align;
    uint8_t                ordinary_channel_length;
} adc_base_config_type; the member parameters are described as follows:
```

#### sequence\_mode

Set ADC sequence mode.

FALSE: Select a single channel for conversion

TRUE: Select multiple channels for conversion

#### repeat\_mode

Set ADC repeat mode.

FALSE: When `SQEN=0`, trigger a single channel conversion each time; when `SQEN=1`, trigger the conversion of a group of channels each time

TRUE: When `SQEN =0`, repeatedly convert a single channel at each trigger; when `SQEN=1`, repeatedly convert a group of channels at each trigger until the `ADCEN` bit is cleared

#### data\_align

Set data alignment of ADC.

`ADC_RIGHT_ALIGNMENT`: right-aligned

`ADC_LEFT_ALIGNMENT`: left-aligned

#### ordinary\_channel\_length

Set the length of ordinary group ADC conversion.

#### Example:

```
adc_base_config_type adc_base_struct;
adc_base_struct.sequence_mode = TRUE;
adc_base_struct.repeat_mode = FALSE;
adc_base_struct.data_align = ADC_RIGHT_ALIGNMENT;
```

```
adc_base_struct.ordinary_channel_length = 3;
adc_base_config(ADC1, &adc_base_struct);
```

## 5.2.5 adc\_common\_default\_para\_init function

The table below describes the function `adc_common_default_para_init`.

**Table 26. adc\_common\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_common_default_para_init</code>   |
| Function prototype     | <code>void adc_common_default_para_init(adc_common_config_type *adc_common_struct)</code> |
| Function description   | Set the initial value for the <code>adc_common_struct</code>                              |
| Input parameter        | <code>adc_common_struct</code> : <code>adc_common_config_type</code> pointer              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The default values of members in the `adc_common_struct`:

```
combine_mode:          ADC_INDEPENDENT_MODE
div:                   ADC_HCLK_DIV_2
common_dma_mode:      ADC_COMMON_DMAMODE_DISABLE
common_dma_request_repeat_state: FALSE
sampling_interval:    ADC_SAMPLING_INTERVAL_5CYCLES
tempvintrv_state:     FALSE
vbat_state:           FALSE
```

### Example:

```
/* initialize a adc_common_config_type structure */
adc_common_config_type adc_common_struct;
adc_common_default_para_init(&adc_common_struct);
```

## 5.2.6 adc\_common\_config function

The table below describes the function `adc_common_config`.

**Table 27. adc\_common\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_common_config</code>  |
| Function prototype     | <code>void adc_common_config(adc_common_config_type *adc_common_struct)</code>                      |
| Function description   | Initialize ADC common register with the parameters programmed in the <code>adc_common_struct</code> |
| Input parameter        | <code>adc_common_struct</code> : <code>adc_common_config_type</code> pointer                        |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**adc\_common\_config\_type structure**

The adc\_common\_config\_type is defined in the at32f435\_437\_adc.h.

typedef struct

```
{
    adc_combine_mode_type          combine_mode;
    adc_div_type                   div;
    adc_common_dma_mode_type       common_dma_mode;
    confirm_state                  common_dma_request_repeat_state;
    adc_sampling_interval_type     sampling_interval;
    confirm_state                  tempervintrv_state;
    confirm_state                  vbat_state;
}
```

} adc\_common\_config\_type; the member parameters are described as follows:

**combine\_mode**

Set ADC master-slave combined mode.

ADC\_INDEPENDENT\_MODE: Non-combined mode

ADC\_ORDINARY\_SMLT\_PREEMPT\_SMLT\_ONESLAVE\_MODE:

Ordinary simultaneous + preempted simultaneous (single slave)

ADC\_ORDINARY\_SMLT\_PREEMPT\_INTERLTRIG\_ONESLAVE\_MODE:

Ordinary simultaneous + alternate preempted trigger (single slave)

ADC\_PREEMPT\_SMLT\_ONLY\_ONESLAVE\_MODE: Preempted simultaneous (single slave)

ADC\_ORDINARY\_SMLT\_ONLY\_ONESLAVE\_MODE: Ordinary simultaneous (single slave)

ADC\_ORDINARY\_SHIFT\_ONLY\_ONESLAVE\_MODE: Ordinary shift (single slave)

ADC\_PREEMPT\_INTERLTRIG\_ONLY\_ONESLAVE\_MODE:

Alternate preempted trigger (single slave)

ADC\_ORDINARY\_SMLT\_PREEMPT\_SMLT\_TWOSLAVE\_MODE:

Ordinary simultaneous + preempted simultaneous (dual slave)

ADC\_ORDINARY\_SMLT\_PREEMPT\_INTERLTRIG\_TWOSLAVE\_MODE:

Ordinary simultaneous + alternate preempted trigger (dual slave)

ADC\_PREEMPT\_SMLT\_ONLY\_TWOSLAVE\_MODE: Preempted simultaneous (dual slave)

ADC\_ORDINARY\_SMLT\_ONLY\_TWOSLAVE\_MODE: Ordinary simultaneous (dual slave)

ADC\_ORDINARY\_SHIFT\_ONLY\_TWOSLAVE\_MODE: Ordinary shift (dual slave)

ADC\_PREEMPT\_INTERLTRIG\_ONLY\_TWOSLAVE\_MODE:

Alternate preempted trigger (dual slave)

**div**

Set ADC frequency division factory.

ADC\_HCLK\_DIV\_2: ADCCLK is clocked by HCLK/2

ADC\_HCLK\_DIV\_3: ADCCLK is clocked by HCLK/3

ADC\_HCLK\_DIV\_4: ADCCLK is clocked by HCLK/4

ADC\_HCLK\_DIV\_5: ADCCLK is clocked by HCLK/5

ADC\_HCLK\_DIV\_6: ADCCLK is clocked by HCLK/6

ADC\_HCLK\_DIV\_7: ADCCLK is clocked by HCLK/7

ADC\_HCLK\_DIV\_8: ADCCLK is clocked by HCLK/8

ADC\_HCLK\_DIV\_9: ADCCLK is clocked by HCLK/9

ADC\_HCLK\_DIV\_10: ADCCLK is clocked by HCLK/10

ADC\_HCLK\_DIV\_11: ADCCLK is clocked by HCLK/11

ADC\_HCLK\_DIV\_12: ADCCLK is clocked by HCLK/12

ADC\_HCLK\_DIV\_13: ADCCLK is clocked by HCLK/13  
 ADC\_HCLK\_DIV\_14: ADCCLK is clocked by HCLK/14  
 ADC\_HCLK\_DIV\_15: ADCCLK is clocked by HCLK/15  
 ADC\_HCLK\_DIV\_16: ADCCLK is clocked by HCLK/16  
 ADC\_HCLK\_DIV\_17: ADCCLK is clocked by HCLK/17

**common\_dma\_mode**

Set ordinary channel DMA transfer mode in master/slave mode.

ADC\_COMMON\_DMAMODE\_DISABLE: No DMA transfer  
 ADC\_COMMON\_DMAMODE\_1: DMA mode 1  
 ADC\_COMMON\_DMAMODE\_2: DMA mode 2  
 ADC\_COMMON\_DMAMODE\_3: DMA mode 3  
 ADC\_COMMON\_DMAMODE\_4: DMA mode 4  
 ADC\_COMMON\_DMAMODE\_5: DMA mode 5

**common\_dma\_request\_repeat\_state**

Enable or disable ordinary channel DMA request continuation in master/slave mode.

FALSE: Disabled (after the completion of the programmed number of DMA transfers, no DMA request generated at the end of ordinary conversion)  
 TRUE: Enabled (don't care about the programmed number of DMA transfers; each channel sends DMA request at the end of ordinary conversion)

**sampling\_interval**

Set the adjacent ADC sampling interval in ordinary shift mode.

ADC\_SAMPLING\_INTERVAL\_5CYCLES: 5 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_6CYCLES: 6 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_7CYCLES: 7 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_8CYCLES: 8 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_9CYCLES: 9 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_10CYCLES: 10 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_11CYCLES: 11 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_12CYCLES: 12 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_13CYCLES: 13 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_14CYCLES: 14 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_15CYCLES: 15 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_16CYCLES: 16 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_17CYCLES: 17 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_18CYCLES: 18 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_19CYCLES: 19 \* TADCCLK  
 ADC\_SAMPLING\_INTERVAL\_20CYCLES: 20 \* TADCCLK

**tempervintrv\_state**

Enable/disable ADC internal temperature sensor and  $V_{INTRV}$ .

FALSE: Disable internal temperature sensor and  $V_{INTRV}$   
 TRUE: Enable internal temperature sensor and  $V_{INTRV}$

**vbat\_state**

Enable/disable ADC  $V_{BAT}$ .

FALSE: Disable  $V_{BAT}$   
 TRUE: Enable  $V_{BAT}$

**Example:**

```

adc_common_config_type adc_common_struct;
adc_common_struct.combine_mode = ADC_INDEPENDENT_MODE;
adc_common_struct.div = ADC_HCLK_DIV_4;
adc_common_struct.common_dma_mode = ADC_COMMON_DMAMODE_DISABLE;
adc_common_struct.common_dma_request_repeat_state = FALSE;
adc_common_struct.sampling_interval = ADC_SAMPLING_INTERVAL_5CYCLES;
adc_common_struct.tempervintrv_state = TRUE;
adc_common_struct.vbat_state = FALSE;
adc_common_config(&adc_common_struct);
    
```

## 5.2.7 adc\_resolution\_set function

The table below describes the function `adc_resolution_set`.

**Table 28. adc\_resolution\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_resolution_set</code>   |
| Function prototype     | <code>void adc_resolution_set(adc_type *adc_x, adc_resolution_type resolution)</code>   |
| Function description   | Set ADC conversion resolution   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | Resolution: ADC conversion resolution selection<br>This parameter can be any enumerated value in the <code>adc_resolution_type</code> . |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**resolution**

The resolution is used to select ADC conversion resolution, including:

ADC\_RESOLUTION\_12B: 12-bit resolution

ADC\_RESOLUTION\_10B: 10-bit resolution

ADC\_RESOLUTION\_8B: 8-bit resolution

ADC\_RESOLUTION\_6B: 6-bit resolution

**Example:**

```

/* set conversion resolution */
adc_resolution_set(ADC1, ADC_RESOLUTION_12B);
    
```

## 5.2.8 adc\_voltage\_battery\_enable function

The table below describes the function `adc_voltage_battery_enable`.

**Table 29. adc\_voltage\_battery\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_voltage_battery_enable</code>  |
| Function prototype     | <code>void adc_voltage_battery_enable(confirm_state new_state)</code>  |
| Function description   | $V_{BAT}$ enable   |
| Input parameter        | <code>new_state</code> : indicates the pre-configured status of $V_{BAT}$ enable bit<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable adc voltage battery */
adc_voltage_battery_enable(TRUE);
```

## 5.2.9 adc\_dma\_mode\_enable function

The table below describes the function `adc_dma_mode_enable`.

**Table 30. adc\_dma\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_dma_mode_enable</code>  |
| Function prototype     | <code>void adc_dma_mode_enable(adc_type *adc_x, confirm_state new_state)</code>   |
| Function description   | Enable DMA transfer for ordinary group conversion   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.                                  |
| Input parameter 2      | <code>new_state</code> : pre-configured status of ordinary group in DMA transfer mode<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable dma transfer adc ordinary conversion data */
adc_dma_mode_enable(ADC1, TRUE);
```



## 5.2.10 adc\_dma\_request\_repeat\_enable function

The table below describes the function `adc_dma_request_repeat_enable`

**Table 31. adc\_dma\_request\_repeat\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_dma_request_repeat_enable</code>  |
| Function prototype     | <code>void adc_dma_request_repeat_enable(adc_type *adc_x, confirm_state new_state)</code>   |
| Function description   | Enable DMA request repetition mode for ordinary group conversion  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>new_state</code> : indicates the pre-configured status of DMA request repetition mode<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* config dma request repeat,it's not useful when common dma mode is use */
adc_dma_request_repeat_enable(ADC1, TRUE);
```

## 5.2.11 adc\_interrupt\_enable function

The table below describes the function `adc_interrupt_enable`.

**Table 32. adc\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_interrupt_enable</code>   |
| Function prototype     | <code>void adc_interrupt_enable(adc_type *adc_x, uint32_t adc_int, confirm_state new_state)</code>                              |
| Function description   | Enable the selected ADC event interrupt   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.                                    |
| Input parameter 2      | <code>adc_int</code> : ADC event interrupt selection<br>This parameter is used to select any event interrupts supported by ADC. |
| Input parameter 3      | <code>new_state</code> : indicates the pre-configured status of ADC event interrupts<br>This parameter can be TRUE or FALSE.    |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**adc\_int**

The `adc_int` is used to select and set event interrupts, with the following parameters:

`ADC_OCCE_INT`: Interrupt enabled at the end of ordinary group conversion

`ADC_VMOR_INT`: Interrupt enabled when voltage monitor is outside the threshold

`ADC_PCCE_INT`: Interrpt enabled at the end of preempted group conversion

ADC\_OCCO\_INT: Overflow interrupt for ordinary group conversion

**Example:**

```
/* enable voltage monitoring out of range interrupt */
adc_interrupt_enable(ADC1, ADC_VMOR_INT, TRUE);
```

### 5.2.12 adc\_calibration\_value\_set

The table below describes the function `adc_calibration_value_set`.

**Table 33. adc\_calibration\_value\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_calibration_value_set</code>  |
| Function prototype     | <code>void adc_calibration_value_set(adc_type *adc_x, uint8_t adc_calibration_value)</code>   |
| Function description   | Set calibration value by software   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>adc_calibration_value</code> : indicates the pre-configured calibration value<br>This parameter can be any enumerated value in the 0x00~0x7F. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* set calibration value */
adc_calibration_value_set(ADC1, 0x3F);
```

### 5.2.13 adc\_calibration\_init function

The table below describes the function `adc_calibration_init`.

**Table 34. adc\_calibration\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_calibration_init</code>  |
| Function prototype     | <code>void adc_calibration_init(adc_type *adc_x)</code>                                      |
| Function description   | Initialization calibration   |
| Input parameter        | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* initialize A/D calibration */
adc_calibration_init(ADC1);
```

## 5.2.14 adc\_calibration\_init\_status\_get function

The table below describes the function `adc_calibration_init_status_get`.

**Table 35. adc\_calibration\_init\_status\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_calibration_init_status_get</code>  |
| Function prototype     | <code>flag_status adc_calibration_init_status_get(adc_type *adc_x)</code>                             |
| Function description   | Get the status of initialization calibration  |
| Input parameter        | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.          |
| Output parameter       | NA  |
| Return value           | <code>flag_status</code> : indicates the status of calibration initialization<br>Return SET or RESET. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* wait initialize A/D calibration success */
while(adc_calibration_init_status_get(ADC1));
```

## 5.2.15 adc\_calibration\_start function

The table below describes the function `adc_calibration_start`.

**Table 36. adc\_calibration\_start function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_calibration_start</code>   |
| Function prototype     | <code>void adc_calibration_start(adc_type *adc_x)</code>                                     |
| Function description   | Start calibration  |
| Input parameter        | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* start calibration process */
adc_calibration_start(ADC1);
```

## 5.2.16 adc\_calibration\_status\_get function

The table below describes the function `adc_calibration_status_get`.

**Table 37. adc\_calibration\_status\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_calibration_status_get</code>  |
| Function prototype     | <code>flag_status adc_calibration_status_get(adc_type *adc_x)</code>                         |
| Function description   | Get the status of calibration  |
| Input parameter        | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3. |
| Output parameter       | NA   |
| Return value           | <code>flag_status</code> : indicates the status of calibration<br>Return SET or RESET.       |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* wait calibration success */
while(adc_calibration_status_get(ADC1));
```

## 5.2.17 adc\_voltage\_monitor\_enable function

The table below describes the function `adc_voltage_monitor_enable`.

**Table 38. adc\_voltage\_monitor\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_voltage_monitor_enable</code>   |
| Function prototype     | <code>void adc_voltage_monitor_enable(adc_type *adc_x, adc_voltage_monitoring_type adc_voltage_monitoring)</code>   |
| Function description   | Enable voltage monitor for ordinary/preempted group and a single channel  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>adc_voltage_monitoring</code> : select ordinary group, preempted group or a single channel for voltage monitoring<br>This parameter can be any enumerated value in the <code>adc_voltage_monitoring_type</code> . |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**adc\_voltage\_monitoring**

The `adc_voltage_monitoring` is used to select one or more channels of ordinary group/preempted group for voltage monitoring, including:

`ADC_VMONITOR_SINGLE_ORDINARY`:

Select a single ordinary channel for voltage monitoring

`ADC_VMONITOR_SINGLE_PREEMPT`:

Select a single preempted channel for voltage monitoring

ADC\_VMONITOR\_SINGLE\_ORDINARY\_PREEMPT:

Select a single channel from ordinary or preempted group for voltage monitoring

ADC\_VMONITOR\_ALL\_ORDINARY:

Select all ordinary channels for voltage monitoring

ADC\_VMONITOR\_ALL\_PREEMPT:

Select all preempted channels for voltage monitoring

ADC\_VMONITOR\_ALL\_ORDINARY\_PREEMPT:

Select all ordinary and preempted channels for voltage monitoring

ADC\_VMONITOR\_NONE:

No channels need voltage monitoring

**Example:**

```
/* enable the voltage monitoring on all ordinary and preempt channels */
adc_voltage_monitor_enable(ADC1, ADC_VMONITOR_ALL_ORDINARY_PREEMPT);
```

### 5.2.18 adc\_voltage\_monitor\_threshold\_value\_set function

The table below describes the function `adc_voltage_monitor_threshold_value_set`.

**Table 39. adc\_voltage\_monitor\_threshold\_value\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_voltage_monitor_threshold_value_set</code>  |
| Function prototype     | <code>void adc_voltage_monitor_threshold_value_set(adc_type *adc_x, uint16_t adc_high_threshold, uint16_t adc_low_threshold)</code>   |
| Function description   | Configure the threshold of voltage monitoring   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>adc_high_threshold</code> : indicates the upper limit for voltage monitoring<br>This parameter can be any value between 0x000~0xFFFF.   |
| Input parameter 3      | <code>adc_low_threshold</code> : indicates the lower limit for voltage monitoring<br>This parameter can be any value lower than that of <code>adc_high_threshold</code> in the range of 0x000~0xFFFF. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* set voltage monitoring's high and low thresholds value */
adc_voltage_monitor_threshold_value_set(ADC1, 0xBBB, 0xAAA);
```

## 5.2.19 adc\_voltage\_monitor\_single\_channel\_select function

The table below describes the function `adc_voltage_monitor_single_channel_select`.

**Table 40. adc\_voltage\_monitor\_single\_channel\_select function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_voltage_monitor_single_channel_select</code>   |
| Function prototype     | <code>void adc_voltage_monitor_single_channel_select(adc_type *adc_x, adc_channel_select_type adc_channel)</code>              |
| Function description   | Select a single channel for voltage monitoring   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.                                   |
| Input parameter 2      | <code>adc_channel</code> : select a single channel for voltage monitoring<br>Refer to <a href="#">adc_channel</a> for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### adc\_channel

The `adc_channel` is used to select a single channel for voltage monitoring, including

`ADC_CHANNEL_0`: ADC channel 0

`ADC_CHANNEL_1`: ADC channel 1

.....

`ADC_CHANNEL_17`: ADC channel 17

`ADC_CHANNEL_18`: ADC channel 18

### Example:

```
/* select the voltage monitoring's channel */
adc_voltage_monitor_single_channel_select(ADC1, ADC_CHANNEL_5);
```

## 5.2.20 adc\_ordinary\_channel\_set function

The table below describes the function `adc_ordinary_channel_set`.

**Table 41. adc\_ordinary\_channel\_set function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>adc_ordinary_channel_set</code>   |
| Function prototype   | <code>void adc_ordinary_channel_set(adc_type *adc_x, adc_channel_select_type adc_channel, uint8_t adc_sequence, adc_sampletime_select_type adc_sampletime)</code> |
| Function description | Configure ordinary channels, including parameters such as channel selection, conversion sequence number and sampling time   |
| Input parameter 1    | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2    | <code>adc_channel</code> : indicates the selected channel<br>Refer to <a href="#">adc_channel</a> for details.  |
| Input parameter 3    | <code>adc_sequence</code> : defines the sequence of channel conversion<br>This parameter can be any value from 1~16.  |

| Name                   | Description   |
|------------------------|---|
| Input parameter 4      | adc_sampletime: defines the sampling time for channel<br>Refer to <a href="#">adc_sampletime</a> for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### adc\_sampletime

The adc\_sampletime is used to configure the sampling time of channels, including:

- ADC\_SAMPLETIME\_2\_5: sampling time is 2.5 ADCCLK cycles
- ADC\_SAMPLETIME\_6\_5: sampling time is 6.5 ADCCLK cycles
- ADC\_SAMPLETIME\_12\_5: sampling time is 12.5 ADCCLK cycles
- ADC\_SAMPLETIME\_24\_5: sampling time is 24.5 ADCCLK cycles
- ADC\_SAMPLETIME\_47\_5: sampling time is 47.5 ADCCLK cycles
- ADC\_SAMPLETIME\_92\_5: sampling time is 92.5 ADCCLK cycles
- ADC\_SAMPLETIME\_247\_5: sampling time is 247.5 ADCCLK cycles
- ADC\_SAMPLETIME\_640\_5: sampling time is 640.5 ADCCLK cycles

#### Example:

```

/* set ordinary channel's corresponding rank in the sequencer and sample time */
adc_ordinary_channel_set(ADC1, ADC_CHANNEL_4, 1, ADC_SAMPLETIME_247_5);
adc_ordinary_channel_set(ADC1, ADC_CHANNEL_5, 2, ADC_SAMPLETIME_247_5);

```

## 5.2.21 adc\_preempt\_channel\_length\_set function

The table below describes the function adc\_preempt\_channel\_length\_set.

**Table 42. adc\_preempt\_channel\_length\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | adc_preempt_channel_length_set  |
| Function prototype     | void adc_preempt_channel_length_set(adc_type *adc_x, uint8_t adc_channel_lenght)                                    |
| Function description   | Set the length of preempted channel conversion  |
| Input parameter 1      | adc_x: indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.                                      |
| Input parameter 2      | adc_channel_lenght: set the length of preempted channel conversion<br>This parameter can be any value from 0x1~0x4. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### Example:

```

/* set preempt channel length */
adc_preempt_channel_length_set(ADC1, 3);

```

### 5.2.22 adc\_preempt\_channel\_set function

The table below describes the function `adc_preempt_channel_set`

**Table 43. adc\_preempt\_channel\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_preempt_channel_set</code>   |
| Function prototype     | <code>void adc_preempt_channel_set(adc_type *adc_x, adc_channel_select_type adc_channel, uint8_t adc_sequence, adc_samptime_select_type adc_samptime)</code> |
| Function description   | Configure preempted group, including parameters such as channel selection, conversion sequence number and sampling time                                      |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.   |
| Input parameter 2      | <code>adc_channel</code> : indicates the selected channel<br>Refer to <a href="#">adc_channel</a> for details.   |
| Input parameter 3      | <code>adc_sequence</code> : set the sequence number for channel conversion<br>This parameter can be any value from 1~4.                                      |
| Input parameter 4      | <code>adc_samptime</code> : set the sampling time for channels<br>Refer to <a href="#">adc_samptime</a> for details.   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```

/* set ordinarychannel's corresponding rank in the sequencer and sample time */
adc_preempt_channel_set(ADC1, ADC_CHANNEL_7, 1, ADC_SAMPETIME_247_5);
adc_preempt_channel_set(ADC1, ADC_CHANNEL_8, 2, ADC_SAMPETIME_247_5);

```

### 5.2.23 adc\_ordinary\_conversion\_trigger\_set function

The table below describes the function `adc_ordinary_conversion_trigger_set`.

**Table 44. adc\_ordinary\_conversion\_trigger\_set function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>adc_ordinary_conversion_trigger_set</code>   |
| Function prototype   | <code>void adc_ordinary_conversion_trigger_set(adc_type *adc_x, adc_ordinary_trig_select_type adc_ordinary_trig, adc_ordinary_trig_edge_type adc_ordinary_trig_edge)</code>                |
| Function description | Enable trigger mode and select trigger events for ordinary group conversion  |
| Input parameter 1    | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.   |
| Input parameter 2    | <code>adc_ordinary_trig</code> : indicates the selected trigger event for ordinary group<br>This parameter can be any enumerated value in the <code>adc_ordinary_trig_select_type</code> . |
| Input parameter 3    | <code>adc_ordinary_trig_edge</code> : indicates the pre-configured status of external trigger edge for ordinary group  |



| Name                   | Description  |
|------------------------|--|
|                        | This parameter can be any enumerated value in the <code>adc_ordinary_trig_edge_type</code> . |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### **adc\_ordinary\_trig**

The `adc_ordinary_trig` is used to select a trigger event for ordinary group conversion, including :

|  |                     |
|--|---------------------|
| <code>ADC_ORDINARY_TRIG_TMR1CH1:</code>      | TMR1 CH1 event      |
| <code>ADC_ORDINARY_TRIG_TMR1CH2:</code>      | TMR1 CH2 event      |
| <code>ADC_ORDINARY_TRIG_TMR1CH3:</code>      | TMR1 CH3 event      |
| <code>ADC_ORDINARY_TRIG_TMR2CH2:</code>      | TMR2 CH2 event      |
| <code>ADC_ORDINARY_TRIG_TMR2CH3:</code>      | TMR2 CH3 event      |
| <code>ADC_ORDINARY_TRIG_TMR2CH4:</code>      | TMR2 CH4 event      |
| <code>ADC_ORDINARY_TRIG_TMR2TRGOUT:</code>   | TMR2 TRGOUT event   |
| <code>ADC_ORDINARY_TRIG_TMR3CH1:</code>      | TMR3 CH1 event      |
| <code>ADC_ORDINARY_TRIG_TMR3TRGOUT:</code>   | TMR3 TRGOUT event   |
| <code>ADC_ORDINARY_TRIG_TMR4CH4:</code>      | TMR4 CH4 event      |
| <code>ADC_ORDINARY_TRIG_TMR5CH1:</code>      | TMR5 CH1 event      |
| <code>ADC_ORDINARY_TRIG_TMR5CH2:</code>      | TMR5 CH2 event      |
| <code>ADC_ORDINARY_TRIG_TMR5CH3:</code>      | TMR5 CH3 event      |
| <code>ADC_ORDINARY_TRIG_TMR8CH1:</code>      | TMR8 CH1 event      |
| <code>ADC_ORDINARY_TRIG_TMR8TRGOUT:</code>   | TMR8 TRGOUT event   |
| <code>ADC_ORDINARY_TRIG_EXINT11:</code>      | EXINT 11 event      |
| <code>ADC_ORDINARY_TRIG_TMR20TRGOUT:</code>  | TMR20 TRGOUT event  |
| <code>ADC_ORDINARY_TRIG_TMR20TRGOUT2:</code> | TMR20 TRGOUT2 event |
| <code>ADC_ORDINARY_TRIG_TMR20CH1:</code>     | TMR20 CH1 event     |
| <code>ADC_ORDINARY_TRIG_TMR20CH2:</code>     | TMR20 CH2 event     |
| <code>ADC_ORDINARY_TRIG_TMR20CH3:</code>     | TMR20 CH3 event     |
| <code>ADC_ORDINARY_TRIG_TMR8TRGOUT2:</code>  | TMR8 TRGOUT2 event  |
| <code>ADC_ORDINARY_TRIG_TMR1TRGOUT2:</code>  | TMR1 TRGOUT2 event  |
| <code>ADC_ORDINARY_TRIG_TMR4TRGOUT:</code>   | TMR4 TRGOUT event   |
| <code>ADC_ORDINARY_TRIG_TMR6TRGOUT:</code>   | TMR6 TRGOUT event   |
| <code>ADC_ORDINARY_TRIG_TMR3CH4:</code>      | TMR3 CH4 event      |
| <code>ADC_ORDINARY_TRIG_TMR4CH1:</code>      | TMR4 CH1 event      |
| <code>ADC_ORDINARY_TRIG_TMR1TRGOUT:</code>   | TMR1 TRGOUT event   |
| <code>ADC_ORDINARY_TRIG_TMR2CH1:</code>      | TMR2 CH1 event      |
| <code>ADC_ORDINARY_TRIG_TMR7TRGOUT:</code>   | TMR7 TRGOUT event   |

### **adc\_ordinary\_trig\_edge**

|   |                                     |
|---|-------------------------------------|
| <code>ADC_ORDINARY_TRIG_EDGE_NONE:</code>           | Edge trigger disabled               |
| <code>ADC_ORDINARY_TRIG_EDGE_RISING:</code>         | Rising edge                         |
| <code>ADC_ORDINARY_TRIG_EDGE_FALLING:</code>        | Falling edge                        |
| <code>ADC_ORDINARY_TRIG_EDGE_RISING_FALLING:</code> | Any edge (rising edge/falling edge) |

### **Example:**

```
/* config ordinarytrigger source and trigger edge */
```

```
adc_ordinary_conversion_trigger_set(ADC1, ADC_ORDINARY_TRIG_TMR1CH1,
ADC_ORDINARY_TRIG_EDGE_NONE);
```

## 5.2.24 adc\_preempt\_conversion\_trigger\_set function

The table below describes the function `adc_preempt_conversion_trigger_set`.

**Table 45. adc\_preempt\_conversion\_trigger\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_preempt_conversion_trigger_set</code>  |
| Function prototype     | <code>void adc_preempt_conversion_trigger_set(adc_type *adc_x, adc_preempt_trig_select_type adc_preempt_trig, adc_preempt_trig_edge_type adc_preempt_trig_edge)</code>   |
| Function description   | Enable trigger mode and trigger events for preempted group conversion  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.   |
| Input parameter 2      | <code>adc_preempt_trig</code> : indicates the selected trigger event for preempted group<br>This parameter can be any enumerated value in the <code>adc_preempt_trig_select_type</code> .                            |
| Input parameter 3      | <code>adc_preempt_trig_edge</code> : indicates the pre-configured status of external trigger edge for preempted group<br>This parameter can be any enumerated value in the <code>adc_preempt_trig_edge_type</code> . |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### adc\_preempt\_trig

The `adc_preempt_trig` is used to select a trigger event for preempted group conversion, including

|   |                     |
|---|---------------------|
| <code>ADC_PREEMPT_TRIG_TMR1CH4:</code>      | TMR1 CH4 event      |
| <code>ADC_PREEMPT_TRIG_TMR1TRGOUT:</code>   | TMR1 TRGOUT event   |
| <code>ADC_PREEMPT_TRIG_TMR2CH1:</code>      | TMR2 CH1 event      |
| <code>ADC_PREEMPT_TRIG_TMR2TRGOUT:</code>   | TMR2 TRGOUT event   |
| <code>ADC_PREEMPT_TRIG_TMR3CH2:</code>      | TMR3 CH2 event      |
| <code>ADC_PREEMPT_TRIG_TMR3CH4:</code>      | TMR3 CH4 event      |
| <code>ADC_PREEMPT_TRIG_TMR4CH1:</code>      | TMR4 CH1 event      |
| <code>ADC_PREEMPT_TRIG_TMR4CH2:</code>      | TMR4 CH2 event      |
| <code>ADC_PREEMPT_TRIG_TMR4CH3:</code>      | TMR4 CH3 event      |
| <code>ADC_PREEMPT_TRIG_TMR4TRGOUT:</code>   | TMR4 TRGOUT event   |
| <code>ADC_PREEMPT_TRIG_TMR5CH4:</code>      | TMR5 CH4 event      |
| <code>ADC_PREEMPT_TRIG_TMR5TRGOUT:</code>   | TMR5 TRGOUT event   |
| <code>ADC_PREEMPT_TRIG_TMR8CH2:</code>      | TMR8 CH2 event      |
| <code>ADC_PREEMPT_TRIG_TMR8CH3:</code>      | TMR8 CH3 event      |
| <code>ADC_PREEMPT_TRIG_TMR8CH4:</code>      | TMR8 CH4 event      |
| <code>ADC_PREEMPT_TRIG_EXINT15:</code>      | EXINT 15 event      |
| <code>ADC_PREEMPT_TRIG_TMR20TRGOUT:</code>  | TMR20 TRGOUT event  |
| <code>ADC_PREEMPT_TRIG_TMR20TRGOUT2:</code> | TMR20 TRGOUT2 event |

|                               |                    |
|-------------------------------|--------------------|
| ADC_PREEMPT_TRIG_TMR20CH4:    | TMR20 CH4 event    |
| ADC_PREEMPT_TRIG_TMR1TRGOUT2: | TMR1 TRGOUT2 event |
| ADC_PREEMPT_TRIG_TMR8TRGOUT:  | TMR8 TRGOUT event  |
| ADC_PREEMPT_TRIG_TMR8TRGOUT2: | TMR8 TRGOUT2 event |
| ADC_PREEMPT_TRIG_TMR3CH3:     | TMR3 CH3 event     |
| ADC_PREEMPT_TRIG_TMR3TRGOUT:  | TMR3 TRGOUT event  |
| ADC_PREEMPT_TRIG_TMR3CH1:     | TMR3 CH1 event     |
| ADC_PREEMPT_TRIG_TMR6TRGOUT:  | TMR6 TRGOUT event  |
| ADC_PREEMPT_TRIG_TMR4CH4:     | TMR4 CH4 event     |
| ADC_PREEMPT_TRIG_TMR1CH3:     | TMR1 CH3 event     |
| ADC_PREEMPT_TRIG_TMR20CH2:    | TMR20 CH2 event    |
| ADC_PREEMPT_TRIG_TMR7TRGOUT:  | TMR7 TRGOUT event  |

**adc\_preempt\_trig\_edge**

|                                       |                                     |
|---------------------------------------|-------------------------------------|
| ADC_PREEMPT_TRIG_EDGE_NONE:           | Edge trigger disabled               |
| ADC_PREEMPT_TRIG_EDGE_RISING:         | Rising edge                         |
| ADC_PREEMPT_TRIG_EDGE_FALLING:        | Falling edge                        |
| ADC_PREEMPT_TRIG_EDGE_RISING_FALLING: | Any edge (rising edge/falling edge) |

**Example:**

```

/* config preempt trigger source and trigger edge */
adc_preempt_conversion_trigger_set(ADC1, ADC_PREEMPT_TRIG_TMR1CH4,
ADC_PREEMPT_TRIG_EDGE_NONE);

```

## 5.2.25 adc\_preempt\_offset\_value\_set function

The table below describes the function `adc_preempt_offset_value_set`.

**Table 46. adc\_preempt\_offset\_value\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_preempt_offset_value_set</code>  |
| Function prototype     | <code>void adc_preempt_offset_value_set(adc_type *adc_x, adc_preempt_channel_type adc_preempt_channel, uint16_t adc_offset_value)</code> |
| Function description   | Set the offset value of preempted group conversion   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.   |
| Input parameter 2      | <code>adc_preempt_channel</code> : indicates the selected channel<br>Refer to <a href="#">adc_preempt_channel</a> for details.           |
| Input parameter 3      | <code>adc_offset_value</code> : set the offset value for the selected channel<br>This parameter can be any value from 0x000~0xFFFF.      |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**adc\_preempt\_channel**

The `adc_preempt_channel` is used to set an offset value for the selected channel, including

|                        |                     |
|------------------------|---------------------|
| ADC_PREEMPT_CHANNEL_1: | Preempted channel 1 |
| ADC_PREEMPT_CHANNEL_2: | Preempted channel 2 |
| ADC_PREEMPT_CHANNEL_3: | Preempted channel 3 |

ADC\_PREEMPT\_CHANNEL\_4:

Preempted channel 4

**Example:**

```

/* set preempt channel's conversion value offset */
adc_preempt_offset_value_set(ADC1, ADC_PREEMPT_CHANNEL_1, 0x111);
adc_preempt_offset_value_set(ADC1, ADC_PREEMPT_CHANNEL_2, 0x222);
adc_preempt_offset_value_set(ADC1, ADC_PREEMPT_CHANNEL_3, 0x333);
    
```

## 5.2.26 adc\_ordinary\_part\_count\_set function

The table below describes the function `adc_ordinary_part_count_set`.

**Table 47. adc\_ordinary\_part\_count\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_ordinary_part_count_set</code>   |
| Function prototype     | <code>void adc_ordinary_part_count_set(adc_type *adc_x, uint8_t adc_channel_count)</code>  |
| Function description   | Set the number of ordinary channels at each triggered conversion in partition mode   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.   |
| Input parameter 2      | <code>adc_channel_count</code> : indicates the number of ordinary group in partition mode<br>This parameter can be any value from 0x1~0x8. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```

/* set partitioned mode channel count */
adc_ordinary_part_count_set(ADC1, 2);
    
```

*Note: In partition mode, only the number of ordinary group is configurable, and that of preempted group is fixed 1.*

## 5.2.27 adc\_ordinary\_part\_mode\_enable function

The table below describes the function `adc_ordinary_part_mode_enable`.

**Table 48. adc\_ordinary\_part\_mode\_enable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>adc_ordinary_part_mode_enable</code>   |
| Function prototype   | <code>void adc_ordinary_part_mode_enable(adc_type *adc_x, confirm_state new_state)</code>  |
| Function description | Enable partition mode for ordinary channels  |
| Input parameter 1    | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.   |
| Input parameter 2    | <code>new_state</code> : indicates the pre-configured status for partition mode of ordinary channels<br>This parameter can be TRUE or FALSE. |
| Output parameter     | NA   |

| Name                   | Description |
|------------------------|-------------|
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

```
/* enable the partitioned mode on ordinarychannel */
adc_ordinary_part_mode_enable(ADC1, TRUE);
```

## 5.2.28 adc\_preempt\_part\_mode\_enable function

The table below describes the function `adc_preempt_part_mode_enable`.

**Table 49. adc\_preempt\_part\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_preempt_part_mode_enable</code>   |
| Function prototype     | <code>void adc_preempt_part_mode_enable(adc_type *adc_x, confirm_state new_state)</code>  |
| Function description   | Enable partition mode for preempted channels  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>new_state</code> : indicates the pre-configured status for partition mode of preempted channels<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable the partitioned mode on preempt channel */
adc_preempt_part_mode_enable(ADC1, TRUE);
```

## 5.2.29 adc\_preempt\_auto\_mode\_enable function

The table below describes the function `adc_preempt_auto_mode_enable`.

**Table 50. adc\_preempt\_auto\_mode\_enable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>adc_preempt_auto_mode_enable</code>  |
| Function prototype   | <code>void adc_preempt_auto_mode_enable(adc_type *adc_x, confirm_state, new_state)</code>  |
| Function description | Enable auto preempted group conversion at the end of ordinary group conversion   |
| Input parameter 1    | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.   |
| Input parameter 2    | <code>new_state</code> : indicates the pre-configured status for auto preempted group conversion<br>This parameter can be TRUE or FALSE. |
| Output parameter     | NA   |
| Return value         | NA   |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

|  |
|--|
| <pre>/* enable automatic preempt group conversion */ adc_preempt_auto_mode_enable(ADC1, TRUE);</pre> |
|--|

### 5.2.30 adc\_conversion\_stop function

The table below describes the function `adc_conversion_stop`.

**Table 51. adc\_conversion\_stop function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_conversion_stop</code>   |
| Function prototype     | <code>void adc_conversion_stop(adc_type *adc_x)</code>                                       |
| Function description   | Stop on-going ADC conversion   |
| Input parameter        | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

|   |
|---|
| <pre>/* stop the ongoing conversion */ adc_conversion_stop(ADC1);</pre> |
|---|

### 5.2.31 adc\_conversion\_stop\_status\_get function

The table below describes the function `adc_conversion_stop_status_get`.

**Table 52. adc\_conversion\_stop\_status\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_conversion_stop_status_get</code>  |
| Function prototype     | <code>flag_status adc_conversion_stop_status_get(adc_type *adc_x)</code>                                 |
| Function description   | Get the status of stop conversion command  |
| Input parameter        | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.             |
| Output parameter       | NA   |
| Return value           | <code>flag_status</code> : get the operational status of stop conversion command<br>Return SET or RESET. |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

|  |
|--|
| <pre>/* wait stop conversion's */ while(adc_conversion_stop_status_get(ADC1));</pre> |
|--|

### 5.2.32 adc\_occe\_each\_conversion\_enable function

The table below describes the function `adc_occe_each_conversion_enable`.

**Table 53. adc\_occe\_each\_conversion\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_occe_each_conversion_enable</code>  |
| Function prototype     | <code>void adc_occe_each_conversion_enable(adc_type *adc_x, confirm_state new_state)</code>                       |
| Function description   | Enable OCCE flag for each ordinary channel conversion   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.                      |
| Input parameter 2      | <code>new_state</code> : indicates the pre-configured status of OCCE flag<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* each ordinary channel conversion set occe flag */
adc_occe_each_conversion_enable(ADC1, TRUE);
```

### 5.2.33 adc\_ordinary\_software\_trigger\_enable function

The table below describes the function `adc_ordinary_software_trigger_enable`

**Table 54. adc\_ordinary\_software\_trigger\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_ordinary_software_trigger_enable</code>   |
| Function prototype     | <code>void adc_ordinary_software_trigger_enable(adc_type *adc_x, confirm_state new_state)</code>  |
| Function description   | Trigger ordinary group conversion by software   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>new_state</code> : indicates the pre-configured status for software-triggered ordinary group conversion<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable ordinary software start conversion */
adc_ordinary_software_trigger_enable(ADC1, TRUE);
```

### 5.2.34 adc\_ordinary\_software\_trigger\_status\_get function

The table below describes the function `adc_ordinary_software_trigger_status_get`.

**Table 55. adc\_ordinary\_software\_trigger\_status\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_ordinary_software_trigger_status_get</code>   |
| Function prototype     | <code>flag_status adc_ordinary_software_trigger_status_get(adc_type *adc_x)</code>                                      |
| Function description   | Get the status of software-triggered ordinary group conversion  |
| Input parameter        | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.                            |
| Output parameter       | NA  |
| Return value           | <code>flag_status</code> : indicates the status of software-triggered ordinary group conversion<br>Return SET or RESET. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* wait ordinary software start conversion */
while(adc_ordinary_software_trigger_status_get(ADC1));
```

### 5.2.35 adc\_preempt\_software\_trigger\_enable function

The table below describes the function `adc_preempt_software_trigger_enable`.

**Table 56. adc\_preempt\_software\_trigger\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_preempt_software_trigger_enable</code>  |
| Function prototype     | <code>void adc_preempt_software_trigger_enable(adc_type *adc_x, confirm_state new_state)</code>   |
| Function description   | Preempted group conversion triggered by software  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>new_state</code> : indicates the pre-configured status of software-triggered preempted group conversion<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable preempt software start conversion */
adc_preempt_software_trigger_enable(ADC1, TRUE);
```



### 5.2.36 adc\_preempt\_software\_trigger\_status\_get function

The table below describes the function `adc_preempt_software_trigger_status_get`.

**Table 57. adc\_preempt\_software\_trigger\_status\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_preempt_software_trigger_status_get</code>   |
| Function prototype     | <code>flag_status adc_preempt_software_trigger_status_get(adc_type *adc_x)</code>  |
| Function description   | Get the status of software-triggered preempted group conversion  |
| Input parameter        | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.                             |
| Output parameter       | NA   |
| Return value           | <code>flag_status</code> : indicates the status of software-triggered preempted group conversion<br>Return SET or RESET. |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* wait preemptsoftware start conversion */
while(adc_preempt_software_trigger_status_get(ADC1));
```

### 5.2.37 adc\_ordinary\_conversion\_data\_get function

The table below describes the function `adc_ordinary_conversion_data_get`.

**Table 58. adc\_ordinary\_conversion\_data\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_ordinary_conversion_data_get</code>  |
| Function prototype     | <code>uint16_t adc_ordinary_conversion_data_get(adc_type *adc_x)</code>                      |
| Function description   | Get the converted data of ordinary group in non-master/slave mode                            |
| Input parameter        | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3. |
| Output parameter       | NA   |
| Return value           | 16-bit converted data by ordinary group  |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
uint16_t adc1_ordinary_index=0;
adc1_ordinary_index= adc_ordinary_conversion_data_get(ADC1);
```

### 5.2.38 adc\_combine\_ordinary\_conversion\_data\_get function

The table below describes the function `adc_combine_ordinary_conversion_data_get`.

**Table 59. adc\_combine\_ordinary\_conversion\_data\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_combine_ordinary_conversion_data_get</code>                |
| Function prototype     | <code>uint32_t adc_combine_ordinary_conversion_data_get(void)</code> |
| Function description   | Get the converted data of ordinary group in master/slave mode        |
| Input parameter        | NA   |
| Output parameter       | NA   |
| Return value           | 32-bit converted data by ordinary group                              |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
uint32_t common_ordinary_index=0;
common_ordinary_index=adc_combine_ordinary_conversion_data_get();
```

### 5.2.39 adc\_preempt\_conversion\_data\_get function

The table below describes the function `adc_preempt_conversion_data_get`.

**Table 60. adc\_preempt\_conversion\_data\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_preempt_conversion_data_get</code>   |
| Function prototype     | <code>uint16_t adc_preempt_conversion_data_get(adc_type *adc_x, adc_preempt_channel_type adc_preempt_channel)</code>                     |
| Function description   | Get the converted data of preempted group  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.   |
| Input parameter 2      | <code>adc_preempt_channel</code> : indicates the selected preempted channel<br>Refer to <a href="#">adc_preempt_channel</a> for details. |
| Output parameter       | NA   |
| Return value           | 16-bit converted data by preempted group   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
uint16_t adc1_preempt_valuetab[3]= {0};
adc1_preempt_valuetab[0]=adc_preempt_conversion_data_get(ADC1,ADC_PREEMPT_CHANNEL_1);
adc1_preempt_valuetab[1]=adc_preempt_conversion_data_get(ADC1,ADC_PREEMPT_CHANNEL_2);
adc1_preempt_valuetab[2]=adc_preempt_conversion_data_get(ADC1,ADC_PREEMPT_CHANNEL_3);
```

## 5.2.40 adc\_flag\_get function

The table below describes the function `adc_flag_get`.

**Table 61. adc\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_flag_get</code>   |
| Function prototype     | <code>flag_status adc_flag_get(adc_type *adc_x, uint8_t adc_flag)</code>                            |
| Function description   | Get the status of the flag bit  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.        |
| Input parameter 2      | <code>adc_flag</code> : indicates the selected flag. Refer to <a href="#">adc_flag</a> for details. |
| Output parameter       | NA  |
| Return value           | <code>flag_status</code> : the status for the selected flag bit<br>Return SET or RESET.             |
| Required preconditions | NA  |
| Called functions       | NA  |

### adc\_flag

The `adc_flag` is used to select a flag to get its status, including

- ADC\_VMOR\_FLAG: Voltage monitor outside threshold
- ADC\_OCCE\_FLAG: End of ordinary channel conversion
- ADC\_PCCE\_FLAG: End of preempted channel conversion
- ADC\_PCCS\_FLAG: Start of preempted channel conversion
- ADC\_OCCS\_FLAG: Start of ordinary channel conversion
- ADC\_OCCO\_FLAG: Overflow flag for ordinary channel conversion
- ADC\_RDY\_FLAG: ADC ready to conversion flag

### Example:

```
/* check if wakeup preempted channels conversion end flag is set */
if(adc_flag_get(ADC1, ADC_PCCE_FLAG) != RESET)
```

## 5.2.41 adc\_flag\_clear function

The table below describes the function `adc_flag_clear`.

**Table 62. adc\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_flag_clear</code>   |
| Function prototype     | <code>void adc_flag_clear(adc_type *adc_x, uint32_t adc_flag)</code>                                  |
| Function description   | Clear the flag bits that have been set  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.          |
| Input parameter 2      | <code>adc_flag</code> : select a flag to be cleared<br>Refer to <a href="#">adc_flag</a> for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* preempted channelsconversion end flag clear */
adc_flag_clear(ADC1,ADC_PCCE_FLAG);
```

### 5.2.42 adc\_ordinary\_oversample\_enable function

The table below describes the function `adc_ordinary_oversample_enable`.

**Table 63. adc\_ordinary\_oversample\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_ordinary_oversample_enable</code>  |
| Function prototype     | <code>void adc_ordinary_oversample_enable(adc_type *adc_x, confirm_state new_state)</code>   |
| Function description   | Enable oversampling for ordinary group   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be <code>ADC1</code> , <code>ADC2</code> or <code>ADC3</code> .                            |
| Input parameter 2      | <code>new_state</code> : indicates the pre-configured status of oversampling of ordinarygroup<br>This parameter can be <code>TRUE</code> or <code>FALSE</code> . |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable ordinaryoversampling */
adc_ordinary_oversample_enable(ADC1, TRUE);
```

### 5.2.43 adc\_preempt\_oversample\_enable function

The table below describes the function `adc_preempt_oversample_enable`.

**Table 64. adc\_preempt\_oversample\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>adc_preempt_oversample_enable</code>   |
| Function prototype     | <code>void adc_preempt_oversample_enable(adc_type *adc_x, confirm_state new_state)</code>  |
| Function description   | Enable oversampling for preempted group  |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be <code>ADC1</code> , <code>ADC2</code> or <code>ADC3</code> .                              |
| Input parameter 2      | <code>new_state</code> : indicates the pre-configured status of oversampling of preempted group<br>This parameter can be <code>TRUE</code> or <code>FALSE</code> . |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable preemptoversampling */
```

```
adc_preempt_oversample_enable(ADC1,TRUE);
```

## 5.2.44 adc\_oversample\_ratio\_shift\_set function

The table below describes the function `adc_oversample_ratio_shift_set`.

**Table 65. adc\_oversample\_ratio\_shift\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_oversample_ratio_shift_set</code>   |
| Function prototype     | <code>void adc_oversample_ratio_shift_set(adc_type *adc_x,<br/>adc_oversample_ratio_type adc_oversample_ratio, adc_oversample_shift_type<br/>adc_oversample_shift)</code> |
| Function description   | Set oversampling ratio and shift mode   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>adc_oversample_ratio</code> : indicates the oversampling rate<br>This parameter can be any enumerated value in the <code>adc_oversample_ratio_type</code> .         |
| Input parameter 3      | <code>adc_oversample_shift</code> : indicates the oversampling shift mode<br>This parameter can be any enumerated value in the <code>adc_oversample_shift_type</code> .   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### adc\_oversample\_ratio

The `adc_oversample_ratio` is used for ADC oversampling ratio selection, including

|   |                    |
|---|--------------------|
| <code>ADC_OVERSAMPLE_RATIO_2</code> :   | 2 x oversampling   |
| <code>ADC_OVERSAMPLE_RATIO_4</code> :   | 4 x oversampling   |
| <code>ADC_OVERSAMPLE_RATIO_8</code> :   | 5 x oversampling   |
| <code>ADC_OVERSAMPLE_RATIO_16</code> :  | 16 x oversampling  |
| <code>ADC_OVERSAMPLE_RATIO_32</code> :  | 32 x oversampling  |
| <code>ADC_OVERSAMPLE_RATIO_64</code> :  | 64 x oversampling  |
| <code>ADC_OVERSAMPLE_RATIO_128</code> : | 128 x oversampling |
| <code>ADC_OVERSAMPLE_RATIO_256</code> : | 256 x oversampling |

### adc\_oversample\_shift

The `adc_oversample_shift` is used for ADC oversampling bit width selection, including

|                                       |             |
|---------------------------------------|-------------|
| <code>ADC_OVERSAMPLE_SHIFT_0</code> : | No shift    |
| <code>ADC_OVERSAMPLE_SHIFT_1</code> : | 1-bit shift |
| <code>ADC_OVERSAMPLE_SHIFT_2</code> : | 2-bit shift |
| <code>ADC_OVERSAMPLE_SHIFT_3</code> : | 3-bit shift |
| <code>ADC_OVERSAMPLE_SHIFT_4</code> : | 4-bit shift |
| <code>ADC_OVERSAMPLE_SHIFT_5</code> : | 5-bit shift |
| <code>ADC_OVERSAMPLE_SHIFT_6</code> : | 6-bit shift |
| <code>ADC_OVERSAMPLE_SHIFT_7</code> : | 7-bit shift |
| <code>ADC_OVERSAMPLE_SHIFT_8</code> : | 8-bit shift |

### Example:

```
/* set oversampling ratio and shift */
```

```
adc_oversample_ratio_shift_set(ADC1, ADC_OVERSAMPLE_RATIO_8, ADC_OVERSAMPLE_SHIFT_3);
```

## 5.2.45 adc\_ordinary\_oversample\_trig\_enable function

The table below describes the function `adc_ordinary_oversample_trig_enable`.

**Table 66. adc\_ordinary\_oversample\_trig\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_ordinary_oversample_trig_enable</code>  |
| Function prototype     | <code>void adc_ordinary_oversample_trig_enable(adc_type *adc_x, confirm_state new_state)</code>   |
| Function description   | Enable oversampling trigger mode for ordinary group   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>new_state</code> : indicates the pre-configured status of oversampling trigger mode of ordinary group<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* disable ordinary oversampling trigger mode */
adc_ordinary_oversample_trig_enable(ADC1, FALSE);
```

## 5.2.46 adc\_ordinary\_oversample\_restart\_set function

The table below describes the function `adc_ordinary_oversample_restart_set`.

**Table 67. adc\_ordinary\_oversample\_restart\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>adc_ordinary_oversample_restart_set</code>  |
| Function prototype     | <code>void adc_ordinary_oversample_restart_set(adc_type *adc_x, adc_ordinary_oversample_restart_type adc_ordinary_oversample_restart)</code>  |
| Function description   | Select oversampling restart mode for ordinary group   |
| Input parameter 1      | <code>adc_x</code> : indicates the selected ADC<br>This parameter can be ADC1, ADC2 or ADC3.  |
| Input parameter 2      | <code>adc_ordinary_oversample_restart</code> : indicates the pre-configured status of oversampling restart mode for ordinary group<br>This parameter can be any enumerated value in the <code>adc_ordinary_oversample_restart_type</code> . |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**adc\_ordinary\_oversample\_restart**

The `adc_ordinary_oversample_restart` is used to select oversampling restart mode for ordinary group ADC conversion, including:

`ADC_OVERSAMPLE_CONTINUE`

Continuous mode (the oversampling buffer area of ordinary group is preserved)

`ADC_OVERSAMPLE_RESTART`

Restart mode (the oversampling buffer area of ordinary group is cleared, that is, the sampling times of the current channel is cleared)

**Example:**

```
/* set ordinaryoversample restart mode */  
adc_ordinary_oversample_restart_set(ADC1, ADC_OVERSAMPLE_CONTINUE);
```

### 5.3 Controller area network (CAN)

CAN register structure `can_type` is defined in the “at32f435\_437\_can.h”.

```
/**
 * @brief type define can register all
 */
typedef struct
{
    ...
} can_type;
```

The table below gives a list of the CAN registers.

**Table 68. Summary of CAN registers**

| Register | Description   |
|----------|---|
| mctrl    | CAN master control register                               |
| msts     | CAN master status register                                |
| tsts     | CAN transmit status register                              |
| rf0      | CAN receive FIFO 0 register                               |
| fr1      | CAN receive FIFO 1 register                               |
| inten    | CAN interrupt enable register                             |
| ests     | CAN error status register                                 |
| btmg     | CAN bit timing register                                   |
| tmi0     | Transmit mailbox0 identifier register                     |
| tmc0     | Transmit mailbox0 data length and time stamp register     |
| tmdtl0   | Transmit mailbox0 data byte low register                  |
| tmdth0   | Transmit mailbox0 data byte high register                 |
| tmi1     | Transmit mailbox 1 identifier register                    |
| tmc1     | Transmit mailbox 1 data length and time stamp register    |
| tmdtl1   | Transmit mailbox 1 data byte low register                 |
| tmdth1   | Transmit mailbox 1 data byte high register                |
| tmi2     | Transmit mailbox2 identifier register                     |
| tmc2     | Transmit mailbox2 data length and time stamp register     |
| tmdtl2   | Transmit mailbox2 data byte low register                  |
| tmdth2   | Transmit mailbox2 data byte high register                 |
| rfi0     | Receive FIFO0 mailbox identifier register                 |
| rfc0     | Receive FIFO0 mailbox data length and time stamp register |
| rfdtl0   | Receive FIFO0 mailbox data byte low register              |
| rfdth0   | Receive FIFO0 mailbox data byte high register             |
| rfi1     | Receive FIFO1 mailbox identifier register                 |
| rfc1     | Receive FIFO1 mailbox data length and time stamp register |
| rfdtl1   | Receive FIFO1 mailbox data byte low register              |
| rfdth1   | Receive FIFO1 mailbox data byte high register             |
| fctrl    | CAN filter control register                               |
| fmcfg    | CAN filter mode configuration register                    |
| fscfg    | CAN filter size configuration register                    |



| Register | Description                          |
|----------|--------------------------------------|
| frf      | CAN filter FIFO association register |
| facfg    | CAN filter activate control register |
| fb0f1    | CAN filter bank 0 filter register 1  |
| fb0f2    | CAN filter bank 0 filter register 2  |
| fb1f1    | CAN filter bank 1 filter register 1  |
| fb1f2    | CAN filter bank 1 filter register 2  |
| ...      | ...                                  |
| Fb27f1   | CAN filter bank 27 filter register 1 |
| Fb27f2   | CAN filter bank 27 filter register 2 |

The table below gives a list of CAN library functions.

**Table 69. Summary of CAN library functions**

| Function name                   | Description  |
|---------------------------------|--|
| can_reset                       | Reset all CAN registers to their reset values  |
| can_baudrate_default_para_init  | Configure the CAN baud rate initial structure with the initial value                 |
| can_baudrate_set                | Configure CAN baud rate  |
| can_default_para_init           | Configure the CAN initial structure with the initial value                           |
| can_base_init                   | Initialize CAN registers with the specified parameters in the can_base_struct        |
| can_filter_default_para_init    | Configure the CAN filter initial structure with the initial value                    |
| can_filter_init                 | Initialize CAN registers with the specified parameters in the can_filter_init_struct |
| can_debug_transmission_prohibit | Select to disalbe/enable message reception and transmission when debug               |
| can_ttc_mode_enable             | Enable time-triggered mode   |
| can_message_transmit            | Transmit a frame of message  |
| can_transmit_status_get         | Get the status of transmission   |
| can_transmit_cancel             | Cancel transmission  |
| can_message_receive             | Receive a frame of message   |
| can_receive_fifo_release        | Release receive FIFO   |
| can_receive_message_pending_get | Get the count of pending messages in FIFO  |
| can_operating_mode_set          | Configure CAN operating mode   |
| can_doze_mode_enter             | Enter sleep mode   |
| can_doze_mode_exit              | Exit sleep mode  |
| can_error_type_record_get       | Read CAN error type  |
| can_receive_error_counter_get   | Read CAN receive error counter   |
| can_transmit_error_counter_get  | Read CAN transmit error counter  |
| can_interrupt_enable            | Enable the selected CAN interrupt  |
| can_flag_get                    | Read the selected CAN flag   |
| can_flag_clear                  | Clear the selected CAN flag  |

### 5.3.1 can\_reset function

The table below describes the function can\_reset.

**Table 70. can\_reset function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_reset  |
| Function prototype     | void can_reset(can_type* can_x);   |
| Function description   | Reset CAN registers to their default values                              |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | crm_periph_reset();  |

**Example:**

```
can_reset(CAN1);
```

### 5.3.2 can\_baudrate\_default\_para\_init function

The table below describes the function can\_baudrate\_default\_para\_init.

**Table 71. can\_baudrate\_default\_para\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_baudrate_default_para_init   |
| Function prototype     | void can_baudrate_default_para_init(can_baudrate_type* can_baudrate_struct);   |
| Function description   | Configure the CAN baud rate initial structure with the initial value           |
| Input parameter 1      | can_baudrate_struct: <a href="#">can_baudrate_type</a> pointer                 |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | It is necessary to define a variable of the can_baudrate_type before starting. |
| Called functions       | NA   |

**Example:**

```
can_baudrate_type can_baudrate_struct;
can_baudrate_default_para_init(&can_baudrate_struct);
```

### 5.3.3 can\_baudrate\_set function

The table below describes the function can\_baudrate\_set.

**Table 72. can\_baudrate\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | can_baudrate_set  |
| Function prototype     | error_status can_baudrate_set(can_type* can_x, can_baudrate_type* can_baudrate_struct); |
| Function description   | Set baud rate for CAN   |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.                |
| Input parameter 2      | can_baudrate_struct: <a href="#">can_baudrate_type</a> pointer                          |
| Output parameter       | NA  |
| Return value           | status_index: check if baud rate is configured successfully                             |
| Required preconditions | It is necessary to define a variable of the can_baudrate_type before starting.          |
| Called functions       | NA  |

The can\_baudrate\_type is defined in the at32f435\_437\_can.h:

typedef struct

```
{
    uint16_t      baudrate_div;
    can_rsaw_type rsaw_size;
    can_bts1_type bts1_size;
    can_bts2_type bts2_size;
} can_baudrate_type;
```

**baudrate\_div**

CAN clock division factor

Value range: 0x001~0x400

**rsaw\_size**

Defines the maximum of time unit that the CAN is allowed to lengthen or shorten in a bit

CAN\_RSAW\_1TQ: Resynchronization width is 1 time unit

CAN\_RSAW\_2TQ: Resynchronization width is 2 time units

CAN\_RSAW\_3TQ: Resynchronization width is 3 time units

CAN\_RSAW\_4TQ: Resynchronization width is 4 time units

**bts1\_size**

segment1 time duration

bts1\_size description

CAN\_BTS1\_1TQ: the bit time segment 1 has 1 time unit

.....

CAN\_BTS1\_16TQ: the bit time segment 1 has 16 time units

**bts2\_size**

segment2 time duration

CAN\_BTS2\_1TQ: the bit time segment 2 has 1 time unit

.....

CAN\_BTS2\_8TQ: the bit time segment 2 has 8 time units

**Example:**

```

/* can baudrate, set baudrate = pclk/(baudrate_div*(1 + bts1_size + bts2_size)) */
can_baudrate_struct.baudrate_div= 10;
can_baudrate_struct.rsaw_size = CAN_RSAW_3TQ;
can_baudrate_struct.bts1_size = CAN_BTS1_8TQ;
can_baudrate_struct.bts2_size = CAN_BTS2_3TQ;
can_baudrate_set(CAN1, &can_baudrate_struct);

```

### 5.3.4 can\_default\_para\_init function

The table below describes the function can\_default\_para\_init.

**Table 73. can\_default\_para\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_default_para_init  |
| Function prototype     | void can_default_para_init(can_base_type* can_base_struct);                |
| Function description   | Set an initial value for CAN initial structure                             |
| Input parameter 1      | can_base_struct: <a href="#">can_base_type</a> pointer                     |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | It is necessary to define a variable of the can_base_type before starting. |
| Called functions       | NA   |

**Example:**

```

can_base_type can_base_struct;
can_default_para_init (&can_base_struct);

```

### 5.3.5 can\_base\_init function

The table below describes the function can\_base\_init.

**Table 74. can\_base\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | can_base_init   |
| Function prototype     | error_status can_base_init(can_type* can_x, can_base_type* can_base_struct);  |
| Function description   | Initialize CAN registers with the specified parameters in the can_base_struct |
| Input parameter 1      | can_base_struct: <a href="#">can_base_type</a> pointer                        |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | It is necessary to define a variable of the can_base_type before starting.    |
| Called functions       | NA  |

The can\_base\_type is defined in the at32f435\_437\_can.h.

typedef struct

```

{
    can_mode_type           mode_selection;
    confirm_state          ttc_enable;
    confirm_state          aebo_enable;

```

```

confirm_state          aed_enable;
confirm_state          prsf_enable;
can_msg_discarding_rule_type mdrsel_selection;
can_msg_sending_rule_type  mmsr_selection;

```

```
} can_base_type;
```

### **mode\_selection**

Test mode selection

```

CAN_MODE_COMMUNICATE:      Communication mode
CAN_MODE_LOOPBACK:        Loopback mode
CAN_MODE_LISTENONLY:      Listen only mode
CAN_MODE_LISTENONLY_LOOPBACK: Loopback + listen only mode

```

### **ttc\_enable**

Enable/disable time-triggered communication mode

FALSE: Disable time-triggered communication mode

TRUE: Enable time-triggered communication mode (while receiving/sending messages, capture time stamp and store it into the CAN\_RFCx and CAN\_TMCx registers)

### **aebo\_enable**

Enable auto exit of bus-off mode

FALSE: Automatic exit of bus-off mode is disabled

TRUE: Automatic exit of bus-off mode is enabled

### **aed\_enable**

Enable auto exit of sleep mode

FALSE: Auto exit of sleep mode is disabled

TRUE: Auto exit of sleep mode is enabled

### **prsf\_enable**

Disable retransmission when transmit failed

FALSE: Retransmission is enabled

TRUE: Retransmission is disabled

### **mdrsel\_selection**

Define message discard rule when reception overflows

CAN\_DISCARDING\_FIRST\_RECEIVED: The previous message is discarded

CAN\_DISCARDING\_LAST\_RECEIVED: The new incoming message is discarded

### **mmsr\_selection**

Define multiple message transmit sequence rule

CAN\_SENDING\_BY\_ID: The message with the smallest identifier number is first transmitted

CAN\_SENDING\_BY\_REQUEST: The message with the first request order is first transmitted

### **Example:**

```

/* can base init */
can_base_struct.mode_selection = CAN_MODE_COMMUNICATE;
can_base_struct.ttc_enable = FALSE;
can_base_struct.aebo_enable = TRUE;
can_base_struct.aed_enable = TRUE;
can_base_struct.prsf_enable = FALSE;
can_base_struct.mdrsel_selection = CAN_DISCARDING_FIRST_RECEIVED;
can_base_struct.mmsr_selection = CAN_SENDING_BY_ID;
can_base_init(CAN1, &can_base_struct);

```

### 5.3.6 can\_filter\_default\_para\_init function

The table below describes the function can\_filter\_default\_para\_init.

**Table 75. can\_filter\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | can_filter_default_para_init  |
| Function prototype     | void can_filter_default_para_init(can_filter_init_type* can_filter_init_struct);  |
| Function description   | Configure CAN filter initialization structure with the initial value              |
| Input parameter 1      | can_filter_init_struct: <a href="#">can_filter_init_type</a> pointer              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | It is necessary to define a variable of the can_filter_init_type before starting. |
| Called functions       | NA  |

**Example:**

```
can_filter_init_type can_filter_init_struct;
can_filter_default_para_init(&can_filter_init_struct);
```

### 5.3.7 can\_filter\_init function

The table below describes the function can\_filter\_init.

**Table 76. can\_filter\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_filter_init  |
| Function prototype     | void can_filter_init(can_type* can_x, can_filter_init_type* can_filter_init_struct); |
| Function description   | Initialize all CAN registers with the specified parameters in the can_base_struct.   |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.             |
| Input parameter 2      | can_filter_init_struct: <a href="#">can_filter_init_type</a> pointer                 |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | It is necessary to define a variable of the can_filter_init_type before starting.    |
| Called functions       | NA   |

The can\_filter\_init\_type is defined in the at32f435\_437\_can.h.

typedef struct

```
{
    confirm_state          filter_activate_enable;
    can_filter_mode_type   filter_mode;
    can_filter_fifo_type   filter_fifo;
    uint8_t                filter_number;
    can_filter_bit_width_type filter_bit;
    uint16_t               filter_id_high;
    uint16_t               filter_id_low;
    uint16_t               filter_mask_high;
```

```
uint16_t          filter_mask_low;
} can_filter_init_type;
```

### **filter\_activate\_enable**

Enable/disable filter bank.

FALSE: Disable filter bank

TRUE: Enable filter bank

### **filter\_mode**

Select filter mode.

CAN\_FILTER\_MODE\_ID\_MASK: Identifier mask mode

CAN\_FILTER\_MODE\_ID\_LIST: Identifier list mode

### **filter\_fifo**

Select filter associated FIFO.

CAN\_FILTER\_FIFO0: Associated with FIFO0

CAN\_FILTER\_FIFO1: Associated with FIFO1

### **filter\_number**

Select filter bank.

Value range: 0~27

### **filter\_bit**

Select filter bit width.

CAN\_FILTER\_16BIT: 16-bit

CAN\_FILTER\_32BIT: 32-bit

### **filter\_id\_high**

The filter\_id\_high is used to configure the upper 16 bits of the filter identifier 1 (32-bit width, Mask/List mode), the filter identifier 2 (16-bit width, List mode) or the filter mask identifier 1 (16-bit width, Mask mode).

Value range: 0x0000~0xFFFF

### **filter\_id\_low**

The filter\_id\_low is used to configure the lower 16 bits of the filter identifier 1 (32-bit width, Mask/List mode), or the filter identifier 1 (16-bit width, List mode).

Value range: 0x0000~0xFFFF

### **filter\_mask\_high**

The filter\_mask\_high is used to configure the upper 16 bits of the filter identifier 1 (32-bit width, Mask mode), the filter mask identifier 2 (16-bit width, Mask mode), the upper 16 bits of the filter mask identifier 2 (32-bit width, List mode), or the filter mask identifier 4 (16-bit width, List mode).

Value range: 0x0000~0xFFFF

### **filter\_mask\_low**

The filter\_mask\_low is used to configure the lower 16 bits of the filter identifier 1 (32-bit width, Mask mode), the filter mask identifier 2 (16-bit width, Mask mode), the lower 16 bits of the filter identifier 2 (32-bit width, List mode), or the filter mask identifier (16-bit width, List mode).

Value range: 0x0000~0xFFFF

### **Example:**

```
/* can filter init */
can_filter_init_struct.filter_activate_enable = TRUE;
can_filter_init_struct.filter_mode = CAN_FILTER_MODE_ID_MASK;
can_filter_init_struct.filter_fifo = CAN_FILTER_FIFO0;
can_filter_init_struct.filter_number = 0;
```

```

can_filter_init_struct.filter_bit=CAN_FILTER_32BIT;
can_filter_init_struct.filter_id_high=0;
can_filter_init_struct.filter_id_low=0;
can_filter_init_struct.filter_mask_high=0;
can_filter_init_struct.filter_mask_low=0;
can_filter_init(CAN1, &can_filter_init_struct);
    
```

### 5.3.8 can\_debug\_transmission\_prohibit function

The table below describes the function can\_debug\_transmission\_prohibit.

**Table 77. can\_debug\_transmission\_prohibit function**

| Name                   | Description   |
|------------------------|---|
| Function name          | can_debug_transmission_prohibit   |
| Function prototype     | void can_debug_transmission_prohibit(can_type* can_x, confirm_state new_state); |
| Function description   | Disable/enable message transceiver when debugging                               |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.        |
| Input parameter 2      | new_state: Enable or disable<br>This parameter can be FALSE or TRUE.            |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* prohibit can trans when debug*/
can_debug_transmission_prohibit(CAN1, TRUE);
    
```

### 5.3.9 can\_ttc\_mode\_enable function

The table below describes the function can\_ttc\_mode\_enable

**Table 78. can\_ttc\_mode\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_ttc_mode_enable  |
| Function prototype     | void can_ttc_mode_enable(can_type* can_x, confirm_state new_state);      |
| Function description   | Enable time-triggered mode   |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2. |
| Input parameter 2      | new_state: Enable or disable<br>This parameter can be FALSE or TRUE.     |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**



```
/* can time trigger operation communication mode enable*/
can_ttc_mode_enable (CAN1, TRUE);
```

*Note: When the ttc\_enable is enabled in the can\_base\_init, it indicates that only the time stamp is enabled (during message receive and transmit, the time stamp is captured and stored in the CAN\_RFCx and CAN\_TMCx registers). But when the can\_ttc\_mode\_enable is enabled, not only the time stamp is enable, but the time stamp transmission feature is enabled (during message transmission, the time stamp is sent on the 7<sup>th</sup> and 8<sup>th</sup> data byte).*

### 5.3.10 can\_message\_transmit function

The table below describes the function can\_message\_transmit.

**Table 79. can\_message\_transmit function**

| Name                   | Description   |
|------------------------|---|
| Function name          | can_message_transmit  |
| Function prototype     | uint8_t can_message_transmit(can_type* can_x, can_tx_message_type* tx_message_struct);            |
| Function description   | Transmit a frame of message.  |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.                          |
| Input parameter 2      | tx_message_struct: message pending for transmission, refer to <a href="#">can_tx_message_type</a> |
| Output parameter       | NA  |
| Return value           | transmit_mailbox: indicates the mailbox number required to send message                           |
| Required preconditions | Write the to-be-sent message in the tx_message_struct   |
| Called functions       | NA  |

The can\_tx\_message\_type is defined in the at32f435\_437\_can.h.

typedef struct

```
{
    uint32_t          standard_id;
    uint32_t          extended_id;
    can_identifier_type id_type;
    can_trans_frame_type frame_type;
    uint8_t           dlc;
    uint8_t           data[8];
}
```

} can\_tx\_message\_type;

#### **standard\_id**

Standard identifier (11 bits active)

Value range: 0x000~0x7FF

#### **extended\_id**

Extended identifier (29 bits active)

Value range: 0x000~0x1FFFFFFF

#### **id\_type**

Identifier type

CAN\_ID\_STANDARD: Standard identifier

CAN\_ID\_EXTENDED: Extended identifier

**frame\_type**

Frame type

CAN\_TFT\_DATA: Data frame

CAN\_TFT\_REMOTE: Remote frame

**dlc**

Data length (in byte)

Value range: 0~8

**data[8]**

Data pending for transmission

Value range: 0x00~0xFF

**Example:**

```

/* can transmit data */
static void can_transmit_data(void)
{
    uint8_t transmit_mailbox;
    can_tx_message_type tx_message_struct;
    tx_message_struct.standard_id = 0x400;
    tx_message_struct.extended_id = 0;
    tx_message_struct.id_type = CAN_ID_STANDARD;
    tx_message_struct.frame_type = CAN_TFT_DATA;
    tx_message_struct.dlc = 8;
    tx_message_struct.data[0] = 0x11;
    tx_message_struct.data[1] = 0x22;
    tx_message_struct.data[2] = 0x33;
    tx_message_struct.data[3] = 0x44;
    tx_message_struct.data[4] = 0x55;
    tx_message_struct.data[5] = 0x66;
    tx_message_struct.data[6] = 0x77;
    tx_message_struct.data[7] = 0x88;

    transmit_mailbox = can_message_transmit(CAN1, &tx_message_struct);
    while(can_transmit_status_get(CAN1, (can_tx_mailbox_num_type)transmit_mailbox) !=
CAN_TX_STATUS_SUCCESSFUL);
}

```

### 5.3.11 can\_transmit\_status\_get function

The table below describes the function can\_transmit\_status\_get.

**Table 80. can\_transmit\_status\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_transmit_status_get  |
| Function prototype     | can_transmit_status_type can_transmit_status_get(can_type* can_x, can_tx_mailbox_num_type transmit_mailbox); |
| Function description   | Get the status of transmission   |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.                                     |
| Input parameter 2      | transmit_mailbox: indicates the mailbox number required to send message                                      |
| Output parameter       | NA   |
| Return value           | state_index: transmission status   |
| Required preconditions | First send a frame of message and get a transmit mailbox number  |
| Called functions       | NA   |

**Example:**

```

/* can transmit data */
static void can_transmit_data(void)
{
    uint8_t transmit_mailbox;
    can_tx_message_type tx_message_struct;
    tx_message_struct.standard_id = 0x400;
    tx_message_struct.extended_id = 0;
    tx_message_struct.id_type = CAN_ID_STANDARD;
    tx_message_struct.frame_type = CAN_TFT_DATA;
    tx_message_struct.dlc = 8;
    tx_message_struct.data[0] = 0x11;
    tx_message_struct.data[1] = 0x22;
    tx_message_struct.data[2] = 0x33;
    tx_message_struct.data[3] = 0x44;
    tx_message_struct.data[4] = 0x55;
    tx_message_struct.data[5] = 0x66;
    tx_message_struct.data[6] = 0x77;
    tx_message_struct.data[7] = 0x88;
    transmit_mailbox = can_message_transmit(CAN1, &tx_message_struct);
    while(can_transmit_status_get(CAN1, (can_tx_mailbox_num_type)transmit_mailbox) !=
CAN_TX_STATUS_SUCCESSFUL);
}

```

### 5.3.12 can\_transmit\_cancel function

The table below describes the function can\_transmit\_cancel.

**Table 81. can\_transmit\_cancel function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_transmit_cancel  |
| Function prototype     | void can_transmit_cancel(can_type* can_x, can_tx_mailbox_num_type transmit_mailbox); |
| Function description   | Cancel transmission  |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.             |
| Input parameter 2      | transmit_mailbox: indicates the mailbox number required to send message              |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | First send a frame of message and get a transmit mailbox number                      |
| Called functions       | NA   |

**Example:**

```

/* cancel a transmit request */
uint8_t transmit_mailbox;
transmit_mailbox = can_message_transmit(CAN1, &tx_message_struct);
can_transmit_cancel(CAN1, (can_tx_mailbox_num_type)transmit_mailbox);

```

### 5.3.13 can\_message\_receive function

The table below describes the function can\_message\_receive.

**Table 82. can\_message\_receive function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_message_receive  |
| Function prototype     | void can_message_receive(can_type* can_x, can_rx_fifo_num_type fifo_number, can_rx_message_type* rx_message_struct); |
| Function description   | Receive a frame of message   |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.   |
| Input parameter 2      | fifo_number: receive FIFO<br>This parameter can be CAN_RX_FIFO0 or CAN_RX_FIFO1.                                     |
| Output parameter       | rx_message_struct: indicates the received message, refer to <a href="#">can_rx_message_type</a>                      |
| Return value           | NA   |
| Required preconditions | Receive FIFO not empty (FIFO message count is not zero)  |
| Called functions       | void can_receive_fifo_release(can_type* can_x, can_rx_fifo_num_type fifo_number);                                    |

The can\_rx\_message\_type is defined in the at32f435\_437\_can.h.

typedef struct

```

{
    uint32_t          standard_id;
    uint32_t          extended_id;

```

```

    can_identifier_type    id_type;
    can_trans_frame_type  frame_type;
    uint8_t               dlc;
    uint8_t               data[8];
    uint8_t               filter_index;
} can_rx_message_type;

```

## **standard\_id**

Standard identifier (11 bits active)

Value range: 0x000~0x7FF

## **extended\_id**

Extended identifier (29 bits active)

Value range: 0x000~0xFFFFFFFF

## **id\_type**

Identifier type

CAN\_ID\_STANDARD: Standard identifier

CAN\_ID\_EXTENDED: Extended identifier

## **frame\_type**

Frame type

CAN\_TFT\_DATA: Data frame

CAN\_TFT\_REMOTE: Remote frame

## **dlc**

Data length (in byte)

Value range: 0~8

## **data[8]**

Data pending for transmission

Value range: 0x00~0xFF

## **filter\_index**

Filter match index (indicating the filter number that a message has passed through)

Value range: 0x00~0xFF

## **Example:**

```

/* can receive message */
can_rx_message_type rx_message_struct;
can_message_receive(CAN1, CAN_RX_FIFO0, &rx_message_struct);

```

### 5.3.14 can\_receive\_fifo\_release function

The table below describes the function can\_receive\_fifo\_release.

**Table 83. can\_receive\_fifo\_release function**

| Name                   | Description   |
|------------------------|---|
| Function name          | can_receive_fifo_release  |
| Function prototype     | void can_receive_fifo_release(can_type* can_x, can_rx_fifo_num_type fifo_number); |
| Function description   | Release receive FIFO  |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.          |
| Input parameter 2      | fifo_number: receive FIFO<br>This parameter can be CAN_RX_FIFO0 or CAN_RX_FIFO1.  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | Message in FIFO has already been read   |
| Called functions       | NA  |

**Example:**

```

/* can receive message */
void can_message_receive(can_type* can_x, can_rx_fifo_num_type fifo_number, can_rx_message_type*
rx_message_struct)
{
    /* get the id type */
    rx_message_struct->id_type = (can_identifier_type)can_x->fifo_mailbox[fifo_number].rfi_bit.rfidi;
    ...

    /* get the data field */
    rx_message_struct->data[0] = can_x->fifo_mailbox[fifo_number].rfdtl_bit.rfdt0;
    ...
    rx_message_struct->data[7] = can_x->fifo_mailbox[fifo_number].rfdth_bit.rfdt7;

    /*FIFO must be read before releasing FIFO */
    /* release the fifo */
    can_receive_fifo_release(can_x, fifo_number);
}

```

### 5.3.15 can\_receive\_message\_pending\_get function

The table below describes the function can\_receive\_message\_pending\_get.

**Table 84. can\_receive\_message\_pending\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | can_receive_message_pending_get   |
| Function prototype     | uint8_t can_receive_message_pending_get(can_type* can_x, can_rx_fifo_num_type fifo_number); |
| Function description   | Get the number of message pending for read in FIFO  |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.                    |
| Input parameter 2      | fifo_number: receive FIFO<br>This parameter can be CAN_RX_FIFO0 or CAN_RX_FIFO1.            |
| Output parameter       | NA  |
| Return value           | message_pending: the count of message pending for read in FIFO                              |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* return the number of pending messages of */
can_receive_message_pending_get(CAN1, CAN_RX_FIFO0);
```

### 5.3.16 can\_operating\_mode\_set function

The table below describes the function can\_operating\_mode\_set.

**Table 85. can\_operating\_mode\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | can_operating_mode_set  |
| Function prototype     | error_status can_operating_mode_set(can_type* can_x, can_operating_mode_type can_operating_mode); |
| Function description   | Configure CAN operating modes   |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.                          |
| Input parameter 2      | <i>can_operating_mode</i> : CAN operating mode selection  |
| Output parameter       | NA  |
| Return value           | status: indicates whether configuration is successful or not                                      |
| Required preconditions | NA  |
| Called functions       | NA  |

**can\_operating\_mode**

CAN\_OPERATINGMODE\_FREEZE: Freeze mode—for CAN controller initialization

CAN\_OPERATINGMODE\_DOZE: Sleep mode—CAN clock stopped to save power consumption

CAN\_OPERATINGMODE\_COMMUNICATE: Communication mode—for communication

**Example:**

```
/* set the operation mode –enter freeze mode*/
```

```

can_operating_mode_set(CAN1, CAN_OPERATINGMODE_FREEZE);

/* Initialize CAN controller */
...

/* set the operation mode –enter communicate mode*/
can_operating_mode_set(CAN1, CAN_OPERATINGMODE_COMMUNICATE);

/* Start communication: send and receive message*/
...

```

### 5.3.17 can\_doze\_mode\_enter function

The table below describes the function can\_doze\_mode\_enter.

**Table 86. can\_doze\_mode\_enter function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_doze_mode_enter  |
| Function prototype     | can_enter_doze_status_type can_doze_mode_enter(can_type* can_x);                   |
| Function description   | Enter sleep mode   |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.           |
| Output parameter       | NA   |
| Return value           | <a href="#">can_enter_doze_status</a> : indicates wheter the Sleep mode is entered |
| Required preconditions | NA   |
| Called functions       | NA   |

#### can\_enter\_doze\_status

Indicates whether the Sleep mode is entered or not

CAN\_ENTER\_DOZE\_FAILED: Sleep mode entry failure

CAN\_ENTER\_DOZE\_SUCCESSFUL: Sleep mode entry success

#### Example:

```

/* can enter the low power mode */
can_enter_doze_status_type can_enter_doze_status;
can_enter_doze_status = can_doze_mode_enter(CAN1);

```

### 5.3.18 can\_doze\_mode\_exit function

The table below describes the function can\_doze\_mode\_exit.

**Table 87. can\_doze\_mode\_exit function**

| Name                 | Description  |
|----------------------|--|
| Function name        | can_doze_mode_exit   |
| Function prototype   | can_quit_doze_status_type can_doze_mode_exit(can_type* can_x);           |
| Function description | Exit Sleep mode  |
| Input parameter 1    | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2. |



| Name                   | Description   |
|------------------------|---|
| Output parameter       | NA  |
| Return value           | <a href="#">can_quit_doze_status</a> : indicates whether the Sleep mode has been left |
| Required preconditions | NA  |
| Called functions       | NA  |

### can\_quit\_doze\_status

Indicates whether the Sleep mode has been left successfully

CAN\_QUIT\_DOZE\_FAILED: Sleep mode exit failure

CAN\_QUIT\_DOZE\_SUCCESSFUL: Sleep mode exit success

#### Example:

```

/* can exit the low power mode */
can_quit_doze_status_type can_quit_doze_status;
can_quit_doze_status = can_doze_mode_exit (CAN1);
    
```

## 5.3.19 can\_error\_type\_record\_get function

The table below describes the function `can_error_type_record_get`.

**Table 88. can\_error\_type\_record\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>can_error_type_record_get</code>   |
| Function prototype     | <code>can_error_record_type can_error_type_record_get(can_type* can_x);</code>         |
| Function description   | Read CAN error type  |
| Input parameter 1      | <code>can_x</code> : indicates the selected CAN<br>This parameter can be CAN1 or CAN2. |
| Output parameter       | NA   |
| Return value           | <a href="#">can_error_record</a> : error type  |
| Required preconditions | NA   |
| Called functions       | NA   |

### can\_error\_record

CAN error record

CAN\_ERRORRECORD\_NOERR: No error

CAN\_ERRORRECORD\_STUFFERR: Bit stuffing error

CAN\_ERRORRECORD\_FORMERR: Format error

CAN\_ERRORRECORD\_ACKERR: Acknowledge error

CAN\_ERRORRECORD\_BITRECESSIVEERR: Recessive bit error

CAN\_ERRORRECORD\_BITDOMINANTERR: Dominant bit error

CAN\_ERRORRECORD\_CRCERR: CRC error

CAN\_ERRORRECORD\_SOFTWARESETERR: Set by software

#### Example:

```

/* get the error type record (etr) */
can_error_record_type can_error_record;
can_error_record = can_error_type_record_get (CAN1);
    
```

### 5.3.20 can\_receive\_error\_counter\_get function

The table below describes the function can\_receive\_error\_counter\_get.

**Table 89. can\_receive\_error\_counter\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_receive_error_counter_get  |
| Function prototype     | uint8_t can_receive_error_counter_get(can_type* can_x);                  |
| Function description   | Read CAN receive error counter   |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2. |
| Output parameter       | NA   |
| Return value           | receive_error_counter: Receive error counter<br>Value range: 0x00~0xFF   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```

/* get the receive error counter (rec) */
uint8_t receive_error_counter;
receive_error_counter = can_receive_error_counter_get (CAN1);

```

### 5.3.21 can\_transmit\_error\_counter\_get function

The table below describes the function can\_transmit\_error\_counter\_get.

**Table 90. can\_transmit\_error\_counter\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_transmit_error_counter_get   |
| Function prototype     | uint8_t can_transmit_error_counter_get(can_type* can_x);                 |
| Function description   | Read CAN transmit error counter  |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2. |
| Output parameter       | NA   |
| Return value           | transmit_error_counter: Transmit error counter<br>Value range: 0x00~0xFF |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```

/* get the transmit error counter (tec) */
uint8_t transmit_error_counter;
transmit_error_counter = can_transmit_error_counter_get (CAN1);

```

### 5.3.22 can\_interrupt\_enable

The table below describes the function can\_interrupt\_enable.

**Table 91. can\_interrupt\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_interrupt_enable   |
| Function prototype     | void can_interrupt_enable(can_type* can_x, uint32_t can_int, confirm_state new_state); |
| Function description   | Enable the selected CAN interrupt  |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.               |
| Input parameter 2      | <a href="#">can_int</a> : Select CAN interrupts  |
| Input parameter 3      | new_state: Enable or disable<br>This parameter can be FALSE or TRUE.                   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### can\_int

CAN interrupt selection

|                   |   |
|-------------------|---|
| CAN_TCIEN_INT:    | Transmit mailbox empty interrupt enable |
| CAN_RF0MIEN_INT:  | FIFO0 receive message interrupt enable  |
| CAN_RF0FIEN_INT:  | Receive FIFO0 full interrupt enable     |
| CAN_RF0OIEEN_INT: | Receive FIFO0 overflow interrupt enable |
| CAN_RF1MIEN_INT:  | FIFO1 receive message interrupt enable  |
| CAN_RF1FIEN_INT:  | Receive FIFO1 full interrupt enable     |
| CAN_RF1OIEEN_INT: | Receive FIFO1 overflow interrupt enable |
| CAN_EAIEN_INT:    | Error active interrupt enable           |
| CAN_EPIEN_INT:    | Error passive interrupt enable          |
| CAN_BOIEN_INT:    | Bus-off interrupt enable                |
| CAN_ETRIEN_INT:   | Error type record interrupt enable      |
| CAN_EOIEEN_INT:   | Error occur interrupt enable            |
| CAN_QDZIEN_INT:   | Quit Sleep mode interrupt enable        |
| CAN_EDZIEN_INT:   | Enter Sleep mode interrupt enable       |

#### Example:

```

/* can interruptconfig */
nvc_irq_enable(CAN1_SE_IRQn, 0x00, 0x00);/*CAN1 error/status change interrupt */
nvc_irq_enable(USBFS_L_CAN1_RX0_IRQn, 0x00, 0x00);/*CAN1 FIFO0 receive interrupt*/

/* FIFO 0 receive message interrupt enable */
can_interrupt_enable(CAN1, CAN_RF0MIEN_INT, TRUE);
/* error type record interrupt enable */
can_interrupt_enable(CAN1, CAN_ETRIEN_INT, TRUE);

```

```
/* This parameter is an error interrupt controller and it is enabled before error-related interrupts */
can_interrupt_enable(CAN1, CAN_EOIEINT, TRUE);
```

### 5.3.23 can\_flag\_get function

The table below describes the function can\_flag\_get.

**Table 92. can\_flag\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_flag_get   |
| Function prototype     | flag_status can_flag_get(can_type* can_x, uint32_t can_flag);  |
| Function description   | Get the status of the selected CAN flag  |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2.                                 |
| Input parameter 2      | <i>can_flag</i> : indicates the selected flag<br>Refer to the “can_flag” description below for details . |
| Output parameter       | NA   |
| Return value           | flag_status: the status of the selected flag<br>Return SET or RESET.                                     |
| Required preconditions | NA   |
| Called functions       | NA   |

#### can\_flag

This is used to select a flag and get its status, including

- CAN\_EAF\_FLAG: Error active flag
- CAN\_EPF\_FLAG: Error passive flag
- CAN\_BOF\_FLAG: Bus-off flag
- CAN\_ETR\_FLAG: Error type record (non-zero error type flag)
- CAN\_EOIF\_FLAG: Error occur interrupt flag
- CAN\_TM0TCF\_FLAG: Mailbox 0 transmission complete flag
- CAN\_TM1TCF\_FLAG: Mailbox 1 transmission complete flag
- CAN\_TM2TCF\_FLAG: Mailbox 2 transmission complete flag
- CAN\_RF0MN\_FLAG: Receive FIFO0 non-empty flag
- CAN\_RF0FF\_FLAG: FIFO0 full flag
- CAN\_RF0OF\_FLAG: FIFO0 overflow flag
- CAN\_RF1MN\_FLAG: FIFO1 non-empty flag
- CAN\_RF1FF\_FLAG: FIFO1 full flag
- CAN\_RF1OF\_FLAG: FIFO1 overflow flag
- CAN\_QDZIF\_FLAG: Quit Sleep mode flag
- CAN\_EDZC\_FLAG: Enter Sleep mode flag
- CAN\_TMEF\_FLAG: Transmit mailbox empty flag (any one of three transmit mailboxes is empty)

#### Example:

```
/* get receive fifo 0 message num flag */
flag_status bit_status = RESET;
bit_status = can_flag_get(CAN1, CAN_RF0MN_FLAG);
```

### 5.3.24 can\_flag\_clear function

The table below describes the function can\_flag\_clear.

**Table 93. can\_flag\_clear function**

| Name                   | Description  |
|------------------------|--|
| Function name          | can_flag_clear   |
| Function prototype     | void can_flag_clear(can_type* can_x, uint32_t can_flag);                 |
| Function description   | Clear the selected CAN flag  |
| Input parameter 1      | can_x: indicates the selected CAN<br>This parameter can be CAN1 or CAN2. |
| Input parameter 2      | <i>can_flag</i> : indicates the selected flag<br>Refer to can_flag.      |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### can\_flag

This is used to clear the selected flag, including:

- CAN\_EAF\_FLAG: Error active flag
- CAN\_EPF\_FLAG: Error passive flag
- CAN\_BOF\_FLAG: Bus-off flag
- CAN\_ETR\_FLAG: Error type record (non-zero Error type flag)
- CAN\_EOIF\_FLAG: Error occur interrupt flag
- CAN\_TM0TCF\_FLAG: Mailbox 0 transmission complete flag
- CAN\_TM1TCF\_FLAG: Mailbox 1 transmission complete flag
- CAN\_TM2TCF\_FLAG: Mailbox 2 transmission complete flag
- CAN\_RF0FF\_FLAG: FIFO0 full flag
- CAN\_RF0OF\_FLAG: FIFO0 overflow flag
- CAN\_RF1FF\_FLAG: FIFO1 full flag
- CAN\_RF1OF\_FLAG: FIFO1 overflow flag
- CAN\_QDZIF\_FLAG: Quit Sleep mode flag
- CAN\_EDZC\_FLAG: Enter Sleep mode flag
- CAN\_TMEF\_FLAG: Transmit mailbox empty flag (any one of three transmit mailboxes is empty)

*Note: The CAN\_RF0MN\_FLAG (FIFO0 non-empty flag) and CAN\_RF1MN\_FLAG (FIFO1 non-empty flag) have no clear operations since both are defined by software.*

#### Example:

```
/* clear receive fifo 0 overflow flag */
can_flag_clear (CAN1, CAN_RF1OF_FLAG);
```

## 5.4 CRC calculation unit (CRC)

The CRC register structure `crc_type` is defined in the “at32f435\_437\_crc.h”.

```
/**
 * @brief type define crc register all
 */
typedef struct
{
    ...
} crc_type;
```

The table below gives a list of the CRC registers.

**Table 94. Summary of CRC registers**

| Register | Description                   |
|----------|-------------------------------|
| dt       | Data register                 |
| cdt      | General-purpose data register |
| ctrl     | Control register              |
| idt      | Initialization register       |

The table below gives a list of CRC library functions.

**Table 95. Summary of CRC library functions**

| Function name                            | Description   |
|--|---|
| <code>crc_data_reset</code>              | Data register reset   |
| <code>crc_one_word_calculate</code>      | Calculate the CRC value using combination of a new 32-bit data and the previous CRC value |
| <code>crc_block_calculate</code>         | Write a data block in sequence to go through CRC check and return the calculated result   |
| <code>crc_data_get</code>                | Get the currently calculated CRC result   |
| <code>crc_common_data_set</code>         | Configure common registers  |
| <code>crc_common_data_get</code>         | Get the value of common registers   |
| <code>crc_init_data_set</code>           | Set the CRC initialization register   |
| <code>crc_reverse_input_data_set</code>  | Set CRC input data bit reverse type   |
| <code>crc_reverse_output_data_set</code> | Set CRC output data reverse type  |

### 5.4.1 crc\_data\_reset function

The table below describes the function `crc_data_reset`.

**Table 96. `crc_data_reset` function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crc_data_reset</code>   |
| Function prototype     | <code>void crc_data_reset(void);</code>   |
| Function description   | When the data register is reset, the value of the initialization register is added into the data register as an initial value. The default reset value is 0xFFFFFFFF. |
| Input parameter 1      | NA  |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* reset crc data register */
crc_data_reset();
```

### 5.4.2 crc\_one\_word\_calculate function

The table below describes the function `crc_one_word_calculate`.

**Table 97. `crc_one_word_calculate` function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crc_one_word_calculate</code>  |
| Function prototype     | <code>uint32_t crc_one_word_calculate(uint32_t data);</code>                                 |
| Function description   | Calculate the CRC value using a combination of a new 32-bit data and the previous CRC value. |
| Input parameter 1      | data: input a 32-bit data  |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | uint32_t: return CRC calculation result  |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* calculate and return result */
uint32_t data = 0x12345678, result = 0;
result = crc_one_word_calculate (data);
```

### 5.4.3 crc\_block\_calculate function

The table below describes the function `crc_block_calculate`.

**Table 98. crc\_block\_calculate function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crc_block_calculate</code>  |
| Function prototype     | <code>uint32_t crc_block_calculate(uint32_t *pbuffer, uint32_t length);</code>    |
| Function description   | Input a data block in sequence to go through CRC calculation and return a result  |
| Input parameter 1      | <code>pbuffer</code> : point to the data block pending for CRC check              |
| Input parameter 2      | <code>length</code> : data block length pending for CRC check, in terms of 32-bit |
| Output parameter       | NA  |
| Return value           | <code>uint32_t</code> : return CRC calculation result                             |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* calculate and return result */
uint32_t pbuffer[2] = {0x12345678, 0x87654321};
uint32_t result = 0;
result = crc_block_calculate(pbuffer, 2);
    
```

### 5.4.4 crc\_data\_get function

The table below describes the function `crc_data_get`.

**Table 99. crc\_data\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crc_data_get</code>                             |
| Function prototype     | <code>uint32_t crc_data_get(void);</code>             |
| Function description   | Return the current CRC calculation result             |
| Input parameter 1      | NA  |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | <code>uint32_t</code> : return CRC calculation result |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* get result */
uint32_t result = 0;
result = crc_data_get();
    
```



### 5.4.5 crc\_common\_data\_set function

The table below describes the function `crc_common_data_set`.

**Table 100. crc\_common\_data\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crc_common_data_set</code>  |
| Function prototype     | <code>void crc_common_data_set(uint8_t cdt_value);</code>                             |
| Function description   | Configure common data register  |
| Input parameter 1      | <code>cdt_value</code> : 8-bit common data that can be used as temporary storage data |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* set common data */
crc_common_data_set(0x88);
```

### 5.4.6 crc\_common\_data\_get function

The table below describes the function `crc_common_data_get`.

**Table 101. crc\_common\_data\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crc_common_data_get</code>  |
| Function prototype     | <code>uint8_t crc_common_data_get(void);</code>   |
| Function description   | Return the value of the common data register  |
| Input parameter 1      | NA  |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | <code>uint8_t</code> : return the value of the previously programmed common data register |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* get common data */
uint8_t cdt_value = 0;
cdt_value = crc_common_data_get();
```

### 5.4.7 crc\_init\_data\_set function

The table below describes the function `crc_init_data_set`.

**Table 102. crc\_init\_data\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crc_init_data_set</code>                       |
| Function prototype     | <code>void crc_init_data_set(uint32_t value);</code> |
| Function description   | Set the value of the CRC initialization register     |
| Input parameter 1      | value: the value of the CRC initialization register  |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

After the value of the CRC initialization register is programmed, the CRC data register is updated with this value whenever the `crc_data_reset` function is called.

**Example:**

```
/* set initial data */
uint32_t init_value = 0x11223344;
crc_init_data_set(init_value);
```

### 5.4.8 crc\_reverse\_input\_data\_set function

The table below describes the function `crc_reverse_input_data_set`.

**Table 103. crc\_reverse\_input\_data\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crc_reverse_input_data_set</code>                                     |
| Function prototype     | <code>void crc_reverse_input_data_set(crc_reverse_input_type value);</code> |
| Function description   | Define the CRC input data bit reverse type                                  |
| Input parameter 1      | value: input data bit reverse type  |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**value**

Define the reverse type of input data bit.

- CRC\_REVERSE\_INPUT\_NO\_AFFECTE: No effect
- CRC\_REVERSE\_INPUT\_BY\_BYTE: Byte reverse
- CRC\_REVERSE\_INPUT\_BY\_HALFWORD: Half-word reverse
- CRC\_REVERSE\_INPUT\_BY\_WORD: Word reverse

**Example:**

```
/* set input data reversing type */
crc_reverse_input_data_set(CRC_REVERSE_INPUT_BY_WORD);
```

### 5.4.9 crc\_reverse\_output\_data\_set function

The table below describes the function `crc_reverse_output_data_set`.

**Table 104. `crc_reverse_output_data_set` function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crc_reverse_output_data_set</code>                                      |
| Function prototype     | <code>void crc_reverse_output_data_set(crc_reverse_output_type value);</code> |
| Function description   | Define the CRC output data reverse type                                       |
| Input parameter 1      | value: output data bit reverse type   |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**value**

Define the reverse type of output data bit.

CRC\_REVERSE\_OUTPUT\_NO\_AFFECTE: No effect

CRC\_REVERSE\_OUTPUT\_DATA: Word reverse

**Example:**

```

/* set output data reversing type */
crc_reverse_output_data_set(CRC_REVERSE_OUTPUT_DATA);

```

## 5.5 Clock and reset management (CRM)

The CRM register structure `crm_type` is defined in the “`at32f435_437_crm.h`”.

```
/**
 * @brief type define crm register all
 */
typedef struct
{
    ...
} crm_type;
```

The table below gives a list of the CRM registers.

**Table 105. Summary of CRM registers**

| Register              | Description  |
|-----------------------|--|
| <code>ctrl</code>     | Clock control register                                   |
| <code>pllcfg</code>   | PLL clock configuration register                         |
| <code>cfg</code>      | Clock configuration register                             |
| <code>clkint</code>   | Clock interrupt register                                 |
| <code>ahbrst1</code>  | AHB peripheral reset register 1                          |
| <code>ahbrst2</code>  | AHB peripheral reset register 2                          |
| <code>ahbrst3</code>  | AHB peripheral reset register 3                          |
| <code>apb1rst</code>  | APB1 peripheral reset register                           |
| <code>apb2rst</code>  | APB2 peripheral reset register                           |
| <code>ahben1</code>   | AHB peripheral clock enable register 1                   |
| <code>ahben2</code>   | AHB peripheral clock enable register 2                   |
| <code>ahben3</code>   | AHB peripheral clock enable register 3                   |
| <code>apb1en</code>   | APB1 peripheral clock enable register                    |
| <code>apb2en</code>   | APB2 peripheral clock enable register                    |
| <code>ahblpen1</code> | AHB peripheral clock enable in low power mode register 1 |
| <code>ahblpen2</code> | AHB peripheral clock enable in low power mode register 2 |
| <code>ahblpen3</code> | AHB peripheral clock enable in low power mode register 3 |
| <code>apb1lpen</code> | APB1 peripheral clock enable in low power mode register  |
| <code>apb2lpen</code> | APB2 peripheral clock enable in low power mode register  |
| <code>bpdcc</code>    | Battery powered domain control register                  |
| <code>ctrlsts</code>  | Control/status register                                  |
| <code>misc1</code>    | Extra register 1   |
| <code>misc2</code>    | Extra register 2   |

The table below gives a list of CRM library functions.

**Table 106. Summary of CRM library functions**

| Function name                      | Description   |
|------------------------------------|---|
| crm_reset                          | Reset clock reset management register and control status                  |
| crm_lxt_bypass                     | Configure low-speed external clock bypass                                 |
| crm_hext_bypass                    | Configure high-speed external clock bypass                                |
| crm_flag_get                       | Check if the selected flag is set or not                                  |
| crm_hext_stable_wait               | Wait HEXT to get stable   |
| crm_hick_clock_trimming_set        | High speed internal clock trimming  |
| crm_hick_clock_calibration_set     | High speed internal clock calibration                                     |
| crm_periph_clock_enable            | Peripheral clock enable   |
| crm_periph_reset                   | Peripheral reset  |
| crm_periph_lowpower_mode_enable    | Enable peripheral clock in low-power mode                                 |
| crm_clock_source_enable            | Clock source enable   |
| crm_flag_clear                     | Clear flag  |
| crm_ertc_clock_select              | ERTC clock source selection   |
| crm_ertc_clock_enable              | ERTC clock enable   |
| crm_ahb_div_set                    | AHB clock division  |
| crm_apb1_div_set                   | APB1 clock division   |
| crm_apb2_div_set                   | APB2 clock division   |
| crm_usb_clock_div_set              | USB clock division  |
| crm_clock_failure_detection_enable | Clock failure detection enable  |
| crm_battery_powered_domain_reset   | Battery powered domain reset  |
| crm_pll_config                     | PLL clock source and frequency multiplication factor                      |
| crm_sysclk_switch                  | System clock source switch  |
| crm_sysclk_switch_status_get       | Get the status of system clock source                                     |
| crm_clocks_freq_get                | Get clock frequency   |
| crm_clock_out1_set                 | Select clock source output on clkout1 pin                                 |
| crm_clock_out2_set                 | Select clock source output on clkout2 pin                                 |
| crm_clkout_div_set                 | Clock frequency division on clock out pins                                |
| crm_interrupt_enable               | Interrupt enable  |
| crm_auto_step_mode_enable          | Auto step-by-step mode enable   |
| crm_hick_sclk_frequency_select     | Set system clock frequency as 8M or 48M when HICK is used as system clock |
| crm_usb_clock_source_select        | Select PLL or internal high-speed clock (48M) as USB clock source         |
| crm_clkout_to_tmr10_enable         | clkout to tmr10 channel 1 enable  |
| crm_emac_output_pulse_set          | EMAC output pulse width   |
| crm_pll_parameter_calculate        | Calculate PLL parameters automatically                                    |

### 5.5.1 crm\_reset function

The table below describes the function crm\_reset.

**Table 107. crm\_reset function**

| Name                   | Description  |
|------------------------|--|
| Function name          | crm_reset  |
| Function prototype     | void crm_reset(void);  |
| Function description   | Reset the clock reset management register and control status |
| Input parameter 1      | NA   |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

1. This function does not change the HICKTRIM[5:0] in the CRM\_CTRL register.
2. Modifying the function does not reset the CRM\_BPDC and CRM\_CTRLSTS registers.

**Example:**

```
/* resetcrm */
crm_reset();
```

### 5.5.2 crm\_lext\_bypass function

The table below describes the function crm\_lext\_bypass.

**Table 108. crm\_lext\_bypass function**

| Name                   | Description   |
|------------------------|---|
| Function name          | crm_lext_bypass   |
| Function prototype     | void crm_lext_bypass(confirm_state new_state);            |
| Function description   | Configure low-speed external clock bypass                 |
| Input parameter 1      | new_state: Enable bypass (TRUE), disable bypass (FALSE)   |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | The LEXT configuration must be done before being enabled. |
| Called functions       | NA  |

**Example:**

```
/* enable lext bypass mode */
crm_lext_bypass(TRUE);
```

### 5.5.3 crm\_hext\_bypass function

The table below describes the function `crm_hext_bypass`.

**Table 109. crm\_hext\_bypass function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crm_hext_bypass</code>  |
| Function prototype     | <code>void crm_hext_bypass(confirm_state new_state);</code>           |
| Function description   | Configure high-speed external clock bypass                            |
| Input parameter 1      | <code>new_state</code> : Enable bypass (TRUE), disable bypass (FALSE) |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | The HEXT configuration must be done before being enabled.             |
| Called functions       | NA  |

**Example:**

```
/* enable hext bypass mode */
crm_hext_bypass(TRUE);
```

### 5.5.4 crm\_flag\_get function

The table below describes the function `crm_flag_get`.

**Table 110. crm\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crm_flag_get</code>   |
| Function prototype     | <code>flag_status crm_flag_get(uint32_t flag);</code>                               |
| Function description   | Check if the selected flag has been set.  |
| Input parameter 1      | <code>flag</code> : flag selection  |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | <code>flag_status</code> : indicates the status of the selected flag (SET or RESET) |
| Required preconditions | NA  |
| Called functions       | NA  |

**flag**

Select a flag to read, including:

- CRM\_HICK\_STABLE\_FLAG: HICK clock stable flag
- CRM\_HEXT\_STABLE\_FLAG: HEXT clock stable flag
- CRM\_PLL\_STABLE\_FLAG: PLL clock stable flag
- CRM\_LEXT\_STABLE\_FLAG: LEXT clock stable flag
- CRM\_LICK\_STABLE\_FLAG: LICK clock stable flag
- CRM\_NRST\_RESET\_FLAG: NRST pin reset flag
- CRM\_POR\_RESET\_FLAG: Power-on/low voltage reset flag
- CRM\_SW\_RESET\_FLAG: Software reset flag
- CRM\_WDT\_RESET\_FLAG: Watchdog reset flag
- CRM\_WWDT\_RESET\_FLAG: Window watchdog reset flag
- CRM\_LOWPOWER\_RESET\_FLAG: Low-power consumption reset flag

CRM\_LICK\_READY\_INT\_FLAG: LICK clock ready interrupt flag  
 CRM\_LEXT\_READY\_INT\_FLAG: LEXT clock ready interrupt flag  
 CRM\_HICK\_READY\_INT\_FLAG: HICK clock ready interrupt flag  
 CRM\_HEXT\_READY\_INT\_FLAG: HEXT clock ready interrupt flag  
 CRM\_PLL\_READY\_INT\_FLAG: PLL clock ready interrupt flag  
 CRM\_CLOCK\_FAILURE\_INT\_FLAG: Clock failure interrupt flag

**Example:**

```

/* wait till pll is ready */
while(crm_flag_get(CRM_PLL_STABLE_FLAG) != SET)
{
}
  
```

### 5.5.5 crm\_hext\_stable\_wait function

The table below describes the function `crm_hext_stable_wait`.

**Table 111. crm\_hext\_stable\_wait function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crm_hext_stable_wait</code>   |
| Function prototype     | <code>error_status crm_hext_stable_wait(void);</code>                     |
| Function description   | Wait for HEXT to activate and become stable                               |
| Input parameter 1      | NA  |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | <code>error_status</code> : Return the status of HEXT (SUCCESS or ERROR). |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* wait till hext is ready */
while(crm_hext_stable_wait() == ERROR)
{
}
  
```

### 5.5.6 crm\_hick\_clock\_trimming\_set function

The table below describes the function `crm_hick_clock_trimming_set`.

**Table 112. crm\_hick\_clock\_trimming\_set function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>crm_hick_clock_trimming_set</code>   |
| Function prototype   | <code>void crm_hick_clock_trimming_set(uint8_t trim_value);</code>   |
| Function description | Trim HICK clock  |
| Input parameter 1    | <code>trim_value</code> : trimming value. Default value is 0x20, and configurable range is from 0 to 0x3F. |
| Input parameter 2    | NA   |
| Output parameter     | NA   |



| Name                   | Description |
|------------------------|-------------|
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

```
/* set trimming value */
crm_hick_clock_trimming_set(0x1F);
```

## 5.5.7 crm\_hick\_clock\_calibration\_set function

The table below describes the function `crm_hick_clock_calibration_set`.

**Table 113. crm\_hick\_clock\_calibration\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_hick_clock_calibration_set</code>  |
| Function prototype     | <code>void crm_hick_clock_calibration_set(uint8_t cali_value);</code>  |
| Function description   | Set HICK clock calibration value   |
| Input parameter 1      | <code>cali_value</code> : calibration compensation value. The factory gate value is the default value, and its configurable range is from 0 to 0xFF. |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* set trimming value */
crm_hick_clock_trimming_set(0x80);
```

## 5.5.8 crm\_periph\_clock\_enable function

The table below describes the function `crm_periph_clock_enable`.

**Table 114. crm\_periph\_clock\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_periph_clock_enable</code>   |
| Function prototype     | <code>void crm_periph_clock_enable(crm_periph_clock_type value, confirm_state new_state);</code> |
| Function description   | Enable peripheral clock  |
| Input parameter 1      | <code>value</code> : defines peripheral clock type   |
| Input parameter 2      | <code>new_state</code> : TRUE or FALSE   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**value**

The `crm_periph_clock_type` is defined in the `at32f435_437_crm.h`.

The naming rule of this parameter is: `CRM_peripheral_PERIPH_CLOCK`.

CRM\_DMA1\_PERIPH\_CLOCK: DMA1 peripheral clock  
 CRM\_DMA2\_PERIPH\_CLOCK: DMA2 peripheral clock  
 ...  
 CRM\_PWC\_PERIPH\_CLOCK: PWC peripheral clock  
 CRM\_DAC\_PERIPH\_CLOCK: DAC peripheral clock

**Example:**

```
/* enable gpioa periph clock */
crm_periph_clock_enable(CRM_GPIOA_PERIPH_CLOCK, TRUE);
```

## 5.5.9 crm\_periph\_reset function

The table below describes the function crm\_periph\_reset.

**Table 115. crm\_periph\_reset function**

| Name                   | Description  |
|------------------------|--|
| Function name          | crm_periph_reset   |
| Function prototype     | void crm_periph_reset(crm_periph_reset_type value, confirm_state new_state); |
| Function description   | Reset peripherals  |
| Input parameter 1      | value: Peripheral reset type   |
| Input parameter 2      | new_state: TRUE or FALSE   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**value**

This indicates the selected peripheral.

The crm\_periph\_reset\_type is defined in the at32f435\_437\_crm.h.

The naming rule of this parameter is: CRM\_peripheral\_PERIPH\_RESET.

CRM\_DMA1\_PERIPH\_RESET: DMA1 peripheral reset  
 CRM\_DMA2\_PERIPH\_RESET: DMA 2 peripheral reset  
 ...  
 CRM\_PWC\_PERIPH\_RESET: PWC peripheral reset  
 CRM\_DAC\_PERIPH\_RESET: DAC peripheral reset

**Example:**

```
/* reset gpioa periph */
crm_periph_reset(CRM_GPIOA_PERIPH_RESET, TRUE);
```

### 5.5.10 crm\_periph\_lowpower\_mode\_enable function

The table below describes the function `crm_periph_lowpower_mode_enable`.

**Table 116. crm\_periph\_lowpower\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crm_periph_lowpower_mode_enable</code>  |
| Function prototype     | <code>void crm_periph_lowpower_mode_enable(crm_periph_clock_lowpower_type value, confirm_state new_state);</code> |
| Function description   | Enable peripheral clock in low-power mode   |
| Input parameter 1      | value: indicates peripheral clock type in low-power mode  |
| Input parameter 2      | new_state: TRUE or FALSE  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**value**

It indicates the selected peripheral.

The `crm_periph_lowpower_type` is defined in the `at32f435_437_crm.h`.

The naming rule of this parameter is: `CRM_peripheral_PERIPH_LOWPOWER`.

`CRM_DMA1_PERIPH_LOWPOWER`: DMA1 peripheral low-power clock definition

`CRM_DMA2_PERIPH_LOWPOWER`: DMA2 peripheral low-power clock definition

...

`CRM_PWC_PERIPH_LOWPOWER`: PWC peripheral low-power clock definition

`CRM_DAC_PERIPH_LOWPOWER`: DAC peripheral low-power clock definition

**Example:**

```
/* disable gpioa periph clock at sleep mode */
crm_periph_reset(CRM_GPIOA_PERIPH_LOWPOWER, FALSE);
```

### 5.5.11 crm\_clock\_source\_enable function

The table below describes the function `crm_clock_source_enable`.

**Table 117. crm\_clock\_source\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crm_clock_source_enable</code>  |
| Function prototype     | <code>void crm_clock_source_enable(crm_clock_source_type source, confirm_state new_state);</code> |
| Function description   | Enable clock source   |
| Input parameter 1      | source: Clock source type   |
| Input parameter 2      | new_state: TRUE or FALSE  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**source**

Clock source selection

```
CRM_CLOCK_SOURCE_HICK:    HICK
CRM_CLOCK_SOURCE_HEXT:    HEXT
CRM_CLOCK_SOURCE_PLL:     PLL
CRM_CLOCK_SOURCE_LEXT:    LEXT
CRM_CLOCK_SOURCE_LICK:    LICK
```

**Example:**

```
/* enable hext */
crm_clock_source_enable(CRM_CLOCK_SOURCE_HEXT, FALSE);
```

## 5.5.12 crm\_flag\_clear function

The table below describes the function `crm_flag_clear`.

**Table 118. crm\_flag\_clear function**

| Name                   | Description                                      |
|------------------------|--|
| Function name          | <code>crm_flag_clear</code>                      |
| Function prototype     | <code>void crm_flag_clear(uint32_t flag);</code> |
| Function description   | Clear the selected flags                         |
| Input parameter 1      | flag: indicates the flag to clear                |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**flag**

Select a flag to clear

```
CRM_NRST_RESET_FLAG:      NRST pin reset flag
CRM_POR_RESET_FLAG:       Power-on/low-voltage reset flag
CRM_SW_RESET_FLAG:        Software reset flag
CRM_WDT_RESET_FLAG:       Watchdog reset flag
CRM_WWDT_RESET_FLAG:      Window watchdog reset flag
CRM_LOWPOWER_RESET_FLAG:  Low-power reset flag
CRM_ALL_RESET_FLAG:       All reset flags
CRM_LICK_READY_INT_FLAG:  LICK clock ready interrupt flag
CRM_LEXT_READY_INT_FLAG:  LEXT clock ready interrupt flag
CRM_HICK_READY_INT_FLAG:  HICK clock ready interrupt flag
CRM_HEXT_READY_INT_FLAG:  HEXT clock ready interrupt flag
CRM_PLL_READY_INT_FLAG:   PLL clock ready interrupt flag
CRM_CLOCK_FAILURE_INT_FLAG: Clock failure interrupt flag
```

**Example:**

```
/* clear clock failure detection flag */
crm_flag_clear(CRM_CLOCK_FAILURE_INT_FLAG);
```

### 5.5.13 crm\_ertc\_clock\_select function

The table below describes the function crm\_ertc\_clock\_select.

**Table 119. crm\_ertc\_clock\_select function**

| Name                   | Description  |
|------------------------|--|
| Function name          | crm_ertc_clock_select                                  |
| Function prototype     | void crm_ertc_clock_select(crm_ertc_clock_type value); |
| Function description   | Select ERTC clock source                               |
| Input parameter 1      | value: indicates ertc clock source type                |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**value**

ERTC clock source selection

- CRM\_ERTC\_CLOCK\_NOCLK: No clock source for ERTC
- CRM\_ERTC\_CLOCK\_LEXT: LEXT selected as ERTC clock
- CRM\_ERTC\_CLOCK\_LICK: LICK selected as ERTC clock
- CRM\_ERTC\_CLOCK\_HEXT\_DIV2: HEXT/2 selected as ERTC clock
- ...
- CRM\_ERTC\_CLOCK\_HEXT\_DIV31: HEXT/31 selected as ERTC clock

**Example:**

```
/* config lext as ertc clock */
crm_ertc_clock_select(CRM_ERTC_CLOCK_LEXT);
```

### 5.5.14 crm\_ertc\_clock\_enable function

The table below describes the function crm\_ertc\_clock\_enable.

**Table 120. crm\_ertc\_clock\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | crm_ertc_clock_enable                                |
| Function prototype     | void crm_ertc_clock_enable(confirm_state new_state); |
| Function description   | Enable ERTC clock                                    |
| Input parameter 1      | new_state: TRUE or FALSE                             |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable ertc clock */
crm_ertc_clock_enable(TRUE);
```

### 5.5.15 crm\_ahb\_div\_set function

The table below describes the function `crm_ahb_div_set`.

**Table 121. crm\_ahb\_div\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_ahb_div_set</code>                               |
| Function prototype     | <code>void crm_ahb_div_set(crm_ahb_div_type value);</code> |
| Function description   | Configure AHB clock division                               |
| Input parameter 1      | value: indicates the division factor                       |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**value**

- CRM\_AHB\_DIV\_1: SCLK/1 used as AHB clock
- CRM\_AHB\_DIV\_2: SCLK/2 used as AHB clock
- CRM\_AHB\_DIV\_4: SCLK/4 used as AHB clock
- CRM\_AHB\_DIV\_8: SCLK/8 used as AHB clock
- CRM\_AHB\_DIV\_16: SCLK/16 used as AHB clock
- CRM\_AHB\_DIV\_64: SCLK/64 used as AHB clock
- CRM\_AHB\_DIV\_128: SCLK/128 used as AHB clock
- CRM\_AHB\_DIV\_256: SCLK/256 used as AHB clock
- CRM\_AHB\_DIV\_512: SCLK/512 used as AHB clock

**Example:**

```
/* config ahbclk */
crm_ahb_div_set(CRM_AHB_DIV_1);
```

### 5.5.16 crm\_apb1\_div\_set function

The table below describes the function `crm_apb1_div_set`.

**Table 122. crm\_apb1\_div\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_apb1_div_set</code>                                |
| Function prototype     | <code>void crm_apb1_div_set(crm_apb1_div_type value);</code> |
| Function description   | Configure APB1 clock division                                |
| Input parameter 1      | value: indicates the division factor                         |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**value**

- CRM\_APB1\_DIV\_1: AHB/1 used as APB1 clock
- CRM\_APB1\_DIV\_2: AHB/2 used as APB1 clock

CRM\_APB1\_DIV\_4: AHB/4 used as APB1 clock  
 CRM\_APB1\_DIV\_8: AHB/8 used as APB1 clock  
 CRM\_APB1\_DIV\_16: AHB/16 used as APB1 clock

**Example:**

```
/* config apb1clk */
crm_apb1_div_set(CRM_APB1_DIV_2);
```

### 5.5.17 crm\_apb2\_div\_set function

The table below describes the function crm\_apb2\_div\_set.

**Table 123. crm\_apb2\_div\_set function**

| Name                   | Description                                     |
|------------------------|---|
| Function name          | crm_apb2_div_set                                |
| Function prototype     | void crm_apb2_div_set(crm_apb2_div_type value); |
| Function description   | Configure APB2 clock division                   |
| Input parameter 1      | value: indicates the division factor            |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**value**

CRM\_APB2\_DIV\_1: AHB/1 used as APB2 clock  
 CRM\_APB2\_DIV\_2: AHB/2 used as APB2 clock  
 CRM\_APB2\_DIV\_4: AHB/4 used as APB2 clock  
 CRM\_APB2\_DIV\_8: AHB/8 used as APB2 clock  
 CRM\_APB2\_DIV\_16: AHB/16 used as APB2 clock

**Example:**

```
/* config apb2clk */
crm_apb2_div_set(CRM_APB2_DIV_2);
```

### 5.5.18 crm\_usb\_clock\_div\_set function

The table below describes the function crm\_usb\_clock\_div\_set.

**Table 124. crm\_usb\_clock\_div\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | crm_usb_clock_div_set                                   |
| Function prototype     | void crm_usb_clock_div_set(crm_usb_div_type div_value); |
| Function description   | Configure PLL clock division                            |
| Input parameter 1      | div_value: indicates the division factor                |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**div\_value**

|                  |                           |
|------------------|---------------------------|
| CRM_USB_DIV_1_5: | PLL/1.5 used as USB clock |
| CRM_USB_DIV_1:   | PLL/1 used as USB clock   |
| CRM_USB_DIV_2_5: | PLL/2.5 used as USB clock |
| CRM_USB_DIV_2:   | PLL/2 used as USB clock   |
| CRM_USB_DIV_3_5: | PLL/3.5 used as USB clock |
| CRM_USB_DIV_3:   | PLL/3 used as USB clock   |
| CRM_USB_DIV_4_5: | PLL/4.5 used as USB clock |
| CRM_USB_DIV_4:   | PLL/4 used as USB clock   |
| CRM_USB_DIV_5_5: | PLL/5.5 used as USB clock |
| CRM_USB_DIV_5:   | PLL/5 used as USB clock   |
| CRM_USB_DIV_6_5: | PLL/6.5 used as USB clock |
| CRM_USB_DIV_6:   | PLL/6 used as USB clock   |
| CRM_USB_DIV_7:   | PLL/7 used as USB clock   |

**Example:**

```
/* config usb div 2 */
crm_usb_clock_div_set(CRM_USB_DIV_2);
```

### 5.5.19 crm\_clock\_failure\_detection\_enable function

The table below describes the function `crm_clock_failure_detection_enable`

**Table 125. crm\_clock\_failure\_detection\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_clock_failure_detection_enable</code>                                |
| Function prototype     | <code>void crm_clock_failure_detection_enable(confirm_state new_state);</code> |
| Function description   | Enable clock failure detection   |
| Input parameter 1      | <code>new_state</code> : TRUE or FALSE   |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable clock failure detection */
crm_clock_failure_detection_enable(TRUE);
```

### 5.5.20 crm\_battery\_powered\_domain\_reset function

The table below describes the function `crm_battery_powered_domain_reset`.

**Table 126. crm\_battery\_powered\_domain\_reset function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>crm_battery_powered_domain_reset</code>                                |
| Function prototype   | <code>void crm_battery_powered_domain_reset(confirm_state new_state);</code> |
| Function description | Reset battery powered domain   |
| Input parameter 1    | <code>new_state</code> : Reset (TRUE) or not reset (FALSE)                   |



| Name                   | Description |
|------------------------|-------------|
| Input parameter 2      | NA          |
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

When it comes to resetting battery powered domain, it is usually necessary to reset battery powered domain through TRUE operation and then disable battery powered domain reset through FALSE operation after the completion of reset.

**Example:**

```
/* reset battery powered domain */
crm_battery_powered_domain_reset(TRUE);
```

### 5.5.21 crm\_pll\_config function

The table below describes the function crm\_pll\_config.

**Table 127. crm\_pll\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | crm_pll_config   |
| Function prototype     | void crm_pll_config(crm_pll_clock_source_type clock_source, uint16_t pll_ns, uint16_t pll_ms, crm_pll_fr_type pll_fr); |
| Function description   | Configure PLL clock source and frequency multiplication and division factors   |
| Input parameter 1      | clock_source: clock source for PLL frequency multiplication  |
| Input parameter 2      | pll_ns: frequency multiplication factor from 31 to 500   |
| Input parameter 3      | pll_ms: pre-division frequency factor from 1 to 15   |
| Input parameter 4      | pll_fr: post-division frequency factor   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | PLL clock source must be enabled and stable before configuring and enabling PLL.                                       |
| Called functions       | NA   |

Frequency multiplication formula:  $PLLCLK = PLL \text{ input clock} / PLL\_MS * PLL\_NS / PLL\_FR$

Requirements:

$2MHz \leq PLL \text{ input clock} / PLL\_MS \leq 16MHz$

$500MHz \leq PLL \text{ input clock} / PLL\_MS * PLL\_NS \leq 1000MHz$

**clock\_source**

CRM\_PLL\_SOURCE\_HICK: HICK is selected as PLL clock source

CRM\_PLL\_SOURCE\_HEX: HEX is selected as PLL clock source

**pll\_fr**

CRM\_PLL\_FR\_1: PLL/1

CRM\_PLL\_FR\_2: PLL/2

CRM\_PLL\_FR\_4: PLL/4

CRM\_PLL\_FR\_8: PLL/8

CRM\_PLL\_FR\_16: PLL/16

CRM\_PLL\_FR\_32: PLL/32

**Example:**

```
/* config pll clock resource */
crm_pll_config(CRM_PLL_SOURCE_HEXT,96, 1, CRM_PLL_FR_8);
```

### 5.5.22 crm\_sysclk\_switch function

The table below describes the function crm\_sysclk\_switch.

**Table 128. crm\_sysclk\_switch function**

| Name                   | Description  |
|------------------------|--|
| Function name          | crm_sysclk_switch                                  |
| Function prototype     | void crm_sysclk_switch(crm_sclk_type value);       |
| Function description   | Switch system clock source                         |
| Input parameter 1      | value: indicates the clock source for system clock |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**value**

CRM\_SCLK\_HICK: HICK is used as system clock

CRM\_SCLK\_HEXT: HECT is used as system clock

CRM\_SCLK\_PLL: PLL is used as system clock

**Example:**

```
/* select pll as system clock source */
crm_sysclk_switch(CRM_SCLK_PLL);
```

### 5.5.23 crm\_sysclk\_switch\_status\_get function

The table below describes the function crm\_sysclk\_switch\_status\_get.

**Table 129. crm\_sysclk\_switch\_status\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | crm_sysclk_switch_status_get                           |
| Function prototype     | crm_sclk_type crm_sysclk_switch_status_get(void);      |
| Function description   | Get the clock source of system clock                   |
| Input parameter 1      | NA   |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | crm_sclk_type: return the clock source of system clock |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* wait till pll is used as system clock source */
while(crm_sysclk_switch_status_get() != CRM_SCLK_PLL)
{
}
```

### 5.5.24 crm\_clocks\_freq\_get function

The table below describes the function `crm_clocks_freq_get`.

**Table 130. crm\_clocks\_freq\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crm_clocks_freq_get</code>  |
| Function prototype     | <code>void crm_clocks_freq_get(crm_clocks_freq_type *clocks_struct);</code>                       |
| Function description   | Get clock frequency   |
| Input parameter 1      | <code>clocks_struct</code> : <code>crm_clocks_freq_type</code> pointer, including clock frequency |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | <code>crm_sclk_type</code> : return the clock source for system clock                             |
| Required preconditions | NA  |
| Called functions       | NA  |

#### **crm\_clocks\_freq\_type**

The `crm_clocks_freq_type` is defined in the `at32f435_437_crm.h`.

typedef struct

```
{
    uint32_t    sclk_freq;
    uint32_t    ahb_freq;
    uint32_t    apb2_freq;
    uint32_t    apb1_freq;
} crm_clocks_freq_type;
```

#### **sclk\_freq**

Get the system clock frequency, in Hz

#### **ahb\_freq**

Get the clock frequency of AHB, in Hz

#### **apb2\_freq**

Get the clock frequency of APB2, in Hz

#### **apb1\_freq**

Get the clock frequency of APB1, in Hz

#### **Example:**

```
/* get frequency */
crm_clocks_freq_type clocks_struct;
crm_clocks_freq_get(&clocks_struct);
```

### 5.5.25 crm\_clock\_out1\_set function

The table below describes the function `crm_clock_out1_set`.

**Table 131. crm\_clock\_out1\_set function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>crm_clock_out1_set</code>                                       |
| Function prototype   | <code>void crm_clock_out1_set(crm_clkout1_select_type clkout);</code> |
| Function description | Select clock source output on <code>clkout1</code> pin                |
| Input parameter 1    | <code>clkout</code> : clock source output on <code>clkout1</code> pin |

| Name                   | Description |
|------------------------|-------------|
| Input parameter 2      | NA          |
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**clkout**

Select clock source output on the clkout1 pin.

CRM\_CLKOUT1\_HICK: HICK output on clkout1 pin  
 CRM\_CLKOUT1\_HEXT: HEXT output on clkout1 pin  
 CRM\_CLKOUT1\_PLL: PLL output on clkout1 pin  
 CRM\_CLKOUT1\_LEXT: LEXT output on clkout1 pin

**Example:**

```
/* config clkout1 output hick */
crm_clock_out1_set(CRM_CLKOUT1_HICK);
```

### 5.5.26 crm\_clock\_out2\_set function

The table below describes the function crm\_clock\_out2\_set.

**Table 132. crm\_clock\_out2\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | crm_clock_out2_set                                       |
| Function prototype     | void crm_clock_out2_set(crm_clkout2_select_type clkout); |
| Function description   | Select clock source output on clkout2 pin                |
| Input parameter 1      | clkout: clock source output on clkout2 pin               |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**clkout**

Select clock source output on the clkout2 pin.

CRM\_CLKOUT2\_SCLK: SCLK output on clkout2 pin  
 CRM\_CLKOUT2\_HEXT: HEXT output on clkout2 pin  
 CRM\_CLKOUT2\_PLL: PLL output on clkout2 pin  
 CRM\_CLKOUT2\_USB: USB output on clkout2 pin  
 CRM\_CLKOUT2\_ADC: ADC output on clkout2 pin  
 CRM\_CLKOUT2\_HICK: HICK output on clkout2 pin  
 CRM\_CLKOUT2\_LICK: LICK output on clkout2 pin  
 CRM\_CLKOUT2\_LEXT: LEXT output on clkout2 pin

**Example:**

```
/* config clkout2 output hick */
crm_clock_out2_set(CRM_CLKOUT2_SCLK);
```

## 5.5.27 crm\_clkout\_div\_set function

The table below describes the function `crm_clkout_div_set`.

**Table 133. crm\_clkout\_div\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_clkout_div_set</code>  |
| Function prototype     | <code>void crm_clkout_div_set(crm_clkout_index_type index, crm_clkout_div1_type div1, crm_clkout_div2_type div2);</code> |
| Function description   | Clock frequency division on clockout pin   |
| Input parameter 1      | index: clkout pin selection  |
| Input parameter 2      | div1: divider 1 clock frequency division   |
| Input parameter 3      | div2: divider 2 clock frequency division   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### index

clkout pin selection

CRM\_CLKOUT\_INDEX\_1: clkout1

CRM\_CLKOUT\_INDEX\_2: clkout2

### div1

Divider 1 clock frequency division

CRM\_CLKOUT\_DIV1\_1: divided by 1

CRM\_CLKOUT\_DIV1\_2: divided by 2

CRM\_CLKOUT\_DIV1\_3: divided by 3

CRM\_CLKOUT\_DIV1\_4: divided by 4

CRM\_CLKOUT\_DIV1\_5: divided by 5

### div2

Divider 2 clock frequency division

CRM\_CLKOUT\_DIV2\_1: divided by 1

CRM\_CLKOUT\_DIV2\_2: divided by 2

CRM\_CLKOUT\_DIV2\_4: divided by 4

CRM\_CLKOUT\_DIV2\_8: divided by 8

CRM\_CLKOUT\_DIV2\_16: divided by 16

CRM\_CLKOUT\_DIV2\_64: divided by 64

CRM\_CLKOUT\_DIV2\_128: divided by 128

CRM\_CLKOUT\_DIV2\_256: divided by 256

CRM\_CLKOUT\_DIV2\_512: divided by 512

### Example:

```
/* config clkout1 div */
crm_clkout_div_set(CRM_CLKOUT_INDEX_1, CRM_CLKOUT_DIV1_1, CRM_CLKOUT_DIV2_8);
```

## 5.5.28 crm\_interrupt\_enable function

The table below describes the function `crm_interrupt_enable`.

**Table 134. crm\_interrupt\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_interrupt_enable</code>  |
| Function prototype     | <code>void crm_interrupt_enable(uint32_t crm_int, confirm_state new_state);</code> |
| Function description   | Enable interrupts  |
| Input parameter 1      | <code>crm_int</code> : indicates the selected crm interrupt                        |
| Input parameter 2      | <code>new_state</code> : Enable (TRUE) or disable (FALSE)                          |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### crm\_int

|                                      |                         |
|--------------------------------------|-------------------------|
| <code>CRM_LICK_STABLE_INT</code> :   | LICK stable interrupt   |
| <code>CRM_LEXT_STABLE_INT</code> :   | LEXT stable interrupt   |
| <code>CRM_HICK_STABLE_INT</code> :   | HICK stable interrupt   |
| <code>CRM_HEXT_STABLE_INT</code> :   | HEXT stable interrupt   |
| <code>CRM_PLL_STABLE_INT</code> :    | PLL stable interrupt    |
| <code>CRM_CLOCK_FAILURE_INT</code> : | Clock failure interrupt |

### Example:

```
/* enable pll stable interrupt */
crm_interrupt_enable(CRM_PLL_STABLE_INT);
```

## 5.5.29 crm\_auto\_step\_mode\_enable function

The table below describes the function `crm_auto_step_mode_enable`.

**Table 135. crm\_auto\_step\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crm_auto_step_mode_enable</code>                                |
| Function prototype     | <code>void crm_auto_step_mode_enable(confirm_state new_state);</code> |
| Function description   | Enable auto step-by-step mode   |
| Input parameter 1      | <code>new_state</code> : Enable (TRUE) or disable (FALSE)             |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### Example:

```
/* enable auto step mode */
crm_auto_step_mode_enable(TRUE);
```

### 5.5.30 crm\_hick\_sclk\_frequency\_select function

The table below describes the function `crm_hick_sclk_frequency_select`.

**Table 136. crm\_hick\_sclk\_frequency\_select function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crm_hick_sclk_frequency_select</code>   |
| Function prototype     | <code>void crm_hick_sclk_frequency_select(crm_hick_sclk_frequency_type value);</code> |
| Function description   | Select 8M or 48M system clock frequency when HICK is used as system clock             |
| Input parameter 1      | value: 8M or 48M HICK   |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**value**

CRM\_HICK\_SCLK\_8MHZ: 8 MHz HICK used as system clock

CRM\_HICK\_SCLK\_48MHZ: 48 MHz HICK used as system clock

**Example:**

```
/* config sysclk with hick 48mhz*/
crm_hick_sclk_frequency_select(CRM_HICK_SCLK_48MHZ);
```

### 5.5.31 crm\_usb\_clock\_source\_select function

The table below describes the function `crm_usb_clock_source_select`.

**Table 137. crm\_usb\_clock\_source\_select function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>crm_usb_clock_source_select</code>  |
| Function prototype     | <code>void crm_usb_clock_source_select(crm_usb_clock_source_type value);</code> |
| Function description   | Select PLL or HICK (48M) as USB clock source                                    |
| Input parameter 1      | value: PLL or HICK (48M)  |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**value**

CRM\_USB\_CLOCK\_SOURCE\_PLL: PLL is used as USB clock source

CRM\_USB\_CLOCK\_SOURCE\_HICK: HICK is used as USB clock source

**Example:**

```
/* select hick48 as usb clock */
crm_usb_clock_source_select(CRM_USB_CLOCK_SOURCE_HICK);
```

### 5.5.32 crm\_clkout\_to\_tmr10\_enable function

The table below describes the function `crm_clkout_to_tmr10_enable`.

**Table 138. crm\_clkout\_to\_tmr10\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_clkout_to_tmr10_enable</code>                                |
| Function prototype     | <code>void crm_clkout_to_tmr10_enable(confirm_state new_state);</code> |
| Function description   | Enable the clkout to tmr10 channel 1                                   |
| Input parameter 1      | <code>new_state</code> : Enable (TRUE) or disable (FALSE)              |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* config clkout internal connect to tmr10 channel1 */
crm_clkout_to_tmr10_enable(TRUE);
```

### 5.5.33 crm\_emac\_output\_pulse\_set function

The table below describes the function `crm_emac_output_pulse_set`.

**Table 139. crm\_emac\_output\_pulse\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_emac_output_pulse_set</code>   |
| Function prototype     | <code>void crm_emac_output_pulse_set(crm_emac_output_pulse_type width);</code> |
| Function description   | Configure EMAC output pulse width  |
| Input parameter 1      | <code>width</code> : emac output pulse width                                   |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**value**

CRM\_EMAC\_PULSE\_125MS: EMAC output pulse width is set as 125ms

CRM\_EMAC\_PULSE\_1SCLK: EMAC output pulse width is set as one system clock cycle

**Example:**

```
/* config emac output pulse 125ms */
crm_emac_output_pulse_set(CRM_EMAC_PULSE_125MS);
```



### 5.5.34 crm\_pll\_parameter\_calculate function

The table below describes the function `crm_pll_parameter_calculate`

**Table 140. crm\_pll\_parameter\_calculate function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>crm_pll_parameter_calculate</code>   |
| Function prototype     | <code>error_status crm_pll_parameter_calculate(crm_pll_clock_source_type pll_rcs, uint32_t target_sclk_freq, uint16_t *ret_ms, uint16_t *ret_ns, uint16_t *ret_fr);</code>                         |
| Function description   | PLL parameter auto calculation   |
| Input parameter 1      | <code>pll_rcs</code> : pll input clock source  |
| Input parameter 2      | <code>target_sclk_freq</code> : target clock frequency multiplication, for example, for 200 MHz, this parameter can be <code>target_sclk_freq=200000000</code>                                     |
| Output parameter 1     | <code>ret_ms</code> : return <code>pll_ms</code> parameter   |
| Output parameter 2     | <code>ret_ns</code> : return <code>pll_ns</code> parameter   |
| Output parameter 3     | <code>ret_fr</code> : return <code>pll_fr</code> parameter   |
| Return value           | <code>error_status</code> : calculation status.<br>SUCCESS: the calculated result equals the target clock PLL parameter<br>ERROR: the calculated result is close to the target clock PLL parameter |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* pll parameter calculate automatic */
uint16_t pll_ms = 0, pll_ns = 0, pll_fr = 0;
crm_pll_parameter_calculate (CRM_PLL_SOURCE_HEX, 200000000, &pll_ms, &pll_ns, &pll_fr);
```

## 5.6 Digital-to-analog converter (DAC)

The DAC register structure `dac_type` is defined in the `at32f435_437_dac.h`.

```
/**
 * @brief type define dac register all
 */
typedef struct
{
    ...
} dac_type;
```

The table below gives a list of the DAC registers.

**Table 141. Summary of DAC registers**

| Register              | Description   |
|-----------------------|---|
| <code>ctrl</code>     | DAC control register                                |
| <code>swtrg</code>    | DAC software trigger register                       |
| <code>d1dth12r</code> | DAC1 12-bit right-aligned data holding register     |
| <code>d1dth12l</code> | DAC1 12-bit left-aligned data holding register      |
| <code>d1dth8r</code>  | DAC1 8-bit right-aligned data holding register      |
| <code>d2dth12r</code> | DAC2 12-bit right-aligned data holding register     |
| <code>d2dth12l</code> | DAC2 12-bit left-aligned data holding register      |
| <code>d2dth8r</code>  | DAC2 8-bit right-aligned data holding register      |
| <code>ddth12r</code>  | Dual DAC 12-bit right-aligned data holding register |
| <code>ddth12l</code>  | Dual DAC 12-bit left-aligned data holding register  |
| <code>ddth8r</code>   | Dual DAC 8-bit right-aligned data holding register  |
| <code>d1odt</code>    | DAC1 data output register                           |
| <code>d2odt</code>    | DAC2 data output register                           |

The table below gives a list of DAC library functions

**Table 142. Summary of DAC library functions**

| Function name                                   | Description                                      |
|---|--|
| <code>dac_reset</code>                          | Reset all DAC registers to their reset values    |
| <code>dac_enable</code>                         | Enable DAC                                       |
| <code>dac_output_buffer_enable</code>           | Enable DAC output buffer                         |
| <code>dac_trigger_enable</code>                 | Enable DAC trigger                               |
| <code>dac_trigger_select</code>                 | Select DAC trigger source                        |
| <code>dac_software_trigger_generate</code>      | Trigger DAC by software                          |
| <code>dac_dual_software_trigger_generate</code> | Simultaneously trigger DAC1 and DAC2 by software |
| <code>dac_wave_generate</code>                  | Select DAC output waveform                       |
| <code>dac_mask_amplitude_select</code>          | Select DAC noise /triangle-wave amplitude        |
| <code>dac_dma_enable</code>                     | DAC DMA enable                                   |
| <code>dac_data_output_get</code>                | Get DAC output value                             |
| <code>dac_1_data_set</code>                     | Set DAC1 output value                            |
| <code>dac_2_data_set</code>                     | Set DAC2 output value                            |
| <code>dac_dual_data_set</code>                  | Set DAC1 and DAC2 output values                  |

### 5.6.1 dac\_reset function

The table below describes the function dac\_reset.

**Table 143. dac\_reset function**

| Name                   | Description                                   |
|------------------------|---|
| Function name          | dac_reset                                     |
| Function prototype     | void dac_reset(void);                         |
| Function description   | Reset all DAC registers to their reset values |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | crm_periph_reset();                           |

**Example:**

```
dac_reset();
```

### 5.6.2 dac\_enable function

The table below describes the function dac\_enable.

**Table 144. dac\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dac_enable  |
| Function prototype     | void dac_enable(dac_select_type dac_select, confirm_state new_state);         |
| Function description   | Enable DAC  |
| Input parameter 1      | dac_select: select a DAC<br>This parameter can be DAC1_SELECT or DAC2_SELECT. |
| Input parameter 2      | new_state: Enable or disable<br>This parameter can be FALSE or TRUE.          |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
dac_enable(DAC1_SELECT, TRUE);
```

### 5.6.3 dac\_output\_buffer\_enable function

The table below describes the function dac\_output\_buffer\_enable.

**Table 145. dac\_output\_buffer\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dac_output_buffer_enable  |
| Function prototype     | void dac_output_buffer_enable(dac_select_type dac_select, confirm_state new_state); |
| Function description   | Enable DAC output buffer  |
| Input parameter 1      | dac_select: select a DAC<br>This parameter can be DAC1_SELECT or DAC2_SELECT.       |
| Input parameter 2      | new_state: Enable or disable<br>This parameter can be FALSE or TRUE.                |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
dac_output_buffer_enable (DAC1_SELECT, TRUE);
```

### 5.6.4 dac\_trigger\_enable function

The table below describes the function dac\_trigger\_enable.

**Table 146. dac\_trigger\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dac_trigger_enable  |
| Function prototype     | void dac_trigger_enable(dac_select_type dac_select, confirm_state new_state); |
| Function description   | Enable DAC trigger  |
| Input parameter 1      | dac_select: select a DAC<br>This parameter can be DAC1_SELECT or DAC2_SELECT. |
| Input parameter 2      | new_state: Enable or disable<br>This parameter can be FALSE or TRUE.          |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
dac_trigger_enable (DAC1_SELECT, TRUE);
```

## 5.6.5 dac\_trigger\_select function

The table below describes the function `dac_trigger_select`.

**Table 147. dac\_trigger\_select function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dac_trigger_select</code>  |
| Function prototype     | <code>void dac_trigger_select(dac_select_type dac_select, dac_trigger_type dac_trigger_source);</code>                 |
| Function description   | Select DAC trigger source  |
| Input parameter 1      | <code>dac_select</code> : select a DAC<br>This parameter can be <code>DAC1_SELECT</code> or <code>DAC2_SELECT</code> . |
| Input parameter 2      | <code>dac_trigger_source</code> : trigger source selected  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### **dac\_trigger\_source**

Trigger source selection

|  |                                 |
|--|---------------------------------|
| <code>DAC_TMR6_TRGOUT_EVENT</code> :         | TMR6 TRGOUT event triggers DAC  |
| <code>DAC_TMR8_TRGOUT_EVENT</code> :         | TMR8 TRGOUT event triggers DAC  |
| <code>DAC_TMR7_TRGOUT_EVENT</code> :         | TMR7 TRGOUT event triggers DAC  |
| <code>DAC_TMR5_TRGOUT_EVENT</code> :         | TMR5 TRGOUT event triggers DAC  |
| <code>DAC_TMR2_TRGOUT_EVENT</code> :         | TMR2 TRGOUT event triggers DAC  |
| <code>DAC_TMR4_TRGOUT_EVENT</code> :         | TMR4 TRGOUT event triggers DAC  |
| <code>DAC_EXTERNAL_INTERRUPT_LINE_9</code> : | EXINT LINE 9 event triggers DAC |
| <code>DAC_SOFTWARE_TRIGGER</code> :          | Software triggers DAC           |

### **Example:**

```

dac_trigger_select(DAC1_SELECT, DAC_TMR2_TRGOUT_EVENT);
dac_trigger_select(DAC2_SELECT, DAC_TMR2_TRGOUT_EVENT);
    
```

## 5.6.6 dac\_software\_trigger\_generate function

The table below describes the function `dac_software_trigger_generate`.

**Table 148. dac\_software\_trigger\_generate function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dac_software_trigger_generate</code>   |
| Function prototype     | <code>void dac_software_trigger_generate(dac_select_type dac_select);</code>   |
| Function description   | Software triggers DAC  |
| Input parameter 1      | <code>dac_select</code> : select a DAC<br>This parameter can be <code>DAC1_SELECT</code> or <code>DAC2_SELECT</code> . |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
dac_software_trigger_generate (DAC1_SELECT);
```

## 5.6.7 dac\_dual\_software\_trigger\_generate function

The table below describes the function `dac_dual_software_trigger_generate`.

**Table 149. dac\_dual\_software\_trigger\_generate function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dac_dual_software_trigger_generate</code>             |
| Function prototype     | <code>void dac_dual_software_trigger_generate(void);</code> |
| Function description   | Trigger DAC1 and DAC2 by software simultaneously            |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
dac_dual_software_trigger_generate ();
```

## 5.6.8 dac\_wave\_generate function

The table below describes the function `dac_wave_generate`.

**Table 150. dac\_wave\_generate function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dac_wave_generate</code>   |
| Function prototype     | <code>void dac_wave_generate(dac_select_type dac_select, dac_wave_type dac_wave);</code>                               |
| Function description   | DAC wave generation enable   |
| Input parameter 1      | <code>dac_select</code> : select a DAC<br>This parameter can be <code>DAC1_SELECT</code> or <code>DAC2_SELECT</code> . |
| Input parameter 2      | <code>dac_wave</code> : wave selected  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**dac\_wave**

Wave generation enable

`DAC_WAVE_GENERATE_NONE`: Wave generation disabled (output fixed register value)

`DAC_WAVE_GENERATE_NOISE`: Noise wave generation

`DAC_WAVE_GENERATE_TRIANGLE`: Triangle wave generation

**Example:**

```
dac_wave_generate(DAC1_SELECT, DAC_WAVE_GENERATE_NONE);
dac_wave_generate(DAC2_SELECT, DAC_WAVE_GENERATE_NOISE);
```

## 5.6.9 dac\_mask\_amplitude\_select function

The table below describes the function `dac_mask_amplitude_select`.

**Table 151. dac\_mask\_amplitude\_select function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dac_mask_amplitude_select</code>   |
| Function prototype     | <code>void dac_mask_amplitude_select(dac_select_type dac_select, dac_mask_amplitude_type dac_mask_amplitude);</code>   |
| Function description   | DAC noise bit width/triangle amplitude selection   |
| Input parameter 1      | <code>dac_select</code> : select a DAC<br>This parameter can be <code>DAC1_SELECT</code> or <code>DAC2_SELECT</code> . |
| Input parameter 2      | <code>dac_mask_amplitude</code> : noise bit width/triangle amplitude selection   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### **dac\_mask\_amplitude**

Noise bit width/triangle amplitude selection

`DAC_LSFR_BIT0_AMPLITUDE_1`: LSFR[0] in noise mode/triangle amplitude equal to 1  
`DAC_LSFR_BIT10_AMPLITUDE_3`: LSFR[1:0] in noise mode/triangle amplitude equal to 3  
`DAC_LSFR_BIT20_AMPLITUDE_7`: LSFR[2:0] in noise mode/triangle amplitude equal to 7  
`DAC_LSFR_BIT30_AMPLITUDE_15`: LSFR[3:0] in noise mode/triangle amplitude equal to 15  
`DAC_LSFR_BIT40_AMPLITUDE_31`: LSFR[4:0] in noise mode/triangle amplitude equal to 31  
`DAC_LSFR_BIT50_AMPLITUDE_63`: LSFR[5:0] in noise mode/triangle amplitude equal to 63  
`DAC_LSFR_BIT60_AMPLITUDE_127`: LSFR[6:0] in noise mode/triangle amplitude equal to 127  
`DAC_LSFR_BIT70_AMPLITUDE_255`: LSFR[7:0] in noise mode/triangle amplitude equal to 255  
`DAC_LSFR_BIT80_AMPLITUDE_511`: LSFR[8:0] in noise mode/triangle amplitude equal to 511  
`DAC_LSFR_BIT90_AMPLITUDE_1023`: LSFR[9:0] in noise mode/triangle amplitude equal to 1023  
`DAC_LSFR_BITA0_AMPLITUDE_2047`: LSFR[10:0] in noise mode/triangle amplitude equal to 2047  
`DAC_LSFR_BITB0_AMPLITUDE_4095`: LSFR[11:0] in noise mode/triangle amplitude equal to 4095

#### **Example:**

```

dac_mask_amplitude_select(DAC1_SELECT, DAC_LSFR_BIT60_AMPLITUDE_127);
dac_mask_amplitude_select(DAC2_SELECT, DAC_LSFR_BIT80_AMPLITUDE_511);
    
```

## 5.6.10 dac\_dma\_enable function

The table below describes the function `dac_dma_enable`.

**Table 152. dac\_dma\_enable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>dac_dma_enable</code>  |
| Function prototype   | <code>void dac_dma_enable(dac_select_type dac_select, confirm_state new_state);</code>                                 |
| Function description | DAC DMA enable   |
| Input parameter 1    | <code>dac_select</code> : select a DAC<br>This parameter can be <code>DAC1_SELECT</code> or <code>DAC2_SELECT</code> . |

| Name                   | Description  |
|------------------------|--|
| Input parameter 2      | new_state: Enable or disable<br>This parameter can be FALSE or TRUE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
dac_dma_enable(DAC1_SELECT, TRUE);
```

### 5.6.11 dac\_data\_output\_get function

The table below describes the function dac\_data\_output\_get.

**Table 153. dac\_data\_output\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dac_data_output_get   |
| Function prototype     | uint16_t dac_data_output_get(dac_select_type dac_select);                     |
| Function description   | Get DAC output value  |
| Input parameter 1      | dac_select: select a DAC<br>This parameter can be DAC1_SELECT or DAC2_SELECT. |
| Output parameter       | NA  |
| Return value           | dacx_data: dac1/dac2 output value   |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
uint16_t dac1_data;  
dac1_data = dac_data_output_get(DAC1_SELECT);
```

### 5.6.12 dac\_1\_data\_set function

The table below describes the function dac\_1\_data\_set.

**Table 154. dac\_1\_data\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dac_1_data_set  |
| Function prototype     | void dac_1_data_set(dac1_aligned_data_type dac1_aligned, uint16_t dac1_data); |
| Function description   | Set DAC1 output data  |
| Input parameter 1      | <i>dac1_aligned</i> : data format selection                                   |
| Input parameter 2      | <i>dac1_data</i> : DAC output value   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |



**dac1\_aligned**

Data format selection

DAC1\_12BIT\_RIGHT: 12-bit right-aligned

DAC1\_12BIT\_LEFT: 12-bit left-aligned

DAC1\_8BIT\_RIGHT: 8-bit right-aligned

**dac1\_data**

DAC output range settings. Value range varies from one format to another.

DAC1\_12BIT\_RIGHT: 0x000~0xFFF

DAC1\_12BIT\_LEFT: 0x0000~0xFFFF0

DAC1\_8BIT\_RIGHT: 0x00~0xFF

**Example:**

```
dac_1_data_set(DAC1_12BIT_RIGHT, 0x666);
```

### 5.6.13 dac\_2\_data\_set function

 The table below describes the function `dac_2_data_set`.

**Table 155. dac\_2\_data\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dac_2_data_set</code>  |
| Function prototype     | <code>void dac_2_data_set(dac2_aligned_data_type dac2_aligned, uint16_t dac2_data);</code> |
| Function description   | Set DAC2 output value  |
| Input parameter 1      | <i>dac2_aligned</i> : data format selection  |
| Input parameter 2      | <i>dac2_data</i> : DAC output value  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**dac2\_aligned**

Data format selection

DAC2\_12BIT\_RIGHT: 12-bit right-aligned

DAC2\_12BIT\_LEFT: 12-bit left-aligned

DAC2\_8BIT\_RIGHT: 8-bit right-aligned

**dac2\_data**

DAC output range settings. Value range varies from one format to another.

DAC2\_12BIT\_RIGHT: 0x000~0xFFF

DAC2\_12BIT\_LEFT: 0x0000~0xFFFF0

DAC2\_8BIT\_RIGHT: 0x00~0xFF

**Example:**

```
dac_2_data_set(DAC2_12BIT_RIGHT, 0x666);
```

## 5.6.14 dac\_dual\_data\_set function

The table below describes the function `dac_dual_data_set`.

**Table 156. dac\_dual\_data\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dac_dual_data_set</code>  |
| Function prototype     | <code>void dac_dual_data_set(dac_dual_data_type dac_dual, uint16_t data1, uint16_t data2);</code> |
| Function description   | Set DAC1 and DAC2 output values   |
| Input parameter 1      | <i>dac_dual</i> : data format selection   |
| Input parameter 2      | <i>data1</i> : DAC1 output value  |
| Input parameter 3      | <i>data2</i> : DAC2 output value  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### **dac\_dual**

Data format selection

DAC\_DUAL\_12BIT\_RIGHT: 12-bit right-aligned

DAC\_DUAL\_12BIT\_LEFT: 12-bit left-aligned

DAC\_DUAL\_8BIT\_RIGHT: 8-bit right-aligned

### **data1/data2**

DAC output range settings. Value range varies from one format to another.

DAC\_DUAL\_12BIT\_RIGHT: 0x000~0xFFF

DAC\_DUAL\_12BIT\_LEFT: 0x0000~0xFFFF0

DAC\_DUAL\_8BIT\_RIGHT: 0x00~0xFF

### **Example:**

```

dac_dual_data_set(DAC_DUAL_12BIT_RIGHT, 0x666, 0x777);
    
```

## 5.7 Debug

The DEBUG register structure `debug_type` is defined in the “at32f435\_437\_debug.h”.

```
/**
 * @brief type define debug register all
 */
typedef struct
{
    ...
} debug_type;
```

The table below gives a list of the DEBUG registers.

**Table 157. Summary of DEBUG registers**

| Register | Description      |
|----------|------------------|
| idcode   | Device ID        |
| ctrl     | Control register |

The table below gives a list of DEBUG library functions.

**Table 158. Summary of DEBUG library functions**

| Function name                      | Description                         |
|------------------------------------|-------------------------------------|
| <code>debug_device_id_get</code>   | Read device idcode                  |
| <code>debug_periph_mode_set</code> | Peripheral debug mode configuration |

### 5.7.1 debug\_device\_id\_get function

The table below describes the function debug\_device\_id\_get.

**Table 159. debug\_device\_id\_get function**

| Name                   | Description                         |
|------------------------|-------------------------------------|
| Function name          | debug_device_id_get                 |
| Function prototype     | uint32_t debug_device_id_get(void); |
| Function description   | Read device idcode                  |
| Input parameter 1      | NA                                  |
| Input parameter 2      | NA                                  |
| Output parameter       | NA                                  |
| Return value           | Return 32-bit idcode                |
| Required preconditions | NA                                  |
| Called functions       | NA                                  |

**Example:**

```

/* get idcode */
uint32_t idcode = 0;
idcode = debug_device_id_get();
    
```

### 5.7.2 debug\_periph\_mode\_set function

The table below describes the function debug\_periph\_mode\_set.

**Table 160. debug\_periph\_mode\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | debug_periph_mode_set  |
| Function prototype     | void debug_periph_mode_set(uint32_t periph_debug_mode, confirm_state new_state); |
| Function description   | Select a peripheral/mode to debug  |
| Input parameter 1      | periph_debug_mode: select a peripheral or mode                                   |
| Input parameter 2      | new_state: Enable (TRUE) or disable (FALSE)                                      |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**periph\_debug\_mode**

Select a peripheral or mode to debug

- DEBUG\_SLEEP: Debug in Sleep mode
- DEBUG\_DEEPSLEEP: Debug in Deepsleep mode
- DEBUG\_STANDBY: Debug in Standby mode
- DEBUG\_WDT\_PAUSE: Watchdog pause control bit
- DEBUG\_WWDT\_PAUSE: Window watchdog pause control bit
- DEBUG\_TMR1\_PAUSE: TMR1 pause control bit
- DEBUG\_TMR2\_PAUSE: TMR2 pause control bit
- DEBUG\_TMR3\_PAUSE: TMR3 pause control bit
- DEBUG\_TMR4\_PAUSE: TMR4 pause control bit

|                           |   |
|---------------------------|---|
| DEBUG_TMR5_PAUSE:         | TMR5 pause control bit                    |
| DEBUG_TMR6_PAUSE:         | TMR6 pause control bit                    |
| DEBUG_TMR7_PAUSE:         | TMR7 pause control bit                    |
| DEBUG_TMR8_PAUSE:         | TMR8 pause control bit                    |
| DEBUG_TMR9_PAUSE:         | TMR9 pause control bit                    |
| DEBUG_TMR10_PAUSE:        | TMR10 pause control bit                   |
| DEBUG_TMR11_PAUSE:        | TMR11 pause control bit                   |
| DEBUG_TMR12_PAUSE:        | TMR12 pause control bit                   |
| DEBUG_TMR13_PAUSE:        | TMR13 pause control bit                   |
| DEBUG_TMR14_PAUSE:        | TMR14 pause control bit                   |
| DEBUG_TMR20_PAUSE:        | TMR20 pause control bit                   |
| DEBUG_I2C1_SMBUS_TIMEOUT: | I2C1 SMBUS TIMEOUT pause control bit      |
| DEBUG_I2C2_SMBUS_TIMEOUT: | I2C2 SMBUS TIMEOUT pause control bit      |
| DEBUG_I2C3_SMBUS_TIMEOUT: | I2C3 SMBUS TIMEOUT pause control bit      |
| DEBUG_CAN1_PAUSE:         | CAN1 receive register pause control bit   |
| DEBUG_CAN2_PAUSE:         | CAN2 receive register pause control bit   |
| DEBUG_ERTC_PAUSE:         | ERTC pause control bit                    |
| DEBUG_ERTC_512_PAUSE:     | ERTC 512Hz pulse output pause control bit |

**Example:**

```
/* enable tmr1 debug mode */
debug_periph_mode_set(DEBUG_TMR1_PAUSE, TRUE);
```

## 5.8 DMA controller

The DMA register structure `dma_type` is defined in the “at32f435\_437\_dma.h”.

```
/**
 * @brief type define dma register
 */
typedef struct
{
    ...

} dma_type;
```

The DMA channel register structure `dma_channel_type` is defined in the “at32f435\_437\_dma.h”.

```
/**
 * @brief type define dma channel register all
 */
typedef struct
{
    ...

} dma_channel_type;
```

The table below gives a list of the DMA registers.

**Table 161. Summary of DMA registers**

| Register                 | Description                               |
|--------------------------|---|
| <code>dma_sts</code>     | DMA status register                       |
| <code>dma_clr</code>     | DMA status clear register                 |
| <code>dma_c1ctrl</code>  | DMA channel 1 configuration register      |
| <code>dma_c1dtcnt</code> | DMA channel 1 number of data register     |
| <code>dma_c1paddr</code> | DMA channel 1 peripheral address register |
| <code>dma_c1maddr</code> | DMA channel 1 memoryaddress register      |
| <code>dma_c2ctrl</code>  | DMA channel 2 configuration register      |
| <code>dma_c2dtcnt</code> | DMA channel 2 number of data register     |
| <code>dma_c2paddr</code> | DMA channel 2 peripheral address register |
| <code>dma_c2maddr</code> | DMA channel 2 memoryaddress register      |
| <code>dma_c3ctrl</code>  | DMA channel 3 configuration register      |
| <code>dma_c3dtcnt</code> | DMA channel 3 number of data register     |
| <code>dma_c3paddr</code> | DMA channel 3 peripheral address register |
| <code>dma_c3maddr</code> | DMA channel 3 memoryaddress register      |
| <code>dma_c4ctrl</code>  | DMA channel 4 configuration register      |
| <code>dma_c4dtcnt</code> | DMA channel 4 number of data register     |
| <code>dma_c4paddr</code> | DMA channel 4 peripheral address register |
| <code>dma_c4maddr</code> | DMA channel 4 memoryaddress register      |
| <code>dma_c5ctrl</code>  | DMA channel 5 configuration register      |
| <code>dma_c5dtcnt</code> | DMA channel 5 number of data register     |

| Register       | Description                                    |
|----------------|--|
| dma_c5paddr    | DMA channel 5 peripheral address register      |
| dma_c5maddr    | DMA channel 5 memory address register          |
| dma_c6ctrl     | DMA channel 6 configuration register           |
| dma_c6dtcnt    | DMA channel 6 number of data register          |
| dma_c6paddr    | DMA channel 6 peripheral address register      |
| dma_c6maddr    | DMA channel 6 memory address register          |
| dma_c7ctrl     | DMA channel 7 configuration register           |
| dma_c7dtcnt    | DMA channel 7 number of data register          |
| dma_c7paddr    | DMA channel 7 peripheral address register      |
| dma_c7maddr    | DMA channel 7 memory address register          |
| dma_muxsel     | DMAMUX enable register                         |
| dma_muxc1ctrl  | DMAMUX channel 1 control register              |
| dma_muxc2ctrl  | DMAMUX channel 2 control register              |
| dma_muxc3ctrl  | DMAMUX channel 3 control register              |
| dma_muxc4ctrl  | DMAMUX channel 4 control register              |
| dma_muxc5ctrl  | DMAMUX channel 5 control register              |
| dma_muxc6ctrl  | DMAMUX channel 6 control register              |
| dma_muxc7ctrl  | DMAMUX channel 7 control register              |
| dma_muxg1ctrl  | DMAMUX request generator 1 control register    |
| dma_muxg2ctrl  | DMAMUX request generator 2 control register    |
| dma_muxg3ctrl  | DMAMUX request generator 3 control register    |
| dma_muxg4ctrl  | DMAMUX request generator 4 control register    |
| dma_muxsyncsts | DMAMUX synchronous status register             |
| dma_muxsyncclr | DMAMUX synchronous status clear register       |
| dma_muxgsts    | DMAMUX request generator status register       |
| dma_muxgclr    | DMAMUX request generator status clear register |

The table below gives a list of DMA library functions.

**Table 162. Summary of DMA library functions**

| Function name                 | Description  |
|-------------------------------|--|
| dma_default_para_init         | Initialize the parameters of the dma_init_struct   |
| dma_init                      | Initialize the selected DMA channel                |
| dma_reset                     | Reset the selected DMA channel                     |
| dma_data_number_set           | Set the number of data transfer of a given channel |
| dma_data_number_get           | Get the number of data transfer of a given channel |
| dma_interrupt_enable          | Enable DMA channel interrupt                       |
| dma_channel_enable            | Enable DMA channel                                 |
| dma_flexible_config           | Configure flexible DMA request mapping             |
| dma_flag_get                  | Get the flag of DMA channels                       |
| dma_flag_clear                | Clear the flag of DMA channels                     |
| dmamux_enable                 | Enable DMAMUX                                      |
| dmamux_init                   | Initialize DMAMUX                                  |
| dmamux_sync_default_para_init | Initialize DMAMUX synchronous module               |

|                                    |   |
|------------------------------------|---|
| dmamux_sync_config                 | Configure DMAMUX synchronous module         |
| dmamux_generator_default_para_init | Initialize DMAMUX request generator         |
| dmamux_generator_config            | Configure DMAMUX request generator          |
| dmamux_sync_interrupt_enable       | Enable DMAMUX synchronous module interrupt  |
| dmamux_generator_interrupt_enable  | Enable DMAMUX request generator interrupt   |
| dmamux_sync_flag_get               | Get the flag of DMAMUX synchronous module   |
| dmamux_sync_flag_clear             | Clear the flag of DMAMUX synchronous module |
| dmamux_generator_flag_get          | Get the flag of DMAMUX request generator    |
| dmamux_generator_flag_clear        | Clear the flag of DMAMUX request generator  |

### 5.8.1 dma\_default\_para\_init function

The table below describes the function dma\_default\_para\_init.

**Table 163. dma\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dma_default_para_init                                       |
| Function prototype     | void dma_default_para_init(dma_init_type* dma_init_struct); |
| Function description   | Initialize the parameters of the dma_init_struct            |
| Input parameter 1      | dma_init_struct: dma_init_type pointer                      |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The table below describes the default values of dma\_init\_struct members.

**Table 164. dma\_init\_struct default values**

| Member                | Default values                 |
|-----------------------|--------------------------------|
| peripheral_base_addr  | 0x0                            |
| memory_base_addr      | 0x0                            |
| direction             | DMA_DIR_PERIPHERAL_TO_MEMORY   |
| buffer_size           | 0x0                            |
| peripheral_inc_enable | FALSE                          |
| memory_inc_enable     | FALSE                          |
| peripheral_data_width | DMA_PERIPHERAL_DATA_WIDTH_BYTE |
| memory_data_width     | DMA_MEMORY_DATA_WIDTH_BYTE     |
| loop_mode_enable      | FALSE                          |
| priority              | DMA_PRIORITY_LOW               |

**Example:**

```

/* dma init config with its default value */
dma_init_type dma_init_struct = {0};
dma_default_para_init(&dma_init_struct);

```



## 5.8.2 dma\_init function

The table below describes the function dma\_init.

**Table 165. dma\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dma_init   |
| Function prototype     | void dma_init(dma_channel_type* dma_channel, dma_init_type* dma_init_struct) |
| Function description   | Initialize the selected DMA channel  |
| Input parameter 1      | dma_channel: DMAx_CHANNELy defines a DMA channel number, x=1 or 2; y=1...7   |
| Input parameter 2      | dma_init_struct: dma_init_type pointer                                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### dma\_init\_type structure

The dma\_init\_type is defined in the at32f435\_437\_dma.h.

typedef struct

```

{
    uint32_t          peripheral_base_addr;
    uint32_t          memory_base_addr;
    dma_dir_type      direction;
    uint16_t          buffer_size;
    confirm_state     peripheral_inc_enable;
    confirm_state     memory_inc_enable;
    dma_peripheral_data_size_type peripheral_data_width;
    dma_memory_data_size_type memory_data_width;
    confirm_state     loop_mode_enable;
    dma_priority_level_type priority;
} dma_init_type;

```

#### peripheral\_base\_addr

Set the peripheral address of a DMA channel.

#### memory\_base\_addr

Set the memory address of a DMA channel.

#### direction

Set the transfer direction of a DMA channel.

DMA\_DIR\_PERIPHERAL\_TO\_MEMORY: Peripheral to memory  
 DMA\_DIR\_MEMORY\_TO\_PERIPHERAL: Memory to peripheral  
 DMA\_DIR\_MEMORY\_TO\_MEMORY: Memory to memory

#### buffer\_size

Set the number of data transfer of a DMA channel.

#### peripheral\_inc\_enable

Enable/disable DMA channel peripheral address auto increment.

FALSE: Peripheral address is not incremented

TRUE: Peripheral address is incremented

**memory\_inc\_enable**

Enable/disable DMA channel memory address auto increment.

FALSE: Memory address is not incremented

TRUE: Memory address is incremented

**peripheral\_data\_width**

Set DMA peripheral data width.

|                                     |           |
|-------------------------------------|-----------|
| DMA_PERIPHERAL_DATA_WIDTH_BYTE:     | Byte      |
| DMA_PERIPHERAL_DATA_WIDTH_HALFWORD: | Half-word |
| DMA_PERIPHERAL_DATA_WIDTH_WORD:     | Word      |

**memory\_data\_width**

Set DMA memory data width.

|                                 |           |
|---------------------------------|-----------|
| DMA_MEMORY_DATA_WIDTH_BYTE:     | Byte      |
| DMA_MEMORY_DATA_WIDTH_HALFWORD: | Half-word |
| DMA_MEMORY_DATA_WIDTH_WORD:     | Word      |

**loop\_mode\_enable**

Set DMA loop mode.

FALSE: DMA single mode

TRUE: DMA loop mode

**priority**

Set DMA channel priority.

|                         |           |
|-------------------------|-----------|
| DMA_PRIORITY_LOW:       | Low       |
| DMA_PRIORITY_MEDIUM:    | Medium    |
| DMA_PRIORITY_HIGH:      | High      |
| DMA_PRIORITY_VERY_HIGH: | Very high |

**Example:**

```

dma_init_type dma_init_struct = {0};
/* dma2 channel1 configuration */
dma_init_struct.buffer_size = BUFFER_SIZE;
dma_init_struct.direction = DMA_DIR_MEMORY_TO_PERIPHERAL;
dma_init_struct.memory_base_addr = (uint32_t)src_buffer;
dma_init_struct.memory_data_width = DMA_MEMORY_DATA_WIDTH_HALFWORD;
dma_init_struct.memory_inc_enable = TRUE;
dma_init_struct.peripheral_base_addr = (uint32_t)0x4001100C;
dma_init_struct.peripheral_data_width = DMA_PERIPHERAL_DATA_WIDTH_HALFWORD;
dma_init_struct.peripheral_inc_enable = FALSE;
dma_init_struct.priority = DMA_PRIORITY_MEDIUM;
dma_init_struct.loop_mode_enable = FALSE;
dma_init(DMA2_CHANNEL1, &dma_init_struct);
    
```

### 5.8.3 dma\_reset function

The table below describes the function dma\_reset.

**Table 166. dma\_reset function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dma_reset  |
| Function prototype     | void dma_reset(dma_channel_type* dma_channel);                             |
| Function description   | Reset the selected DMA channel   |
| Input parameter 1      | dma_channel: DMAx_CHANNELy defines a DMA channel number, x=1 or 2; y=1...7 |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* reset dma2 channel1 */
dma_reset(DMA2_CHANNEL1);
```

### 5.8.4 dma\_data\_number\_set function

The table below describes the function dma\_data\_number\_set.

**Table 167. dma\_data\_number\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dma_data_number_set  |
| Function prototype     | void dma_data_number_set(dma_channel_type* dma_channel, uint16_t data_number); |
| Function description   | Set the number of data transfer of the selected DMA channel                    |
| Input parameter 1      | dma_channel: DMAx_CHANNELy defines a DMA channel number, x=1 or 2; y=1...7     |
| Input parameter 2      | data_number: indicates the number of data transfer, up to 65535                |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* set dma2 channel1 data count is 0x100*/
dma_data_number_set(DMA2_CHANNEL1, 0x100);
```

### 5.8.5 dma\_data\_number\_get function

The table below describes the function dma\_data\_number\_get.

**Table 168. dma\_data\_number\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dma_data_number_get  |
| Function prototype     | uint16_t dma_data_number_get(dma_channel_type* dma_channel);               |
| Function description   | Get the number of data transfer of the selected DMA channel                |
| Input parameter 1      | dma_channel: DMAx_CHANNELy defines a DMA channel number, x=1 or 2; y=1...7 |
| Output parameter       | NA   |
| Return value           | Get the number of data transfer of a DMA channel                           |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* get dma2 channel1 data count*/
uint16_t data_counter;
data_counter = dma_data_number_get(DMA2_CHANNEL1);
```

### 5.8.6 dma\_interrupt\_enable function

The table below describes the function dma\_interrupt\_enable.

**Table 169. dma\_interrupt\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dma_interrupt_enable   |
| Function prototype     | void dma_interrupt_enable(dma_channel_type* dma_channel, uint32_t dma_int, confirm_state new_state); |
| Function description   | Enable DMA channel interrupt   |
| Input parameter 1      | dma_channel: DMAx_CHANNELy defines a DMA channel number, x=1 or 2; y=1...7                           |
| Input parameter 2      | dma_int: interrupt source selection  |
| Input parameter 3      | new_state: interrupt enable/disable  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**dma\_int**

Select DMA interrupt source

- DMA\_FDT\_INT: Transfer complete interrupt
- DMA\_HDT\_INT: Half transfer complete interrupt
- DMA\_DTERR\_INT: Transfer error interrupt

**new\_state**

Enable or disable DMA channel interrupt

- FALSE: Disabled
- TRUE: Enabled

**Example:**

```
/* enable dma2 channel1 transfer full data interrupt */
dma_interrupt_enable(DMA2_CHANNEL1, DMA_FDT_INT, TRUE);
```

## 5.8.7 dma\_channel\_enable function

The table below describes the function dma\_channel\_enable.

**Table 170. dma\_channel\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dma_channel_enable   |
| Function prototype     | void dma_channel_enable(dma_channel_type* dma_channel, confirm_state new_state); |
| Function description   | Enable the selected DMA channel  |
| Input parameter 1      | dma_channel: DMAx_CHANNELy defines a DMA channel number, x=1 or 2; y=1...7       |
| Input parameter 2      | new_state: Enable or disable the selected DMA channel                            |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**new\_state**

Enable or disable DMA channels

FALSE: Disabled

TRUE: Enabled

**Example:**

```
/* enable dma channel */
dma_channel_enable(DMA2_CHANNEL1, TRUE);
```

## 5.8.8 dma\_flag\_get function

The table below describes the function dma\_flag\_get.

**Table 171. dma\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dma_flag_get  |
| Function prototype     | flag_status dma_flag_get(uint32_t dma_flag);                  |
| Function description   | Get the flag of the selected DMA channel                      |
| Input parameter 1      | dma_flag: select the desired flag                             |
| Output parameter       | NA  |
| Return value           | flag_status: indicates whether the desired flag is set or not |
| Required preconditions | NA  |
| Called functions       | NA  |

**dma\_flag**

The dma\_flag is used for flag section, including:

DMA1\_GL1\_FLAG: DMA1 channel 1 global flag

DMA1\_FDT1\_FLAG: DMA1 channel 1 transfer complete flag

|                   |  |
|-------------------|--|
| DMA1_HDT1_FLAG:   | DMA1 channel 1 half transfer complete flag |
| DMA1_DTERR1_FLAG: | DMA1 channel 1 transfer error flag         |
| DMA1_GL2_FLAG:    | DMA1 channel 2 global flag                 |
| DMA1_FDT2_FLAG:   | DMA1 channel 2 transfer complete flag      |
| DMA1_HDT2_FLAG:   | DMA1 channel 2 half transfer complete flag |
| DMA1_DTERR2_FLAG: | DMA1 channel 2 transfer error flag         |
| DMA1_GL3_FLAG:    | DMA1 channel 3 global flag                 |
| DMA1_FDT3_FLAG:   | DMA1 channel 3 transfer complete flag      |
| DMA1_HDT3_FLAG:   | DMA1 channel 3 half transfer complete flag |
| DMA1_DTERR3_FLAG: | DMA1 channel 3 transfer error flag         |
| DMA1_GL4_FLAG:    | DMA1 channel 4 global flag                 |
| DMA1_FDT4_FLAG:   | DMA1 channel 4 transfer complete flag      |
| DMA1_HDT4_FLAG:   | DMA1 channel 4 half transfer complete flag |
| DMA1_DTERR4_FLAG: | DMA1 channel 4 transfer error flag         |
| DMA1_GL5_FLAG:    | DMA1 channel 5 global flag                 |
| DMA1_FDT5_FLAG:   | DMA1 channel 5 transfer complete flag      |
| DMA1_HDT5_FLAG:   | DMA1 channel 5 half transfer complete flag |
| DMA1_DTERR5_FLAG: | DMA1 channel 5 transfer error flag         |
| DMA1_GL6_FLAG:    | DMA1 channel 6 global flag                 |
| DMA1_FDT6_FLAG:   | DMA1 channel 6 transfer complete flag      |
| DMA1_HDT6_FLAG:   | DMA1 channel 6 half transfer complete flag |
| DMA1_DTERR6_FLAG: | DMA1 channel 6 transfer error flag         |
| DMA1_GL7_FLAG:    | DMA1 channel 7 global flag                 |
| DMA1_FDT7_FLAG:   | DMA1 channel 7 transfer complete flag      |
| DMA1_HDT7_FLAG:   | DMA1 channel 7 half transfer complete flag |
| DMA1_DTERR7_FLAG: | DMA1 channel 7 transfer error flag         |
| DMA2_GL1_FLAG:    | DMA2 channel 1 global flag                 |
| DMA2_FDT1_FLAG:   | DMA2 channel 1 transfer complete flag      |
| DMA2_HDT1_FLAG:   | DMA2 channel 1 half transfer complete flag |
| DMA2_DTERR1_FLAG: | DMA2 channel 1 transfer error flag         |
| DMA2_GL2_FLAG:    | DMA2 channel 2 global flag                 |
| DMA2_FDT2_FLAG:   | DMA2 channel 2 transfer complete flag      |
| DMA2_HDT2_FLAG:   | DMA2 channel 2 half transfer complete flag |
| DMA2_DTERR2_FLAG: | DMA2 channel 2 transfer error flag         |
| DMA2_GL3_FLAG:    | DMA2 channel 3 global flag                 |
| DMA2_FDT3_FLAG:   | DMA2 channel 3 transfer complete flag      |
| DMA2_HDT3_FLAG:   | DMA2 channel 3 half transfer complete flag |
| DMA2_DTERR3_FLAG: | DMA2 channel 3 transfer error flag         |
| DMA2_GL4_FLAG:    | DMA2 channel 4 global flag                 |
| DMA2_FDT4_FLAG:   | DMA2 channel 4 transfer complete flag      |
| DMA2_HDT4_FLAG:   | DMA2 channel 4 half transfer complete flag |
| DMA2_DTERR4_FLAG: | DMA2 channel 4 transfer error flag         |
| DMA2_GL5_FLAG:    | DMA2 channel 5 global flag                 |
| DMA2_FDT5_FLAG:   | DMA2 channel 5 transfer complete flag      |
| DMA2_HDT5_FLAG:   | DMA2 channel 5 half transfer complete flag |
| DMA2_DTERR5_FLAG: | DMA2 channel 5 transfer error flag         |

|                   |  |
|-------------------|--|
| DMA2_GL6_FLAG:    | DMA2 channel 6 global flag                 |
| DMA2_FDT6_FLAG:   | DMA2 channel 6 transfer complete flag      |
| DMA2_HDT6_FLAG:   | DMA2 channel 6 half transfer complete flag |
| DMA2_DTERR6_FLAG: | DMA2 channel 6 transfer error flag         |
| DMA2_GL7_FLAG:    | DMA2 channel 7 global flag                 |
| DMA2_FDT7_FLAG:   | DMA2 channel 7 transfer complete flag      |
| DMA2_HDT7_FLAG:   | DMA2 channel 7 half transfer complete flag |
| DMA2_DTERR7_FLAG: | DMA2 channel 7 transfer error flag         |

**flag\_status**

RESET: Flag is reset

SET: Flag is set

**Example:**

```

if(dma_flag_get(DMA2_FDT1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
}
    
```

### 5.8.9 dma\_flag\_clear function

The table below describes the function dma\_flag\_clear.

**Table 172. dma\_flag\_clear function**

| Name                   | Description                                |
|------------------------|--|
| Function name          | dma_flag_clear                             |
| Function prototype     | void dma_flag_clear(uint32_t dmax_flag);   |
| Function description   | Clear the selected flag                    |
| Input parameter 1      | dmax_flag: a flag that needs to be cleared |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**dmax\_flag**

The dmax\_flag is used to select the desired flag, including:

|                   |  |
|-------------------|--|
| DMA1_GL1_FLAG:    | DMA1 channel 1 global flag                 |
| DMA1_FDT1_FLAG:   | DMA1 channel 1 transfer complete flag      |
| DMA1_HDT1_FLAG:   | DMA1 channel 1 half transfer complete flag |
| DMA1_DTERR1_FLAG: | DMA1 channel 1 transfer error flag         |
| DMA1_GL2_FLAG:    | DMA1 channel 2 global flag                 |
| DMA1_FDT2_FLAG:   | DMA1 channel 2 transfer complete flag      |
| DMA1_HDT2_FLAG:   | DMA1 channel 2 half transfer complete flag |
| DMA1_DTERR2_FLAG: | DMA1 channel 2 transfer error flag         |
| DMA1_GL3_FLAG:    | DMA1 channel 3 global flag                 |
| DMA1_FDT3_FLAG:   | DMA1 channel 3 transfer complete flag      |

|                   |  |
|-------------------|--|
| DMA1_HDT3_FLAG:   | DMA1 channel 3 half transfer complete flag |
| DMA1_DTERR3_FLAG: | DMA1 channel 3 transfer error flag         |
| DMA1_GL4_FLAG:    | DMA1 channel 4 global flag                 |
| DMA1_FDT4_FLAG:   | DMA1 channel 4 transfer complete flag      |
| DMA1_HDT4_FLAG:   | DMA1 channel 4 half transfer complete flag |
| DMA1_DTERR4_FLAG: | DMA1 channel 4 transfer error flag         |
| DMA1_GL5_FLAG:    | DMA1 channel 5 global flag                 |
| DMA1_FDT5_FLAG:   | DMA1 channel 5 transfer complete flag      |
| DMA1_HDT5_FLAG:   | DMA1 channel 5 half transfer complete flag |
| DMA1_DTERR5_FLAG: | DMA1 channel 5 transfer error flag         |
| DMA1_GL6_FLAG:    | DMA1 channel 6 global flag                 |
| DMA1_FDT6_FLAG:   | DMA1 channel 6 transfer complete flag      |
| DMA1_HDT6_FLAG:   | DMA1 channel 6 half transfer complete flag |
| DMA1_DTERR6_FLAG: | DMA1 channel 6 transfer error flag         |
| DMA1_GL7_FLAG:    | DMA1 channel 7 global flag                 |
| DMA1_FDT7_FLAG:   | DMA1 channel 7 transfer complete flag      |
| DMA1_HDT7_FLAG:   | DMA1 channel 7 half transfer complete flag |
| DMA1_DTERR7_FLAG: | DMA1 channel 7 transfer error flag         |
| DMA2_GL1_FLAG:    | DMA2 channel 1 global flag                 |
| DMA2_FDT1_FLAG:   | DMA2 channel 1 transfer complete flag      |
| DMA2_HDT1_FLAG:   | DMA2 channel 1 half transfer complete flag |
| DMA2_DTERR1_FLAG: | DMA2 channel 1 transfer error flag         |
| DMA2_GL2_FLAG:    | DMA2 channel 2 global flag                 |
| DMA2_FDT2_FLAG:   | DMA2 channel 2 transfer complete flag      |
| DMA2_HDT2_FLAG:   | DMA2 channel 2 half transfer complete flag |
| DMA2_DTERR2_FLAG: | DMA2 channel 2 transfer error flag         |
| DMA2_GL3_FLAG:    | DMA2 channel 3 global flag                 |
| DMA2_FDT3_FLAG:   | DMA2 channel 3 transfer complete flag      |
| DMA2_HDT3_FLAG:   | DMA2 channel 3 half transfer complete flag |
| DMA2_DTERR3_FLAG: | DMA2 channel 3 transfer error flag         |
| DMA2_GL4_FLAG:    | DMA2 channel 4 global flag                 |
| DMA2_FDT4_FLAG:   | DMA2 channel 4 transfer complete flag      |
| DMA2_HDT4_FLAG:   | DMA2 channel 4 half transfer complete flag |
| DMA2_DTERR4_FLAG: | DMA2 channel 4 transfer error flag         |
| DMA2_GL5_FLAG:    | DMA2 channel 5 global flag                 |
| DMA2_FDT5_FLAG:   | DMA2 channel 5 transfer complete flag      |
| DMA2_HDT5_FLAG:   | DMA2 channel 5 half transfer complete flag |
| DMA2_DTERR5_FLAG: | DMA2 channel 5 transfer error flag         |
| DMA2_GL6_FLAG:    | DMA2 channel 6 global flag                 |
| DMA2_FDT6_FLAG:   | DMA2 channel 6 transfer complete flag      |
| DMA2_HDT6_FLAG:   | DMA2 channel 6 half transfer complete flag |
| DMA2_DTERR6_FLAG: | DMA2 channel 6 transfer error flag         |
| DMA2_GL7_FLAG:    | DMA2 channel 7 global flag                 |
| DMA2_FDT7_FLAG:   | DMA2 channel 7 transfer complete flag      |
| DMA2_HDT7_FLAG:   | DMA2 channel 7 half transfer complete flag |
| DMA2_DTERR7_FLAG: | DMA2 channel 7 transfer error flag         |



**Example:**

```

if(dma_flag_get(DMA2_FDT1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
    dma_flag_clear(DMA2_FDT1_FLAG);
}
    
```

### 5.8.10 dma\_flexible\_config function

The table below describes the function dma\_flexible\_enable.

**Table 173. dma\_flexible\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dma_flexible_config   |
| Function prototype     | void dma_flexible_config(dma_type* dma_x, dmamux_channel_type *dmamux_channelx, dmamux_reqst_id_sel_type dmamux_req_sel); |
| Function description   | Configure DMAMUX  |
| Input parameter 1      | dma_x: DMAx, x=1 or 2   |
| Input parameter 2      | <i>dmamux_channelx</i><br>:DMAMUX channel selected, x=1...7   |
| Input parameter 3      | <i>dmamux_req_sel</i><br>:DMAMUX channel request ID   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**dmamux\_channelx**

DMAMUX channel selection, including:

- DMA1MUX\_CHANNEL1
- DMA1MUX\_CHANNEL2
- DMA1MUX\_CHANNEL3
- DMA1MUX\_CHANNEL4
- DMA1MUX\_CHANNEL5
- DMA1MUX\_CHANNEL6
- DMA1MUX\_CHANNEL7
- DMA2MUX\_CHANNEL1
- DMA2MUX\_CHANNEL2
- DMA2MUX\_CHANNEL3
- DMA2MUX\_CHANNEL4
- DMA2MUX\_CHANNEL5
- DMA2MUX\_CHANNEL6
- DMA2MUX\_CHANNEL7

**dmamux\_req\_sel**

The table below shows the DMAMUX channel request ID.

**Table 174. DMAMUX channel request source ID**

| Request source ID | Description                    | Request source ID | Description                    |
|-------------------|--------------------------------|-------------------|--------------------------------|
| 0x01              | DMAMUX_DMAREQ_ID_REQ_G1        | 0x02              | DMAMUX_DMAREQ_ID_REQ_G2        |
| 0x03              | DMAMUX_DMAREQ_ID_REQ_G3        | 0x04              | DMAMUX_DMAREQ_ID_REQ_G4        |
| 0x05              | DMAMUX_DMAREQ_ID_ADC1          | 0x24              | DMAMUX_DMAREQ_ID_ADC2          |
| 0x25              | DMAMUX_DMAREQ_ID_ADC3          | 0x06              | DMAMUX_DMAREQ_ID_DAC1          |
| 0x29              | DMAMUX_DMAREQ_ID_DAC2          | 0x08              | DMAMUX_DMAREQ_ID_TMR6_OVERFLOW |
| 0x09              | DMAMUX_DMAREQ_ID_TMR7_OVERFLOW | 0x0A              | DMAMUX_DMAREQ_ID_SPI1_RX       |
| 0x0B              | DMAMUX_DMAREQ_ID_SPI1_TX       | 0x0C              | DMAMUX_DMAREQ_ID_SPI2_RX       |
| 0x0D              | DMAMUX_DMAREQ_ID_SPI2_TX       | 0x0E              | DMAMUX_DMAREQ_ID_SPI3_RX       |
| 0x0F              | DMAMUX_DMAREQ_ID_SPI3_TX       | 0x6A              | DMAMUX_DMAREQ_ID_SPI4_RX       |
| 0x6B              | DMAMUX_DMAREQ_ID_SPI4_TX       | 0x6E              | DMAMUX_DMAREQ_ID_I2S2_EXT_RX   |
| 0x6F              | DMAMUX_DMAREQ_ID_I2S2_EXT_TX   | 0x70              | DMAMUX_DMAREQ_ID_I2S3_EXT_RX   |
| 0x71              | DMAMUX_DMAREQ_ID_I2S3_EXT_TX   | 0x10              | DMAMUX_DMAREQ_ID_I2C1_RX       |
| 0x11              | DMAMUX_DMAREQ_ID_I2C1_TX       | 0x12              | DMAMUX_DMAREQ_ID_I2C2_RX       |
| 0x13              | DMAMUX_DMAREQ_ID_I2C2_TX       | 0x14              | DMAMUX_DMAREQ_ID_I2C3_RX       |
| 0x15              | DMAMUX_DMAREQ_ID_I2C3_TX       | 0x18              | DMAMUX_DMAREQ_ID_USART1_RX     |
| 0x19              | DMAMUX_DMAREQ_ID_USART1_TX     | 0x1A              | DMAMUX_DMAREQ_ID_USART2_RX     |
| 0x1B              | DMAMUX_DMAREQ_ID_USART2_TX     | 0x1C              | DMAMUX_DMAREQ_ID_USART3_RX     |
| 0x1D              | DMAMUX_DMAREQ_ID_USART3_TX     | 0x1E              | DMAMUX_DMAREQ_ID_UART4_RX      |
| 0x1F              | DMAMUX_DMAREQ_ID_UART4_TX      | 0x20              | DMAMUX_DMAREQ_ID_UART5_RX      |
| 0x21              | DMAMUX_DMAREQ_ID_UART5_TX      | 0x72              | DMAMUX_DMAREQ_ID_USART6_RX     |
| 0x73              | DMAMUX_DMAREQ_ID_USART6_TX     | 0x74              | DMAMUX_DMAREQ_ID_UART7_RX      |
| 0x75              | DMAMUX_DMAREQ_ID_UART7_TX      | 0x76              | DMAMUX_DMAREQ_ID_UART8_RX      |
| 0x77              | DMAMUX_DMAREQ_ID_UART8_TX      | 0x27              | DMAMUX_DMAREQ_ID_SDIO1         |
| 0x67              | DMAMUX_DMAREQ_ID_SDIO2         | 0x28              | DMAMUX_DMAREQ_ID_QSPI1         |
| 0x68              | DMAMUX_DMAREQ_ID_QSPI2         | 0x2A              | DMAMUX_DMAREQ_ID_TMR1_CH1      |
| 0x2B              | DMAMUX_DMAREQ_ID_TMR1_CH2      | 0x2C              | DMAMUX_DMAREQ_ID_TMR1_CH3      |
| 0x2D              | DMAMUX_DMAREQ_ID_TMR1_CH4      | 0x2E              | DMAMUX_DMAREQ_ID_TMR1_OVERFLOW |
| 0x2F              | DMAMUX_DMAREQ_ID_TMR1_TRIG     | 0x30              | DMAMUX_DMAREQ_ID_TMR1_HALL     |
| 0x31              | DMAMUX_DMAREQ_ID_TMR8_CH1      | 0x32              | DMAMUX_DMAREQ_ID_TMR8_CH2      |
| 0x33              | DMAMUX_DMAREQ_ID_TMR8_CH3      | 0x34              | DMAMUX_DMAREQ_ID_TMR8_CH4      |
| 0x35              | DMAMUX_DMAREQ_ID_TMR8_OVERFLOW | 0x36              | DMAMUX_DMAREQ_ID_TMR8_TRIG     |
| 0x37              | DMAMUX_DMAREQ_ID_TMR8_HALL     | 0x38              | DMAMUX_DMAREQ_ID_TMR2_CH1      |
| 0x39              | DMAMUX_DMAREQ_ID_TMR2_CH2      | 0x3A              | DMAMUX_DMAREQ_ID_TMR2_CH3      |
| 0x3B              | DMAMUX_DMAREQ_ID_TMR2_CH4      | 0x3C              | DMAMUX_DMAREQ_ID_TMR2_OVERFLOW |
| 0x7E              | DMAMUX_DMAREQ_ID_TMR2_TRIG     | 0x3D              | DMAMUX_DMAREQ_ID_TMR3_CH1      |
| 0x3E              | DMAMUX_DMAREQ_ID_TMR3_CH2      | 0x3F              | DMAMUX_DMAREQ_ID_TMR3_CH3      |
| 0x40              | DMAMUX_DMAREQ_ID_TMR3_CH4      | 0x41              | DMAMUX_DMAREQ_ID_TMR3_OVERFLOW |
| 0x42              | DMAMUX_DMAREQ_ID_TMR3_TRIG     | 0x43              | DMAMUX_DMAREQ_ID_TMR4_CH1      |
| 0x44              | DMAMUX_DMAREQ_ID_TMR4_CH2      | 0x45              | DMAMUX_DMAREQ_ID_TMR4_CH3      |
| 0x46              | DMAMUX_DMAREQ_ID_TMR4_CH4      | 0x47              | DMAMUX_DMAREQ_ID_TMR4_OVERFLOW |

| Request source ID | Description                 | Request source ID | Description                     |
|-------------------|-----------------------------|-------------------|---------------------------------|
| 0x7F              | DMAMUX_DMAREQ_ID_TMR4_TRIG  | 0x48              | DMAMUX_DMAREQ_ID_TMR5_CH1       |
| 0x49              | DMAMUX_DMAREQ_ID_TMR5_CH2   | 0x4A              | DMAMUX_DMAREQ_ID_TMR5_CH3       |
| 0x4B              | DMAMUX_DMAREQ_ID_TMR5_CH4   | 0x4C              | DMAMUX_DMAREQ_ID_TMR5_OVERFLOW  |
| 0x4D              | DMAMUX_DMAREQ_ID_TMR5_TRIG  | 0x56              | DMAMUX_DMAREQ_ID_TMR20_CH1      |
| 0x57              | DMAMUX_DMAREQ_ID_TMR20_CH2  | 0x58              | DMAMUX_DMAREQ_ID_TMR20_CH3      |
| 0x59              | DMAMUX_DMAREQ_ID_TMR20_CH4  | 0x5A              | DMAMUX_DMAREQ_ID_TMR20_OVERFLOW |
| 0x5D              | DMAMUX_DMAREQ_ID_TMR20_TRIG | 0x5E              | DMAMUX_DMAREQ_ID_TMR20_HALL     |
| 0x69              | DMAMUX_DMAREQ_ID_DVP        |                   |                                 |

**Example:**

```
/* tmr20 hall dmamuxfunction enable */
dma_flexible_config(DMA2, DMA1MUX_CHANNEL1, DMAMUX_DMAREQ_ID_TMR20_HALL);
```

### 5.8.11 dmamux\_enable function

The table below describes the function dmamux\_enable.

**Table 175. dmamux\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dmamux_enable   |
| Function prototype     | void dmamux_enable(dma_type *dma_x, confirm_state new_state); |
| Function description   | Enable DMAMUX feature   |
| Input parameter 1      | dma_x: DMAx, x=1 or 2   |
| Input parameter 2      | new_state: enable or disable a channel                        |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**new\_state**

Enable or disable a DMA channel

FALSE: Channel disabled

TRUE: Channel enabled

**Example:**

```
/* dmamuxfunction enable */
dmamux_enable(DMA2, TRUE);
```

### 5.8.12 dmamux\_init function

The table below describes the function dmamux\_init.

**Table 176. dmamux\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dmamux_init  |
| Function prototype     | void dmamux_init(dmamux_channel_type *dmamux_channelx, dmamux_reqst_id_sel_type dmamux_req_sel); |
| Function description   | Configure DMAMUX   |
| Input parameter 1      | <i>dmamux_channelx</i><br>:DMAMUX channel selection, x=1...7                                     |
| Input parameter 2      | <i>dmamux_req_sel</i><br>:DMAMUX channel request ID  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* generator1 for dmamuxchannel4 as dma request */
dmamux_init(DMA2MUX_CHANNEL4, DMAMUX_DMAREQ_ID_REQ_G1);
```

### 5.8.13 dmamux\_sync\_default\_para\_init function

The table below describes the function dmamux\_sync\_default\_para\_init.

**Table 177. dmamux\_sync\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dmamux_sync_default_para_init   |
| Function prototype     | void dmamux_sync_default_para_init(dmamux_sync_init_type *dmamux_sync_init_struct); |
| Function description   | Initialize the parameters in the dmamux_sync_init_struct                            |
| Input parameter 1      | dmamux_sync_init_struct: dmamux_sync_init_type pointer                              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The table below shows the default values of members in the dmamux\_sync\_init\_struct.

**Table 178. dmamux\_sync\_init\_struct default values**

| Member              | Default value                |
|---------------------|------------------------------|
| sync_enable         | FALSE                        |
| sync_event_enable   | FALSE                        |
| sync_polarity       | DMAMUX_SYNC_POLARITY_DISABLE |
| sync_request_number | 0x0                          |
| sync_signal_sel     | (dmamux_sync_id_sel_type)0   |

**Example:**

```

/* dmamuxsync init config with its default value */
dmamux_sync_init_type dmamux_sync_init_struct = {0};
dmamux_sync_default_para_init (&dmamux_sync_init_struct);
    
```

### 5.8.14 dmamux\_sync\_config function

The table below describes the function dmamux\_sync\_config.

**Table 179. dmamux\_sync\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dmamux_sync_config  |
| Function prototype     | void dmamux_sync_config(dmamux_channel_type *dmamux_channel, dmamux_sync_init_type *dmamux_sync_init_struct); |
| Function description   | Configure DMAMUX synchronous feature  |
| Input parameter 1      | <a href="#">dmamux_channelx</a><br>:DMAMUX channel selection, x=1...7   |
| Input parameter 2      | dmamux_sync_init_struct: dmamux_sync_init_type pointer  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### dmamux\_sync\_init\_struct

The dmamux\_sync\_init\_type is defined in the at32f435\_437\_dma.h.

typedef struct

```

{
    dmamux_sync_id_sel_type    sync_signal_sel;
    uint32_t                  sync_polarity;
    uint32_t                  sync_request_number;
    confirm_state             sync_event_enable;
    confirm_state             sync_enable;
} dmamux_sync_init_type;
    
```

#### sync\_signal\_sel

Select signal source for synchronous module.

```

DMAMUX_SYNC_ID_EXINT0:    External exint0 signal
DMAMUX_SYNC_ID_EXINT1:    External exint1 signal
DMAMUX_SYNC_ID_EXINT2:    External exint2 signal
DMAMUX_SYNC_ID_EXINT3:    External exint3 signal
DMAMUX_SYNC_ID_EXINT4:    External exint4 signal
DMAMUX_SYNC_ID_EXINT5:    External exint5 signal
DMAMUX_SYNC_ID_EXINT6:    External exint6 signal
DMAMUX_SYNC_ID_EXINT7:    External exint7 signal
DMAMUX_SYNC_ID_EXINT8:    External exint8 signal
DMAMUX_SYNC_ID_EXINT9:    External exint9 signal
DMAMUX_SYNC_ID_EXINT10:   External exint10 signal
DMAMUX_SYNC_ID_EXINT11:   External exint11 signal
DMAMUX_SYNC_ID_EXINT12:   External exint12 signal
    
```

DMAMUX\_SYNC\_ID\_EXINT13: External exint13 signal  
 DMAMUX\_SYNC\_ID\_EXINT14: External exint14 signal  
 DMAMUX\_SYNC\_ID\_EXINT15: External exint15 signal  
 DMAMUX\_SYNC\_ID\_DMAMUX\_CH1\_EVT: dmamux channel 1 event  
 DMAMUX\_SYNC\_ID\_DMAMUX\_CH2\_EVT: dmamux channel 2 event  
 DMAMUX\_SYNC\_ID\_DMAMUX\_CH3\_EVT: dmamux channel 3 event  
 DMAMUX\_SYNC\_ID\_DMAMUX\_CH4\_EVT: dmamux channel 4 event  
 DMAMUX\_SYNC\_ID\_DMAMUX\_CH5\_EVT: dmamux channel 5 event  
 DMAMUX\_SYNC\_ID\_DMAMUX\_CH6\_EVT: dmamux channel 6 event  
 DMAMUX\_SYNC\_ID\_DMAMUX\_CH7\_EVT: dmamux channel 7 event

**sync\_polarity**

Polarity selection for synchronous signal

DMAMUX\_SYNC\_POLARITY\_RISING: Rising edge  
 DMAMUX\_SYNC\_POLARITY\_FALLING: Falling edge  
 DMAMUX\_SYNC\_POLARITY\_RISING\_FALLING: Rising edge and falling edge

**sync\_request\_number**

The number of DMA requests that can be synchronized

Range: 1~32

**sync\_event\_enable**

Enable or disable synchronous event generation

TRUE: Synchronous event generated  
 FALSE: No synchronous event generated

**sync\_enable**

Enable or disable synchronous module

FALSE: Disabled  
 TRUE: Enabled

**Example:**

```
dmamux_sync_default_para_init(&dmamux_sync_init_struct);
dmamux_sync_init_struct.sync_request_number = 4;
dmamux_sync_init_struct.sync_signal_sel = DMAMUX_SYNC_ID_EXINT1;
dmamux_sync_init_struct.sync_polarity = DMAMUX_SYNC_POLARITY_RISING;
dmamux_sync_init_struct.sync_event_enable = TRUE;
dmamux_sync_init_struct.sync_enable = TRUE;
dmamux_sync_config(DMA2MUX_CHANNEL4, &dmamux_sync_init_struct);
```

### 5.8.15 dmamux\_generator\_default\_para\_init function

The table below describes the function dmamux\_generator\_default\_para\_init.

**Table 180. dmamux\_generator\_default\_para\_init function**

| Name                 | Description  |
|----------------------|--|
| Function name        | dmamux_generator_default_para_init   |
| Function prototype   | void dmamux_generator_default_para_init(dmamux_gen_init_type *dmamux_gen_init_struct); |
| Function description | Initialize the parameters of the dmamux_gen_init_struct                                |
| Input parameter 1    | dmamux_gen_init_struct: dmamux_gen_init_type pointer                                   |

| Name                   | Description |
|------------------------|-------------|
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

The below table shows the default values of members in the `dmamux_gen_init_struct`.

**Table 181. dmamux\_gen\_init\_struct default values**

| Member                          | Default value                            |
|---------------------------------|--|
| <code>gen_signal_sel</code>     | <code>(dmamux_gen_id_sel_type)0x0</code> |
| <code>gen_polarity</code>       | <code>DMAMUX_GEN_POLARITY_DISABLE</code> |
| <code>gen_request_number</code> | <code>0x0</code>                         |
| <code>gen_enable</code>         | <code>FALSE</code>                       |

Example:

```
/* dmamuxgen init config with its default value */
dmamux_gen_init_type dmamux_gen_init_struct = {0};
dmamux_gen_default_para_init(&dmamux_gen_init_struct);
```

### 5.8.16 dmamux\_generator\_config function

The table below describes the function `dmamux_generator_config`.

**Table 182. dmamux\_generator\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dmamux_generator_config</code>  |
| Function prototype     | <code>void dmamux_generator_config(dmamux_generator_type * dmamux_gen_x, dmamux_gen_init_type * dmamux_gen_init_struct);</code> |
| Function description   | Configure DMAMUX request generator feature  |
| Input parameter 1      | <a href="#"><i>dmamux_gen_x</i></a><br>: request generator channel  |
| Input parameter 2      | <code>dmamux_sync_init_struct</code> : <code>dmamux_sync_init_type</code> pointer   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### **dmamux\_gen\_x**

dma request generator channel selection

- DMA1MUX\_GENERATOR1
- DMA1MUX\_GENERATOR2
- DMA1MUX\_GENERATOR3
- DMA1MUX\_GENERATOR4
- DMA2MUX\_GENERATOR1
- DMA2MUX\_GENERATOR2
- DMA2MUX\_GENERATOR3
- DMA2MUX\_GENERATOR4

#### **dmamux\_sync\_init\_struct**

The `dmamux_gen_init_type` is defined in the `at32f435_437_dma.h`.

```
typedef struct
{
    dmamux_gen_id_sel_type      gen_signal_sel;
    uint32_t                   gen_polarity;
    uint32_t                   gen_request_number;
    confirm_state               gen_enable;
} dmamux_gen_init_type;
```

### **gen\_signal\_sel**

Select signal source for synchronous module

|                               |                         |
|-------------------------------|-------------------------|
| DMAMUX_GEN_ID_EXINT0:         | External exint0 singal  |
| DMAMUX_GEN_ID_EXINT1:         | External exint0 singal  |
| DMAMUX_GEN_ID_EXINT2:         | External exint2 singal  |
| DMAMUX_GEN_ID_EXINT3:         | External exint3 singal  |
| DMAMUX_GEN_ID_EXINT4:         | External exint4 singal  |
| DMAMUX_GEN_ID_EXINT5:         | External exint5 singal  |
| DMAMUX_GEN_ID_EXINT6:         | External exint6 singal  |
| DMAMUX_GEN_ID_EXINT7:         | External exint7 singal  |
| DMAMUX_GEN_ID_EXINT8:         | External exint8 singal  |
| DMAMUX_GEN_ID_EXINT9:         | External exint9 singal  |
| DMAMUX_GEN_ID_EXINT10:        | External exint10 singal |
| DMAMUX_GEN_ID_EXINT11:        | External exint11 singal |
| DMAMUX_GEN_ID_EXINT12:        | External exint12 singal |
| DMAMUX_GEN_ID_EXINT13:        | External exint13 singal |
| DMAMUX_GEN_ID_EXINT14:        | External exint14 singal |
| DMAMUX_GEN_ID_EXINT15:        | External exint15 singal |
| DMAMUX_GEN_ID_DMAMUX_CH1_EVT: | dmamux channel 1 event  |
| DMAMUX_GEN_ID_DMAMUX_CH2_EVT: | dmamux channel 2 event  |
| DMAMUX_GEN_ID_DMAMUX_CH3_EVT: | dmamux channel 3 event  |
| DMAMUX_GEN_ID_DMAMUX_CH4_EVT: | dmamux channel 4 event  |
| DMAMUX_GEN_ID_DMAMUX_CH5_EVT: | dmamux channel 5 event  |
| DMAMUX_GEN_ID_DMAMUX_CH6_EVT: | dmamux channel 6 event  |
| DMAMUX_GEN_ID_DMAMUX_CH7_EVT: | dmamux channel 7 event  |

### **gen\_polarity**

Polarity selection for request generator signal

|                                     |                              |
|-------------------------------------|------------------------------|
| DMAMUX_GEN_POLARITY_RISING:         | Rising edge                  |
| DMAMUX_GEN_POLARITY_FALLING:        | Falling edge                 |
| DMAMUX_GEN_POLARITY_RISING_FALLING: | Rising edge and falling edge |

### **gen\_request\_number**

The number of DMA requests that are generated by request generator

Range: 1~32

### **gen\_enable**

Enable or disable request generator

FALSE: Disabled

TRUE: Enabled

### **Example:**



```

/* genertor1 configuration */
dmamux_generator_default_para_init(&dmamux_gen_init_struct);
dmamux_gen_init_struct.gen_polarity= DMAMUX_GEN_POLARITY_RISING;
dmamux_gen_init_struct.gen_request_number = 4;
dmamux_gen_init_struct.gen_signal_sel = DMAMUX_GEN_ID_EXINT1;
dmamux_gen_init_struct.gen_enable = TRUE;
dmamux_generator_config(DMA2MUX_GENERATOR1, &dmamux_gen_init_struct);
    
```

### 5.8.17 dmamux\_sync\_interrupt\_enable function

The table below describes the function dmamux\_sync\_interrupt\_enable.

**Table 183. dmamux\_sync\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dmamux_sync_interrupt_enable  |
| Function prototype     | void dmamux_sync_interrupt_enable(dmamux_channel_type *dmamux_channelx, confirm_state new_state); |
| Function description   | Enable synchronous module overflow interrupt  |
| Input parameter 1      | <i>dmamux_channelx</i><br>:DMAMUX channel selection, x=1...7                                      |
| Input parameter 2      | new_state: enable or disable interrupts   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**new\_state**

Enable or disable DMA channel interrupts

FALSE: Interrupt disabled

TRUE: Interrupt enabled

**Example:**

```

/* enable sync overrun interrupt */
dmamux_sync_interrupt_enable (DMA2MUX_CHANNEL1, TRUE);
    
```

### 5.8.18 dmamux\_generator\_interrupt\_enable function

The table below describes the function dmamux\_generator\_interrupt\_enable.

**Table 184. dmamux\_generator\_interrupt\_enable function**

| Name                 | Description   |
|----------------------|---|
| Function name        | dmamux_generator_interrupt_enable   |
| Function prototype   | void dmamux_generator_interrupt_enable(dmamux_generator_type *dmamux_gen_x, confirm_state new_state); |
| Function description | Enable request generator overflow interrupt   |
| Input parameter 1    | <i>dmamux_gen_x</i><br>:DMAMUX request generator channel selection, x=1...4                           |
| Input parameter 2    | new_state: enable or disable interrupts   |

| Name                   | Description |
|------------------------|-------------|
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**new\_state**

Enable or disable request generator channel interrupts

FALSE: Interrupt disabled

TRUE: Interrupt enabled

**Example:**

```
/* enable gen overrun interrupt */
dmamux_generator_interrupt_enable(DMA2MUX_GENERATOR3, TRUE);
```

### 5.8.19 dmamux\_sync\_flag\_get function

The table below describes the function dmamux\_sync\_flag\_get.

**Table 185. dmamux\_sync\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dmamux_sync_flag_get  |
| Function prototype     | flag_status dmamux_sync_flag_get(dma_type *dma_x, uint32_t flag); |
| Function description   | Get dmamuxsynchronous flag  |
| Input parameter 1      | dma_x: DMAx, x=1 or 2   |
| Input parameter 2      | flag: flag selection  |
| Output parameter       | NA  |
| Return value           | flag_status: indicates whether or not the selected flag is set    |
| Required preconditions | NA  |
| Called functions       | NA  |

**flag**

This is used for flag selection, including:

DMAMUX\_SYNC\_OV1\_FLAG

DMAMUX\_SYNC\_OV2\_FLAG

DMAMUX\_SYNC\_OV3\_FLAG

DMAMUX\_SYNC\_OV4\_FLAG

DMAMUX\_SYNC\_OV5\_FLAG

DMAMUX\_SYNC\_OV6\_FLAG

DMAMUX\_SYNC\_OV7\_FLAG

**flag\_status**

RESET: Corresponding flag is not set

SET: Corresponding flag is set

**Example:**

```
if(dmamux_sync_flag_get(DMA2, DMAMUX_SYNC_OV1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
```

```

at32_led_on(LED3);
at32_led_on(LED4);
}

```

### 5.8.20 dmamux\_sync\_flag\_clear function

The table below describes the function dmamux\_sync\_flag\_clear.

**Table 186. dmamux\_sync\_flag\_clear function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dmamux_sync_flag_clear                                       |
| Function prototype     | void dmamux_sync_flag_clear(dma_type *dma_x, uint32_t flag); |
| Function description   | Clear synchronous module flag                                |
| Input parameter 1      | dma_x: DMAx, x=1 or 2  |
| Input parameter 2      | flag: flag selection   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**flag**

This is used for flag selection, including:

- DMAMUX\_SYNC\_OV1\_FLAG
- DMAMUX\_SYNC\_OV2\_FLAG
- DMAMUX\_SYNC\_OV3\_FLAG
- DMAMUX\_SYNC\_OV4\_FLAG
- DMAMUX\_SYNC\_OV5\_FLAG
- DMAMUX\_SYNC\_OV6\_FLAG
- DMAMUX\_SYNC\_OV7\_FLAG

**Example:**

```

if(dmamux_sync_flag_get(DMA2, DMAMUX_SYNC_OV1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
    dmamux_sync_flag_clear(DMA2, DMAMUX_SYNC_OV1_FLAG);
}

```

## 5.8.21 dmamux\_generator\_flag\_get function

The table below describes the function dmamux\_generator\_flag\_get.

**Table 187. dmamux\_generator\_flag\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dmamux_generator_flag_get  |
| Function prototype     | flag_status dmamux_generator_flag_get(dma_type *dma_x, uint32_t flag); |
| Function description   | Get dmamuxrequest generator flag                                       |
| Input parameter 1      | dma_x: DMAx, x=1 or 2  |
| Input parameter 2      | flag: flag selection   |
| Output parameter       | NA   |
| Return value           | flag_status: indicates whether or not the selected flag is set         |
| Required preconditions | NA   |
| Called functions       | NA   |

### flag

This is used for flag selection, including:

DMAMUX\_GEN\_TRIG\_OV1\_FLAG

DMAMUX\_GEN\_TRIG\_OV2\_FLAG

DMAMUX\_GEN\_TRIG\_OV3\_FLAG

DMAMUX\_GEN\_TRIG\_OV4\_FLAG

### flag\_status

RESET: Corresponding flag is not set

SET: Corresponding flag is set

### Example:

```

if(dmamux_generator_flag_get(DMA2, DMAMUX_GEN_TRIG_OV1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
}
    
```

## 5.8.22 dmamux\_generator\_flag\_clear function

The table below describes the function dmamux\_generator\_flag\_clear.

**Table 188. dmamux\_generator\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dmamux_generator_flag_clear                                       |
| Function prototype     | void dmamux_generator_flag_clear(dma_type *dma_x, uint32_t flag); |
| Function description   | Clear request generator flag                                      |
| Input parameter 1      | dma_x: DMAx, x=1 or 2   |
| Input parameter 2      | flag: flag selection  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### flag

This is used for flag selection, including:

DMAMUX\_GEN\_TRIG\_OV1\_FLAG

DMAMUX\_GEN\_TRIG\_OV2\_FLAG

DMAMUX\_GEN\_TRIG\_OV3\_FLAG

DMAMUX\_GEN\_TRIG\_OV4\_FLAG

### Example:

```

if(dmamux_generator_flag_get(DMA2, DMAMUX_GEN_TRIG_OV1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
    dmamux_generator_flag_clear(DMA2, DMAMUX_GEN_TRIG_OV1_FLAG);
}
    
```

## 5.9 Digital video parallel interface (DVP)

The DVP register structure `dvp_type` is defined in the “at32f435\_437\_dvp.h”.

```
/**
 * @brief type define dvp register all
 */
typedef struct
{

} dvp_type;
```

The table below gives a list of the DVP registers.

**Table 189. Summary of DVP registers**

| Register | Description                                     |
|----------|---|
| ctrl     | DVP control register                            |
| sts      | DVP status register                             |
| ests     | DVP event status register                       |
| iena     | DVP interrupt enable register                   |
| ists     | DVP interrupt status register                   |
| iclr     | DVP interrupt clear register                    |
| scr      | DVP embedded synchronization code register      |
| sur      | DVP mbedded synchronization unmask register     |
| cwst     | DVP crop window start register                  |
| cwsz     | DVP crop window size register                   |
| dt       | DVP data register                               |
| actrl    | DVP advanced control register                   |
| hscf     | DVP enhanced horizontal scaling factor register |
| vscf     | DVP enhanced vertical scaling factor register   |
| frf      | DVP enhanced frame rate control factor register |
| bth      | DVP binarization threshold register             |

The table below gives a list of DVP library functions.

**Table 190. Summary of CVP library functions**

| Function name                       | Description                                 |
|-------------------------------------|---|
| <code>dvp_reset</code>              | Reset DVP by CRM reset register             |
| <code>dvp_capture_enable</code>     | Enable/disable DVP capture                  |
| <code>dvp_capture_mode_set</code>   | Configure DVP capture mode                  |
| <code>dvp_window_crop_enable</code> | Enable/disable DVP crop window              |
| <code>dvp_window_crop_set</code>    | Configure DVP crop window                   |
| <code>dvp_jpeg_enable</code>        | Enable/disable DVP JPEG mode                |
| <code>dvp_sync_mode_set</code>      | Configure DVP synchronization mode          |
| <code>dvp_sync_code_set</code>      | Configure DVP embedded synchronization code |
| <code>dvp_sync_unmask_set</code>    | Configure DVP synchronization code unmask   |

|                                       |   |
|---------------------------------------|---|
| dvp_pclk_polarity_set                 | Configure DVP pixel clock polarity                        |
| dvp_hsync_polarity_set                | Configure DVP horizontal synchronization polarity         |
| dvp_vsync_polarity_set                | Configure DVP vertical synchronization polarity           |
| dvp_basic_frame_rate_control_set      | Configure DVP basic frame rate control                    |
| dvp_pixel_data_length_set             | Configure DVP pixel data length                           |
| dvp_enable                            | Enable/disable DVP  |
| dvp_zoomout_select                    | Configure the basic pixel capture/drop extended selection |
| dvp_zoomout_set                       | Configure DVP capture/drop feature                        |
| dvp_basic_status_get                  | Get the DVP basic status                                  |
| dvp_interrupt_enable                  | Enable/disable DVP interrupts                             |
| dvp_flag_get                          | Get DVP event/interrupt flag                              |
| dvp_flag_clear                        | Clear DVP event/interrupt flag                            |
| dvp_enhanced_scaling_resize_enable    | Enable/disable DVP enhanced image reduction feature       |
| dvp_enhanced_scaling_resize_set       | Configure the DVP enhanced image reduction size           |
| dvp_enhanced_framerate_set            | Configure enhanced frame rate control feature             |
| dvp_monochrome_image_binarization_set | Configure DVP monochrome image binarization threshold     |
| dvp_enhanced_data_format_set          | Configure DVP enhanced function data format               |
| dvp_input_data_unused_set             | Configure DVP input data unused setting and bit number    |
| dvp_dma_burst_set                     | Configure DVP burst DMA transfer                          |
| dvp_sync_event_interrupt_set          | Configure DVP HSYNC/VSNC event and interrupt definition   |

### 5.9.1 dvp\_reset function

The table below describes the function dvp\_reset.

**Table 191. dvp\_reset function**

| Name                   | Description                     |
|------------------------|---------------------------------|
| Function name          | dvp_reset                       |
| Function prototype     | void dvp_reset(void);           |
| Function description   | Reset DVP by CRM reset register |
| Input parameter        | NA                              |
| Output parameter       | NA                              |
| Return value           | NA                              |
| Required preconditions | NA                              |
| Called functions       | crm_periph_reset();             |

**Example:**

```
dvp_reset();
```

## 5.9.2 dvp\_capture\_enable function

The table below describes the function `dvp_capture_enable`.

**Table 192. dvp\_capture\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_capture_enable</code>                                |
| Function prototype     | <code>void dvp_capture_enable(confirm_state new_state);</code> |
| Function description   | Enable/disable DVP capture                                     |
| Input parameter        | <code>new_state</code> : Enable (TRUE) or disable (FALSE)      |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
dvp_capture_enable(TRUE);
```

## 5.9.3 dvp\_capture\_mode\_set function

The table below describes the function `dvp_capture_mode_set`.

**Table 193. dvp\_capture\_mode\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_capture_mode_set</code>                              |
| Function prototype     | <code>void dvp_capture_mode_set(dvp_cfm_type cap_mode);</code> |
| Function description   | Configure DVP capture mode                                     |
| Input parameter        | <code>cap_mode</code> : DVP capture mode                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**cap\_mode**

This is used to configure the DVP capture mode.

DVP\_CAP\_FUNC\_MODE\_CONTINUOUS: Continuous capture mode

DVP\_CAP\_FUNC\_MODE\_SINGLE: Single frame capture mode

**Example:**

```
dvp_capture_mode_set(DVP_CAP_FUNC_MODE_CONTINUOUS);
```

## 5.9.4 dvp\_window\_crop\_enable function

The table below describes the function `dvp_window_crop_enable`.

**Table 194. dvp\_window\_crop\_enable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>dvp_window_crop_enable</code>                                |
| Function prototype   | <code>void dvp_window_crop_enable(confirm_state new_state);</code> |
| Function description | Enable/disable DVP crop window                                     |



| Name                   | Description                                 |
|------------------------|---|
| Input parameter        | new_state: Enable (TRUE) or disable (FALSE) |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
dvp_window_crop_enable(TRUE);
```

## 5.9.5 dvp\_window\_crop\_set function

The table below describes the function dvp\_window\_crop\_set.

**Table 195. dvp\_window\_crop\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | dvp_window_crop_set  |
| Function prototype     | void dvp_window_crop_set(uint16_t crop_x, uint16_t crop_y, uint16_t crop_w, uint16_t crop_h, uint8_t bytes);   |
| Function description   | Configure DVP crop window  |
| Input parameter 1      | crop_x: Crop window horizontal start pixel, range: 0x0000~0x3FFF/bytes   |
| Input parameter 2      | crop_y: Crop window vertical start pixel, range: 0x0000~0x1FFF   |
| Input parameter 3      | crop_w: Crop window horizontal pixel number minus one, range: 0x0001~(0x40000)/bytes   |
| Input parameter 4      | crop_h: Crop window vertical line number minus one, range: 0x0001~0x40000  |
| Input parameter 5      | bytes: number of bytes of one pixel, for example, in Y8 format, one pixel corresponds to 1 byte, therefore bytes = 1; in RGB565 format, one pixel corresponds to 2 bytes, therefore bytes = 2. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
dvp_window_crop_set(0x0F, 0x0F, 0x100, 0x100, 0x02);
```

## 5.9.6 dvp\_jpeg\_enable function

The table below describes the function dvp\_jpeg\_enable.

**Table 196. dvp\_jpeg\_enable function**

| Name                   | Description                                    |
|------------------------|--|
| Function name          | dvp_jpeg_enable                                |
| Function prototype     | void dvp_jpeg_enable(confirm_state new_state); |
| Function description   | Enable/disable DVP JPEG mode                   |
| Input parameter        | new_state: Enable (TRUE) or disable (FALSE)    |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |

| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**Example:**

```
dvp_jpeg_enable(TRUE);
```

## 5.9.7 dvp\_sync\_mode\_set function

The table below describes the function `dvp_sync_mode_set`.

**Table 197. dvp\_sync\_mode\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_sync_mode_set</code>                              |
| Function prototype     | <code>void dvp_sync_mode_set(dvp_sm_type sync_mode);</code> |
| Function description   | Configure DVP synchronization mode                          |
| Input parameter        | <code>sync_mode</code> : DVP synchronization mode           |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**sync\_mode**

This is used to select the DVP synchronization mode.

DVP\_SYNC\_MODE\_HARDWARE: Hardware synchronization

DVP\_SYNC\_MODE\_EMBEDDED: Embedded code synchronization

**Example:**

```
dvp_sync_mode_set(DVP_SYNC_MODE_HARDWARE);
```

## 5.9.8 dvp\_sync\_code\_set function

The table below describes the function `dvp_sync_code_set`.

**Table 198. dvp\_sync\_code\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_sync_code_set</code>   |
| Function prototype     | <code>void dvp_sync_code_set(uint8_t fmsc, uint8_t fmec, uint8_t lmsc, uint8_t lnec);</code> |
| Function description   | Configure DVP embedded code synchronization  |
| Input parameter 1      | <code>fmsc</code> : Frame start synchronization code, range: 0x00~0xFF                       |
| Input parameter 2      | <code>fmec</code> : Frame end synchronization code, range: 0x00~0xFF                         |
| Input parameter 3      | <code>lmsc</code> : Line start synchronization code, range: 0x00~0xFF                        |
| Input parameter 4      | <code>lnec</code> : Line end synchronization code, range: 0x00~0xFF                          |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
dvp_sync_code_set(0xFF, 0xFF, 0xC7, 0xDA);
```

### 5.9.9 dvp\_sync\_unmask\_set function

The table below describes the function `dvp_sync_unmask_set`.

**Table 199. dvp\_sync\_unmask\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_sync_unmask_set</code>  |
| Function prototype     | <code>void dvp_sync_unmask_set(uint8_tfmsu, uint8_fmeh, uint8_tlnsu, uint8_tlneu);</code> |
| Function description   | Configure DVP embedded synchronization code unmask  |
| Input parameter 1      | fmsu: Frame start synchronization code unmask, range: 0x00~0xFF                           |
| Input parameter 2      | fmeu: Frame end synchronization code unmask, range: 0x00~0xFF                             |
| Input parameter 3      | lnsu: Line start synchronization code unmask, range: 0x00~0xFF                            |
| Input parameter 4      | lneu: Line end synchronization code unmask, range: 0x00~0xFF                              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
dvp_sync_unmask_set(0x0F, 0x0F, 0xF0, 0xF0);
```

### 5.9.10 dvp\_pclk\_polarity\_set function

The table below describes the function `dvp_pclk_polarity_set`.

**Table 200. dvp\_pclk\_polarity\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_pclk_polarity_set</code>                          |
| Function prototype     | <code>void dvp_pclk_polarity_set(dvp_ckp_type eage);</code> |
| Function description   | Configure DVP pixel clock polarity                          |
| Input parameter        | eage: DVP pixel clock polarity                              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**eage**

This is used to select the DVP pixel clock polarity.

DVP\_CLK\_POLARITY\_RISING: Input data capture on DVP\_PCLK rising edge

DVP\_CLK\_POLARITY\_FALLING: Input data capture on DVP\_PCLK falling edge

**Example:**

```
dvp_pclk_polarity_set(DVP_CLK_POLARITY_RISING);
```

### 5.9.11 dvp\_hsync\_polarity\_set function

The table below describes the function `dvp_hsync_polarity_set`.

**Table 201. dvp\_hsync\_polarity\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_hsync_polarity_set</code>                               |
| Function prototype     | <code>void dvp_hsync_polarity_set(dvp_hsp_type hsync_pol);</code> |
| Function description   | Configure DVP horizontal synchronization polarity                 |
| Input parameter        | <code>hsync_pol</code> : DVP horizontal synchronization polarity  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### **hsync\_pol**

This is used to select the DVP horizontal synchronization polarity.

`DVP_HSYNC_POLARITY_HIGH`: `DVP_HSYNC` high level indicates that the captured data is a valid pixel data, and Line start signal on the rising edge

`DVP_HSYNC_POLARITY_LOW`: `DVP_HSYNC` low level indicates that the captured data is a valid pixel data, and Line start signal on the falling edge

#### **Example:**

```
dvp_hsync_polarity_set(DVP_HSYNC_POLARITY_HIGH);
```

### 5.9.12 dvp\_vsync\_polarity\_set function

The table below describes the function `dvp_vsync_polarity_set`.

**Table 202. dvp\_vsync\_polarity\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_vsync_polarity_set</code>                               |
| Function prototype     | <code>void dvp_vsync_polarity_set(dvp_vsp_type vsync_pol);</code> |
| Function description   | Configure DVP vertical synchronization polarity                   |
| Input parameter        | <code>vsync_pol</code> : DVP vertical synchronization polarity    |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### **vsync\_pol**

This is used to select DVP vertical synchronization polarity.

Frame start:

`DVP_VSYNC_POLARITY_LOW`: `DVP_VSYNC` low level indicates a Frame start signal

`DVP_VSYNC_POLARITY_HIGH`: `DVP_VSYNC` high level indicates a Frame start signal

Frame effective:

`DVP_VSYNC_POLARITY_LOW`: `DVP_VSYNC` low level indicates that the captured data is in vertical blanking

`DVP_VSYNC_POLARITY_HIGH`: `DVP_VSYNC` high level indicates that the captured data is in vertical blanking

**Example:**

```
dvp_vsync_polarity_set(DVP_VSYNC_POLARITY_LOW);
```

### 5.9.13 dvp\_basic\_frame\_rate\_control\_set function

The table below describes the function `dvp_basic_frame_rate_control_set`.

**Table 203. dvp\_basic\_frame\_rate\_control\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_basic_frame_rate_control_set</code>                               |
| Function prototype     | <code>void dvp_basic_frame_rate_control_set(dvp_bfrc_type dvp_bfrc);</code> |
| Function description   | Configure DVP basic frame rate control                                      |
| Input parameter        | <code>dvp_bfrc</code> : DVP basic frame rate control                        |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**dvp\_bfrc**

This is used to select DVP basic frame rate control.

`DVP_BFRC_ALL`: All frames are captured or use enhanced frame rate control feature

`DVP_BFRC_HALF`: Enable frame rate control, every alternate frame captured

`DVP_BFRC_QUARTER`: Enable frame rate control, one frame in 4 frames captured

**Example:**

```
dvp_basic_frame_rate_control_set(DVP_BFRC_ALL);
```

### 5.9.14 dvp\_pixel\_data\_length\_set function

The table below describes the function `dvp_pixel_data_length_set`.

**Table 204. dvp\_pixel\_data\_length\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_pixel_data_length_set</code>                             |
| Function prototype     | <code>void dvp_pixel_data_length_set(dvp_pdl_type dvp_pdl);</code> |
| Function description   | Configure DVP pixel data length                                    |
| Input parameter        | <code>dvp_pdl</code> : DVP pixel data length                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**dvp\_pdl**

This is used to select DVP pixel data length.

`DVP_PIXEL_DATA_LENGTH_8`: Interface captures 8-bit data

`DVP_PIXEL_DATA_LENGTH_10`: Interface captures 10-bit data

`DVP_PIXEL_DATA_LENGTH_12`: Interface captures 12-bit data

`DVP_PIXEL_DATA_LENGTH_14`: Interface captures 14-bit data

**Example:**

```
dvp_pixel_data_length_set(DVP_PIXEL_DATA_LENGTH_8);
```

### 5.9.15 dvp\_enable function

The table below describes the function dvp\_enable.

**Table 205. dvp\_enable function**

| Name                   | Description                                 |
|------------------------|---|
| Function name          | dvp_enable                                  |
| Function prototype     | void dvp_enable(confirm_state new_state);   |
| Function description   | Enable/disable DVP                          |
| Input parameter        | new_state: Enable (TRUE) or disable (FALSE) |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
dvp_enable(TRUE);
```

### 5.9.16 dvp\_zoomout\_select function

The table below describes the function dvp\_zoomout\_select.

**Table 206. dvp\_zoomout\_select function**

| Name                   | Description   |
|------------------------|---|
| Function name          | dvp_zoomout_select  |
| Function prototype     | void dvp_zoomout_select(dvp_pcdes_type dvp_pcdes);        |
| Function description   | Configure the basic pixel capture/drop extended selection |
| Input parameter        | dvp_pcdes: extended DVP pixel capture/drop configuration  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**dvp\_pcdes**

This is used for the basic pixel capture/drop extended selection.

PCDS = 0:

DVP\_PCDES\_CAP\_FIRST: Capture the first pixel data and drop others

DVP\_PCDES\_DROP\_FIRST: Capture the second pixel data and drop others

PCDS = 1:

DVP\_PCDES\_CAP\_FIRST: Capture the third pixel data and drop others

DVP\_PCDES\_DROP\_FIRST: Capture the fourth pixel data and drop others

**Example:**

```
dvp_zoomout_select(DVP_PCDES_CAP_FIRST);
```

### 5.9.17 dvp\_zoomout\_set function

The table below describes the function `dvp_zoomout_set`.

**Table 207. dvp\_zoomout\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_zoomout_set</code>   |
| Function prototype     | <code>void dvp_zoomout_set(dvp_pcdc_type dvp_pcdc, dvp_pcds_type dvp_pcds, dvp_lcdc_type dvp_lcdc, dvp_lcds_type dvp_lcds);</code> |
| Function description   | Configure DVP capture/drop feature   |
| Input parameter 1      | <code>dvp_pcdc</code> : basic pixel capture/drop control   |
| Input parameter 2      | <code>dvp_pcds</code> : basic pixel capture/drop selection   |
| Input parameter 3      | <code>dvp_lcdc</code> : basic line capture/drop control  |
| Input parameter 4      | <code>dvp_lcds</code> : basic line capture/drop selection  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **dvp\_pcdc**

This is used to select basic pixel capture/drop control.

`DVP_PCDC_ALL`: All frames are captured or use enhanced image scaling resize feature

`DVP_PCDC_ONE_IN_TWO`: Enable capture/drop control to capture one in two pixel data

`DVP_PCDC_ONE_IN_FOUR`: Enable capture/drop control to capture one in four pixel data

`DVP_PCDC_TWO_IN_FOUR`:

Enable capture/drop control to capture two consecutive data in four pixel data

#### **dvp\_pcds**

This is used for basic pixel capture/drop selection.

`DVP_PCDS_CAP_FIRST`:

Capture the first group of data (one or two pixel data) and drop the next group

`DVP_PCDS_DROP_FIRST`:

Drop the first group of data (one or two pixel data) and capture the next group

#### **dvp\_lcdc**

This is used for basic line capture/drop control.

`DVP_LCDC_ALL`:

All frames are captured or use enhanced image scaling resize feature

`DVP_LCDC_ONE_IN_TWO`:

Enable capture/drop control to capture one in two lines

#### **dvp\_lcds**

This is used for basic line capture/drop selection.

`DVP_LCDS_CAP_FIRST`:

Capture the first line and drop the next line

`DVP_LCDS_DROP_FIRST`:

Drop the first line and capture the first line

#### **Example:**

```
dvp_zoomout_set(DVP_PCDC_ONE_IN_TWO, DVP_PCDS_CAP_FIRST, DVP_LCDC_ONE_IN_TWO,
DVP_LCDS_CAP_FIRST);
```

### 5.9.18 dvp\_basic\_status\_get function

The table below describes the function `dvp_basic_status_get`.

**Table 208. dvp\_basic\_status\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_basic_status_get</code>  |
| Function prototype     | <code>flag_status dvp_basic_status_get(dvp_status_basic_type dvp_status_basic);</code> |
| Function description   | Get the DVP basic status   |
| Input parameter        | <code>dvp_status_basic</code> : DVP basic status                                       |
| Output parameter       | NA   |
| Return value           | Return SET or RESET.   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **dvp\_status\_basic**

This is used to select the DVP basic status.

DVP\_STATUS\_HSYN: Horizontal synchronization status

DVP\_STATUS\_VSYN: Vertical synchronization status

DVP\_STATUS\_OFNE: Output data FIFO status

#### **Example:**

```
flag_status dvp_status;
dvp_status = dvp_basic_status_get(DVP_STATUS_HSYN);
```

### 5.9.19 dvp\_interrupt\_enable function

The table below describes the function `dvp_interrupt_enable`.

**Table 209. dvp\_interrupt\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_interrupt_enable</code>  |
| Function prototype     | <code>void dvp_interrupt_enable(uint32_t dvp_int, confirm_state new_state);</code> |
| Function description   | Enable/disable DVP interrupt   |
| Input parameter 1      | <code>dvp_int</code> : DVP interrupt   |
| Input parameter 2      | <code>new_state</code> : Enable (TRUE) or disable (FALSE)                          |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **dvp\_int**

This is used to select the DVP interrupt.

DVP\_CFD\_INT: DVP capture frame done interrupt

DVP\_OVR\_INT: DVP output data FIFO overrun interrupt

DVP\_ESE\_INT: DVP embedded synchronization error interrupt

DVP\_VS\_INT: DVP Vertical synchronization interrupt

DVP\_HS\_INT: DVP horizontal synchronization interrupt

#### **Example:**

```
dvp_interrupt_enable(DVP_CFD_INT, TRUE);
```



## 5.9.20 dvp\_flag\_get function

The table below describes the function `dvp_flag_get`.

**Table 210. dvp\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_flag_get</code>                             |
| Function prototype     | <code>flag_status dvp_flag_get(uint32_t flag);</code> |
| Function description   | Get the DVP event/interrupt flag                      |
| Input parameter        | flag: DVP event/interrupt flag                        |
| Output parameter       | NA  |
| Return value           | Return SET or RESET.                                  |
| Required preconditions | NA  |
| Called functions       | NA  |

### flag

This is used to select the DVP event/interrupt flag.

DVP\_CFD\_EVT\_FLAG: Capture frame done raw event status

DVP\_OVR\_EVT\_FLAG: Output data FIFO overrun event status

DVP\_ESE\_EVT\_FLAG: Embedded synchronization error event status

DVP\_VS\_EVT\_FLAG: Vertical synchronization event status

DVP\_HS\_EVT\_FLAG: Horizontal synchronization event status

DVP\_CFD\_INT\_FLAG: Capture frame done interrupt status

DVP\_OVR\_INT\_FLAG: Output data FIFO overrun interrupt status

DVP\_ESE\_INT\_FLAG: Embedded synchronization error interrupt status

DVP\_VS\_INT\_FLAG: Vertical synchronization interrupt status

DVP\_HS\_INT\_FLAG: Horizontal synchronization interrupt status

### Example:

```
flag_status dvp_flag;
dvp_flag = dvp_flag_get(DVP_CFD_EVT_FLAG);
```

## 5.9.21 dvp\_flag\_clear function

The table below describes the function `dvp_flag_clear`.

**Table 211. dvp\_flag\_clear function function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_flag_clear</code>   |
| Function prototype     | <code>void dvp_flag_clear(uint32_t flag);</code>                    |
| Function description   | Clear DVP event/ interrupt flag                                     |
| Input parameter        | flag: DVP event/ interrupt flag to be cleared; refer to <i>flag</i> |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### Example:

```
dvp_flag_clear(DVP_CFD_EVT_FLAG);
```

### 5.9.22 dvp\_enhanced\_scaling\_resize\_enable function

The table below describes the function `dvp_enhanced_scaling_resize_enable`.

**Table 212. dvp\_enhanced\_scaling\_resize\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_enhanced_scaling_resize_enable</code>                                |
| Function prototype     | <code>void dvp_enhanced_scaling_resize_enable(confirm_state new_state);</code> |
| Function description   | Enable/disable DVP enhanced scaling resize feature                             |
| Input parameter        | <code>new_state</code> : Enable (TRUE) or disable (FALSE)                      |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
dvp_enhanced_scaling_resize_enable(TRUE);
```

### 5.9.23 dvp\_enhanced\_scaling\_resize\_set function

The table below describes the function `dvp_enhanced_scaling_resize_set`.

**Table 213. dvp\_enhanced\_scaling\_resize\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_enhanced_scaling_resize_set</code>   |
| Function prototype     | <code>void dvp_enhanced_scaling_resize_set(uint16_t src_w, uint16_t des_w, uint16_t src_h, uint16_t des_h);</code> |
| Function description   | Configure the DVP enhanced scaling resize  |
| Input parameter 1      | <code>src_w</code> : Horizontal scaling resize source factor, range: 0x0001~0x1FFF                                 |
| Input parameter 2      | <code>des_w</code> : Horizontal scaling resize target factor, range: 0x0001~0x1FFF                                 |
| Input parameter 3      | <code>src_h</code> : Vertical scaling resize source factor, range: 0x0001~0x1FFF                                   |
| Input parameter 4      | <code>des_h</code> : Vertical scaling resize target factor, range: 0x0001~0x1FFF                                   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
dvp_enhanced_scaling_resize_set(0xFFFF, 0x0F, 0xFFFF, 0x0F);
```

### 5.9.24 dvp\_enhanced\_framerate\_set function

The table below describes the function `dvp_enhanced_framerate_set`.

**Table 214. dvp\_enhanced\_framerate\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_enhanced_framerate_set</code>  |
| Function prototype     | <code>void dvp_enhanced_framerate_set(uint16_t efrcsf, uint16_t efrctf, confirm_state new_state);</code> |
| Function description   | Configure the enhanced frame rate control  |
| Input parameter 1      | <code>efrcsf</code> : Enhanced frame rate control source factor, range: 0x00~0x1F                        |
| Input parameter 2      | <code>efrcf</code> : Enhanced frame rate control target factor, range: 0x00~0x1F                         |
| Input parameter 3      | <code>new_state</code> : Enable (TRUE) or disable (FALSE)  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
dvp_enhanced_framerate_set(0x0F, 0x0F , TRUE);
```

### 5.9.25 dvp\_monochrome\_image\_binarization\_set function

The table below describes the function `dvp_monochrome_image_binarization_set`.

**Table 215. dvp\_monochrome\_image\_binarization\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_monochrome_image_binarization_set</code>  |
| Function prototype     | <code>void dvp_monochrome_image_binarization_set(uint8_t mibthd, confirm_state new_state);</code>             |
| Function description   | Configure the DVP monochrome image binarization threshold   |
| Input parameter 1      | <code>mibthd</code> : DVP monochrome image binarization threshold, range: 0x00~0xFF                           |
| Input parameter 2      | <code>new_state</code> : DVP monochrome image binarization threshold status; enable (TRUE) or disable (FALSE) |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
dvp_monochrome_image_binarization_set(0x0F, TRUE);
```

### 5.9.26 dvp\_enhanced\_data\_format\_set function

The table below describes the function `dvp_enhanced_data_format_set`.

**Table 216. dvp\_enhanced\_data\_format\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_enhanced_data_format_set</code>                               |
| Function prototype     | <code>void dvp_enhanced_data_format_set(dvp_efdf_type dvp_efdf);</code> |
| Function description   | Configure the DVP enhanced function data format                         |
| Input parameter        | <code>dvp_efdf</code> : DVP enhanced function data format               |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### **dvp\_efdf**

This is used to select the DVP enhanced function data format.

- DVP\_EFDF\_BYPASS: Enhanced function data management disabled
- DVP\_EFDF\_YUV422\_UYVY: YUV422 (UYVY / VYUY) format data
- DVP\_EFDF\_YUV422\_YUYV: YUV422 (YUYV / YVYU) format data
- DVP\_EFDF\_RGB565\_555: RGB565 RGB555 format data
- DVP\_EFDF\_Y8: Y8 (Y only) format data

#### **Example:**

```
dvp_enhanced_data_format_set(DVP_EFDF_RGB565_555);
```

### 5.9.27 dvp\_input\_data\_unused\_set function

The table below describes the function `dvp_input_data_unused_set`.

**Table 217. dvp\_input\_data\_unused\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_input_data_unused_set</code>   |
| Function prototype     | <code>void dvp_input_data_unused_set(dvp_idus_type dvp_idus, dvp_idun_type dvp_idun);</code> |
| Function description   | Configure DVP input data unused setting and bit number                                       |
| Input parameter 1      | <code>dvp_idus</code> : input data unused setting  |
| Input parameter 2      | <code>dvp_idun</code> : input data unused bit number   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **dvp\_idus**

This is used to select the input data unused setting.

- DVP\_IDUS\_MSB: Unused data bit in the MSB
- DVP\_IDUS\_LSB: Unused data bit in the LSB

#### **dvp\_idun**

This is used to select the input data unused bit number.

- DVP\_IDUN\_0: No unused bit

DVP\_IDUN\_2: 2-bit unused data  
 DVP\_IDUN\_4: 4-bit unused data  
 DVP\_IDUN\_6: 6-bit unused data

**Example:**

```
dvp_input_data_unused_set(DVP_IDUS_MSB, DVP_IDUN_2);
```

### 5.9.28 dvp\_dma\_burst\_set function

The table below describes the function `dvp_dma_burst_set`.

**Table 218. dvp\_dma\_burst\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>dvp_dma_burst_set</code>                                 |
| Function prototype     | <code>void dvp_dma_burst_set(dvp_dmabt_type dvp_dmabt);</code> |
| Function description   | Configure DVP burst DMA transfer                               |
| Input parameter        | <code>dvp_dmabt</code> : DVP burst DMA transfer                |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**dvp\_dmabt**

This is used for DVP burst DMA transfer configuration.

DVP\_DMABT\_SINGLE: Burst DMA transfer configuration disabled

DVP\_DMABT\_BURST: Burst DMA transfer configuration enabled

**Example:**

```
dvp_dma_burst_set(DVP_DMABT_BURST);
```

### 5.9.29 dvp\_sync\_event\_interrupt\_set function

The table below describes the function `dvp_sync_event_interrupt_set`.

**Table 219. dvp\_sync\_event\_interrupt\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>dvp_sync_event_interrupt_set</code>   |
| Function prototype     | <code>void dvp_sync_event_interrupt_set(dvp_hseid_type dvp_hseid, dvp_vseid_type dvp_vseid);</code> |
| Function description   | Configure the DVP HSYNC/SYNC event and interrupt definition   |
| Input parameter 1      | <code>dvp_hseid</code> : Horizontal synchronization event and interrupt definition                  |
| Input parameter 2      | <code>dvp_vseid</code> : Vertical synchronization event and interrupt definition                    |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**dvp\_hseid**

This is used to select horizontal synchronization event and interrupt definition.

DVP\_HSEID\_LINE\_END: HSES and HEIS indicate line end event and interrupt

DVP\_HSEID\_LINE\_START: HSES and HEIS indicate line start event and interrupt

**dvp\_vseid**

This is used to select vertical synchronization event and interrupt definition.

DVP\_VSEID\_FRAME\_END: VSES and VEIS indicate frame end event and interrupt

DVP\_VSEID\_FRMAE\_START: VSES and VEIS indicate frame start event and interrupt

**Example:**

```
dvp_sync_event_interrupt_set(DVP_HSEID_LINE_START, DVP_VSEID_FRAME_END);
```

## 5.10 EDMA controller (EDMA)

The EDMA register structure `edma_type` is defined in the “`at32f435_437_edma.h`”.

```
/**
 * @brief type define edma register all
 */
typedef struct
{
    .....
} edma_type;
```

The EDMA stream register structure `edma_stream_type` is defined in the “`at32f435_437_edma.h`”.

```
/**
 * @brief type define edma stream register all
 */
typedef struct
{
    .....
} edma_stream_type;
```

The EDMA linked table control register structure `edma_stream_link_list_type` is defined in the “`at32f435_437_edma.h`”.

```
/**
 * @brief type define edma stream link list pointer register
 */
typedef struct
{
    .....
} edma_stream_link_list_type;
```

The EDMA 2D transfer control register structure `edma_stream_2d_type` is defined in the “`at32f435_437_edma.h`”.

```
/**
 * @brief type define edma 2d register all
 */
typedef struct
{
    .....
} edma_stream_2d_type;
```

The EDMAMUX channel control register structure `edmamux_channel_type` is defined in the “`at32f435_437_edma.h`”.

```
/**
 * @brief type define edmamux muxsctrl register
 */
typedef struct
{
```

```
.....
} edmamux_channel_type;
```

The EDMAMUX generator control register structure `edmamux_generator_type` is defined in the “at32f435\_437\_edma.h”.

```
/**
 * @brief type define edmamux request generator register all
 */
typedef struct
{
.....
} edmamux_generator_type;
```

The table below gives a list of the EDMA registers.

**Table 220. Summary of EDMA registers**

| Register                   | Description                               |
|----------------------------|---|
| <code>edma_sts1</code>     | EDMA status register 1                    |
| <code>edma_sts2</code>     | EDMA status register 2                    |
| <code>edma_clr1</code>     | EDMA status clear register 1              |
| <code>edma_clr2</code>     | EDMA status clear register 2              |
| <code>edma_s1ctrl</code>   | EDMA stream 1 control register            |
| <code>edma_s1dtcnt</code>  | EDMA stream 1 number of data register     |
| <code>edma_s1paddr</code>  | EDMA stream 1 peripheral address register |
| <code>edma_s1m0addr</code> | EDMA stream 1 memory0 address register    |
| <code>edma_s1m1addr</code> | EDMA stream 1 memory1 address register    |
| <code>edma_s1fctrl</code>  | EDMA stream 1 FIFO control register       |
| <code>edma_s2ctrl</code>   | EDMA stream 2 control register            |
| <code>edma_s2dtcnt</code>  | EDMA stream 2 number of data register     |
| <code>edma_s2paddr</code>  | EDMA stream 2 peripheral address register |
| <code>edma_s2m0addr</code> | EDMA stream 2 memory0 address register    |
| <code>edma_s2m1addr</code> | EDMA stream 2 memory1 address register    |
| <code>edma_s2fctrl</code>  | EDMA stream 2 FIFO control register       |
| <code>edma_s3ctrl</code>   | EDMA stream 3 control register            |
| <code>edma_s3dtcnt</code>  | EDMA stream 3 number of data register     |
| <code>edma_s3paddr</code>  | EDMA stream 3 peripheral address register |
| <code>edma_s3m0addr</code> | EDMA stream 3 memory0 address register    |
| <code>edma_s3m1addr</code> | EDMA stream 3 memory1 address register    |
| <code>edma_s3fctrl</code>  | EDMA stream 3 FIFO control register       |
| <code>edma_s4ctrl</code>   | EDMA stream 4 control register            |
| <code>edma_s4dtcnt</code>  | EDMA stream 4 number of data register     |
| <code>edma_s4paddr</code>  | EDMA stream 4 peripheral address register |
| <code>edma_s4m0addr</code> | EDMA stream 4 memory0 address register    |
| <code>edma_s4m1addr</code> | EDMA stream 4 memory1 address register    |
| <code>edma_s4fctrl</code>  | EDMA stream 4 FIFO control register       |
| <code>edma_s5ctrl</code>   | EDMA stream 5 control register            |
| <code>edma_s5dtcnt</code>  | EDMA stream 5 number of data register     |



| Register      | Description                                 |
|---------------|---|
| edma_s5paddr  | EDMA stream 5 peripheral address register   |
| edma_s5m0addr | EDMA stream 5 memory0 address register      |
| edma_s5m1addr | EDMA stream 5 memory1 address register      |
| edma_s5ctrl   | EDMA stream 5 FIFO control register         |
| edma_s6ctrl   | EDMA stream 6 control register              |
| edma_s6dtcnt  | EDMA stream 6 number of data register       |
| edma_s6paddr  | EDMA stream 6 peripheral address register   |
| edma_s6m0addr | EDMA stream 6 memory0 address register      |
| edma_s6m1addr | EDMA stream 6 memory1 address register      |
| edma_s6ctrl   | EDMA stream 6 FIFO control register         |
| edma_s7ctrl   | EDMA stream 7 control register              |
| edma_s7dtcnt  | EDMA stream 7 number of data register       |
| edma_s7paddr  | EDMA stream 7 peripheral address register   |
| edma_s7m0addr | EDMA stream 7 memory0 address register      |
| edma_s7m1addr | EDMA stream 7 memory1 address register      |
| edma_s7ctrl   | EDMA stream 7 FIFO control register         |
| edma_s8ctrl   | EDMA stream 8 control register              |
| edma_s8dtcnt  | EDMA stream 8 number of data register       |
| edma_s8paddr  | EDMA stream 8 peripheral address register   |
| edma_s8m0addr | EDMA stream 8 memory0 address register      |
| edma_s8m1addr | EDMA stream 8 memory1 address register      |
| edma_s8ctrl   | EDMA stream 8 FIFO control register         |
| edma_llctrl   | EDMA linked table control register          |
| edma_s1lp     | EDMA stream 1 linked table pointer register |
| edma_s2lp     | EDMA stream 2 linked table pointer register |
| edma_s3lp     | EDMA stream 3 linked table pointer register |
| edma_s4lp     | EDMA stream 4 linked table pointer register |
| edma_s5lp     | EDMA stream 5 linked table pointer register |
| edma_s6lp     | EDMA stream 6 linked table pointer register |
| edma_s7lp     | EDMA stream 7 linked table pointer register |
| edma_s8lp     | EDMA stream 8 linked table pointer register |
| edma_s2dctrl  | EDMA 2D transfer control register           |
| edma_s12dcnt  | EDMA stream 1 2D transfer count register    |
| edma_s1stride | EDMA stream 1 2D transfer stride register   |
| edma_s22dcnt  | EDMA stream 2 2D transfer count register    |
| edma_s2stride | EDMA stream 2 2D transfer stride register   |
| edma_s32dcnt  | EDMA stream 3 2D transfer count register    |
| edma_s3stride | EDMA stream 3 2D transfer stride register   |
| edma_s42dcnt  | EDMA stream 4 2D transfer count register    |
| edma_s4stride | EDMA stream 4 2D transfer stride register   |
| edma_s52dcnt  | EDMA stream 5 2D transfer count register    |
| edma_s5stride | EDMA stream 5 2D transfer stride register   |
| edma_s62dcnt  | EDMA stream 6 2D transfer count register    |
| edma_s6stride | EDMA stream 6 2D transfer stride register   |

| Register        | Description                                     |
|-----------------|---|
| edma_s72dcnt    | EDMA stream 7 2D transfer count register        |
| edma_s7stride   | EDMA stream 7 2D transfer stride register       |
| edma_s82dcnt    | EDMA stream 8 2D transfer count register        |
| edma_s8stride   | EDMA stream 8 2D transfer stride register       |
| edma_muxsel     | EDMAMUX enable register                         |
| edma_muxc1ctrl  | EDMAMUX channel 1 control register              |
| edma_muxc2ctrl  | EDMAMUX channel 2 control register              |
| edma_muxc3ctrl  | EDMAMUX channel 3 control register              |
| edma_muxc4ctrl  | EDMAMUX channel 4 control register              |
| edma_muxc5ctrl  | EDMAMUX channel 5 control register              |
| edma_muxc6ctrl  | EDMAMUX channel 6 control register              |
| edma_muxc7ctrl  | EDMAMUX channel 7 control register              |
| edma_muxg1ctrl  | EDMAMUX request generator 1 control register    |
| edma_muxg2ctrl  | EDMAMUX request generator 2 control register    |
| edma_muxg3ctrl  | EDMAMUX request generator 3 control register    |
| edma_muxg4ctrl  | EDMAMUX request generator 4 control register    |
| edma_muxsyncsts | EDMAMUX synchronization status register         |
| edma_muxsyncclr | EDMAMUX synchronization status clear register   |
| edma_muxgsts    | EDMAMUX request generator status register       |
| edma_muxgclr    | EDMAMUX request generator status clear register |

### 5.10.1 edma\_reset function

The table below describes the function edma\_reset.

**Table 221. edma\_reset function**

| Name                   | Description                                      |
|------------------------|--|
| Function name          | edma_reset                                       |
| Function prototype     | void edma_reset(edma_stream_type *edma_streamx); |
| Function description   | Reset the selected EDMA stream                   |
| Input parameter 1      | edma_streamx: EDMA stream, x=1...8               |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* reset edma stream 1 */
edma_reset(EDMA_STREAM1);
```

## 5.10.2 edma\_init function

The table below describes the function edma\_init.

**Table 222. edma\_init function function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edma_init   |
| Function prototype     | void edma_init(edma_stream_type *edma_streamx, edma_init_type *edma_init_struct); |
| Function description   | Initialize the selected EDMA stream   |
| Input parameter 1      | edma_streamx: EDMA stream, x=1...8  |
| Input parameter 2      | edma_init_struct: edma_init_type pointer  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### edma\_init\_type structure

The edma\_init\_type is defined in the at32f435\_437\_edma.h.

typedef struct

```
{
    uint32_t          peripheral_base_addr;
    uint32_t          memory0_base_addr;
    dma_dir_type      direction;
    uint16_t          buffer_size;
    confirm_state     peripheral_inc_enable;
    confirm_state     memory_inc_enable;
    dma_peripheral_data_size_type peripheral_data_width;
    dma_memory_data_size_type memory_data_width;
    confirm_state     loop_mode_enable;
    dma_priority_level_type priority;
    confirm_state     fifo_mode_enable;
    edma_fifo_threshold_type fifo_threshold;
    edma_memory_burst_type memory_burst_mode;
    edma_peripheral_burst_type peripheral_burst_mode;
} edma_init_type;
```

#### peripheral\_base\_addr

Set the peripheral address of EDMA data stream.

#### memory\_base\_addr

Set the memory address of EDMA data stream.

#### direction

Set the transfer direction of EDMA data stream.

EDMA\_DIR\_PERIPHERAL\_TO\_MEMORY: Peripheral to memory

EDMA\_DIR\_MEMORY\_TO\_PERIPHERAL: Memory to peripheral

EDMA\_DIR\_MEMORY\_TO\_MEMORY: Memory to memory

#### buffer\_size

Set the number of data transfer of a EDMA channel.

**peripheral\_inc\_enable**

Enable/disable EDMA data stream peripheral address auto increment

FALSE: Peripheral address is not incremented

TRUE: Peripheral address is incremented

**memory\_inc\_enable**

Enable/disable EDMA data stream memory address auto increment

FALSE: Memory address is not incremented

TRUE: Memory address is incremented

**peripheral\_data\_width**

Set EDMA peripheral data width

EDMA\_PERIPHERAL\_DATA\_WIDTH\_BYTE: Byte

EDMA\_PERIPHERAL\_DATA\_WIDTH\_HALFWORD: Half-word

EDMA\_PERIPHERAL\_DATA\_WIDTH\_WORD: Word

**memory\_data\_width**

Set EDMA memory data width

EDMA\_MEMORY\_DATA\_WIDTH\_BYTE: Byte

EDMA\_MEMORY\_DATA\_WIDTH\_HALFWORD: Half-word

EDMA\_MEMORY\_DATA\_WIDTH\_WORD: Word

**loop\_mode\_enable**

Set EDMA loop mode.

FALSE: EDMA single mode

TRUE: EDMA loop mode

**priority**

Set EDMA data stream priority.

EDMA\_PRIORITY\_LOW: Low

EDMA\_PRIORITY\_MEDIUM: Medium

EDMA\_PRIORITY\_HIGH: High

EDMA\_PRIORITY\_VERY\_HIGH: Very high

**fifo\_mode\_enable**

Enable/disable EDMA data stream FIFO mode.

FALSE: Direct mode

TRUE: FIFO mode

**fifo\_threshold**

Set EDMA data stream FIFO threshold.

EDMA\_FIFO\_THRESHOLD\_1QUARTER: 1/4 FIFO

EDMA\_FIFO\_THRESHOLD\_HALF: 1/2 FIFO

EDMA\_FIFO\_THRESHOLD\_3QUARTER: 3/4 FIFO

EDMA\_FIFO\_THRESHOLD\_FULL: Full FIFO

**memory\_burst\_mode**

Enable/disable EDMA memory burst mode.

EDMA\_MEMORY\_SINGLE: Memory burst disabled

EDMA\_MEMORY\_BURST\_4: Memory burst enabled, transfer 4 data each time

EDMA\_MEMORY\_BURST\_8: Memory burst enabled, transfer 8 data each time

EDMA\_MEMORY\_BURST\_16: Memory burst enabled, transfer 16 data each time

**peripheral\_burst\_mode**

Enable/disable EDMA peripheral burst mode.

EDMA\_PERIPHERAL\_SINGLE: Peripheral burst disabled  
 EDMA\_PERIPHERAL\_BURST\_4: Peripheral burst enabled, transfer 4 data each time  
 EDMA\_PERIPHERAL\_BURST\_8: Peripheral burst enabled, transfer 8 data each time  
 EDMA\_PERIPHERAL\_BURST\_16: Peripheral burst enabled, transfer 16 data each time

**Example:**

```

edmamux_sync_init_type edmamux_sync_init_struct;
/* edma stream4 configuration */
edma_init_struct.direction = EDMA_DIR_PERIPHERAL_TO_MEMORY;
edma_init_struct.buffer_size = (uint32_t)16;
edma_init_struct.peripheral_data_width = EDMA_PERIPHERAL_DATA_WIDTH_HALFWORD;
edma_init_struct.peripheral_base_addr = (uint32_t)src_buffer;
edma_init_struct.peripheral_inc_enable = TRUE;
edma_init_struct.memory_data_width = EDMA_MEMORY_DATA_WIDTH_HALFWORD;
edma_init_struct.memory0_base_addr = (uint32_t)dst_buffer;
edma_init_struct.memory_inc_enable = TRUE;
edma_init_struct.peripheral_burst_mode = EDMA_PERIPHERAL_SINGLE;
edma_init_struct.memory_burst_mode = EDMA_MEMORY_SINGLE;
edma_init_struct.fifo_mode_enable = FALSE;
edma_init_struct.fifo_threshold = EDMA_FIFO_THRESHOLD_1QUARTER;
edma_init_struct.priority = EDMA_PRIORITY_HIGH;
edma_init_struct.loop_mode_enable = FALSE;
edma_init(EDMA_STREAM4, &edma_init_struct);
    
```

### 5.10.3 edma\_default\_para\_init function

The table below describes the function edma\_default\_para\_init.

**Table 223. edma\_default\_para\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | edma_default_para_init   |
| Function prototype     | void edma_default_para_init(edma_init_type *edma_init_struct); |
| Function description   | Initialize the parameters of the edma_init_struct              |
| Input parameter 1      | edma_init_struct: edma_init_type pointer                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

The table below describes the default values of the edma\_init\_struct members.

**Table 224. edma\_init\_struct default values**

| Member                | Default value                 |
|-----------------------|-------------------------------|
| peripheral_base_addr  | 0x0                           |
| memory_base_addr      | 0x0                           |
| direction             | EDMA_DIR_PERIPHERAL_TO_MEMORY |
| buffer_size           | 0x0                           |
| peripheral_inc_enable | FALSE                         |

| Member                | Default value                   |
|-----------------------|---------------------------------|
| memory_inc_enable     | FALSE                           |
| peripheral_data_width | EDMA_PERIPHERAL_DATA_WIDTH_BYTE |
| memory0_data_width    | EDMA_MEMORY_DATA_WIDTH_BYTE     |
| loop_mode_enable      | FALSE                           |
| priority              | EDMA_PRIORITY_LOW               |
| fifo_mode_enable      | FALSE                           |
| fifo_threshold        | EDMA_FIFO_THRESHOLD_1QUARTER    |
| memory_burst_mode     | EDMA_MEMORY_SINGLE              |
| peripheral_burst_mode | EDMA_PERIPHERAL_SINGLE          |

Example:

```

/* edma init config with its default value */
edmamux_sync_init_type edmamux_sync_init_struct;
edma_default_para_init(&edma_init_struct);

```

### 5.10.4 edma\_stream\_enable function

The table below describes the function edma\_stream\_enable.

**Table 225. edma\_stream\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edma_stream_enable  |
| Function prototype     | void edma_stream_enable(edma_stream_type *edma_streamx, confirm_state new_state); |
| Function description   | Enable the selected EDMA stream   |
| Input parameter 1      | edma_streamx: EDMA stream, x=1...8  |
| Input parameter 2      | new_state: Enable/disable stream  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**new\_state**

Enable/disable EDMA data stream.

FALSE: Disabled

TRUE: Enabled

**Example:**

```

/* enable edma stream4 */
edma_stream_enable(EDMA_STREAM4, TRUE);

```

### 5.10.5 edma\_interrupt\_enable function

The table below describes the function edma\_interrupt\_enable.

**Table 226. edma\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edma_interrupt_enable   |
| Function prototype     | void edma_interrupt_enable(edma_stream_type *edma_streamx, uint32_t edma_int, confirm_state new_state); |
| Function description   | Enable the selected EDMA stream interrupt   |
| Input parameter 1      | edma_streamx: EDMA stream, x=1...8  |
| Input parameter 2      | edma_int: selected interrupt source   |
| Input parameter 3      | new_state: enable or disable interrupt  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### edma\_int

Select EDMA stream interrupt source.

- EDMA\_FDT\_INT: Transfer complete interrupt
- EDMA\_HDT\_INT: Half transfer complete interrupt
- EDMA\_DTERR\_INT: Transfer error interrupt
- EDMA\_DMERR\_INT: Direct mode error interrupt
- EDMA\_FERR\_INT: FIFO error interrupt

#### new\_state

Enable/disable DMA channel interrupt.

- FALSE: Interrupt disabled
- TRUE: Interrupt enabled

#### Example:

```
/* enable transfer full data interrupt */
edma_interrupt_enable(EDMA_STREAM4, EDMA_FDT_INT, TRUE);
```

### 5.10.6 edma\_peripheral\_inc\_offset\_set function

The table below describes the function edma\_peripheral\_inc\_offset\_set.

**Table 227. edma\_peripheral\_inc\_offset\_set function**

| Name                 | Description  |
|----------------------|--|
| Function name        | edma_peripheral_inc_offset_set   |
| Function prototype   | void edma_peripheral_inc_offset_set(edma_stream_type *edma_streamx, edma_peripheral_inc_offset_type offset); |
| Function description | Configure peripheral address auto offset mode  |
| Input parameter 1    | edma_streamx: EDMA stream, x=1...8   |
| Input parameter 2    | offset: auto offset mode,  |
| Output parameter     | NA   |
| Return value         | NA   |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

**offset**

Select auto offset mode.

EDMA\_PERIPHERAL\_INC\_PSIZE: Offset is determined by psice

EDMA\_PERIPHERAL\_INC\_4\_BYTE: Auto offset of 4 bytes

**Example:**

```
/* cofig peripheral offset */
edma_peripheral_inc_offset_set(EDMA_STREAM4, EDMA_PERIPHERAL_INC_4_BYTE);
```

### 5.10.7 edma\_flow\_controller\_enable

The table below describes the function edma\_flow\_controller\_enable

**Table 228. edma\_flow\_controller\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | edma_flow_controller_enable  |
| Function prototype     | void edma_flow_controller_enable(edma_stream_type *edma_streamx, confirm_state new_state); |
| Function description   | Enable EDMA peripheral flow control  |
| Input parameter 1      | edma_streamx: EDMA stream, x=1...8   |
| Input parameter 2      | new_state: enable/disable peripheral flow control  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**new\_state**

Enable or disable EDMA channel interrupt.

FALSE: Interrupt disabled

TRUE: Interrupt enabled

**Example:**

```
/* enable stream4 peripheral stream control */
edma_flow_controller_enable(EDMA_STREAM4, TRUE);
```

### 5.10.8 edma\_data\_number\_set function

The table below describes the function edma\_data\_number\_set

**Table 229. edma\_data\_number\_set function**

| Name                 | Description  |
|----------------------|--|
| Function name        | edma_data_number_set   |
| Function prototype   | void edma_data_number_set(edma_stream_type *edma_streamx, uint16_t data_number); |
| Function description | Configure the EDMA stream-x number of data register                              |
| Input parameter 1    | edma_streamx: EDMA stream, x=1...8   |



| Name                   | Description                                     |
|------------------------|---|
| Input parameter 2      | data_number: data transfer size, maximum: 65535 |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* set edma stream 1 data count is 0x100*/
edma_data_number_set(EDMA_STREAM1, 0x100);
```

### 5.10.9 edma\_data\_number\_get function

The table below describes the function `edma_data_number_get`.

**Table 230. edma\_data\_number\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>edma_data_number_get</code>   |
| Function prototype     | <code>uint16_t edma_data_number_get(edma_stream_type *edma_streamx);</code> |
| Function description   | Get the value of EDMA stream-x number of data register                      |
| Input parameter 1      | <code>edma_streamx</code> : EDMA stream, x=1...8                            |
| Output parameter       | NA  |
| Return value           | Return the number of data transfer  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* get edma stream 1 data count*/
uint16_t data_counter;
data_counter = edma_data_number_get(EDMA_STREAM1);
```

### 5.10.10 edma\_double\_buffer\_mode\_init function

The table below describes the function `edma_double_buffer_mode_init`.

**Table 231. edma\_double\_buffer\_mode\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>edma_double_buffer_mode_init</code>   |
| Function prototype     | <code>void edma_double_buffer_mode_init(edma_stream_type *edma_streamx, uint32_t memory1_addr, edma_memory_type current_memory);</code> |
| Function description   | Configure the EDMA stream dual buffer mode  |
| Input parameter 1      | <code>edma_streamx</code> : EDMA stream, x=1...8  |
| Input parameter 2      | <code>memory1_addr</code> : memory0 address   |
| Input parameter 3      | <code>current_memory</code> : memory0 or memory1  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* stream4 double buffer mode config */
edma_double_buffer_mode_init(EDMA_STREAM4, 0x20000400;EDMA_MEMORY_0);
```

### 5.10.11 edma\_double\_buffer\_mode\_enable function

The table below describes the function edma\_double\_buffer\_mode\_enable.

**Table 232. edma\_double\_buffer\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edma_double_buffer_mode_enable  |
| Function prototype     | void edma_double_buffer_mode_enable(edma_stream_type *edma_streamx, confirm_state new_state); |
| Function description   | Enable EDMA stream dual buffer mode   |
| Input parameter 1      | edma_streamx: EDMA stream, x=1...8  |
| Input parameter 2      | new_state: Enable/disable dual buffer mode  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* stream4 double buffer mode enable */
edma_double_buffer_mode_enable (EDMA_STREAM4, TRUE);
```

### 5.10.12 edma\_memory\_addr\_set function

The table below describes the function edma\_memory\_addr\_set.

**Table 233. edma\_memory\_addr\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | edma_memory_addr_set   |
| Function prototype     | void edma_memory_addr_set(edma_stream_type *edma_streamx, uint32_t memory_addr, uint32_t memory_target); |
| Function description   | Configure the EDMA stream memory address in dual buffer mode   |
| Input parameter 1      | edma_streamx: EDMA stream, x=1...8   |
| Input parameter 2      | memory_addr: memory address  |
| Input parameter 2      | memory_target: the target memory   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* set edma stream 1 memory1 address */
edma_memory_addr_set(EDMA_STREAM1, 0x20000400, EDMA_MEMORY_1);
```

### 5.10.13 edma\_stream\_status\_get function

The table below describes the function edma\_stream\_status\_get.

**Table 234. edma\_stream\_status\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edma_stream_status_get  |
| Function prototype     | flag_status edma_stream_status_get(edma_stream_type *edma_streamx); |
| Function description   | Get the EDMA stream status  |
| Input parameter 1      | edma_streamx: EDMA stream, x=1...8                                  |
| Output parameter       | NA  |
| Return value           | Return the EDMA stream status                                       |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* get edma stream 1 status*/
flag_status sts;
sts = edma_stream_status_get(EDMA_STREAM1);
```

### 5.10.14 edma\_fifo\_status\_get function

The table below describes the function edma\_fifo\_status\_get.

**Table 235. edma\_fifo\_status\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edma_fifo_status_get  |
| Function prototype     | uint8_t edma_fifo_status_get(edma_stream_type *edma_streamx); |
| Function description   | Get the EDMA stream FIFO status                               |
| Input parameter 1      | edma_streamx: EDMA stream, x=1...8                            |
| Output parameter       | NA  |
| Return value           | Return the EDMA stream FIFO status                            |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* get edma stream 1 fifo status*/
uint8_t fifosts;
fifosts = edma_fifo_status_get(EDMA_STREAM1);
```

### 5.10.15 edma\_flag\_get function

The table below describes the function edma\_flag\_get.

**Table 236. edma\_flag\_get function**

| Name                 | Description                                    |
|----------------------|--|
| Function name        | edma_flag_get                                  |
| Function prototype   | flag_status edma_flag_get(uint32_t edma_flag); |
| Function description | Get the EDMA stream status flag                |

| Name                   | Description                                   |
|------------------------|---|
| Input parameter 1      | <i>edma_flag</i><br>: the desired status flag |
| Output parameter       | NA  |
| Return value           | Return the EDMA stream status flag            |
| Required preconditions | NA  |
| Called functions       | NA  |

**edma\_flag**

The edma\_flag is used to get a status flag, including:

|                   |   |
|-------------------|---|
| EDMA_FERR1_FLAG:  | Data stream 1 FIFO error flag             |
| EDMA_DMERR1_FLAG: | Data stream 1 dual buffer error flag      |
| EDMA_DTERR1_FLAG: | Data stream 1 direct mode error flag      |
| EDMA_HDT1_FLAG:   | Data stream 1 half transfer complete flag |
| EDMA_FDT1_FLAG:   | Data stream 1 transfer complete flag      |
| EDMA_FERR2_FLAG:  | Data stream 2 FIFO error flag             |
| EDMA_DMERR2_FLAG: | Data stream 2 dual buffer error flag      |
| EDMA_DTERR2_FLAG: | Data stream 2 direct mode error flag      |
| EDMA_HDT2_FLAG:   | Data stream 2 half transfer complete flag |
| EDMA_FDT2_FLAG:   | Data stream 2 transfer complete flag      |
| EDMA_FERR3_FLAG:  | Data stream 3 FIFO error flag             |
| EDMA_DMERR3_FLAG: | Data stream 3 dual buffer error flag      |
| EDMA_DTERR3_FLAG: | Data stream 3 direct mode error flag      |
| EDMA_HDT3_FLAG:   | Data stream 3 half transfer complete flag |
| EDMA_FDT3_FLAG:   | Data stream 3 transfer complete flag      |
| EDMA_FERR4_FLAG:  | Data stream 4 FIFO error flag             |
| EDMA_DMERR4_FLAG: | Data stream 4 dual buffer error flag      |
| EDMA_DTERR4_FLAG: | Data stream 4 direct mode error flag      |
| EDMA_HDT4_FLAG:   | Data stream 4 half transfer complete flag |
| EDMA_FDT4_FLAG:   | Data stream 4 transfer complete flag      |
| EDMA_FERR5_FLAG:  | Data stream 5 FIFO error flag             |
| EDMA_DMERR5_FLAG: | Data stream 5 dual buffer error flag      |
| EDMA_DTERR5_FLAG: | Data stream 5 direct mode error flag      |
| EDMA_HDT5_FLAG:   | Data stream 5 half transfer complete flag |
| EDMA_FDT5_FLAG:   | Data stream 5 transfer complete flag      |
| EDMA_FERR6_FLAG:  | Data stream 6 FIFO error flag             |
| EDMA_DMERR6_FLAG: | Data stream 6 dual buffer error flag      |
| EDMA_DTERR6_FLAG: | Data stream 6 direct mode error flag      |
| EDMA_HDT6_FLAG:   | Data stream 6 half transfer complete flag |
| EDMA_FDT6_FLAG:   | Data stream 6 transfer complete flag      |
| EDMA_FERR7_FLAG:  | Data stream 7 FIFO error flag             |
| EDMA_DMERR7_FLAG: | Data stream 7 dual buffer error flag      |
| EDMA_DTERR7_FLAG: | Data stream 7 direct mode error flag      |
| EDMA_HDT7_FLAG:   | Data stream 7 half transfer complete flag |
| EDMA_FDT7_FLAG:   | Data stream 7 transfer complete flag      |
| EDMA_FERR8_FLAG:  | Data stream 8 FIFO error flag             |
| EDMA_DMERR8_FLAG: | Data stream 8 dual buffer error flag      |

EDMA\_DTERR8\_FLAG: Data stream 8 direct mode error flag  
 EDMA\_HDT8\_FLAG: Data stream 8 half transfer complete flag  
 EDMA\_FDT8\_FLAG: Data stream 8 transfer complete flag

**Example:**

```
/* get edma stream 1 full data transfer flag dstatus */
uint8_t sts;
sts = edma_flag_get(EDMA_FDT1_FLAG);
```

### 5.10.16 edma\_2d\_init function

The table below describes the function edma\_2d\_init.

**Table 237. edma\_2d\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | edma_2d_init   |
| Function prototype     | void edma_2d_init(edma_stream_2d_type *edma_streamx_2d, int16_t src_stride, int16_t dst_stride, uint16_t xcnt, uint16_t ycnt); |
| Function description   | Configure EDMA stream 2D transfer mode   |
| Input parameter 1      | <a href="#">edma_streamx_2d</a><br>: 2D transfer EDMA stream, x=1...8  |
| Input parameter 2      | src_stride: source stride  |
| Input parameter 3      | dst_stride: destination stride   |
| Input parameter 4      | xcnt: x-axis count   |
| Input parameter 5      | ycnt: y-axis count   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**edma\_streamx\_2d**

The edma\_streamx\_2d is used to select a status flag, including:

EDMA\_STREAM1\_2D  
 EDMA\_STREAM2\_2D  
 EDMA\_STREAM3\_2D  
 EDMA\_STREAM4\_2D  
 EDMA\_STREAM5\_2D  
 EDMA\_STREAM6\_2D  
 EDMA\_STREAM7\_2D  
 EDMA\_STREAM8\_2D

**Example:**

```
/* stream4 2d transfer mode config */
edma_2d_init(EDMA_STREAM4_2D, 0x00; 0x00; 0x04; 0x10);
```

### 5.10.17 edma\_2d\_enable function

The table below describes the function edma\_2d\_enable.

**Table 238. edma\_2d\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edma_2d_enable  |
| Function prototype     | void edma_2d_enable(edma_stream_2d_type *edma_streamx_2d, confirm_state new_state); |
| Function description   | Enable EDMA stream 2D transfer mode   |
| Input parameter 1      | <a href="#">edma_streamx_2d</a><br>: 2D transfer EDMA stream, x=1...8               |
| Input parameter 2      | new_state: enable/disable 2D transfer mode  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* stream4 2d transfer mode enable */
edma_2d_enable (EDMA_STREAM4_2D, TRUE);
```

### 5.10.18 edma\_link\_list\_init function

The table below describes the function edma\_link\_list\_init.

**Table 239. edma\_link\_list\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | edma_link_list_init  |
| Function prototype     | void edma_link_list_init(edma_stream_link_list_type *edma_streamx_ll, uint32_t pointer); |
| Function description   | Initialize EDMA linked table transfer  |
| Input parameter 1      | <a href="#">edma_streamx_ll</a><br>: EDMA stream, x=1...8                                |
| Input parameter 2      | pointer: linked table transfer descriptor storage pointer address                        |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**edma\_streamx\_ll**

The edma\_streamx\_ll is used to select a status flag, including

- EDMA\_STREAM1\_ll
- EDMA\_STREAM2\_ll
- EDMA\_STREAM3\_ll
- EDMA\_STREAM4\_ll
- EDMA\_STREAM5\_ll
- EDMA\_STREAM6\_ll
- EDMA\_STREAM7\_ll

EDMA\_STREAM8\_II

**Example:**

```
/* link list descriptor array, start address must be aligned by 16 bytes */
__ALIGNED(16) ll_descriptors_type edma_ll_descriptors_tx[LIST_COUNT];
/* edma stream 1 link list mode configuration */
edma_link_list_init(EDMA_STREAM1_LL, (uint32_t)edma_ll_descriptors_tx);
```

### 5.10.19 edma\_link\_list\_enable function

The table below describes the function edma\_link\_list\_enable.

**Table 240. edma\_link\_list\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edma_link_list_enable   |
| Function prototype     | void edma_link_list_enable(edma_stream_link_list_type *edma_streamx_ll, confirm_state new_state); |
| Function description   | Enable EDMA stream linked table transfer  |
| Input parameter 1      | <a href="#">edma_streamx_ll</a><br>: EDMA stream, x=1...8   |
| Input parameter 2      | new_state: enable/disable 2D transfer mode  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* edma stream 1 link list mode enable */
void edma_link_list_enable(edma_stream_link_list_type *edma_streamx_ll, confirm_state new_state);
```

### 5.10.20 edma\_flag\_clear function

The table below describes the function edma\_flag\_clear.

**Table 241. edma\_flag\_clear function**

| Name                   | Description  |
|------------------------|--|
| Function name          | edma_flag_clear                                    |
| Function prototype     | void edma_flag_clear(uint32_t edma_flag);          |
| Function description   | Get the EDMA stream status flag                    |
| Input parameter 1      | <a href="#">edma_flag</a><br>: desired status flag |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* clear edma stream 1 full data transfer flag dstatus */
edma_flag_get(EDMA_FDT1_FLAG);
```

The The table below describes the default values of the dmamux\_sync\_init\_struct members.

**Table 242. dmamux\_sync\_init\_struct values**

| Member              | Default value                |
|---------------------|------------------------------|
| sync_enable         | FALSE                        |
| sync_event_enable   | FALSE                        |
| sync_polarity       | DMAMUX_SYNC_POLARITY_DISABLE |
| sync_request_number | 0x0                          |
| sync_signal_sel     | (dmamux_sync_id_sel_type)0   |

Example:

```
/* dmamuxsync init config with its default value */
dmamux_sync_init_type dmamux_sync_init_struct={0};
dmamux_sync_default_para_init(&dmamux_sync_init_struct);
```

### 5.10.21 edmamux\_enable function

The table below describes the function edmamux\_enable.

**Table 243. edmamux\_enable function**

| Name                   | Description                                   |
|------------------------|---|
| Function name          | edmamux_enable                                |
| Function prototype     | void edmamux_enable(confirm_state new_state); |
| Function description   | Enable EDMAMUX feature                        |
| Input parameter 1      | new_state: enable or disable channel          |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### new\_state

Enable or disable DMA channel.

FALSE: Channel disabled

TRUE: Channel enabled

#### Example:

```
/* edmamuxfunction enable */
edmamux_enable(TRUE);
```

### 5.10.22 edmamux\_init function

The table below describes the function edmamux\_init.

**Table 244. edmamux\_init function**

| Name                 | Description  |
|----------------------|--|
| Function name        | edmamux_init   |
| Function prototype   | void edmamux_init(edmamux_channel_type *edmamux_channelx, edmamux_reqst_id_sel_type edmamux_req_id); |
| Function description | Configure EDMAMUX  |
| Input parameter 1    | <i>edmamux_channelx</i><br>: EDMAMUX channel, x=1...8  |
| Input parameter 2    | <i>edmamux_req_id</i>  |



| Name                   | Description                 |
|------------------------|-----------------------------|
|                        | : DMAMUX channel request ID |
| Output parameter       | NA                          |
| Return value           | NA                          |
| Required preconditions | NA                          |
| Called functions       | NA                          |

**edmamux\_channelx**

This is used to select a DMAMUX channel, including:

- EDMAMUX\_CHANNEL1
- EDMAMUX\_CHANNEL2
- EDMAMUX\_CHANNEL3
- EDMAMUX\_CHANNEL4
- EDMAMUX\_CHANNEL5
- EDMAMUX\_CHANNEL6
- EDMAMUX\_CHANNEL7
- EDMAMUX\_CHANNEL8

**edmamux\_req\_id**

The table below describes the EDMAMUX channel request ID.

**Table 245. EDMAMUX channel request source ID**

| Request source ID | Description                     | Request source ID | Description                     |
|-------------------|---------------------------------|-------------------|---------------------------------|
| 0x01              | EDMAMUX_DMAREQ_ID_REQ_G1        | 0x02              | EDMAMUX_DMAREQ_ID_REQ_G2        |
| 0x03              | EDMAMUX_DMAREQ_ID_REQ_G3        | 0x04              | EDMAMUX_DMAREQ_ID_REQ_G4        |
| 0x05              | EDMAMUX_DMAREQ_ID_ADC1          | 0x24              | EDMAMUX_DMAREQ_ID_ADC2          |
| 0x25              | EDMAMUX_DMAREQ_ID_ADC3          | 0x06              | EDMAMUX_DMAREQ_ID_DAC1          |
| 0x29              | EDMAMUX_DMAREQ_ID_DAC2          | 0x08              | EDMAMUX_DMAREQ_ID_TMR6_OVERFLOW |
| 0x09              | EDMAMUX_DMAREQ_ID_TMR7_OVERFLOW | 0x0A              | EDMAMUX_DMAREQ_ID_SPI1_RX       |
| 0x0B              | EDMAMUX_DMAREQ_ID_SPI1_TX       | 0x0C              | EDMAMUX_DMAREQ_ID_SPI2_RX       |
| 0x0D              | EDMAMUX_DMAREQ_ID_SPI2_TX       | 0x0E              | EDMAMUX_DMAREQ_ID_SPI3_RX       |
| 0x0F              | EDMAMUX_DMAREQ_ID_SPI3_TX       | 0x6A              | EDMAMUX_DMAREQ_ID_SPI4_RX       |
| 0x6B              | EDMAMUX_DMAREQ_ID_SPI4_TX       | 0x6E              | EDMAMUX_DMAREQ_ID_I2S2_EXT_RX   |
| 0x6F              | EDMAMUX_DMAREQ_ID_I2S2_EXT_TX   | 0x70              | EDMAMUX_DMAREQ_ID_I2S3_EXT_RX   |
| 0x71              | EDMAMUX_DMAREQ_ID_I2S3_EXT_TX   | 0x10              | EDMAMUX_DMAREQ_ID_I2C1_RX       |
| 0x11              | EDMAMUX_DMAREQ_ID_I2C1_TX       | 0x12              | EDMAMUX_DMAREQ_ID_I2C2_RX       |
| 0x13              | EDMAMUX_DMAREQ_ID_I2C2_TX       | 0x14              | EDMAMUX_DMAREQ_ID_I2C3_RX       |
| 0x15              | EDMAMUX_DMAREQ_ID_I2C3_TX       | 0x18              | EDMAMUX_DMAREQ_ID_USART1_RX     |
| 0x19              | EDMAMUX_DMAREQ_ID_USART1_TX     | 0x1A              | EDMAMUX_DMAREQ_ID_USART2_RX     |
| 0x1B              | EDMAMUX_DMAREQ_ID_USART2_TX     | 0x1C              | EDMAMUX_DMAREQ_ID_USART3_RX     |
| 0x1D              | EDMAMUX_DMAREQ_ID_USART3_TX     | 0x1E              | EDMAMUX_DMAREQ_ID_UART4_RX      |
| 0x1F              | EDMAMUX_DMAREQ_ID_UART4_TX      | 0x20              | EDMAMUX_DMAREQ_ID_UART5_RX      |
| 0x21              | EDMAMUX_DMAREQ_ID_UART5_TX      | 0x72              | EDMAMUX_DMAREQ_ID_USART6_RX     |
| 0x73              | EDMAMUX_DMAREQ_ID_USART6_TX     | 0x74              | EDMAMUX_DMAREQ_ID_UART7_RX      |
| 0x75              | EDMAMUX_DMAREQ_ID_UART7_TX      | 0x76              | EDMAMUX_DMAREQ_ID_UART8_RX      |
| 0x77              | EDMAMUX_DMAREQ_ID_UART8_TX      | 0x27              | EDMAMUX_DMAREQ_ID_SDIO1         |

| Request source ID | Description                     | Request source ID | Description                      |
|-------------------|---------------------------------|-------------------|----------------------------------|
| 0x67              | EDMAMUX_DMAREQ_ID_SDIO2         | 0x28              | EDMAMUX_DMAREQ_ID_QSPI1          |
| 0x68              | EDMAMUX_DMAREQ_ID_QSPI2         | 0x2A              | EDMAMUX_DMAREQ_ID_TMR1_CH1       |
| 0x2B              | EDMAMUX_DMAREQ_ID_TMR1_CH2      | 0x2C              | EDMAMUX_DMAREQ_ID_TMR1_CH3       |
| 0x2D              | EDMAMUX_DMAREQ_ID_TMR1_CH4      | 0x2E              | EDMAMUX_DMAREQ_ID_TMR1_OVERFLOW  |
| 0x2F              | EDMAMUX_DMAREQ_ID_TMR1_TRIG     | 0x30              | EDMAMUX_DMAREQ_ID_TMR1_HALL      |
| 0x31              | EDMAMUX_DMAREQ_ID_TMR8_CH1      | 0x32              | EDMAMUX_DMAREQ_ID_TMR8_CH2       |
| 0x33              | EDMAMUX_DMAREQ_ID_TMR8_CH3      | 0x34              | EDMAMUX_DMAREQ_ID_TMR8_CH4       |
| 0x35              | EDMAMUX_DMAREQ_ID_TMR8_OVERFLOW | 0x36              | EDMAMUX_DMAREQ_ID_TMR8_TRIG      |
| 0x37              | EDMAMUX_DMAREQ_ID_TMR8_HALL     | 0x38              | EDMAMUX_DMAREQ_ID_TMR2_CH1       |
| 0x39              | EDMAMUX_DMAREQ_ID_TMR2_CH2      | 0x3A              | EDMAMUX_DMAREQ_ID_TMR2_CH3       |
| 0x3B              | EDMAMUX_DMAREQ_ID_TMR2_CH4      | 0x3C              | EDMAMUX_DMAREQ_ID_TMR2_OVERFLOW  |
| 0x7E              | EDMAMUX_DMAREQ_ID_TMR2_TRIG     | 0x3D              | EDMAMUX_DMAREQ_ID_TMR3_CH1       |
| 0x3E              | EDMAMUX_DMAREQ_ID_TMR3_CH2      | 0x3F              | EDMAMUX_DMAREQ_ID_TMR3_CH3       |
| 0x40              | EDMAMUX_DMAREQ_ID_TMR3_CH4      | 0x41              | EDMAMUX_DMAREQ_ID_TMR3_OVERFLOW  |
| 0x42              | EDMAMUX_DMAREQ_ID_TMR3_TRIG     | 0x43              | EDMAMUX_DMAREQ_ID_TMR4_CH1       |
| 0x44              | EDMAMUX_DMAREQ_ID_TMR4_CH2      | 0x45              | EDMAMUX_DMAREQ_ID_TMR4_CH3       |
| 0x46              | EDMAMUX_DMAREQ_ID_TMR4_CH4      | 0x47              | EDMAMUX_DMAREQ_ID_TMR4_OVERFLOW  |
| 0x7F              | EDMAMUX_DMAREQ_ID_TMR4_TRIG     | 0x48              | EDMAMUX_DMAREQ_ID_TMR5_CH1       |
| 0x49              | EDMAMUX_DMAREQ_ID_TMR5_CH2      | 0x4A              | EDMAMUX_DMAREQ_ID_TMR5_CH3       |
| 0x4B              | EDMAMUX_DMAREQ_ID_TMR5_CH4      | 0x4C              | EDMAMUX_DMAREQ_ID_TMR5_OVERFLOW  |
| 0x4D              | EDMAMUX_DMAREQ_ID_TMR5_TRIG     | 0x56              | EDMAMUX_DMAREQ_ID_TMR20_CH1      |
| 0x57              | EDMAMUX_DMAREQ_ID_TMR20_CH2     | 0x58              | EDMAMUX_DMAREQ_ID_TMR20_CH3      |
| 0x59              | EDMAMUX_DMAREQ_ID_TMR20_CH4     | 0x5A              | EDMAMUX_DMAREQ_ID_TMR20_OVERFLOW |
| 0x5D              | EDMAMUX_DMAREQ_ID_TMR20_TRIG    | 0x5E              | EDMAMUX_DMAREQ_ID_TMR20_HALL     |
| 0x69              | EDMAMUX_DMAREQ_ID_DVP           |                   |                                  |

**Example:**

```
/* generator1 for edmamuxchannel4 as dma request */
edmamux_init(EDMAMUX_CHANNEL4, EDMAMUX_DMAREQ_ID_REQ_G1);
```

### 5.10.23 edmamux\_sync\_default\_para\_init function

The table below describes the function edmamux\_sync\_default\_para\_init.

**Table 246. edmamux\_sync\_default\_para\_init function**

| Name                 | Description  |
|----------------------|--|
| Function name        | edmamux_sync_default_para_init   |
| Function prototype   | void edmamux_sync_default_para_init(edmamux_sync_init_type *edmamux_sync_init_struct); |
| Function description | Initialize parameters in the edmamux_sync_init_struct                                  |
| Input parameter 1    | edmamux_sync_init_struct: edmamux_sync_init_type pointer                               |
| Output parameter     | NA   |
| Return value         | NA   |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

The table below describes the default values of the `edmamux_sync_init_struct` members.

**Table 247. edmamux\_sync\_init\_struct default values**

| Member                           | Default values                             |
|----------------------------------|--|
| <code>sync_enable</code>         | FALSE                                      |
| <code>sync_event_enable</code>   | FALSE                                      |
| <code>sync_polarity</code>       | EDMAMUX_SYNC_POLARITY_DISABLE              |
| <code>sync_request_number</code> | 0x0  |
| <code>sync_signal_sel</code>     | ( <code>edmamux_sync_id_sel_type</code> )0 |

Example:

```
/* edmamuxsyncinit config with its default value */
edmamux_sync_init_type edmamux_sync_init_struct={0};
edmamux_sync_default_para_init(&edmamux_sync_init_struct);
```

## 5.10.24 edmamux\_sync\_config function

The table below describes the function `edmamux_sync_config`.

**Table 248. edmamux\_sync\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>edmamux_sync_config</code>  |
| Function prototype     | <code>void edmamux_sync_config(edmamux_channel_type * edmamux_channelx, edmamux_sync_init_type *edmamux_sync_init_struct);</code> |
| Function description   | Configure the EDMAMUX synchronous module  |
| Input parameter 1      | <a href="#">edmamux_channelx</a><br>DMAMUX channel, x=1...7   |
| Input parameter 2      | <code>edmamux_sync_init_struct:edmamux_sync_init_type</code> pointer  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### **edmamux\_sync\_init\_struct**

The `edmamux_sync_init_type` is defined in the `at32f435_437_dma.h`.

typedef struct

```
{
    dmamux_sync_id_sel_type    sync_signal_sel;
    uint32_t                   sync_polarity;
    uint32_t                   sync_request_number;
    confirm_state               sync_event_enable;
    confirm_state               sync_enable;
} edmamux_sync_init_type;
```

### **sync\_signal\_sel**

Select signal source for synchronous module.

EDMAMUX\_SYNC\_ID\_EXINT0: External exint0 signal

|                                 |                         |
|---------------------------------|-------------------------|
| EDMAMUX_SYNC_ID_EXINT1:         | External exint1 signal  |
| EDMAMUX_SYNC_ID_EXINT2:         | External exint2 signal  |
| EDMAMUX_SYNC_ID_EXINT3:         | External exint3 signal  |
| EDMAMUX_SYNC_ID_EXINT4:         | External exint4 signal  |
| EDMAMUX_SYNC_ID_EXINT5:         | External exint5 signal  |
| EDMAMUX_SYNC_ID_EXINT6:         | External exint6 signal  |
| EDMAMUX_SYNC_ID_EXINT7:         | External exint7 signal  |
| EDMAMUX_SYNC_ID_EXINT8:         | External exint8 signal  |
| EDMAMUX_SYNC_ID_EXINT9:         | External exint9 signal  |
| EDMAMUX_SYNC_ID_EXINT10:        | External exint10 signal |
| EDMAMUX_SYNC_ID_EXINT11:        | External exint11 signal |
| EDMAMUX_SYNC_ID_EXINT12:        | External exint12 signal |
| EDMAMUX_SYNC_ID_EXINT13:        | External exint13 signal |
| EDMAMUX_SYNC_ID_EXINT14:        | External exint14 signal |
| EDMAMUX_SYNC_ID_EXINT15:        | External exint15 signal |
| EDMAMUX_SYNC_ID_DMAMUX_CH1_EVT: | dmamux channel 1 event  |
| EDMAMUX_SYNC_ID_DMAMUX_CH2_EVT: | dmamux channel 2 event  |
| EDMAMUX_SYNC_ID_DMAMUX_CH3_EVT: | dmamux channel 3 event  |
| EDMAMUX_SYNC_ID_DMAMUX_CH4_EVT: | dmamux channel 4 event  |
| EDMAMUX_SYNC_ID_DMAMUX_CH5_EVT: | dmamux channel 5 event  |
| EDMAMUX_SYNC_ID_DMAMUX_CH6_EVT: | dmamux channel 6 event  |
| EDMAMUX_SYNC_ID_DMAMUX_CH7_EVT: | dmamux channel 7 event  |

**sync\_polarity**

Select the signal polarity for synchronous module.

|                                       |                              |
|---------------------------------------|------------------------------|
| EDMAMUX_SYNC_POLARITY_RISING:         | Rising edge                  |
| EDMAMUX_SYNC_POLARITY_FALLING:        | Falling edge                 |
| EDMAMUX_SYNC_POLARITY_RISING_FALLING: | Rising edge and falling edge |

**sync\_request\_number**

The number of DMA requests that can be synchronized

Range: 1~32

**sync\_event\_enable**

Generation of synchronous event

|        |                                    |
|--------|------------------------------------|
| TRUE:  | Synchronous event is generated     |
| FALSE: | Synchronous event is not generated |

**sync\_enable**

Enable or disable synchronous module

|        |                             |
|--------|-----------------------------|
| FALSE: | Synchronous module disabled |
| TRUE:  | Synchronous module enabled  |

**Example:**

```

edmamux_sync_default_para_init(&edmamux_sync_init_struct);
edmamux_sync_init_struct.sync_request_number = 4;
edmamux_sync_init_struct.sync_signal_sel = DMAMUX_SYNC_ID_EXINT1;
edmamux_sync_init_struct.sync_polarity = DMAMUX_SYNC_POLARITY_RISING;
edmamux_sync_init_struct.sync_event_enable = TRUE;
edmamux_sync_init_struct.sync_enable = TRUE;
    
```

```
edmamux_sync_config(EDMAMUX_CHANNEL4, &edmamux_sync_init_struct);
```

## 5.10.25 edmamux\_generator\_default\_para\_init function

The table below describes the function `edmamux_generator_default_para_init`.

**Table 249. edmamux\_generator\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>edmamux_generator_default_para_init</code>  |
| Function prototype     | <code>void edmamux_generator_default_para_init(edmamux_gen_init_type * edmamux_gen_init_struct);</code> |
| Function description   | Initialize parameters in the <code>edmamux_gen_init_struct</code>                                       |
| Input parameter 1      | <code>edmamux_gen_init_struct</code> : <code>edmamux_gen_init_type</code> pointer                       |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The table below describes the default values of the `edmamux_gen_init_struct` members.

**Table 250. edmamux\_gen\_init\_struct default values**

| Member                          | Default value                             |
|---------------------------------|---|
| <code>gen_signal_sel</code>     | <code>(edmamux_gen_id_sel_type)0x0</code> |
| <code>gen_polarity</code>       | <code>EDMAMUX_GEN_POLARITY_DISABLE</code> |
| <code>gen_request_number</code> | <code>0x0</code>                          |
| <code>gen_enable</code>         | <code>FALSE</code>                        |

Example:

```
/* edmamuxgen init config with its default value */
edmamux_gen_init_type edmamux_gen_init_struct={0};
edmamux_gen_default_para_init(&edmamux_gen_init_struct);
```

## 5.10.26 edmamux\_generator\_config function

The table below describes the function `edmamux_generator_config`.

**Table 251. edmamux\_generator\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>edmamux_generator_config</code>   |
| Function prototype     | <code>void edmamux_generator_config(edmamux_generator_type * edmamux_gen_x, edmamux_gen_init_type *edmamux_gen_init_struct);</code> |
| Function description   | Configure EDMAMUX request generator   |
| Input parameter 1      | <a href="#"><i>xmc_sdram_init_struct</i></a><br>: request generator channel   |
| Input parameter 2      | <code>edmamux_sync_init_struct</code> : <code>edmamux_sync_init_type</code> pointer   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**edmamux\_gen\_x**

This is used to select DMA request generator channel.

EDMAMUX\_GENERATOR1

EDMAMUX\_GENERATOR2

EDMAMUX\_GENERATOR3

EDMAMUX\_GENERATOR4

**edmamux\_sync\_init\_struct**

The edmamux\_gen\_init\_type is defined in the at32f435\_437\_dma.h.

typedef struct

```
{
    edmamux_gen_id_sel_type      gen_signal_sel;
    uint32_t                     gen_polarity;
    uint32_t                     gen_request_number;
    confirm_state                gen_enable;
} edmamux_gen_init_type;
```

**gen\_signal\_sel**

Select signal source for synchronous module

|                                |                         |
|--------------------------------|-------------------------|
| EDMAMUX_GEN_ID_EXINT0:         | External exint0 signal  |
| EDMAMUX_GEN_ID_EXINT1:         | External exint1 signal  |
| EDMAMUX_GEN_ID_EXINT2:         | External exint2 signal  |
| EDMAMUX_GEN_ID_EXINT3:         | External exint3 signal  |
| EDMAMUX_GEN_ID_EXINT4:         | External exint4 signal  |
| EDMAMUX_GEN_ID_EXINT5:         | External exint5 signal  |
| EDMAMUX_GEN_ID_EXINT6:         | External exint6 signal  |
| EDMAMUX_GEN_ID_EXINT7:         | External exint7 signal  |
| EDMAMUX_GEN_ID_EXINT8:         | External exint8 signal  |
| EDMAMUX_GEN_ID_EXINT9:         | External exint9 signal  |
| EDMAMUX_GEN_ID_EXINT10:        | External exint10 signal |
| EDMAMUX_GEN_ID_EXINT11:        | External exint11 signal |
| EDMAMUX_GEN_ID_EXINT12:        | External exint12 signal |
| EDMAMUX_GEN_ID_EXINT13:        | External exint13 signal |
| EDMAMUX_GEN_ID_EXINT14:        | External exint14 signal |
| EDMAMUX_GEN_ID_EXINT15:        | External exint15 signal |
| EDMAMUX_GEN_ID_DMAMUX_CH1_EVT: | dmamux channel 1 event  |
| EDMAMUX_GEN_ID_DMAMUX_CH2_EVT: | dmamux channel 2 event  |
| EDMAMUX_GEN_ID_DMAMUX_CH3_EVT: | dmamux channel 3 event  |
| EDMAMUX_GEN_ID_DMAMUX_CH4_EVT: | dmamux channel 4 event  |
| EDMAMUX_GEN_ID_DMAMUX_CH5_EVT: | dmamux channel 5 event  |
| EDMAMUX_GEN_ID_DMAMUX_CH6_EVT: | dmamux channel 6 event  |
| EDMAMUX_GEN_ID_DMAMUX_CH7_EVT: | dmamux channel 7 event  |

**gen\_polarity**

Select generator signal polarity

|                                      |                              |
|--------------------------------------|------------------------------|
| EDMAMUX_GEN_POLARITY_RISING:         | Rising edge                  |
| EDMAMUX_GEN_POLARITY_FALLING:        | Falling edge                 |
| EDMAMUX_GEN_POLARITY_RISING_FALLING: | Rising edge and falling edge |

**gen\_request\_number**

Number of DMA request generated by the generator

Range: 1~32

**gen\_enable**

Enable or disable request generator

FALSE: Disabled

TRUE: Enabled

**Example:**

```

/* genertor1 configuration */
edmamux_generator_default_para_init(&edmamux_gen_init_struct);
edmamux_gen_init_struct.gen_polarity= EDMAMUX_GEN_POLARITY_RISING;
edmamux_gen_init_struct.gen_request_number= 4;
edmamux_gen_init_struct.gen_signal_sel = EDMAMUX_GEN_ID_EXINT1;
edmamux_gen_init_struct.gen_enable = TRUE;
edmamux_generator_config(EDMAMUX_GENERATOR1, &edmamux_gen_init_struct);
    
```

### 5.10.27 edmamux\_sync\_interrupt\_enable function

The table below describes the function edmamux\_sync\_interrupt\_enable.

**Table 252. edmamux\_sync\_interrupt\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | edmamux_sync_interrupt_enable  |
| Function prototype     | void edmamux_sync_interrupt_enable(edmamux_channel_type *edmamux_channelx, confirm_state new_state); |
| Function description   | Enable synchronous module overrun interrupt  |
| Input parameter 1      | <a href="#">edmamux_channelx</a><br>: EDMAMUX channel, x=1...7                                       |
| Input parameter 2      | new_state: enable or disable interrupt   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**new\_state**

Enable or disable the DMA channel interrupt.

FALSE: Interrupt disabled

TRUE: Interrupt enabled

**Example:**

```

/* enable sync overrun interrupt */
edmamux_sync_interrupt_enable (EDMAMUX_CHANNEL1, TRUE);
    
```

## 5.10.28 edmamux\_generator\_interrupt\_enable function

The table below describes the function `edmamux_generator_interrupt_enable`.

**Table 253. edmamux\_generator\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>edmamux_generator_interrupt_enable</code>   |
| Function prototype     | <code>void edmamux_generator_interrupt_enable(edmamux_generator_type *edmamux_gen_x, confirm_state new_state);</code> |
| Function description   | Enable request generator overrun interrupt  |
| Input parameter 1      | <code>xmc_sdram_init_struct</code><br>: EDMAMUX request generator channel, x=1...4                                    |
| Input parameter 2      | <code>new_state</code> : enable or disable interrupt  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### **new\_state**

Enable or disable the request generator channel interrupt.

FALSE: Interrupt disabled

TRUE: Interrupt enabled

### **Example:**

```
/* enable gen overrun interrupt */
edmamux_generator_interrupt_enable(EDMAMUX_GENERATOR3, TRUE);
```

## 5.10.29 edmamux\_sync\_flag\_get function

The table below describes the function `edmamux_sync_flag_get`.

**Table 254. edmamux\_sync\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>edmamux_sync_flag_get</code>  |
| Function prototype     | <code>flag_status edmamux_sync_flag_get(dma_type *dma_x, uint32_t flag);</code> |
| Function description   | Get the edmamux synchronous module flag   |
| Input parameter 1      | <code>flag</code> : the desired flag  |
| Output parameter       | NA  |
| Return value           | <code>flag_status</code> : indicates whether or not the flag is set             |
| Required preconditions | NA  |
| Called functions       | NA  |

### **flag**

The flag is used to select the desired status flag, including:

EDMAMUX\_SYNC\_OV1\_FLAG

EDMAMUX\_SYNC\_OV2\_FLAG

EDMAMUX\_SYNC\_OV3\_FLAG

EDMAMUX\_SYNC\_OV4\_FLAG

EDMAMUX\_SYNC\_OV5\_FLAG



EDMAMUX\_SYNC\_OV6\_FLAG  
 EDMAMUX\_SYNC\_OV7\_FLAG  
 EDMAMUX\_SYNC\_OV8\_FLAG

**flag\_status**

RESET: Corresponding flag is reset

SET: Corresponding flag is set

**Example:**

```

if(edmamux_sync_flag_get(EDMAMUX_SYNC_OV1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
}
    
```

### 5.10.30 edmamux\_sync\_flag\_clear function

The table below describes the function edmamux\_sync\_flag\_clear.

**Table 255. edmamux\_sync\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edmamux_sync_flag_clear                                       |
| Function prototype     | void edmamux_sync_flag_clear(dma_type *dma_x, uint32_t flag); |
| Function description   | Clear the synchronous module flag                             |
| Input parameter 1      | flag: the flag to be cleared                                  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**flag**

The flag is used to select the flag to be cleared, including:

EDMAMUX\_SYNC\_OV1\_FLAG  
 EDMAMUX\_SYNC\_OV2\_FLAG  
 EDMAMUX\_SYNC\_OV3\_FLAG  
 EDMAMUX\_SYNC\_OV4\_FLAG  
 EDMAMUX\_SYNC\_OV5\_FLAG  
 EDMAMUX\_SYNC\_OV6\_FLAG  
 EDMAMUX\_SYNC\_OV7\_FLAG  
 EDMAMUX\_SYNC\_OV8\_FLAG

**Example:**

```

if(edmamux_sync_flag_get(EDMAMUX_SYNC_OV1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
    edmamux_sync_flag_clear(EDMAMUX_SYNC_OV1_FLAG);
}
    
```

```
}

```

### 5.10.31 edmamux\_generator\_flag\_get function

The table below describes the function edmamux\_generator\_flag\_get.

**Table 256. edmamux\_generator\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | edmamux_generator_flag_get  |
| Function prototype     | flag_status edmamux_generator_flag_get(dma_type *dma_x, uint32_t flag); |
| Function description   | Get the edmamux request generator flag                                  |
| Input parameter 1      | flag: the desired flag  |
| Output parameter       | NA  |
| Return value           | flag_status: indicates whether or not the flag is set                   |
| Required preconditions | NA  |
| Called functions       | NA  |

#### flag

The flag is used to select the desired flag, including:

- EDMAMUX\_GEN\_TRIG\_OV1\_FLAG
- EDMAMUX\_GEN\_TRIG\_OV2\_FLAG
- EDMAMUX\_GEN\_TRIG\_OV3\_FLAG
- EDMAMUX\_GEN\_TRIG\_OV4\_FLAG

#### flag\_status

RESET: Corresponding flag is reset

SET: Corresponding flag is set

#### Example:

```
if(edmamux_generator_flag_get(DMA2, EDMAMUX_GEN_TRIG_OV1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
}
```

### 5.10.32 edmamux\_generator\_flag\_clear function

The table below describes the function edmamux\_generator\_flag\_clear.

**Table 257. edmamux\_generator\_flag\_clear function**

| Name                   | Description  |
|------------------------|--|
| Function name          | edmamux_generator_flag_clear                                       |
| Function prototype     | void edmamux_generator_flag_clear(dma_type *dma_x, uint32_t flag); |
| Function description   | Clear the request generator flag                                   |
| Input parameter 1      | flag: the flag to be cleared                                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |

| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**flag**

The flag is used to select the flag to be cleared, including:

EDMAMUX\_GEN\_TRIG\_OV1\_FLAG

EDMAMUX\_GEN\_TRIG\_OV2\_FLAG

EDMAMUX\_GEN\_TRIG\_OV3\_FLAG

EDMAMUX\_GEN\_TRIG\_OV4\_FLAG

**Example:**

```
if(edmamux_generator_flag_get(DMA2, EDMAMUX_GEN_TRIG_OV1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
    edmamux_generator_flag_clear(EDMAMUX_GEN_TRIG_OV1_FLAG);
}
```

## 5.11 Real-time clock (ERTC)

The ERTC register structure `ertc_type` is defined in the “`at32f435_437_ertc.h`”.

```
/**
 * @brief type define ertc register all
 */
typedef struct
{

} ertc_type;
```

The table below gives a list of the ERTC registers.

**Table 258. Summary of ERTC registers**

| Register | Description                               |
|----------|---|
| time     | ERTC time register                        |
| date     | ERTC date register                        |
| ctrl     | ERTC control register                     |
| sts      | ERTC initialization and status register   |
| div      | ERTC divider register                     |
| wat      | ERTC wakeup timer register                |
| ccal     | ERTC coarse calibration register          |
| ala      | ERTC alarm clock A register               |
| alb      | ERTC alarm clock B register               |
| wp       | ERTC write protection register            |
| sbs      | ERTC subsecond register                   |
| tadj     | ERTC time adjustment register             |
| tstm     | ERTC time stamp time register             |
| tsdt     | ERTC time stamp date register             |
| tssbs    | ERTC time stamp subsecond register        |
| scal     | ERTC smooth calibration register          |
| tamp     | ERTC tamper configuration register        |
| alabs    | ERTC alarm clock A subsecond register     |
| albsbs   | ERTC alarm clock B subsecond register     |
| bprx     | ERTC battery powered domain data register |

The table below gives a list of ERTC library functions.

**Table 259. Summary of ERTC library functions**

| Function name                           | Description                       |
|---|-----------------------------------|
| <code>ertc_num_to_bcd</code>            | Convert number to BCD code        |
| <code>ertc_bcd_to_num</code>            | Convert BCD code to number        |
| <code>ertc_write_protect_enable</code>  | Enable write protection           |
| <code>ertc_write_protect_disable</code> | Disable write protection          |
| <code>ertc_wait_update</code>           | Wait for register update complete |

|                                |   |
|--------------------------------|---|
| ertc_wait_flag                 | Wait flag   |
| ertc_init_mode_enter           | Enter initialization mode   |
| ertc_init_mode_exit            | Exit initialization mode  |
| ertc_reset                     | Reset ERTC registers  |
| ertc_divider_set               | Divider setting   |
| ertc_hour_mode_set             | Hour mode setting   |
| ertc_date_set                  | Date setting  |
| ertc_time_set                  | Time setting  |
| ertc_calendar_get              | Get calendar  |
| ertc_sub_second_get            | Get the current subsecond   |
| ertc_alarm_mask_set            | Set alarm mask  |
| ertc_alarm_week_date_select    | Alarm time format selection (week/date)                                   |
| ertc_alarm_set                 | Set alarm   |
| ertc_alarm_sub_second_set      | Set alarm subsecond   |
| ertc_alarm_enable              | Enable alarm  |
| ertc_alarm_get                 | Get alarm value   |
| ertc_alarm_sub_second_get      | Get alarm subsecond   |
| ertc_wakeup_clock_set          | Select wakeup clock source  |
| ertc_wakeup_counter_set        | Set wakeup counter value  |
| ertc_wakeup_counter_get        | Get wakeup counter value  |
| ertc_wakeup_enable             | Enable wakeup timer   |
| ertc_smooth_calibration_config | Configure smooth calibration  |
| ertc_coarse_calibration_set    | Configure coarse calibration  |
| ertc_coarse_calibration_enable | Enable coarse calibration   |
| ertc_cal_output_select         | Calibration output source selection                                       |
| ertc_cal_output_enable         | Enable calibration output   |
| ertc_time_adjust               | Time adjustment   |
| ertc_daylight_set              | Set daylight saving time  |
| ertc_daylight_bpr_get          | Get daylight saving time battery powered domain data register value (BPR) |
| ertc_refer_clock_detect_enable | Enable reference clock detection  |
| ertc_direct_read_enable        | Enable direct read mode   |
| ertc_output_set                | Set event output  |
| ertc_timestamp_pin_select      | Time stamp detection pin selection  |
| ertc_timestamp_valid_edge_set  | Set time stamp detection valid edge                                       |
| ertc_timestamp_enable          | Enable time stamp   |
| ertc_timestamp_get             | Get time stamp  |
| ertc_timestamp_sub_second_get  | Get time stamp subsecond  |
| ertc_tamper_1_pin_select       | Tamper detection 1 pin selection  |
| ertc_tamper_pull_up_enable     | Enable tamper pin pull-up resistor  |
| ertc_tamper_precharge_set      | Set tamper pin precharge time   |
| ertc_tamper_filter_set         | Set tamper filter time  |
| ertc_tamper_detect_freq_set    | Set tamper detection frequency  |
| ertc_tamper_valid_edge_set     | Set tamper detection valid edge   |
| ertc_tamper_timestamp_enable   | Enable time stamp upon a tamper event                                     |
| ertc_tamper_enable             | Enable tamper detection   |

|                       |  |
|-----------------------|--|
| ertc_interrupt_enable | Enable interrupts                                  |
| ertc_interrupt_get    | Get the status of interrupt enable                 |
| ertc_flag_get         | Get flag status                                    |
| ertc_flag_clear       | Clear flag   |
| ertc_bpr_data_write   | Write data to battery powered data register (BPR)  |
| ertc_bpr_data_read    | Read data from battery powered data register (BPR) |

### 5.11.1 ertc\_num\_to\_bcd function

The table below describes the function ertc\_num\_to\_bcd.

**Table 260. ertc\_num\_to\_bcd function**

| Name                   | Description                           |
|------------------------|---------------------------------------|
| Function name          | ertc_num_to_bcd                       |
| Function prototype     | uint8_t ertc_num_to_bcd(uint8_t num); |
| Function description   | Convert number into BCD format        |
| Input parameter 1      | num: number to be converted           |
| Output parameter       | NA                                    |
| Return value           | BCD code                              |
| Required preconditions | NA                                    |
| Called functions       | NA                                    |

**Example:**

```
ertc_num_to_bcd(12);
```

### 5.11.2 ertc\_bcd\_to\_num function

The table below describes the function ertc\_bcd\_to\_num.

**Table 261. ertc\_bcd\_to\_num function**

| Name                   | Description                                 |
|------------------------|---|
| Function name          | ertc_bcd_to_num                             |
| Function prototype     | uint8_t ertc_bcd_to_num(uint8_t bcd);       |
| Function description   | Convert BCD code into number                |
| Input parameter 1      | bcd: BCD code to be converted               |
| Output parameter       | NA  |
| Return value           | Return the number corresponding to BCD code |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
ertc_bcd_to_num(0x12);
```

### 5.11.3 ertc\_write\_protect\_enable function

The table below describes the function ertc\_write\_protect\_enable.

**Table 262. ertc\_write\_protect\_enable function**

| Name                   | Description                           |
|------------------------|---------------------------------------|
| Function name          | ertc_write_protect_enable             |
| Function prototype     | void ertc_write_protect_enable(void); |
| Function description   | Write protection enable               |
| Input parameter 1      | NA                                    |
| Output parameter       | NA                                    |
| Return value           | NA                                    |
| Required preconditions | NA                                    |
| Called functions       | NA                                    |

**Example:**

```
ertc_write_protect_enable();
```

### 5.11.4 ertc\_write\_protect\_disable function

The table below describes the function ertc\_write\_protect\_disable.

**Table 263. ertc\_write\_protect\_disable function**

| Name                   | Description                            |
|------------------------|--|
| Function name          | ertc_write_protect_disable             |
| Function prototype     | void ertc_write_protect_disable(void); |
| Function description   | Write protection disable               |
| Input parameter 1      | NA                                     |
| Output parameter       | NA                                     |
| Return value           | NA                                     |
| Required preconditions | NA                                     |
| Called functions       | NA                                     |

**Example:**

```
ertc_write_protect_disable();
```

### 5.11.5 ertc\_wait\_update function

The table below describes the function ertc\_wait\_update.

**Table 264. ertc\_wait\_update function**

| Name                 | Description  |
|----------------------|--|
| Function name        | ertc_wait_update   |
| Function prototype   | error_status ertc_wait_update(void);                         |
| Function description | Wait for register to finish update                           |
| Input parameter 1    | NA   |
| Output parameter     | NA   |
| Return value         | SUCCESS: register update complete<br>ERROR: flag waittimeout |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

|                                |
|--------------------------------|
| <pre>ertc_wait_update();</pre> |
|--------------------------------|

### 5.11.6 ertc\_wait\_flag function

The table below describes the function ertc\_wait\_flag.

**Table 265. ertc\_wait\_flag function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_wait_flag   |
| Function prototype     | error_status ertc_wait_flag(uint32_t flag, flag_status status);  |
| Function description   | Wait flag  |
| Input parameter 1      | flag: flag selection<br>Refer to the “flag” description below for details.   |
| Input parameter 1      | status: flag status<br>After the flag status is set, the function remains stuck here until flag status changes.<br>This parameter can be SET or RESET. |
| Output parameter       | NA   |
| Return value           | SUCCESS: flag status changed<br>ERROR: flag wait timeout   |
| Required preconditions | NA   |
| Called functions       | NA   |

**flag**

Flag selection

|                    |   |
|--------------------|---|
| ERTC_ALAWF_FLAG:   | Alarm A write enable flag               |
| ERTC_ALBWF_FLAG:   | Alarm B write enable flag               |
| ERTC_WATWF_FLAG:   | Wakeup timer register write enable flag |
| ERTC_TADJF_FLAG:   | Time adjustment flag                    |
| ERTC_CALUPDF_FLAG: | Calibration value update complete flag  |

**Example:**

|  |
|--|
| <pre>ertc_wait_flag(ERTC_ALAWF_FLAG, RESET);</pre> |
|--|

### 5.11.7 ertc\_init\_mode\_enter function

The table below describes the function ertc\_init\_mode\_enter.

**Table 266. ertc\_init\_mode\_enter function**

| Name                 | Description                              |
|----------------------|--|
| Function name        | ertc_init_mode_enter                     |
| Function prototype   | error_status ertc_init_mode_enter(void); |
| Function description | Enter initialization mode                |
| Input parameter 1    | NA                                       |
| Output parameter     | NA                                       |



| Name                   | Description  |
|------------------------|--|
| Return value           | SUCCESS: Initialization mode is entered successfully<br>ERROR: Timeout |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_init_mode_enter();
```

## 5.11.8 ertc\_init\_mode\_exit function

The table below describes the function ertc\_init\_mode\_exit.

**Table 267. ertc\_init\_mode\_exit function**

| Name                   | Description                     |
|------------------------|---------------------------------|
| Function name          | ertc_init_mode_exit             |
| Function prototype     | void ertc_init_mode_exit(void); |
| Function description   | Exit initialization mode        |
| Input parameter 1      | NA                              |
| Output parameter       | NA                              |
| Return value           | NA                              |
| Required preconditions | NA                              |
| Called functions       | NA                              |

**Example:**

```
ertc_init_mode_exit();
```

## 5.11.9 ertc\_reset function

The table below describes the function ertc\_reset.

**Table 268. ertc\_reset function**

| Name                   | Description                                    |
|------------------------|--|
| Function name          | ertc_reset                                     |
| Function prototype     | error_status ertc_reset(void);                 |
| Function description   | Reset all ERTC registers                       |
| Input parameter 1      | NA   |
| Output parameter       | NA   |
| Return value           | SUCCESS: reset success<br>ERROR: reset failure |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_reset();
```

### 5.11.10 ertc\_divider\_set function

The table below describes the function ertc\_divider\_set.

**Table 269. ertc\_divider\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_divider_set   |
| Function prototype     | error_status ertc_divider_set(uint16_t div_a, uint16_t div_b);   |
| Function description   | Divider settings, frequency division value $(div\_a + 1) * (div\_b + 1) = ERTC\_CLK$ frequency<br>For example, if 32768 Hz is used, the frequency division should be $div\_a = 127$ , $div\_b = 255$ |
| Input parameter 1      | div_a: divider A, range: 0~0x7F  |
| Input parameter 2      | div_b: divider B, range: 0~0x7FFF  |
| Output parameter       | NA   |
| Return value           | SUCCESS: Reset successful<br>ERROR: Reset failed   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_divider_set(127,255);
```

### 5.11.11 ertc\_hour\_mode\_set function

The table below describes the function ertc\_hour\_mode\_set.

**Table 270. ertc\_hour\_mode\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_hour_mode_set  |
| Function prototype     | error_status ertc_hour_mode_set(ertc_hour_mode_set_type mode);            |
| Function description   | Hour mode settings  |
| Input parameter 1      | mode: hour mode<br>Refer to the following description "Mode" for details. |
| Output parameter       | NA  |
| Return value           | SUCCESS: Setting success<br>ERROR: Setting error                          |
| Required preconditions | NA  |
| Called functions       | NA  |

**mode**

ERTC\_HOUR\_MODE\_24: 24-hour format

ERTC\_HOUR\_MODE\_12: 12-hour format

**Example:**

```
ertc_hour_mode_set(ERTC_HOUR_MODE_24);
```

### 5.11.12 ertc\_date\_set function

The table below describes the function ertc\_date\_set.

**Table 271. ertc\_date\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_date_set  |
| Function prototype     | error_status ertc_date_set(uint8_t year, uint8_t month, uint8_t date, uint8_t week); |
| Function description   | Set date: year, month, date, weekday   |
| Input parameter 1      | year: 0~99   |
| Input parameter 2      | month: 1~12  |
| Input parameter 3      | date: 1~31   |
| Input parameter 4      | weekday: 1~7   |
| Output parameter       | NA   |
| Return value           | SUCCESS: Setting success<br>ERROR: Setting error                                     |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_date_set(22, 5, 26, 4);
```

### 5.11.13 ertc\_time\_set function

The table below describes the function ertc\_time\_set.

**Table 272. ertc\_time\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_time_set  |
| Function prototype     | error_status ertc_time_set(uint8_t hour, uint8_t min, uint8_t sec, ertc_am_pm_type ampm);  |
| Function description   | Set time: hour, minute, second, AM/PM (for 12-hour format only)  |
| Input parameter 1      | hour: 0~23   |
| Input parameter 2      | min: 0~59  |
| Input parameter 3      | sec: 0~59  |
| Input parameter 4      | ampm: 12 AM/PM in 12-hour format (for 12-hour format only, don't care in 24-hour format)<br>Refer to the following description "ampm" for details. |
| Output parameter       | NA   |
| Return value           | SUCCESS: Setting success<br>ERROR: Setting error   |
| Required preconditions | NA   |
| Called functions       | NA   |

**ampm**

AM/PM in 12-hour format (for 12-hour format only, don't care in 24-hour format)

ERTC\_24H: 24-hour format (for 24-hour format)

ERTC\_AM: AM in 12-hour format

ERTC\_PM: PM in 12-hour format

**Example:**

```
ertc_time_set(12, 1, 20, ERTC_24H);
```

### 5.11.14 ertc\_calendar\_get function

The table below describes the function ertc\_calendar\_get.

**Table 273. ertc\_calendar\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_calendar_get   |
| Function prototype     | void ertc_calendar_get(ertc_time_type* time);                                   |
| Function description   | Get calendar, including year, month, date, weekday, hour, minute, second, AM/PM |
| Input parameter 1      | time: ertc_time_type pointer  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

ertc\_time\_type\* time

The ertc\_time\_type is defined in the at32f435\_437\_ertc.h.

typedef struct

```
{
    uint8_t      year;
    uint8_t      month;
    uint8_t      day;
    uint8_t      hour;
    uint8_t      min;
    uint8_t      sec;
    uint8_t      week;
    ertc_am_pm_type ampm;
}
```

} ertc\_time\_type;

**year**

Range 0~99

**month**

Range 1~12

**day**

Range 1~31

**week**

Range 1~7

**hour**

Range 0~23

**min**

Range 0~59

**sec**

Range 0~59

**ampm**

AM/PM in 12-hour format (for 12-hour format only, don't care in 24 hour), including:

ERTC\_AM: AM in 12-hour format

ERTC\_PM: PM in 12-hour format

**Example:**

```
ertc_calendar_get(&time);
```

### 5.11.15 ertc\_sub\_second\_get function

The table below describes the function ertc\_sub\_second\_get.

**Table 274. ertc\_sub\_second\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_sub_second_get                                    |
| Function prototype     | uint32_t ertc_sub_second_get(void);                    |
| Function description   | Get current subsecond (the current value of divider B) |
| Input parameter 1      | NA   |
| Output parameter       | NA   |
| Return value           | Current subsecond                                      |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_sub_second_get();
```

### 5.11.16 ertc\_alarm\_mask\_set function

The table below describes the function ertc\_alarm\_mask\_set.

**Table 275. ertc\_alarm\_mask\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_alarm_mask_set   |
| Function prototype     | void ertc_alarm_mask_set(ertc_alarm_type alarm_x, uint32_t mask);                     |
| Function description   | Set alarm mask  |
|                        | alarm_x: alarm selection<br>Refer to the following description "alarm_x" for details. |
| Input parameter 1      | mask: Set alarm mask<br>Refer to the following description "mask" for details.        |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**alarm\_x**

Alarm selection

ERTC\_ALA: Alarm A

ERTC\_ALB: Alarm B

**mask**

Set alarm mask

ERTC\_ALARM\_MASK\_NONE: No mask, alarm is relevant to all fields

ERTC\_ALARM\_MASK\_SEC: Mask second, alarm is not relevant to second

ERTC\_ALARM\_MASK\_MIN: Mask minute, alarm is not relevant to minute

ERTC\_ALARM\_MASK\_HOUR: Mask hour, alarm is not relevant to hour  
 ERTC\_ALARM\_MASK\_DATE\_WEEK: Mask date, alarm is not relevant to date  
 ERTC\_ALARM\_MASK\_ALL: Mask all, generate an alarm per one second

**Example:**

```
ertc_alarm_mask_set(ERTC_ALA, ERTC_ALARM_MASK_NONE);
```

### 5.11.17 ertc\_alarm\_week\_date\_select function

The table below describes the function ertc\_alarm\_week\_date\_select.

**Table 276. ertc\_alarm\_week\_date\_select function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_alarm_week_date_select  |
| Function prototype     | void ertc_alarm_week_date_select(ertc_alarm_type alarm_x, ertc_week_date_select_type wk);    |
| Function description   | Alarm time format selection: week/date   |
| Input parameter 1      | alarm_x: alarm selection<br>Refer to the following description "alarm_x" for details.        |
| Input parameter 2      | wk: alarm week/date format selection<br>Refer to the following description "wk" for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**alarm\_x**

Alarm selection

ERTC\_ALA: Alarm A

ERTC\_ALB: Alarm B

**wk**

Alarm week/date format selection

ERTC\_SLECT\_DATE: Date mode

ERTC\_SLECT\_WEEK: Week mode

**Example:**

```
ertc_alarm_week_date_select(ERTC_ALA, ERTC_SLECT_DATE);
```

### 5.11.18 ertc\_alarm\_set function

The table below describes the function ertc\_alarm\_set.

**Table 277. ertc\_alarm\_set function**

| Name                 | Description  |
|----------------------|--|
| Function name        | ertc_alarm_set   |
| Function prototype   | void ertc_alarm_set(ertc_alarm_type alarm_x, uint8_t week_date, uint8_t hour, uint8_t min, uint8_t sec, ertc_am_pm_type ampm); |
| Function description | Set alarm  |
| Input parameter 1    | alarm_x: alarm selection<br>Refer to the following description "alarm_x" for details.  |

| Name                   | Description   |
|------------------------|---|
| Input parameter 2      | week_date: date or week, depending on the ertc_alarm_week_date_select()<br>Date: 1~31<br>Weekday: 1~7                                       |
| Input parameter 3      | hour: 0~23  |
| Input parameter 4      | min: 0~59   |
| Input parameter 5      | sec: 0~59   |
| Input parameter 6      | ampm: AM/PM in 12-hour format (12 hour format only, don't care in 24-hour format)<br>Refer to the following description "ampm" for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**alarm\_x**

Alarm selection

ERTC\_ALA: Alarm A

ERTC\_ALB: Alarm B

**ampm**

AM/PM in 12-hour format (for 12 hour format only, don't care in 24 hour)

ERTC\_24H: 24-hour format (for 24-hour format)

ERTC\_AM: AM in 12-hour format

ERTC\_PM: PM in 12-hour format

**Example:**

```
ertc_alarm_set(ERTC_ALA, 15, 8, 0, 0, ERTC_24H);
```

### 5.11.19 ertc\_alarm\_sub\_second\_set function

The table below describes the function ertc\_alarm\_sub\_second\_set.

**Table 278. ertc\_alarm\_sub\_second\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_alarm_sub_second_set   |
| Function prototype     | void ertc_alarm_sub_second_set(ertc_alarm_type alarm_x, uint32_t value, ertc_alarm_sbs_mask_type mask); |
| Function description   | Set alarm subsecond   |
| Input parameter 1      | alarm_x: alarm selection<br>Refer to the following description "alarm_x" for details.                   |
| Input parameter 2      | value: subsecond value, range 0~0x7FFF  |
| Input parameter 3      | mask: alarm mask settings<br>Refer to the following description "mask" for details.                     |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**alarm\_x**

Alarm selection

ERTC\_ALA: Alarm A

ERTC\_ALB: Alarm B

**mask**

Subsecond mask

- ERTC\_ALARM\_SBS\_MASK\_ALL: Mask all
- ERTC\_ALARM\_SBS\_MASK\_14\_1: Only match SBS bit [0]
- ERTC\_ALARM\_SBS\_MASK\_14\_2: Only match SBS bit [1:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_3: Only match SBS bit [2:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_4: Only match SBS bit [3:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_5: Only match SBS bit [4:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_6: Only match SBS bit [5:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_7: Only match SBS bit [6:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_8: Only match SBS bit [7:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_9: Only match SBS bit [8:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_10: Only match SBS bit [9:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_11: Only match SBS bit [10:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_12: Only match SBS bit [11:0]
- ERTC\_ALARM\_SBS\_MASK\_14\_13: Only match SBS bit [12:0]
- ERTC\_ALARM\_SBS\_MASK\_14: Only match SBS bit [13:0]
- ERTC\_ALARM\_SBS\_MASK\_NONE: Only match SBS bit [14:0]

**Example:**

```
ertc_alarm_sub_second_set(ERTC_ALA, 200, ERTC_ALARM_SBS_MASK_NONE);
```

### 5.11.20 ertc\_alarm\_enable function

The table below describes the function ertc\_alarm\_enable.

**Table 279. ertc\_alarm\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_alarm_enable   |
| Function prototype     | error_status ertc_alarm_enable(ertc_alarm_type alarm_x, confirm_state new_state);     |
| Function description   | Alarm enable  |
| Input parameter 1      | alarm_x: alarm selection<br>Refer to the following description "alarm_x" for details. |
| Input parameter 2      | new_state: alarm enable status<br>This parameter can be TRUE or FALSE.                |
| Output parameter       | NA  |
| Return value           | SUCCESS: Setting success<br>ERROR: Setting error                                      |
| Required preconditions | NA  |
| Called functions       | NA  |

**alarm\_x**

Alarm selection

ERTC\_ALA: Alarm A

ERTC\_ALB: Alarm B



**Example:**

```
ertc_alarm_enable(ERTC_ALA, TRUE);
```

## 5.11.21 ertc\_alarm\_get function

The table below describes the function ertc\_alarm\_get.

**Table 280. ertc\_alarm\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_alarm_get  |
| Function prototype     | void ertc_alarm_get(ertc_alarm_type alarm_x, ertc_alarm_value_type* alarm);           |
| Function description   | Get alarm value   |
| Input parameter 1      | alarm_x: alarm selection<br>Refer to the following description "alarm_x" for details. |
| Input parameter 2      | alarm: ertc_alarm_value_type pointer  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**alarm\_x**

Alarm selection

ERTC\_ALA: Alarm A

ERTC\_ALB: Alarm B

ertc\_alarm\_value\_type\* alarm

The ertc\_alarm\_value\_type is defined in the at32f435\_437\_ertc.h.

typedef struct

```
{
    uint8_t      day;
    uint8_t      hour;
    uint8_t      min;
    uint8_t      sec;
    ertc_am_pm_type ampm;
    uint32_t     mask;
    uint8_t      week_date_sel;
    uint8_t      week;
}
```

} ertc\_alarm\_value\_type;

**day**

Range: 1~31

**hour**

Range: 0~23

**min**

Range: 0~59

**sec**

Range: 0~59

**ampm**

AM/PM in 12-hour format (for 12-hour format only, don't care in 24 hour), including

ERTC\_AM: AM in 12-hour format

ERTC\_PM: PM in 12-hour format

**mask**

Alarm mask value, including

- ERTC\_ALARM\_MASK\_NONE: No mask
- ERTC\_ALARM\_MASK\_SEC: Mask second
- ERTC\_ALARM\_MASK\_MIN: Mask minute
- ERTC\_ALARM\_MASK\_HOUR: Mask hour
- ERTC\_ALARM\_MASK\_DATE\_WEEK: Mask date
- ERTC\_ALARM\_MASK\_ALL: Mask all, generate an alarm per one second

**week\_date\_sel**

Alarm week/date format, including

- ERTC\_SLECT\_DATE: date mode
- ERTC\_SLECT\_WEEK: week mode

**week**

Range: 1~7

**Example:**

```
ertc_alarm_get(ERTC_ALA, &alarm);
```

### 5.11.22 ertc\_alarm\_sub\_second\_get function

The table below describes the function ertc\_alarm\_sub\_second\_get.

**Table 281. ertc\_alarm\_sub\_second\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_alarm_sub_second_get   |
| Function prototype     | uint32_t ertc_alarm_sub_second_get(ertc_alarm_type alarm_x);                          |
| Function description   | Get alarm subsecond value   |
| Input parameter 1      | alarm_x: alarm selection<br>Refer to the following description "alarm_x" for details. |
| Output parameter       | NA  |
| Return value           | Alarm subsecond   |
| Required preconditions | NA  |
| Called functions       | NA  |

**alarm\_x**

Alarm selection

ERTC\_ALA: Alarm A

ERTC\_ALB: Alarm B

**Example:**

```
ertc_alarm_sub_second_get(ERTC_ALA);
```

### 5.11.23 ertc\_wakeup\_clock\_set function

The table below describes the function ertc\_wakeup\_clock\_set.

**Table 282. ertc\_wakeup\_clock\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_wakeup_clock_set   |
| Function prototype     | void ertc_wakeup_clock_set(ertc_wakeup_clock_type clock);                                       |
| Function description   | Select wakeup timer clock source  |
| Input parameter 1      | clock: clock source for wakeup timer<br>Refer to the following description "clock" for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### clock

Wakeup timer clock source

ERTC\_WAT\_CLK\_ERTCCLK\_DIV16: ERTC\_CLK / 16

ERTC\_WAT\_CLK\_ERTCCLK\_DIV8: ERTC\_CLK / 8

ERTC\_WAT\_CLK\_ERTCCLK\_DIV4: ERTC\_CLK / 4

ERTC\_WAT\_CLK\_ERTCCLK\_DIV2: ERTC\_CLK / 2

ERTC\_WAT\_CLK\_CK\_B\_16BITS: CK\_B (1Hz calendar clock), wakeup counter value = ERTC\_WAT

ERTC\_WAT\_CLK\_CK\_B\_17BITS: CK\_B (1Hz calendar clock), wakeup counter value = ERTC\_WAT + 65535

#### Example:

```
ertc_wakeup_clock_set(ERTC_WAT_CLK_CK_B_16BITS);
```

### 5.11.24 ertc\_wakeup\_counter\_set function

The table below describes the function ertc\_wakeup\_counter\_set.

**Table 283. ertc\_wakeup\_counter\_set function**

| Name                   | Description                                     |
|------------------------|---|
| Function name          | ertc_wakeup_counter_set                         |
| Function prototype     | void ertc_wakeup_counter_set(uint32_t counter); |
| Function description   | Set wakeup counter value                        |
| Input parameter 1      | counter: counter value, range: 0~0xFFFF         |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### Example:

```
ertc_wakeup_counter_set(0x7FFF);
```

### 5.11.25 ertc\_wakeup\_counter\_get function

The table below describes the function ertc\_wakeup\_counter\_get.

**Table 284. ertc\_wakeup\_counter\_get function**

| Name                   | Description                             |
|------------------------|---|
| Function name          | ertc_wakeup_counter_get                 |
| Function prototype     | uint16_t ertc_wakeup_counter_get(void); |
| Function description   | Get the current wakeup counter value    |
| Input parameter 1      | NA                                      |
| Output parameter       | NA                                      |
| Return value           | Return the current wakeup counter value |
| Required preconditions | NA                                      |
| Called functions       | NA                                      |

**Example:**

```
ertc_wakeup_counter_get();
```

### 5.11.26 ertc\_wakeup\_enable function

The table below describes the function ertc\_wakeup\_enable.

**Table 285. ertc\_wakeup\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_wakeup_enable   |
| Function prototype     | error_status ertc_wakeup_enable(confirm_state new_state);                    |
| Function description   | Enable wakeup timer  |
| Input parameter 1      | new_state: wakeup timer enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | SUCCESS: Setting success<br>ERROR: Setting error                             |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_wakeup_enable(TRUE);
```

### 5.11.27 ertc\_smooth\_calibration\_config function

The table below describes the function ertc\_smooth\_calibration\_config.

**Table 286. ertc\_smooth\_calibration\_config function**

| Name                 | Description  |
|----------------------|--|
| Function name        | ertc_smooth_calibration_config   |
| Function prototype   | error_status ertc_smooth_calibration_config(ertc_smooth_cal_period_type period, ertc_smooth_cal_clk_add_type clk_add, uint32_t clk_dec); |
| Function description | Set smooth digital calibration   |
| Input parameter 1    | period: calibration period   |

| Name                   | Description  |
|------------------------|--|
|                        | Refer to the following “period” descriptions for details.                                  |
| Input parameter 2      | clk_add: add ERTC CLK cycles<br>Refer to the following “clk_add” descriptions for details. |
| Input parameter 3      | clk_dec: reduce ERTC CLK cycles, range 0~511   |
| Output parameter       | NA   |
| Return value           | SUCCESS: Setting success<br>ERROR: Setting error   |
| Required preconditions | NA   |
| Called functions       | NA   |

**period**

Calibration period

ERTC\_SMOOTH\_CAL\_PERIOD\_32: 32 seconds

ERTC\_SMOOTH\_CAL\_PERIOD\_16: 16 seconds

ERTC\_SMOOTH\_CAL\_PERIOD\_8: 8 seconds

**clk\_add**

Add ERTC CLK

ERTC\_SMOOTH\_CAL\_CLK\_ADD\_0: No effect

ERTC\_SMOOTH\_CAL\_CLK\_ADD\_512: Add 512 ERTC\_CLK cycles

**Example:**

```
ertc_smooth_calibration_config(ERTC_SMOOTH_CAL_PERIOD_32, ERTC_SMOOTH_CAL_CLK_ADD_0, 511);
```

## 5.11.28 ertc\_coarse\_calibration\_set function

The table below describes the function ertc\_coarse\_calibration\_set.

**Table 287. ertc\_coarse\_calibration\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_coarse_calibration_set  |
| Function prototype     | error_status ertc_coarse_calibration_set(ertc_cal_direction_type dir, uint32_t value); |
| Function description   | Set coarse digital calibration   |
| Input parameter 1      | dir: calibration direction<br>Refer to the following “dir” descriptions for details.   |
| Input parameter 2      | value: calibration value, range 0~31   |
| Output parameter       | NA   |
| Return value           | SUCCESS: Setting success<br>ERROR: Setting error                                       |
| Required preconditions | NA   |
| Called functions       | NA   |

**dir**

Calibration direction

ERTC\_CAL\_DIR\_POSITIVE: Positive directin calibration

ERTC\_CAL\_DIR\_NEGATIVE: Negative directin calibration

**Example:**

```
ertc_coarse_calibration_set(ERTC_CAL_DIR_POSITIVE, 10);
```

### 5.11.29 ertc\_coarse\_calibration\_enable function

The table below describes the function ertc\_coarse\_calibration\_enable.

**Table 288. ertc\_coarse\_calibration\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_coarse_calibration_enable   |
| Function prototype     | error_status ertc_coarse_calibration_enable(confirm_state new_state);                      |
| Function description   | Enable coarse digital calibration  |
| Input parameter 1      | new_state: coarse digital calibration enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | SUCCESS: Setting success<br>ERROR: Setting error   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_coarse_calibration_enable(TRUE);
```

### 5.11.30 ertc\_cal\_output\_select function

The table below describes the function ertc\_cal\_output\_select.

**Table 289. ertc\_cal\_output\_select function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_cal_output_select  |
| Function prototype     | void ertc_cal_output_select(ertc_cal_output_select_type output);                                |
| Function description   | Calibration output source selection   |
| Input parameter 1      | output: Calibration output source<br>Refer to the following "output" descriptions for details . |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**output**

Calibration output source

ERTC\_CAL\_OUTPUT\_512HZ: 512 Hz output

ERTC\_CAL\_OUTPUT\_1HZ: 1 Hz output

**Example:**

```
ertc_cal_output_select(ERTC_CAL_OUTPUT_1HZ);
```

### 5.11.31 ertc\_cal\_output\_enable function

The table below describes the function ertc\_cal\_output\_enable.

**Table 290. ertc\_cal\_output\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_cal_output_enable   |
| Function prototype     | void ertc_cal_output_enable(confirm_state new_state);                              |
| Function description   | Calibration output enable  |
| Input parameter 1      | new_state: calibration output enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_cal_output_enable(TRUE);
```

### 5.11.32 ertc\_time\_adjust function

The table below describes the function ertc\_time\_adjust.

**Table 291. ertc\_time\_adjust function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_time_adjust   |
| Function prototype     | error_status ertc_time_adjust(ertc_time_adjust_type add1s, uint32_t decsbs);   |
| Function description   | Adjust time  |
| Input parameter 1      | add1s: add seconds<br>Refer to the following "add1s" descriptions for details. |
| Input parameter 2      | decsbs: reduce subseconds, range 0~0x7FFF                                      |
| Output parameter       | NA   |
| Return value           | SUCCESS: setting success<br>ERROR: setting error                               |
| Required preconditions | NA   |
| Called functions       | NA   |

**add1s**

This bit is used to add seconds.

ERTC\_TIME\_ADD\_NONE: No effect

ERTC\_TIME\_ADD\_1S: Add 1 second

**Example:**

```
ertc_time_adjust(ERTC_TIME_ADD_1S, 254);
```

### 5.11.33 ertc\_daylight\_set function

The table below describes the function ertc\_daylight\_set.

**Table 292. ertc\_daylight\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_daylight_set   |
| Function prototype     | void ertc_daylight_set(ertc_dst_operation_type operation, ertc_dst_save_type save);                       |
| Function description   | Set daylight-saving time  |
| Input parameter 1      | operation: daylight-saving time settings<br>Refer to the following “operation” descriptions for details . |
| Input parameter 2      | save: save daylight time<br>Refer to the following “save” descriptions for details .                      |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### **operation**

Daylight-saving time settings

ERTC\_DST\_ADD\_1H: Add 1 hour

ERTC\_DST\_DEC\_1H: Reduce 1 hour

#### **save**

Save daylight time

ERTC\_DST\_SAVE\_0: Set BPR=0 in the CTRL register

ERTC\_DST\_SAVE\_1: Set BPR=1 in the CTRL register

#### **Example:**

```
ertc_daylight_set(ERTC_DST_ADD_1H, ERTC_DST_SAVE_1);
```

### 5.11.34 ertc\_daylight\_bpr\_get function

The table below describes the function ertc\_daylight\_bpr\_get.

**Table 293. ertc\_daylight\_bpr\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_daylight_bpr_get  |
| Function prototype     | uint8_t ertc_daylight_bpr_get(void);   |
| Function description   | Get the value of daylight-saving time battery powered register (BPR bit in the CTRL register)    |
| Input parameter 1      | NA   |
| Output parameter       | NA   |
| Return value           | Return the value of daylight-saving time battery powered register (BPR bit in the CTRL register) |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **Example:**

```
ertc_daylight_bpr_get();
```



### 5.11.35 ertc\_refer\_clock\_detect\_enable function

The table below describes the function ertc\_refer\_clock\_detect\_enable.

**Table 294. ertc\_refer\_clock\_detect\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_refer_clock_detect_enable  |
| Function prototype     | error_status ertc_refer_clock_detect_enable(confirm_state new_state);                     |
| Function description   | Enable reference clock detection  |
| Input parameter 1      | new_state: reference clock detection enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | SUCCESS: Setting success<br>ERROR: Setting error  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
ertc_refer_clock_detect_enable(TRUE);
```

### 5.11.36 ertc\_direct\_read\_enable function

The table below describes the function ertc\_direct\_read\_enable

**Table 295. ertc\_direct\_read\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_direct_read_enable  |
| Function prototype     | void ertc_direct_read_enable(confirm_state new_state);                           |
| Function description   | Enable direct read mode  |
| Input parameter 1      | new_state: direct read mode enable state<br>This parameter can be TRUE or FALSE, |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_direct_read_enable(TRUE);
```

### 5.11.37 ertc\_output\_set function

The table below describes the function ertc\_output\_set.

**Table 296. ertc\_output\_set function**

| Name                 | Description  |
|----------------------|--|
| Function name        | ertc_output_set  |
| Function prototype   | void ertc_output_set(ertc_output_source_type source, ertc_output_polarity_type polarity, ertc_output_type type); |
| Function description | Set event output, event output on PC13   |

| Name                   | Description   |
|------------------------|---|
| Input parameter 1      | source: output source selection<br>Refer to the following “source” descriptions for details . |
| Input parameter 2      | polarity: output polarity<br>Refer to the following “polarity” descriptions for details .     |
| Input parameter 3      | type: output type<br>Refer to the following “type” descriptions for details .                 |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**source**

Output source selection

|                      |                      |
|----------------------|----------------------|
| ERTC_OUTPUT_DISABLE: | Output disabled      |
| ERTC_OUTPUT_ALARM_A: | Output alarm A event |
| ERTC_OUTPUT_ALARM_B: | Output alarm B event |
| ERTC_OUTPUT_WAKEUP:  | Output wakeup event  |

**polarity**

Output polarity

|                            |                                    |
|----------------------------|------------------------------------|
| ERTC_OUTPUT_POLARITY_HIGH: | Output high when an event occurred |
| ERTC_OUTPUT_POLARITY_LOW:  | Output low when an event occurred  |

**type**

Output type

|                              |                   |
|------------------------------|-------------------|
| ERTC_OUTPUT_TYPE_OPEN_DRAIN: | Open-drain output |
| ERTC_OUTPUT_TYPE_PUSH_PULL:  | Push-pull output  |

**Example:**

```
ertc_output_set(ERTC_OUTPUT_ALARM_A, ERTC_OUTPUT_POLARITY_HIGH,
ERTC_OUTPUT_TYPE_PUSH_PULL);
```

### 5.11.38 ertc\_timestamp\_pin\_select function

The table below describes the function ertc\_timestamp\_pin\_select.

**Table 297. ertc\_timestamp\_pin\_select function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_timestamp_pin_select   |
| Function prototype     | void ertc_timestamp_pin_select(ertc_pin_select_type pin);                               |
| Function description   | Timestamp detection pin selection   |
| Input parameter 1      | pin: Timestamp detection pin<br>Refer to the following “pin” descriptions for details . |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**pin**

Timestampe detection pin

ERTC\_PIN\_PC13: PC13 is selected as timestamp detection pin

ERTC\_PIN\_PA0: PA0 is selected as timestamp detection pin

**Example:**

```
ertc_timestamp_pin_select(ERTC_PIN_PC13);
```

### 5.11.39 ertc\_timestamp\_valid\_edge\_set function

The table below describes the function ertc\_timestamp\_valid\_edge\_set.

**Table 298. ertc\_timestamp\_valid\_edge\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_timestamp_valid_edge_set   |
| Function prototype     | void ertc_timestamp_valid_edge_set(ertc_timestamp_valid_edge_type edge);                        |
| Function description   | Set timestamp detection valid edge  |
| Input parameter 1      | edge: timestamp detection valid edge<br>Refer to the following "edge" descriptions for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**edge**

Timestamp detection valid edge

ERTC\_TIMESTAMP\_EDGE\_RISING: Rising edge

ERTC\_TIMESTAMP\_EDGE\_FALLING: Falling edge

**Example:**

```
ertc_timestamp_valid_edge_set(ERTC_TIMESTAMP_EDGE_RISING);
```

### 5.11.40 ertc\_timestamp\_enable function

The table below describes the function ertc\_timestamp\_enable.

**Table 299. ertc\_timestamp\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_timestamp_enable   |
| Function prototype     | void ertc_timestamp_enable(confirm_state new_state);                      |
| Function description   | Enable timestamp  |
| Input parameter 1      | new_state: timestamp enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
ertc_timestamp_enable(TRUE);
```

### 5.11.41 ertc\_timestamp\_get function

The table below describes the function ertc\_timestamp\_get.

**Table 300. ertc\_timestamp\_get function**

| Name                   | Description                                    |
|------------------------|--|
| Function name          | ertc_timestamp_get                             |
| Function prototype     | void ertc_timestamp_get(ertc_time_type* time); |
| Function description   | Get timestamp                                  |
| Input parameter 1      | time: ertc_time_type pointer                   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

ertc\_time\_type\* time

The ertc\_time\_type is defined in the at32f435\_437\_ertc.h.

typedef struct

```
{
    uint8_t      year;
    uint8_t      month;
    uint8_t      day;
    uint8_t      hour;
    uint8_t      min;
    uint8_t      sec;
    uint8_t      week;
    ertc_am_pm_type ampm;
}
```

} ertc\_time\_type;

**year**

Range: 0~99

**month**

Range: 1~12

**day**

Range: 1~31

**week**

Range: 1~7

**hour**

Range: 0~23

**min**

Range: 0~59

**sec**

Range: 0~59

**ampm**

AM/PM in 12-hour format (only for 12-hour format, don't care in 24-hour format), including:

ERTC\_AM: AM in 12-hour format

ERTC\_PM: PM in 12-hour format

**Example:**

```
ertc_timestamp_get(&time);
```

### 5.11.42 ertc\_timestamp\_sub\_second\_get function

The table below describes the function ertc\_timestamp\_sub\_second\_get.

**Table 301. ertc\_timestamp\_sub\_second\_get function**

| Name                   | Description                                   |
|------------------------|---|
| Function name          | ertc_timestamp_sub_second_get                 |
| Function prototype     | uint32_t ertc_timestamp_sub_second_get(void); |
| Function description   | Get timestamp subsecond                       |
| Input parameter 1      | NA  |
| Output parameter       | NA  |
| Return value           | Return timestamp subsecond                    |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
ertc_timestamp_sub_second_get();
```

### 5.11.43 ertc\_tamper\_1\_pin\_select function

The table below describes the function ertc\_tamper\_1\_pin\_select.

**Table 302. ertc\_tamper\_1\_pin\_select function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_tamper_1_pin_select  |
| Function prototype     | void ertc_tamper_1_pin_select(ertc_pin_select_type pin);                            |
| Function description   | Tamper detection 1 pin selection  |
| Input parameter 1      | pin: Tamper detection pin<br>Refer to the following “pin” descriptions for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**pin**

Tamper detection pin

ERTC\_PIN\_PC13: PC13 is selected as a tamper detection pin

ERTC\_PIN\_PA0: PA0 is selected as a tamper detection pin

**Example:**

```
ertc_tamper_1_pin_select(ERTC_PIN_PC13);
```

### 5.11.44 ertc\_tamper\_pull\_up\_enable function

The table below describes the function ertc\_tamper\_pull\_up\_enable.

**Table 303. ertc\_tamper\_pull\_up\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_tamper_pull_up_enable  |
| Function prototype     | void ertc_tamper_pull_up_enable(confirm_state new_state);                                   |
| Function description   | Enable tamper pin pull-up resistor  |
| Input parameter 1      | new_state: tamper pin pull-up resistor enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
ertc_tamper_pull_up_enable(TRUE);
```

### 5.11.45 ertc\_tamper\_precharge\_set function

The table below describes the function ertc\_tamper\_precharge\_set.

**Table 304. ertc\_tamper\_precharge\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_tamper_precharge_set   |
| Function prototype     | void ertc_tamper_precharge_set(ertc_tamper_precharge_type precharge);   |
| Function description   | Set tamper pin precharge time. This setting is needed only when the tamper pull-up resistor is enabled through the ertc_tamper_pull_up_enable function. |
| Input parameter 1      | precharge: tamper pin precharge time<br>Refer to the following “precharge” descriptions for details.  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**precharge**

Tamper pin precharge time

- ERTC\_TAMPER\_PR\_1\_ERTCCLK: One ERTC\_CLK cycle
- ERTC\_TAMPER\_PR\_2\_ERTCCLK: Two ERTC\_CLK cycles
- ERTC\_TAMPER\_PR\_4\_ERTCCLK: Four ERTC\_CLK cycles
- ERTC\_TAMPER\_PR\_8\_ERTCCLK: Eight ERTC\_CLK cycles

**Example:**

```
ertc_tamper_precharge_set(ERTC_TAMPER_PR_2_ERTCCLK);
```

### 5.11.46 ertc\_tamper\_filter\_set function

The table below describes the function ertc\_tamper\_filter\_set.

**Table 305. ertc\_tamper\_filter\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_tamper_filter_set   |
| Function prototype     | void ertc_tamper_filter_set(ertc_tamper_filter_type filter);                               |
| Function description   | Set tamper filtering time  |
| Input parameter 1      | filter: tamper filtering time<br>Refer to the following "filter" descriptions for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**filter**

Set tamper filtering time

ERTC\_TAMPER\_FILTER\_DISABLE:

No filtering

ERTC\_TAMPER\_FILTER\_2:

Tamper event is considered to have occur after two valid consecutive samplings

ERTC\_TAMPER\_FILTER\_4:

Tamper event is considered to have occur after four valid consecutive samplings

ERTC\_TAMPER\_FILTER\_8:

Tamper event is considered to have occur after eight valid consecutive samplings

**Example:**

```
ertc_tamper_filter_set(ERTC_TAMPER_FILTER_2);
```

### 5.11.47 ertc\_tamper\_detect\_freq\_set function

The table below describes the function ertc\_tamper\_detect\_freq\_set.

**Table 306. ertc\_tamper\_detect\_freq\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_tamper_detect_freq_set   |
| Function prototype     | void ertc_tamper_detect_freq_set(ertc_tamper_detect_freq_type freq);                        |
| Function description   | Set tamper detection frequency  |
| Input parameter 1      | freq: tamper detection frequency<br>Refer to the following "freq" descriptions for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**freq**

Select tamper detection frequency

ERTC\_TAMPER\_FREQ\_DIV\_32768: ERTC\_CLK / 32768

ERTC\_TAMPER\_FREQ\_DIV\_16384: ERTC\_CLK / 16384

```

ERTC_TAMPER_FREQ_DIV_8192:   ERTC_CLK / 8192
ERTC_TAMPER_FREQ_DIV_4096:   ERTC_CLK / 4096
ERTC_TAMPER_FREQ_DIV_2048:   ERTC_CLK / 2048
ERTC_TAMPER_FREQ_DIV_1024:   ERTC_CLK / 1024
ERTC_TAMPER_FREQ_DIV_512:    ERTC_CLK / 512
ERTC_TAMPER_FREQ_DIV_256:    ERTC_CLK / 256
    
```

**Example:**

```

ertc_tamper_detect_freq_set(ERTC_TAMPER_FREQ_DIV_512);
    
```

### 5.11.48 ertc\_tamper\_valid\_edge\_set function

The table below describes the function ertc\_tamper\_valid\_edge\_set.

**Table 307. ertc\_tamper\_valid\_edge\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_tamper_valid_edge_set  |
| Function prototype     | void ertc_tamper_valid_edge_set(ertc_tamper_select_type tamper_x, ertc_tamper_valid_edge_type trigger); |
| Function description   | Set tamper detection valid edge   |
| Input parameter 1      | tamper_x: tamper selection<br>Refer to the following "tamper_x" descriptions for details.               |
| Input parameter 2      | trigger: tamper detection valid edge<br>Refer to the following "trigger" descriptions for details.      |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**tamper\_x**

Tamper selection

ERTC\_TAMPER\_1: Tamper selection 1

ERTC\_TAMPER\_2: Tamper selection 2

**trigger**

Tamper detection valid edge selection

ERTC\_TAMPER\_EDGE\_RISING: Rising edge

ERTC\_TAMPER\_EDGE\_FALLING: Falling edge

ERTC\_TAMPER\_EDGE\_LOW: Low level

ERTC\_TAMPER\_EDGE\_HIGH: High level

**Example:**

```

ertc_tamper_valid_edge_set(ERTC_TAMPER_1, ERTC_TAMPER_EDGE_RISING);
    
```



### 5.11.49 ertc\_tamper\_timestamp\_enable function

The table below describes the function ertc\_tamper\_timestamp\_enable.

**Table 308. ertc\_tamper\_timestamp\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_tamper_timestamp_enable   |
| Function prototype     | void ertc_tamper_timestamp_enable(confirm_state new_state);  |
| Function description   | Enable timestamp when a tamper event occurs  |
| Input parameter 1      | new_state: timestamp feature enable state when a tamper event occurs<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
ertc_tamper_timestamp_enable(TRUE);
```

### 5.11.50 ertc\_tamper\_enable function

The table below describes the function ertc\_tamper\_enable.

**Table 309. ertc\_tamper\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_tamper_enable  |
| Function prototype     | void ertc_tamper_enable(ertc_tamper_select_type tamper_x, confirm_state new_state);       |
| Function description   | Enable tamper detection   |
| Input parameter 1      | tamper_x: tamper detection<br>Refer to the following “tamper_x” descriptions for details. |
| Input parameter 2      | new_state: tamper detection enable state<br>This parameter can be TRUE or FALSE.          |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**tamper\_x**

Tamper selection

ERTC\_TAMPER\_1: Tamper selection 1

ERTC\_TAMPER\_2: Tamper selection 2

**Example:**

```
ertc_tamper_enable(ERTC_TAMPER_1, TRUE);
```

### 5.11.51 ertc\_interrupt\_enable function

The table below describes the function ertc\_interrupt\_enable.

**Table 310. ertc\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_interrupt_enable   |
| Function prototype     | void ertc_interrupt_enable(uint32_t source, confirm_state new_state);                               |
| Function description   | Interrupt enable  |
|                        | source: interrupt source to be enabled<br>Refer to the following "source" descriptions for details. |
| Input parameter 1      | new_state: interrupt enable state<br>This parameter can be TRUE or FALSE.                           |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**source**

Interrupt source to be enabled

ERTC\_TP\_INT: Tamper detection interrupt

ERTC\_ALA\_INT: Alarm A interrupt

ERTC\_ALB\_INT: Alarm B interrupt

ERTC\_WAT\_INT: Wakeup timer interrupt

ERTC\_TS\_INT: Time stamp interrupt

**Example:**

```
ertc_interrupt_enable(ERTC_TP_INT, TRUE);
```

### 5.11.52 ertc\_interrupt\_get function

The table below describes the function ertc\_interrupt\_get.

**Table 311. ertc\_interrupt\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_interrupt_get  |
| Function prototype     | flag_status ertc_interrupt_get(uint32_t source);  |
| Function description   | Get interrupt enable state  |
| Input parameter 1      | source: interrupt enable state<br>Refer to the following "source" descriptions for details. |
| Output parameter       | NA  |
| Return value           | flag_status: flag status<br>This parameter can be SET or RESET.                             |
| Required preconditions | NA  |
| Called functions       | NA  |

**source**

Interrupt source

ERTC\_TP\_INT: Tamper detection interrupt

ERTC\_ALA\_INT: Alarm A interrupt

ERTC\_ALB\_INT: Alarm B interrupt  
 ERTC\_WAT\_INT: Wakeup timer interrupt  
 ERTC\_TS\_INT: Time stamp interrupt

**Example:**

```
ertc_interrupt_get(ERTC_TP_INT);
```

### 5.11.53 ertc\_flag\_get function

The table below describes the function ertc\_flag\_get.

**Table 312. ertc\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_flag_get   |
| Function prototype     | flag_status ertc_flag_get(uint32_tflag);  |
| Function description   | Get flag status   |
| Input parameter 1      | flag: flag selection<br>Refer to the following "flag" descriptions for details. |
| Output parameter       | NA  |
| Return value           | flag_status: flag status<br>This parameter can be SET or RESET.                 |
| Required preconditions | NA  |
| Called functions       | NA  |

**flag**

This bit is used to select a flag. Optional parameters are as follows:

ERTC\_ALAWF\_FLAG: Alarm A write enable flag  
 ERTC\_ALBWF\_FLAG: Alarm B write enable flag  
 ERTC\_WATWF\_FLAG: Wakeup timer register write enable flag  
 ERTC\_TADJF\_FLAG: Time adjust flag  
 ERTC\_INITF\_FLAG: Calendar initialization flag  
 ERTC\_UPDF\_FLAG: Calendar update flag  
 ERTC\_IMF\_FLAG: Initialization mode entry flag  
 ERTC\_ALAF\_FLAG: Alarm A flag  
 ERTC\_ALBF\_FLAG: Alarm B flag  
 ERTC\_WATF\_FLAG: Wakeup timer flag  
 ERTC\_TSF\_FLAG: Time stamp flag  
 ERTC\_TSOF\_FLAG: Time stamp overflow flag  
 ERTC\_TP1F\_FLAG: Tamper detection 1 flag  
 ERTC\_TP2F\_FLAG: Tamper detection 2 flag  
 ERTC\_CALUPDF\_FLAG: Calibration value update complete flag

**Example:**

```
ertc_flag_get(ERTC_TP1F_FLAG);
```

### 5.11.54 ertc\_flag\_clear function

The table below describes the function ertc\_flag\_clear.

**Table 313. ertc\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | ertc_flag_clear   |
| Function prototype     | void ertc_flag_clear(uint32_t flag);  |
| Function description   | Clear flag  |
| Input parameter 1      | flag: flag selection<br>Refer to the following "flag" descriptions for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### flag

This bit is used to select a flag. Optional parameters are as follows:

- ERTC\_ALAWF\_FLAG: Alarm A write enable flag
- ERTC\_ALBWF\_FLAG: Alarm B write enable flag
- ERTC\_WATWF\_FLAG: Wakeup timer register write enable flag
- ERTC\_TADJF\_FLAG: Time adjust flag
- ERTC\_INITF\_FLAG: Calendar initialization flag
- ERTC\_UPDF\_FLAG: Calendar update flag
- ERTC\_IMF\_FLAG: Initialization mode entry flag
- ERTC\_ALAF\_FLAG: Alarm A flag
- ERTC\_ALBF\_FLAG: Alarm B flag
- ERTC\_WATF\_FLAG: Wakeup timer flag
- ERTC\_TSF\_FLAG: Time stamp flag
- ERTC\_TSOFF\_FLAG: Time stamp overflow flag
- ERTC\_TP1F\_FLAG: Tamper detection 1 flag
- ERTC\_TP2F\_FLAG: Tamper detection 2 flag
- ERTC\_CALUPDF\_FLAG: Calibration value update complete flag

#### Example:

```
ertc_flag_clear(ERTC_TP1F_FLAG);
```

### 5.11.55 ertc\_bpr\_data\_write function

The table below describes the function ertc\_bpr\_data\_write.

**Table 314. ertc\_bpr\_data\_write function**

| Name                 | Description  |
|----------------------|--|
| Function name        | ertc_bpr_data_write  |
| Function prototype   | void ertc_bpr_data_write(ertc_dt_type dt, uint32_t data);                  |
| Function description | Write data to BPR register (battery powered data register)                 |
| Input parameter 1    | dt: data register<br>Refer to the following "dt" descriptions for details. |
| Input parameter 2    | data: 32-bit data  |

| Name                   | Description |
|------------------------|-------------|
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**dt**

Data register

ERTC\_DT1: Data register 1

ERTC\_DT2: Data register 2

ERTC\_DT19: Data register 19

ERTC\_DT20: Data register 20

**Example:**

```
ertc_bpr_data_write(ERTC_DT1,0x12345678);
```

### 5.11.56 ertc\_bpr\_data\_read function

The table below describes the function ertc\_bpr\_data\_read.

**Table 315. ertc\_bpr\_data\_read function**

| Name                   | Description  |
|------------------------|--|
| Function name          | ertc_bpr_data_read   |
| Function prototype     | uint32_t ertc_bpr_data_read(ertc_dt_type dt);                              |
| Function description   | Read data from BPR register (battery powered data register)                |
| Input parameter 1      | dt: data register<br>Refer to the following "dt" descriptions for details. |
| Output parameter       | NA   |
| Return value           | BPR register data  |
| Required preconditions | NA   |
| Called functions       | NA   |

**dt**

Data register

ERTC\_DT1: Data register 1

ERTC\_DT2: Data register 2

...

ERTC\_DT19: Data register 19

ERTC\_DT20: Data register 20

**Example:**

```
ertc_bpr_data_read(ERTC_DT1);
```

## 5.12 External interrupt/event controller (EXINT)

The EXINT register structure `exint_type` is defined in the “at32f435\_437\_exint.h”.

```
/**
 * @brief type define exint register all
 */
typedef struct
{
    ...
} exint_type;
```

The table below gives a list of the EXINT registers:

**Table 316. Summary of EXINT registers**

| Register | Description                       |
|----------|-----------------------------------|
| inten    | Interrupt enable register         |
| evten    | Event enable register             |
| polcfg1  | Polarity configuration register 1 |
| polcfg2  | Polarity configuration register 2 |
| swtrg    | Software trigger register         |
| intsts   | Interrupt status register         |

The table below gives a list of EXINT library functions.

**Table 317. Summary of EXINT library functions**

| Function name  | Description  |
|--|--|
| <code>exint_reset</code>                             | Reset all EXINT registers to their reset values              |
| <code>exint_default_para_init</code>                 | Configure the EXINT initial structure with the initial value |
| <code>exint_init</code>                              | Initialize EXINT   |
| <code>exint_flag_clear</code>                        | Clear the selected EXINT interrupt flag                      |
| <code>exint_flag_get</code>                          | Read the selected EXINT interrupt flag                       |
| <code>exint_software_interrupt_event_generate</code> | Software interrupt event generation                          |
| <code>exint_interrupt_enable</code>                  | Enable the selected EXINT interrupt                          |
| <code>exint_event_enable</code>                      | Enable the selected EXINT event                              |

### 5.12.1 `exint_reset` function

The table below describes the function `exint_reset`.

**Table 318. `exint_reset` function**

| Name                 | Description                                     |
|----------------------|---|
| Function name        | <code>exint_reset</code>                        |
| Function prototype   | <code>void exint_reset(void);</code>            |
| Function description | Reset all EXINT registers to their reset values |
| Input parameter      | NA  |
| Output parameter     | NA  |
| Return value         | NA  |

| Name                   | Description         |
|------------------------|---------------------|
| Required preconditions | NA                  |
| Called functions       | crm_periph_reset(); |

**Example:**

```
exint_reset();
```

### 5.12.2 exint\_default\_para\_init function

The table below describes the function `exint_default_para_init`.

**Table 319. exint\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>exint_default_para_init</code>  |
| Function prototype     | <code>void exint_default_para_init(exint_init_type *exint_struct);</code>                 |
| Function description   | Configure the EXINT initial structure with the initial value                              |
| Input parameter 1      | <code>exint_struct</code> : <a href="#">exint_init_type</a> pointer                       |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | It is necessary to define a variable of the <code>exint_init_type</code> before starting. |
| Called functions       | NA  |

**Example:**

```
exint_init_type exint_init_struct;
exint_default_para_init(&exint_init_struct);
```

### 5.12.3 exint\_init function

The table below describes the function `exint_init`.

**Table 320. exint\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>exint_init</code>   |
| Function prototype     | <code>void exint_init(exint_init_type *exint_struct);</code>                              |
| Function description   | Initialize EXINT  |
| Input parameter 1      | <a href="#">exint_init_type</a> : <code>exint_init_struct</code> pointer                  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | It is necessary to define a variable of the <code>exint_init_type</code> before starting. |
| Called functions       | NA  |

The `exint_init_type` is defined in the `at32f435_437_exint.h`.

typedef struct

```
{
    exint_line_mode_type    line_mode;
    uint32_t                line_select;
    exint_polarity_config_type line_polarity;
```

```
confirm_state          line_enable;
} exint_init_type;
```

**line\_mode**

Select event mode or interrupt mode

EXINT\_LINE\_INTERRUPT: Interrupt mode

EXINT\_LINE\_EVENT: Event mode

**line\_select**

Line selection

EXINT\_LINE\_NONE: No line

EXINT\_LINE\_0: line0

EXINT\_LINE\_1: line1

...

EXINT\_LINE\_21: line21

EXINT\_LINE\_22: line22

**line\_polarity**

Trigger edge selection

EXINT\_TRIGGER\_RISING\_EDGE: Rising edge

EXINT\_TRIGGER\_FALLING\_EDGE: Falling edge

EXINT\_TRIGGER\_BOTH\_EDGE: Rising/falling edge

**line\_enable**

Enable/disable line

FALSE: Disable line

TRUE: Enable line

**Example:**

```
exint_init_type exint_init_struct;
exint_default_para_init(&exint_init_struct);
exint_init_struct.line_enable = TRUE;
exint_init_struct.line_mode = EXINT_LINE_INTERRUPT;
exint_init_struct.line_select = EXINT_LINE_0;
exint_init_struct.line_polarity = EXINT_TRIGGER_RISING_EDGE;
exint_init(&exint_init_struct);
```

## 5.12.4 exint\_flag\_clear function

The table below describes the function `exint_flag_clear`.

**Table 321. exint\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>exint_flag_clear</code>   |
| Function prototype     | <code>void exint_flag_clear(uint32_t exint_line);</code>  |
| Function description   | Clear the selected EXINT interrupt flag   |
| Input parameter        | <code>exint_line</code> : line selection<br>Refer to the <a href="#">line_select</a> for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |



| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**Example:**

```
exint_flag_clear(EXINT_LINE_0);
```

### 5.12.5 exint\_flag\_get function

The table below describes the function `exint_flag_get`.

**Table 322. exint\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>exint_flag_get</code>   |
| Function prototype     | <code>flag_status exint_flag_get(uint32_t exint_line);</code>   |
| Function description   | Get the selected EXINT interrupt flag   |
| Input parameter        | <code>exint_line</code> : line selection<br>Refer to the <a href="#">line_select</a> for details.           |
| Output parameter       | NA  |
| Return value           | <code>flag_status</code> : indicates the status of the selected flag<br>This parameter can be SET or RESET. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flag_status status = RESET;
status = exint_flag_get(EXINT_LINE_0);
```

### 5.12.6 exint\_software\_interrupt\_event\_generate function

The table below describes the function `exint_software_interrupt_event_generate`.

**Table 323. exint\_software\_interrupt\_event\_generate function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>exint_software_interrupt_event_generate</code>  |
| Function prototype     | <code>void exint_software_interrupt_event_generate(uint32_t exint_line);</code>                   |
| Function description   | Generate software interrupt event   |
| Input parameter        | <code>exint_line</code> : line selection<br>Refer to the <a href="#">line_select</a> for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
exint_software_interrupt_event_generate (EXINT_LINE_0);
```

### 5.12.7 exint\_interrupt\_enable function

The table below describes the function `exint_interrupt_enable`.

**Table 324. exint\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>exint_interrupt_enable</code>   |
| Function prototype     | <code>void exint_interrupt_enable(uint32_t exint_line, confirm_state new_state);</code>           |
| Function description   | Enable the selected EXINT interrupt   |
| Input parameter 1      | <code>exint_line</code> : line selection<br>Refer to the <a href="#">line_select</a> for details. |
| Input parameter 2      | <code>new_state</code> : enable or disable<br>This parameter can be FALSE or TRUE.                |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
exint_interrupt_enable (EXINT_LINE_0);
```

### 5.12.8 exint\_event\_enable function

The table below describes the function `exint_event_enable`.

**Table 325. exint\_event\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>exint_event_enable</code>   |
| Function prototype     | <code>void exint_event_enable(uint32_t exint_line, confirm_state new_state);</code>               |
| Function description   | Enable the selected EXINT event   |
| Input parameter 1      | <code>exint_line</code> : line selection<br>Refer to the <a href="#">line_select</a> for details. |
| Input parameter 2      | <code>new_state</code> : enable or disable<br>This parameter can be FALSE or TRUE.                |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
exint_event_enable (EXINT_LINE_0);
```

## 5.13 Flash memory controller (FLASH)

The FLASH register structure flash\_type is defined in the “at32f435\_437\_flash.h”.

```
/**
 * @brief type define flash register all
 */
typedef struct
{
    ...
} flash_type;
```

The table below gives a list of the FLASH registers.

**Table 326. Summary of FLASH registers**

| Register         | Description                                   |
|------------------|---|
| flash_psr        | Flash performance select register             |
| flash_unlock     | Flash unlock register                         |
| flash_usd_unlock | Flash user system data unlock register        |
| flash_sts        | Flash status register                         |
| flash_ctrl       | Flash control register                        |
| flash_addr       | Flash address register                        |
| flash_usd        | User system data register                     |
| flash_epps0      | Erase/program protection status register 0    |
| flash_epps1      | Erase/program protection status register 1    |
| flash_unlock2    | Flash unlock register 2                       |
| flash_sts2       | Flash status register 2                       |
| flash_ctrl2      | Flash control register 2                      |
| flash_addr2      | Flash address register 2                      |
| flash_contr      | Flash continue read register                  |
| flash_divr       | Flash divider register                        |
| slib_sts2        | Flash securitylibrary status register 2       |
| slib_sts0        | Flash securitylibrary status register 0       |
| slib_sts1        | Flash securitylibrary status register 1       |
| slib_pwd_clr     | Flash securitylibrary password clear register |
| slib_misc_sts    | Security library additional status register   |
| slib_set_pwd     | Security library password setting register    |
| slib_set_range0  | Security library password setting register 0  |
| slib_set_range1  | Security library password setting register 1  |
| slib_unlock      | Security library unlock register              |
| flash_crc_ctrl   | Flash CRC calibration control register        |
| flash_crc_chkr   | Flash CRC check result register               |

The table below gives a list of FLASH library functions.

**Table 327. Summary of FLASH library functions**

| Function name                    | Description  |
|----------------------------------|--|
| flash_flag_get                   | Get flag status  |
| flash_flag_clear                 | Clear flag   |
| flash_operation_status_get       | Get Flash operation status                             |
| flash_bank1_operation_status_get | Get Flash operation status (Flash memorybank 1)        |
| flash_bank2_operation_status_get | Get Flash operation status (Flash memorybank 2)        |
| flash_operation_wait_for         | Wait for Flash operation complete                      |
| flash_bank1_operation_wait_for   | Wait for Flash operation complete (Flash memorybank 1) |
| flash_bank2_operation_wait_for   | Wait for Flash operation complete (Flash memorybank 2) |
| flash_unlock                     | Unlock Flash (Flash memorybank 1 and bank 2)           |
| flash_bank1_unlock               | Unlock Flash (Flash memorybank 1)                      |
| flash_bank2_unlock               | Unlock Flash (Flash memorybank 2)                      |
| flash_lock                       | Lock Flash (Flash memorybank 1 and bank 2)             |
| flash_bank1_lock                 | Lock Flash (Flash memorybank 1)                        |
| flash_bank2_lock                 | Lock Flash (Flash memorybank 2)                        |
| flash_sector_erase               | Erase Flash sector                                     |
| flash_block_erase                | Erase Flash memoryblock                                |
| flash_internal_all_erase         | Erase internal Flash                                   |
| flash_bank1_erase                | Erase Flash memorybank 1                               |
| flash_bank2_erase                | Erase Flash memorybank 2                               |
| flash_user_system_data_erase     | Erase user system data                                 |
| flash_eopb0_config               | Extended system option configuration                   |
| flash_word_program               | Flash word programming                                 |
| flash_halfword_program           | Flash half-word programming                            |
| flash_byte_program               | Flash byte programming                                 |
| flash_user_system_data_program   | User system data programming                           |
| flash_epp_set                    | Erase/programming protection configuration             |
| flash_epp_status_get             | Get erase/programming protection status                |
| flash_fap_enable                 | Configure Flash access protection                      |
| flash_fap_status_get             | Get Flash access protection status                     |
| flash_ssb_set                    | System configuration byte configuration                |
| flash_ssb_status_get             | Get system configuration byte configuration status     |
| flash_interrupt_enable           | Flash interrupt configuration                          |
| flash_slib_enable                | sLib enable  |
| flash_slib_disable               | sLib disable   |
| flash_slib_remaining_count_get   | Get sLib remaining count                               |
| flash_slib_state_get             | Get sLib status  |
| flash_slib_start_sector_get      | Get sLib start sector                                  |
| flash_slib_inststart_sector_get  | Get sLib instruction start sector                      |
| flash_slib_end_sector_get        | Get sLib end sector                                    |
| flash_crc_calibrate              | Flash CRC verify                                       |
| flash_nzw_boost_enable           | Flash non-zero-wait area boost enable                  |
| flash_continue_read_enable       | Flash continuous read enable                           |

### 5.13.1 flash\_flag\_get function

The table below describes the function flash\_flag\_get.

**Table 328. flash\_flag\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | flash_flag_get   |
| Function prototype     | flag_status flash_flag_get(uint32_t flash_flag);               |
| Function description   | Get flag status  |
| Input parameter        | flash_flag: flag selection                                     |
| Output parameter       | NA   |
| Return value           | flag_status: indicates the flag status<br>Return SET or RESET. |
| Required preconditions | NA   |
| Called functions       | NA   |

#### flash\_flag

Flag selection

|                          |                                   |
|--------------------------|-----------------------------------|
| FLASH_OBF_FLAG           | Flash operation busy              |
| FLASH_ODF_FLAG           | Flash operation complete          |
| FLASH_PRGMERR_FLAG       | Flash programming error           |
| FLASH_EPPERR_FLAG        | Flash erase error                 |
| FLASH_BANK1_OBF_FLAG     | Flash operation busy (bank 1)     |
| FLASH_BANK1_ODF_FLAG     | Flash operation complete (bank 1) |
| FLASH_BANK1_PRGMERR_FLAG | Flash programming error (bank 1)  |
| FLASH_BANK1_EPPERR_FLAG  | Flash erase error (bank 1)        |
| FLASH_BANK2_OBF_FLAG     | Flash operation busy (bank 2)     |
| FLASH_BANK2_ODF_FLAG     | Flash operation complete (bank 2) |
| FLASH_BANK2_PRGMERR_FLAG | Flash programming error (bank 2)  |
| FLASH_BANK2_EPPERR_FLAG  | Flash erase error (bank 2)        |
| FLASH_USDERR_FLAG        | User system data area error       |

#### Example:

```
flag_status status;
status = flash_flag_get(FLASH_ODF_FLAG);
```

### 5.13.2 flash\_flag\_clear function

The table below describes the function flash\_flag\_clear.

**Table 329. flash\_flag\_clear function**

| Name                   | Description                                 |
|------------------------|---|
| Function name          | flash_flag_clear                            |
| Function prototype     | void flash_flag_clear(uint32_t flash_flag); |
| Function description   | Clear flag                                  |
| Input parameter        | flash_flag: flag selection                  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |

| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**flash\_flag**

Flag selection

|                          |   |
|--------------------------|---|
| FLASH_ODF_FLAG           | Flash operation complete                |
| FLASH_PRGMERR_FLAG       | Flash programming error                 |
| FLASH_EPPERR_FLAG        | Flash erase error                       |
| FLASH_BANK1_ODF_FLAG     | Flash operation complete (Flash bank 1) |
| FLASH_BANK1_PRGMERR_FLAG | Flash programming error (Flash bank 1)  |
| FLASH_BANK1_EPPERR_FLAG  | Flash erase error (Flash bank 1)        |
| FLASH_BANK2_ODF_FLAG     | Flash operation complete (Flash bank 2) |
| FLASH_BANK2_PRGMERR_FLAG | Flash programming error (Flash bank 2)  |
| FLASH_BANK2_EPPERR_FLAG  | Flash erase error (Flash bank 2)        |

**Example:**

```
flash_flag_clear(FLASH_ODF_FLAG);
```

### 5.13.3 flash\_operation\_status\_get function

The table below describes the function `flash_operation_status_get`.

**Table 330. flash\_operation\_status\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>flash_operation_status_get</code>                                     |
| Function prototype     | <code>flash_status_type flash_operation_status_get(void);</code>            |
| Function description   | Get operation status  |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**flash\_status\_type**

|                       |                                |
|-----------------------|--------------------------------|
| FLASH_OPERATE_BUSY    | Operate busy                   |
| FLASH_PROGRAM_ERROR   | Programming error              |
| FLASH_EPP_ERROR       | Erase/program protection error |
| FLASH_OPERATE_DONE    | Operation complete             |
| FLASH_OPERATE_TIMEOUT | Flash operate timeout          |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
/* check for the flash status */
status = flash_operation_status_get();
```

### 5.13.4 flash\_bank1\_operation\_status\_get function

The table below describes the function flash\_bank1\_operation\_status\_get.

**Table 331. flash\_bank1\_operation\_status\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_bank1_operation_status_get  |
| Function prototype     | flash_status_type flash_bank1_operation_status_get(void);                   |
| Function description   | Get the Flash bank 1 operation status                                       |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
/* check for the flash status */
status = flash_bank1_operation_status_get();
```

### 5.13.5 flash\_bank2\_operation\_status\_get function

The table below describes the function flash\_bank2\_operation\_status\_get.

**Table 332. flash\_bank2\_operation\_status\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_bank2_operation_status_get  |
| Function prototype     | flash_status_type flash_bank2_operation_status_get(void);                   |
| Function description   | Get the Flash bank 2 operation status                                       |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
/* check for the flash status */
status = flash_bank2_operation_status_get();
```

### 5.13.6 flash\_operation\_wait\_for function

The table below describes the function flash\_operation\_wait\_for.

**Table 333. flash\_operation\_wait\_for function**

| Name                   | Description  |
|------------------------|--|
| Function name          | flash_operation_wait_for   |
| Function prototype     | flash_status_type flash_operation_wait_for(uint32_t time_out);   |
| Function description   | Wait for Flash operation   |
| Input parameter        | time_out: wait timeout<br>The timeout value is defined in the flash.h file. Refer to <a href="#">flash_time_out</a> for details. |
| Output parameter       | NA   |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.  |
| Required preconditions | NA   |
| Called functions       | NA   |

#### flash\_time\_out

|                     |                           |
|---------------------|---------------------------|
| ERASE_TIMEOUT       | Erase timeout             |
| PROGRAMMING_TIMEOUT | Programming timeout       |
| OPERATION_TIMEOUT   | General operation timeout |

#### Example:

```
/* wait for operation to be completed */
status = flash_operation_wait_for(PROGRAMMING_TIMEOUT);
```

### 5.13.7 flash\_bank1\_operation\_wait\_for function

The table below describes the function flash\_bank1\_operation\_wait\_for.

**Table 334. flash\_bank1\_operation\_wait\_for function**

| Name                   | Description  |
|------------------------|--|
| Function name          | flash_bank1_operation_wait_for   |
| Function prototype     | flash_status_type flash_bank1_operation_wait_for(uint32_t time_out);   |
| Function description   | Wait for Flash bank 1 operation  |
| Input parameter        | time_out: wait timeout<br>The timeout value is defined in the flash.h file. Refer to <a href="#">flash_time_out</a> for details. |
| Output parameter       | NA   |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.  |
| Required preconditions | NA   |
| Called functions       | NA   |

#### Example:

```
/* wait for operation to be completed */
status = flash_bank1_operation_wait_for(PROGRAMMING_TIMEOUT);
```



### 5.13.8 flash\_bank2\_operation\_wait\_for function

The table below describes the function flash\_bank2\_operation\_wait\_for.

**Table 335. flash\_bank2\_operation\_wait\_for function**

| Name                   | Description  |
|------------------------|--|
| Function name          | flash_bank2_operation_wait_for   |
| Function prototype     | flash_status_type flash_bank2_operation_wait_for(uint32_t time_out);   |
| Function description   | Wait for Flash bank 2 operation  |
| Input parameter        | time_out: wait timeout<br>The timeout value is defined in the flash.h file. Refer to <a href="#">flash_time_out</a> for details. |
| Output parameter       | NA   |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.  |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* wait for operation to be completed */
status = flash_bank2_operation_wait_for(PROGRAMMING_TIMEOUT);
```

### 5.13.9 flash\_unlock function

The table below describes the function flash\_unlock.

**Table 336. flash\_unlock function**

| Name                   | Description                   |
|------------------------|-------------------------------|
| Function name          | flash_unlock                  |
| Function prototype     | void flash_unlock(void);      |
| Function description   | Unlock Flash control register |
| Input parameter        | NA                            |
| Output parameter       | NA                            |
| Return value           | NA                            |
| Required preconditions | NA                            |
| Called functions       | NA                            |

**Example:**

```
flash_unlock();
```

### 5.13.10 flash\_bank1\_unlock function

The table below describes the function flash\_bank1\_unlock.

**Table 337. flash\_bank1\_unlock function**

| Name                 | Description                          |
|----------------------|--------------------------------------|
| Function name        | flash_bank1_unlock                   |
| Function prototype   | void flash_bank1_unlock(void);       |
| Function description | Unlock Flash bank 1 control register |
| Input parameter      | NA                                   |

| Name                   | Description |
|------------------------|-------------|
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

```
flash_bank1_unlock();
```

### 5.13.11 flash\_bank2\_unlock function

The table below describes the function flash\_bank2\_unlock.

**Table 338. flash\_bank2\_unlock function**

| Name                   | Description                          |
|------------------------|--------------------------------------|
| Function name          | flash_bank2_unlock                   |
| Function prototype     | void flash_bank2_unlock(void);       |
| Function description   | Unlock Flash bank 2 control register |
| Input parameter        | NA                                   |
| Output parameter       | NA                                   |
| Return value           | NA                                   |
| Required preconditions | NA                                   |
| Called functions       | NA                                   |

**Example:**

```
flash_bank2_unlock();
```

### 5.13.12 flash\_lock function

The table below describes the function flash\_lock.

**Table 339. flash\_lock function**

| Name                   | Description                 |
|------------------------|-----------------------------|
| Function name          | flash_lock                  |
| Function prototype     | void flash_lock(void);      |
| Function description   | Lock Flash control register |
| Input parameter        | NA                          |
| Output parameter       | NA                          |
| Return value           | NA                          |
| Required preconditions | NA                          |
| Called functions       | NA                          |

**Example:**

```
flash_lock();
```

### 5.13.13 flash\_bank1\_lock function

The table below describes the function flash\_bank1\_lock.

**Table 340. flash\_bank1\_lock function**

| Name                   | Description                        |
|------------------------|------------------------------------|
| Function name          | flash_bank1_lock                   |
| Function prototype     | void flash_bank1_lock(void);       |
| Function description   | Lock Flash bank 1 control register |
| Input parameter        | NA                                 |
| Output parameter       | NA                                 |
| Return value           | NA                                 |
| Required preconditions | NA                                 |
| Called functions       | NA                                 |

**Example:**

```
flash_bank1_lock();
```

### 5.13.14 flash\_bank2\_lock function

The table below describes the function flash\_bank2\_lock.

**Table 341. flash\_bank2\_lock function**

| Name                   | Description                        |
|------------------------|------------------------------------|
| Function name          | flash_bank2_lock                   |
| Function prototype     | void flash_bank2_lock(void);       |
| Function description   | Lock Flash bank 2 control register |
| Input parameter        | NA                                 |
| Output parameter       | NA                                 |
| Return value           | NA                                 |
| Required preconditions | NA                                 |
| Called functions       | NA                                 |

**Example:**

```
flash_bank2_lock();
```

### 5.13.15 flash\_sector\_erase function

The table below describes the function flash\_sector\_erase.

**Table 342. flash\_sector\_erase function**

| Name                 | Description  |
|----------------------|--|
| Function name        | flash_sector_erase   |
| Function prototype   | flash_status_type flash_sector_erase(uint32_t sector_address);                                   |
| Function description | Erase data in the selected Flash sector address  |
| Input parameter      | sector_address: select the Flash sector address to be erased, usually Flash sector start address |
| Output parameter     | NA   |
| Return value         | Operation status   |

| Name                   | Description   |
|------------------------|---|
|                        | Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_sector_erase(0x08001000);
```

### 5.13.16 flash\_block\_erase function

The table below describes the function flash\_block\_erase.

**Table 343. flash\_block\_erase function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_block_erase   |
| Function prototype     | flash_status_type flash_block_erase(uint32_t block_address);                                  |
| Function description   | Erase data in the selected Flash block address  |
| Input parameter        | block_address: select the Flash block address to be erased, usually Flash block start address |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.                   |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_block_erase(0x08010000);
```

### 5.13.17 flash\_internal\_all\_erase function

The table below describes the function flash\_internal\_all\_erase.

**Table 344. flash\_internal\_all\_erase function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_internal_all_erase  |
| Function prototype     | flash_status_type flash_internal_all_erase(void);                           |
| Function description   | Erase internal Flash data   |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
```

```
flash_unlock();
status = flash_internal_all_erase();
```

### 5.13.18 flash\_bank1\_erase function

The table below describes the function flash\_bank1\_erase.

**Table 345. flash\_bank1\_erase function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_bank1_erase   |
| Function prototype     | flash_status_type flash_bank1_erase(void);                                  |
| Function description   | Erase Flash bank 1 data   |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_bank1_unlock();
status = flash_bank1_erase();
```

### 5.13.19 flash\_bank2\_erase function

The table below describes the function flash\_bank2\_erase.

**Table 346. flash\_bank2\_erase function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_bank2_erase   |
| Function prototype     | flash_status_type flash_bank2_erase(void);                                  |
| Function description   | Erase Flash bank 2 data   |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_bank2_unlock();
status = flash_bank2_erase();
```

### 5.13.20 flash\_user\_system\_data\_erase function

The table below describes the function flash\_user\_system\_data\_erase.

**Table 347. flash\_user\_system\_data\_erase function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_user_system_data_erase  |
| Function prototype     | flash_status_type flash_user_system_data_erase(void);                       |
| Function description   | Erase user system data  |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

*Note: As this function remains in FAP state, it only erases data except FAP in the user system data area.*

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_user_system_data_erase();
```

### 5.13.21 flash\_eopb0\_config function

The table below describes the function flash\_eopb0\_config.

**Table 348. flash\_eopb0\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_eopb0_config  |
| Function prototype     | flash_status_type flash_eopb0_config(flash_usd_eopb0_type data);            |
| Function description   | Extended system option configuration  |
| Input parameter        | data: Extended system size; refer to flash_usd_eopb0_type.                  |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**flash\_usd\_eopb0\_type**

|                       |   |
|-----------------------|---|
| FLASH_EOPB0_SRAM_512K | On-chip 512 KB SRAM + 128 KB zero-wait-state Flash  |
| FLASH_EOPB0_SRAM_448K | On-chip 448 KB SRAM + 192 KB zero-wait-state Flash  |
| FLASH_EOPB0_SRAM_384K | On-chip 384 KB SRAM + 256 KB zero-wait-state Flash  |
| FLASH_EOPB0_SRAM_320K | On-chip 320 KB SRAM + 320 KB zero-wait-state Flash  |
| FLASH_EOPB0_SRAM_256K | On-chip 256 KB SRAM + 384 KB zero-wait-state Flash  |
| FLASH_EOPB0_SRAM_192K | On-chip 192k KB SRAM + 448 KB zero-wait-state Flash |
| FLASH_EOPB0_SRAM_128K | On-chip 128k KB SRAM + 512 KB zero-wait-state Flash |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
```

```
flash_unlock();
status = flash_eopb0_config(FLASH_EOPB0_SRAM_512K);
```

### 5.13.22 flash\_word\_program function

The table below describes the function flash\_word\_program.

**Table 349. flash\_word\_program function**

| Name                   | Description  |
|------------------------|--|
| Function name          | flash_word_program   |
| Function prototype     | flash_status_type flash_word_program(uint32_t address, uint32_t data);               |
| Function description   | Write one word data to a given address   |
| Input parameter 1      | address: programmed address, word-aligned  |
| Input parameter 2      | data: programmed data  |
| Output parameter       | NA   |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.          |
| Required preconditions | The programming operation can be allowed only when data in the address are all 0xFF. |
| Called functions       | NA   |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
uint32_t i;
flash_unlock();
status = flash_sector_erase(0x08001000);
if(status == FLASH_OPERATE_DONE)
{
    /* program 256 words */
    for(i = 0; i < 256; i++)
    {
        status = flash_word_program(0x08001000 + i*4, i);
    }
}
```

### 5.13.23 flash\_halfword\_program function

The table below describes the function flash\_halfword\_program.

**Table 350. flash\_halfword\_program function**

| Name                 | Description  |
|----------------------|--|
| Function name        | flash_halfword_program   |
| Function prototype   | flash_status_type flash_halfword_program(uint32_t address, uint16_t data); |
| Function description | Write a half-word data to a given address                                  |
| Input parameter 1    | address: programmed address, half-word-aligned                             |
| Input parameter 2    | data: programmed data  |
| Output parameter     | NA   |
| Return value         | Operation status   |

| Name                   | Description  |
|------------------------|--|
|                        | Refer to <a href="#">flash_status_type</a> for details.                              |
| Required preconditions | The programming operation can be allowed only when data in the address are all 0xFF. |
| Called functions       | NA   |

**Example:**

```

flash_status_type status = FLASH_OPERATE_DONE;
uint32_t i;
flash_unlock();
status = flash_sector_erase(0x08001000);
if(status == FLASH_OPERATE_DONE)
{
    /* program 256 halfwords */
    for(i = 0; i < 256; i++)
    {
        status = flash_halfword_program(0x08001000 + i*2, (uint16_t)i);
    }
}

```

### 5.13.24 flash\_byte\_program function

The table below describes the function flash\_byte\_program

**Table 351. flash\_byte\_program function**

| Name                   | Description  |
|------------------------|--|
| Function name          | flash_byte_program   |
| Function prototype     | flash_status_type flash_byte_program(uint32_t address, uint8_t data);                |
| Function description   | Program a byte data to a given address   |
| Input parameter 1      | address: programmed address  |
| Input parameter 2      | data: programmed data  |
| Output parameter       | NA   |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.          |
| Required preconditions | The programming operation can be allowed only when data in the address are all 0xFF. |
| Called functions       | NA   |

**Example:**

```

flash_status_type status = FLASH_OPERATE_DONE;
uint32_t i;
flash_unlock();
status = flash_sector_erase(0x08001000);
if(status == FLASH_OPERATE_DONE)
{
    /* program 256 bytes */
    for(i = 0; i < 256; i++)
    {

```



```

status = flash_byte_program(0x08001000 + i*2, (uint8_t)i);
}
}

```

### 5.13.25 flash\_user\_system\_data\_program function

The table below describes the function flash\_user\_system\_data\_program.

**Table 352. flash\_user\_system\_data\_program function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_user_system_data_program  |
| Function prototype     | flash_status_type flash_user_system_data_program (uint32_t address, uint8_t data);                                      |
| Function description   | Program a byte data to a given address in the user system data area   |
| Input parameter 1      | address: programmed address   |
| Input parameter 2      | data: programmed data   |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.   |
| Required preconditions | The programming operation can be allowed only when data and its inverse data in the user system data area are all 0xFF. |
| Called functions       | NA  |

**Example:**

```

flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_user_system_data_erase();
if(status == FLASH_OPERATE_DONE)
{
/* program user system data */
status = flash_user_system_data_program(0x1FFFF804, 0x55);
}

```

### 5.13.26 flash\_epp\_set function

The table below describes the function flash\_epp\_set.

**Table 353. flash\_epp\_set function**

| Name                 | Description  |
|----------------------|--|
| Function name        | flash_epp_set  |
| Function prototype   | flash_status_type flash_epp_set(uint32_t*sector_bits);   |
| Function description | Configure erase/programming protection   |
| Input parameter      | *sector_bits: Erase/programming protection sector address pointer.<br>Each bit in bits [31:0] protects 4KB sectors, and each bit in bits [62:32] protects 128KB sectors.<br>Setting this bit to 1 enables sector protection. |
| Output parameter     | NA   |
| Return value         | Operation status   |

| Name                   | Description   |
|------------------------|---|
|                        | Refer to <a href="#">flash_status_type</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

flash_status_type status = FLASH_OPERATE_DONE;
uint32_t epp_val[2];
flash_unlock();
status = flash_user_system_data_erase();
if(status == FLASH_OPERATE_DONE)
{
    epp_val[0] = 0x00000001;
    epp_val[1] = 0x00000001;
    /* program epp */
    status = flash_epp_set(epp_val);
}
    
```

### 5.13.27 flash\_epp\_status\_get function

The table below describes the function `flash_epp_status_get`.

**Table 354. flash\_epp\_status\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>flash_epp_status_get</code>  |
| Function prototype     | <code>void flash_epp_status_get(uint32_t*sector_bits);</code>  |
| Function description   | Get the status of erase/programming protection   |
| Input parameter        | NA   |
| Output parameter       | *sector_bits: Erase/programming protection sector address pointer.<br>Each bit in bits [31:0] protects 4KB sectors, and each bit in bits [62:32] protects 128KB sectors.<br>Setting this bit to 1 enables sector protection. |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```

uint32_t epp_val[2];
/* get epp status */
flash_epp_status_get(epp_val);
    
```

### 5.13.28 flash\_fap\_enable function

The table below describes the function flash\_fap\_enable.

**Table 355. flash\_fap\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_fap_enable  |
| Function prototype     | flash_status_type flash_fap_enable(confirm_state new_state);                      |
| Function description   | Enable Flash access protection  |
| Input parameter        | new_state: Flash access protection status<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.       |
| Required preconditions | NA  |
| Called functions       | NA  |

*Note: This function will erase the whole user system data area. If there were data programmed in the user system data area before calling this function, they have to be re-programmed after calling this function.*

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_fap_enable(TRUE);
```

### 5.13.29 flash\_fap\_status\_get function

The table below describes the function flash\_fap\_status\_get.

**Table 356. flash\_fap\_status\_get function**

| Name                   | Description                                      |
|------------------------|--|
| Function name          | flash_fap_status_get                             |
| Function prototype     | flag_status flash_fap_status_get(void);          |
| Function description   | Get the status of Flash access protection        |
| Input parameter        | NA   |
| Output parameter       | NA   |
| Return value           | flag_status: flag status<br>Return SET or RESET. |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
flag_status status;
status = flash_fap_status_get();
```

### 5.13.30 flash\_ssb\_set function

The table below describes the function flash\_ssb\_set.

**Table 357. flash\_ssb\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_ssb_set   |
| Function prototype     | flash_status_type flash_ssb_set(uint8_t usd_ssb);                                       |
| Function description   | Set the status of system setting bytes  |
| Input parameter        | usd_ssb: system setting bytes.<br>Refer to <a href="#">ssb_data_define</a> for details. |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.             |
| Required preconditions | NA  |
| Called functions       | NA  |

#### ssb\_data\_define

type 1:

USD\_WDT\_ATO\_DISABLE      Watchdog is disabled  
 USD\_WDT\_ATO\_ENABLE      Watchdog is enabled

type 2:

USD\_DEPSLP\_NO\_RST      No reset occurs when entering Deepsleep mode  
 USD\_DEPSLP\_RST      Reset occurs when entering Deepsleep mode

type 3: USD\_STDBY\_NO\_RST      No reset occurs when entering Standby mode  
 USD\_STDBY\_RST      Reset occurs when entering Standby mode

type 4:

FLASH\_BOOT\_FROM\_BANK1      Start from Flash memory bank 1  
 FLASH\_BOOT\_FROM\_BANK2      Start from Flash memory bank 2

type 5:

USD\_WDT\_DEPSLP\_CONTINUE      WDT does not stop counting while entering Deepsleep mode  
 USD\_WDT\_DEPSLP\_STOP      WDT stops counting while entering Deepsleep mode

type 6:

USD\_WDT\_STDBY\_CONTINUE      WDT does not stop counting while entering Standby mode  
 USD\_WDT\_STDBY\_STOP      WDT stops counting while entering Standby mode

type 7:

USD\_WDT\_STDBY\_CONTINUE      WDT does not stop counting while entering Standby mode  
 USD\_WDT\_STDBY\_STOP      WDT stops counting while entering Standby mode

#### Example:

```

flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_user_system_data_erase();
if(status == FLASH_OPERATE_DONE)
{
    status = flash_ssb_set(USD_WDT_ATO_DISABLE | USD_DEPSLP_NO_RST | USD_STDBY_RST |
FLASH_BOOT_FROM_BANK1);
}
    
```

### 5.13.31 flash\_ssb\_status\_get function

The table below describes the function flash\_ssb\_status\_get.

**Table 358. flash\_ssb\_status\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_ssb_status_get  |
| Function prototype     | uint8_t flash_ssb_status_get(void);   |
| Function description   | Get the status of system setting bytes  |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | System setting bytes<br>Refer to <a href="#">ssb_data_define</a> for details. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
uint8_t ssb_val;
ssb_val = flash_ssb_status_get();
```

### 5.13.32 flash\_interrupt\_enable function

The table below describes the function flash\_interrupt\_enable.

**Table 359. flash\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_interrupt_enable  |
| Function prototype     | void flash_interrupt_enable(uint32_t flash_int, confirm_state new_state);                   |
| Function description   | Enable Flash interrupts   |
| Input parameter 1      | flash_int: Flash interrupt type. Refer to <a href="#">flash_interrupt_type</a> for details. |
| Input parameter 2      | new_state: interrupt status<br>This parameter can be TRUE or FALSE.                         |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**flash\_interrupt\_type**

- FLASH\_ERR\_INT                      Flash error interrupt
- FLASH\_ODF\_INT                     Flash operation complete interrupt
- FLASH\_BANK1\_ERR\_INT              Flash bank 1 error interrupt
- FLASH\_BANK1\_ODF\_INT              Flash bank 1 operation complete interrupt
- FLASH\_BANK2\_ERR\_INT              Flash bank 2 error interrupt
- FLASH\_BANK2\_ODF\_INT              Flash bank 2 operation complete interrupt

**Example:**

```
flash_interrupt_enable(FLASH_BANK1_ERR_INT | FLASH_BANK1_ODF_INT, TRUE);
```

### 5.13.33 flash\_slib\_enable function

The table below describes the function flash\_slib\_enable

**Table 360. flash\_slib\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_slib_enable   |
| Function prototype     | flash_status_type flash_slib_enable(uint32_t pwd, uint16_t start_sector, uint16_t inst_start_sector, uint16_t end_sector);                                      |
| Function description   | Enable security library (sLib) and configure its address range  |
| Input parameter 1      | pwd: sLib password.<br>The sLib data are saved as ciphertext, associated with encrypted computing. A correct password is entered in order to unlock encryption. |
| Input parameter 2      | start_sector: sLib start sector number  |
| Input parameter 3      | inst_start_sector: sLib instruction area start sector number  |
| Input parameter 4      | end_sector: sLib end sector number  |
| Output parameter       | NA  |
| Return value           | Operation status<br>Refer to <a href="#">flash_status_type</a> for details.   |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flash_status_type status = FLASH_OPERATE_DONE;
status = flash_slib_enable(0x12345678, 0x04, 0x05, 0x06);
```

### 5.13.34 flash\_slib\_disable function

The table below describes the function flash\_slib\_disable.

**Table 361. flash\_slib\_disable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | flash_slib_disable   |
| Function prototype     | error_status flash_slib_disable(uint32_t pwd);   |
| Function description   | Disable security library (sLib)  |
| Input parameter        | pwd: sLib password.<br>It must be entered correctly, otherwise it is not allowed to enter until reset. |
| Output parameter       | NA   |
| Return value           | Return error status<br>This parameter can be ERROR or SUCCESS.   |
| Required preconditions | NA   |
| Called functions       | NA   |

*Note: Successful calling of this function will erase the whole internal Flash memory*

**Example:**

```
error_status status;
status = flash_slib_disable(0x12345678);
```

### 5.13.35 flash\_slib\_remaining\_count\_get function

The table below describes the function flash\_slib\_remaining\_count\_get.

**Table 362. flash\_slib\_remaining\_count\_get function**

| Name                   | Description                                    |
|------------------------|--|
| Function name          | flash_slib_remaining_count_get                 |
| Function prototype     | uint32_t flash_slib_remaining_count_get(void); |
| Function description   | Get the sLib remaining count                   |
| Input parameter        | NA   |
| Output parameter       | NA   |
| Return value           | Return the sLib remaining count                |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
uint32_t num;
num = flash_slib_remaining_count_get();
```

### 5.13.36 flash\_slib\_state\_get function

The table below describes the function flash\_slib\_state\_get.

**Table 363. flash\_slib\_state\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_slib_state_get  |
| Function prototype     | flag_status flash_slib_state_get(void);                         |
| Function description   | Get the status of sLib  |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | flag_status: flag status<br>This parameter can be SET or RESET. |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flag_status status;
status = flash_slib_state_get();
```

### 5.13.37 flash\_slib\_start\_sector\_get function

The table below describes the function flash\_slib\_start\_sector\_get.

**Table 364. flash\_slib\_start\_sector\_get function**

| Name                 | Description                                 |
|----------------------|---|
| Function name        | flash_slib_start_sector_get                 |
| Function prototype   | uint16_t flash_slib_start_sector_get(void); |
| Function description | Get the start sector number of sLib         |
| Input parameter      | NA  |

| Name                   | Description                            |
|------------------------|--|
| Output parameter       | NA                                     |
| Return value           | Return the start sector number of sLib |
| Required preconditions | NA                                     |
| Called functions       | NA                                     |

**Example:**

```
uint16_t num;
num = flash_slb_start_sector_get();
```

### 5.13.38 flash\_slb\_inststart\_sector\_get function

The table below describes the function flash\_slb\_inststart\_sector\_get.

**Table 365. flash\_slb\_inststart\_sector\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_slb_inststart_sector_get                          |
| Function prototype     | uint16_t flash_slb_inststart_sector_get(void);          |
| Function description   | Get the start sector number of sLib instruction area    |
| Input parameter        | NA  |
| Output parameter       | NA  |
| Return value           | Return the start sector number of sLib instruction area |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
uint16_t num;
num = flash_slb_inststart_sector_get();
```

### 5.13.39 flash\_slb\_end\_sector\_get function

The table below describes the function flash\_slb\_end\_sector\_get.

**Table 366. flash\_slb\_end\_sector\_get function**

| Name                   | Description                              |
|------------------------|--|
| Function name          | flash_slb_end_sector_get                 |
| Function prototype     | uint16_t flash_slb_end_sector_get(void); |
| Function description   | Get the end sector number of sLib        |
| Input parameter        | NA                                       |
| Output parameter       | NA                                       |
| Return value           | Return the end sector number of sLib     |
| Required preconditions | NA                                       |
| Called functions       | NA                                       |

**Example:**

```
uint16_t num;
num = flash_slb_end_sector_get();
```



### 5.13.40 flash\_crc\_calibrate function

The table below describes the function flash\_crc\_calibrate.

**Table 367. flash\_crc\_calibrate function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_crc_calibrate   |
| Function prototype     | uint32_t flash_crc_calibrate(uint32_t start_sector, uint32_t sector_cnt); |
| Function description   | Enable Flash CRC check  |
| Input parameter 1      | start_sector: CRC check start address                                     |
| Input parameter 2      | sector_cnt: CRC check sector count  |
| Output parameter       | NA  |
| Return value           | Return CRC calculation result   |
| Required preconditions | NA  |
| Called functions       | NA  |

*Note: The sector set to go through CRC check is only allowed to be on a single area, rather than on both security library and common area.*

**Example:**

```
uint32_t crc_val;
crc_val = flash_crc_calibrate(0, 10);
```

### 5.13.41 flash\_nzw\_boost\_enable function

The table below describes the function flash\_nzw\_boost\_enable.

**Table 368. flash\_nzw\_boost\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | flash_nzw_boost_enable   |
| Function prototype     | void flash_nzw_boost_enable(confirm_state new_state);                              |
| Function description   | Enable Flash non-zero-wait area boost  |
| Input parameter        | new_state: non-zero-wait area boost status<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
flash_nzw_boost_enable(TRUE);
```

### 5.13.42 flash\_continue\_read\_enable function

The table below describes the function flash\_continue\_read\_enable.

**Table 369. flash\_continue\_read\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | flash_continue_read_enable  |
| Function prototype     | void flash_continue_read_enable(confirm_state new_state);                 |
| Function description   | Enable Flash continuous read  |
| Input parameter        | new_state: continuous read status<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
flash_continue_read_enable(TRUE);
```

## 5.14 General-purpose I/Os and multiplexed I/Os (GPIO/IOMUX)

The GPIO register structure `gpio_type` is defined in the "at32f435\_437\_gpio.h".

```
/**
 * @brief type define gpio register all
 */
typedef struct
{

} gpio_type;
```

The table below gives a list of the GPIO registers.

**Table 370. Summary of GPIO registers**

| Register | Description                                   |
|----------|---|
| cfgr     | GPIO configuration register                   |
| omode    | GPIO output mode register                     |
| odrvr    | GPIO drive capability switch control register |
| pull     | GPIO pull-up/pull-down register               |
| idt      | GPIO input data register                      |
| odt      | GPIO output data register                     |
| scr      | GPIO set/clear register                       |
| wpr      | GPIO write protection register                |
| muxl     | GPIO multiplexed function low register        |
| muxh     | GPIO multiplexed function high register       |
| clr      | GPIO port bit clear register                  |
| hdrv     | GPIO huge current control register            |

The table below gives a list of the GPIO and IOMUX library functions.

**Table 371. Summary of GPIO and IOMUX library functions**

| Function name                             | Description                          |
|---|--------------------------------------|
| <code>gpio_reset</code>                   | GPIO is reset by CRM reset register  |
| <code>gpio_init</code>                    | Initialize GPIO peripherals          |
| <code>gpio_default_para_init</code>       | Initialize GPIO default parameters   |
| <code>gpio_input_data_bit_read</code>     | Read GPIO input data bit             |
| <code>gpio_input_data_read</code>         | Read GPIO input data                 |
| <code>gpio_output_data_bit_read</code>    | Read GPIO output data bit            |
| <code>gpio_output_data_read</code>        | Read GPIO output data                |
| <code>gpio_bits_set</code>                | Set GPIO bits                        |
| <code>gpio_bits_reset</code>              | Reset GPIO bits                      |
| <code>gpio_bits_write</code>              | Write GPIO bits                      |
| <code>gpio_port_write</code>              | Write GPIO ports                     |
| <code>gpio_pin_wp_config</code>           | Configure GPIO pin write protection  |
| <code>gpio_pins_huge_driven_config</code> | Configure GPIO huge drive capability |

|                     |   |
|---------------------|---|
| gpio_pin_mux_config | Configure GPIO pin multiplexed function |
|---------------------|---|

### 5.14.1 gpio\_reset function

The table below describes the function gpio\_reset.

**Table 372. gpio\_reset function**

| Name                   | Description  |
|------------------------|--|
| Function name          | gpio_reset   |
| Function prototype     | void gpio_reset(gpio_type *gpio_x);  |
| Function description   | GPIO is reset by CRM reset register  |
| Input parameter        | gpio_x: Selected GPIO peripheral.<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | crm_periph_reset();  |

**Example:**

|                    |
|--------------------|
| gpio_reset(GPIOA); |
|--------------------|

### 5.14.2 gpio\_init function

The table below describes the function gpio\_init.

**Table 373. gpio\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | gpio_init  |
| Function prototype     | void gpio_init(gpio_type *gpio_x, gpio_init_type *gpio_init_struct);   |
| Function description   | Initialize GPIO peripherals  |
| Input parameter 1      | gpio_x: Selected GPIO peripheral.<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Input parameter 2      | gpio_init_struct: gpio_init_type pointer   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**gpio\_init\_type structure**

The gpio\_init\_type is defined in the at32f435\_437\_gpio.h.

typedef struct

```

{
    uint32_t          gpio_pins;
    gpio_output_type  gpio_out_type;
    gpio_pull_type    gpio_pull;
    gpio_mode_type    gpio_mode;
    gpio_drive_type   gpio_drive_strength;
}
    
```

```
} gpio_init_type;
```

### **gpio\_pins**

Select a GPIO pin

```
GPIO_PINS_0:    GPIO pin 0
GPIO_PINS_1:    GPIO pin 1
GPIO_PINS_2:    GPIO pin 2
GPIO_PINS_3:    GPIO pin 3
GPIO_PINS_4:    GPIO pin 4
GPIO_PINS_5:    GPIO pin 5
GPIO_PINS_6:    GPIO pin 6
GPIO_PINS_7:    GPIO pin 7
GPIO_PINS_8:    GPIO pin 8
GPIO_PINS_9:    GPIO pin 9
GPIO_PINS_10:   GPIO pin 10
GPIO_PINS_11:   GPIO pin 11
GPIO_PINS_12:   GPIO pin 12
GPIO_PINS_13:   GPIO pin 13
GPIO_PINS_14:   GPIO pin 14
GPIO_PINS_15:   GPIO pin 15
```

### **gpio\_out\_type**

Set GPIO output type

```
GPIO_OUTPUT_PUSH_PULL:    GPIO push-pull
GPIO_OUTPUT_OPEN_DRAIN:   GPIO open drain
```

### **gpio\_pull**

Set GPIO pull-up or pull-down

```
GPIO_PULL_NONE:    No GPIO pull-up/pull-down
GPIO_PULL_UP:      GPIO pull-up
GPIO_PULL_DOWN:    GPIO pull-down
```

### **gpio\_mode**

Set GPIO mode

```
GPIO_MODE_INPUT:      GPIO input mode
GPIO_MODE_OUTPUT:     GPIO output mode
GPIO_MODE_MUX:        GPIO multiplexed mode
GPIO_MODE_ANALOG:     GPIO analog mode
```

### **gpio\_drive\_strength**

Set GPIO driver capability

```
GPIO_DRIVE_STRENGTH_STRONGER:    Strong drive strength
GPIO_DRIVE_STRENGTH_MODERATE:    Moderate drive strength
```

### **Example:**

```
gpio_init_type gpio_init_struct;
gpio_init_struct.gpio_pins = GPIO_PINS_0;
gpio_init_struct.gpio_mode = GPIO_MODE_MUX;
gpio_init_struct.gpio_out_type = GPIO_OUTPUT_PUSH_PULL;
gpio_init_struct.gpio_pull = GPIO_PULL_NONE;
gpio_init_struct.gpio_drive_strength = GPIO_DRIVE_STRENGTH_STRONGER;
gpio_init(GPIOA, &gpio_init_struct);
```

### 5.14.3 gpio\_default\_para\_init function

The table below describes the function `gpio_default_para_init`.

**Table 374. gpio\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_default_para_init</code>   |
| Function prototype     | <code>void gpio_default_para_init(gpio_init_type *gpio_init_struct);</code> |
| Function description   | Initialize GPIO default parameters  |
| Input parameter        | <code>gpio_init_struct</code> : <code>gpio_init_type</code> pointer         |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The table below describes the default values of members of `gpio_init_struct`.

**Table 375. gpio\_init\_struct default values**

| Member                           | Default value                             |
|----------------------------------|---|
| <code>gpio_pins</code>           | <code>GPIO_PINS_ALL</code>                |
| <code>gpio_mode</code>           | <code>GPIO_MODE_INPUT</code>              |
| <code>gpio_out_type</code>       | <code>GPIO_OUTPUT_PUSH_PULL</code>        |
| <code>gpio_pull</code>           | <code>GPIO_PULL_NONE</code>               |
| <code>gpio_drive_strength</code> | <code>GPIO_DRIVE_STRENGTH_STRONGER</code> |

**Example:**

```
gpio_init_type gpio_init_struct;
gpio_default_para_init(&gpio_init_struct);
```

### 5.14.4 gpio\_input\_data\_bit\_read function

The table below describes the function `gpio_input_data_bit_read`.

**Table 376. gpio\_input\_data\_bit\_read function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_input_data_bit_read</code>   |
| Function prototype     | <code>flag_status gpio_input_data_bit_read(gpio_type *gpio_x, uint16_t pins);</code>  |
| Function description   | Read GPIO input port pins   |
| Input parameter 1      | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Input parameter 2      | <code>pins</code> : indicates the GPIO pins; refer to <a href="#">gpio_pins</a> for details.                                      |
| Output parameter       | NA  |
| Return value           | Return GPIO input pin status  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_input_data_bit_read(GPIOA, GPIO_PINS_0);
```

### 5.14.5 gpio\_input\_data\_read function

The table below describes the function `gpio_input_data_read`.

**Table 377. gpio\_input\_data\_read function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_input_data_read</code>   |
| Function prototype     | <code>uint16_t gpio_input_data_read(gpio_type *gpio_x);</code>  |
| Function description   | Read GPIO input ports   |
| Input parameter        | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Output parameter       | NA  |
| Return value           | Return GPIO input port status   |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_input_data_read(GPIOA);
```

### 5.14.6 gpio\_output\_data\_bit\_read function

The table below describes the function `gpio_output_data_bit_read`.

**Table 378. gpio\_output\_data\_bit\_read function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_output_data_bit_read</code>  |
| Function prototype     | <code>uint16_t gpio_output_data_bit_read(gpio_type *gpio_x);</code>   |
| Function description   | Read GPIO output port pin   |
| Input parameter 1      | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Input parameter 2      | <code>pins</code> : indicates the GPIO pins; refer to <a href="#">gpio_pins</a> for details.                                      |
| Output parameter       | NA  |
| Return value           | Return GPIO output pin status   |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_output_data_bit_read(GPIOA, GPIO_PINS_0);
```

### 5.14.7 gpio\_output\_data\_read function

The table below describes the function `gpio_output_data_read`.

**Table 379. gpio\_output\_data\_read function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_output_data_read</code>  |
| Function prototype     | <code>uint16_t gpio_output_data_read(gpio_type *gpio_x);</code>   |
| Function description   | Read GPIO output port   |
| Input parameter        | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Output parameter       | NA  |
| Return value           | Read GPIO output port status  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_output_data_read(GPIOA);
```

### 5.14.8 gpio\_bits\_set function

The table below describes the function `gpio_bits_set`.

**Table 380. gpio\_bits\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_bits_set</code>  |
| Function prototype     | <code>void gpio_bits_set(gpio_type *gpio_x, uint16_t pins);</code>  |
| Function description   | Set GPIO pins   |
| Input parameter 1      | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Input parameter 2      | <code>pins</code> : indicates the GPIO pins; refer to <a href="#">gpio_pins</a> for details.                                      |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_bits_set(GPIOA, GPIO_PINS_0);
```



### 5.14.9 gpio\_bits\_reset function

The table below describes the function `gpio_bits_reset`.

**Table 381. gpio\_bits\_reset function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_bits_reset</code>  |
| Function prototype     | <code>void gpio_bits_reset(gpio_type *gpio_x, uint16_t pins);</code>  |
| Function description   | Reset GPIO pins   |
| Input parameter 1      | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Input parameter 2      | <code>pins</code> : indicates the GPIO pins; refer to <a href="#">gpio_pins</a> for details.                                      |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_bits_reset(GPIOA, GPIO_PINS_0);
```

### 5.14.10 gpio\_bits\_write function

The table below describes the function `gpio_bits_write`.

**Table 382. gpio\_bits\_write function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_bits_write</code>  |
| Function prototype     | <code>void gpio_bits_write(gpio_type *gpio_x, uint16_t pins, confirm_state bit_state);</code>                                     |
| Function description   | Write GPIO pins   |
| Input parameter 1      | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Input parameter 2      | <code>pins</code> : indicates the GPIO pins; refer to <a href="#">gpio_pins</a> for details.                                      |
| Input parameter 3      | <code>bit_state</code> : GPIO pin value to be written; it can be 1 (TRUE) or 0 (FALSE)  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_bits_write(GPIOA, GPIO_PINS_0, TRUE);
```

### 5.14.11 gpio\_port\_write function

The table below describes the function `gpio_port_write`.

**Table 383. gpio\_port\_write function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_port_write</code>  |
| Function prototype     | <code>void gpio_port_write(gpio_type *gpio_x, uint16_t port_value);</code>  |
| Function description   | Write GPIO ports  |
| Input parameter 1      | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Input parameter 2      | <code>port_value</code> : the port value to be written; it can be 0x0000~0xFFFF.  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_port_write(GPIOA, 0xFFFF);
```

### 5.14.12 gpio\_pin\_wp\_config function

The table below describes the function `gpio_pin_wp_config`.

**Table 384. gpio\_pin\_wp\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_pin_wp_config</code>   |
| Function prototype     | <code>void gpio_pin_wp_config(gpio_type *gpio_x, uint16_t pins);</code>   |
| Function description   | Configure GPIO pin write protection   |
| Input parameter 1      | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Input parameter 2      | <code>pins</code> : indicates the GPIO pins; refer to <a href="#">gpio_pins</a> for details.                                      |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_pin_wp_config(GPIOA, GPIO_PINS_0);
```

### 5.14.13 gpio\_pins\_huge\_driven\_config function

The table below describes the function `gpio_pins_huge_driven_config`.

**Table 385. gpio\_pins\_huge\_driven\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>gpio_pins_huge_driven_config</code>   |
| Function prototype     | <code>void gpio_pins_huge_driven_config(gpio_type *gpio_x, uint16_t pins, confirm_state new_state);</code>                        |
| Function description   | Configure huge drive capability of GPIO pins  |
| Input parameter 1      | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH. |
| Input parameter 2      | <code>pins</code> : indicates the GPIO pins; refer to <a href="#">gpio_pins</a> for details.                                      |
| Input parameter 3      | <code>new_state</code> : Enable (TRUE) or disable (FALSE)   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
gpio_pins_huge_driven_config(GPIOA, GPIO_PINS_0, TRUE);
```

### 5.14.14 gpio\_pin\_mux\_config function

The table below describes the function `gpio_pin_mux_config`.

**Table 386. gpio\_pin\_mux\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>gpio_pin_mux_config</code>   |
| Function prototype     | <code>void gpio_pin_mux_config(gpio_type *gpio_x, gpio_pins_source_type gpio_pin_source, gpio_mux_sel_type gpio_mux);</code>     |
| Function description   | Configure GPIO pin multiplexed function  |
| Input parameter 1      | <code>gpio_x</code> : selected GPIO peripheral<br>This parameter can be GPIOA, GPIOB, GPIOC, GPIOD, GPIOE, GPIOF, GPIOG or GPIOH |
| Input parameter 2      | <code>gpio_pin_source</code> : GPIO pin to be configured   |
| Input parameter 3      | <code>gpio_mux</code> : IOMUX index to be configured   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**gpio\_pin\_source**

Set GPIO pins

- GPIO\_PINS\_SOURCE0: GPIO pin 0
- GPIO\_PINS\_SOURCE1: GPIO pin 1
- GPIO\_PINS\_SOURCE2: GPIO pin 2
- GPIO\_PINS\_SOURCE3: GPIO pin 3

GPIO\_PINS\_SOURCE4: GPIO pin 4  
 GPIO\_PINS\_SOURCE5: GPIO pin 5  
 GPIO\_PINS\_SOURCE6: GPIO pin 6  
 GPIO\_PINS\_SOURCE7: GPIO pin 7  
 GPIO\_PINS\_SOURCE8: GPIO pin 8  
 GPIO\_PINS\_SOURCE9: GPIO pin 9  
 GPIO\_PINS\_SOURCE10: GPIO pin 10  
 GPIO\_PINS\_SOURCE11: GPIO pin 11  
 GPIO\_PINS\_SOURCE12: GPIO pin 12  
 GPIO\_PINS\_SOURCE13: GPIO pin 13  
 GPIO\_PINS\_SOURCE14: GPIO pin 14  
 GPIO\_PINS\_SOURCE15: GPIO pin 15

### **gpio\_mux**

Select IOMUX index

GPIO\_MUX\_0  
 GPIO\_MUX\_1  
 GPIO\_MUX\_2  
 GPIO\_MUX\_3  
 GPIO\_MUX\_4  
 GPIO\_MUX\_5  
 GPIO\_MUX\_6  
 GPIO\_MUX\_7  
 GPIO\_MUX\_8  
 GPIO\_MUX\_9  
 GPIO\_MUX\_10  
 GPIO\_MUX\_11  
 GPIO\_MUX\_12  
 GPIO\_MUX\_13  
 GPIO\_MUX\_14  
 GPIO\_MUX\_15

### **Example:**

```
gpio_pin_mux_config(GPIOA, GPIO_PINS_SOURCE0, GPIO_MUX_0);
```

## 5.15 I2C interface

The I2C register structure `i2c_type` is defined in the "at32f435\_437\_i2c.h".

```
/**
 * @brief type define i2c register all
 */
typedef struct
{

} i2c_type;
```

The table below gives a list of the I2C registers.

**Table 387. Summary of I2C registers**

| Register | Description                |
|----------|----------------------------|
| ctrl1    | I2C control register 1     |
| ctrl2    | I2C control register 2     |
| oaddr1   | I2C Own address register 1 |
| oaddr2   | I2C Own address register 2 |
| clkctrl  | Timing register            |
| timeout  | Timeout register           |
| sts      | Status register            |
| clr      | Status clear register      |
| pec      | PEC register               |
| rxdt     | Receive data register      |
| txdt     | Transmit data register     |

The table below gives a list of I2C library functions.

**Table 388. Summary of I2C library functions**

| Function name                         | Description                                      |
|---------------------------------------|--|
| <code>i2c_reset</code>                | I2C peripheral reset                             |
| <code>i2c_init</code>                 | Initialize I2C, set bus speed and digital filter |
| <code>i2c_own_address1_set</code>     | Set I2C own address 1                            |
| <code>i2c_own_address2_set</code>     | Set I2C own address 2                            |
| <code>i2c_own_address2_enable</code>  | Enable I2C own address 2                         |
| <code>i2c_smbus_enable</code>         | Enable SMBus mode                                |
| <code>i2c_enable</code>               | Enable I2C                                       |
| <code>i2c_clock_stretch_enable</code> | Enable clock stretching capability               |
| <code>i2c_ack_enable</code>           | Enable ACK response                              |
| <code>i2c_addr10_mode_enable</code>   | Enable master transmit 10-bit address mode       |
| <code>i2c_transfer_addr_set</code>    | Set master transfer address (slave address)      |
| <code>i2c_transfer_addr_get</code>    | Get slave address from master                    |
| <code>i2c_transfer_dir_set</code>     | Set master data transfer direction               |
| <code>i2c_transfer_dir_get</code>     | Slave gets data transfer direction               |

|                            |  |
|----------------------------|--|
| i2c_matched_addr_get       | Slave gets address match value                 |
| i2c_auto_stop_enable       | Enable auto transmission stop conditions       |
| i2c_reload_enable          | Enable transmitted data reload mode            |
| i2c_cnt_set                | Set number of data to send/receive             |
| i2c_addr10_header_enable   | Enable 10-bit address header read timing       |
| i2c_general_call_enable    | Enable general call (broadcast address enable) |
| i2c_smbus_alert_set        | Set SMBus alert pin level                      |
| i2c_slave_data_ctrl_enable | Enable slave single-byte receive control       |
| i2c_pec_calculate_enable   | Enable PEC calculation                         |
| i2c_pec_transmit_enable    | Enable PEC transmit                            |
| i2c_pec_value_get          | Get current PEC value                          |
| i2c_timeout_set            | Set clock level timeout detection              |
| i2c_timeout_detcet_set     | Set clock level timeout detect mode            |
| i2c_timeout_enable         | Enable clock level timeout detect              |
| i2c_ext_timeout_set        | Set accumulated clock stretching timeout       |
| i2c_ext_timeout_enable     | Enable accumulated clock stretching timeout    |
| i2c_interrupt_enable       | I2C interrupt enable                           |
| i2c_interrupt_get          | Get interrupt status                           |
| i2c_dma_enable             | DMA transfer enable                            |
| i2c_transmit_set           | Set master-initiated transfer                  |
| i2c_start_generate         | Generate start conditions                      |
| i2c_stop_generate          | Generate stop conditions                       |
| i2c_data_send              | Send data                                      |
| i2c_data_receive           | Receive data                                   |
| i2c_flag_get               | Get flag                                       |
| i2c_flag_clear             | Clear flag                                     |

**Table 389. I2C application-layer library functions**

| Function name           | Description                                |
|-------------------------|--|
| i2c_config              | I2C application initialization             |
| i2c_lowlevel_init       | I2C low-layer initialization               |
| i2c_wait_end            | I2C wait data transmit complete            |
| i2c_wait_flag           | I2C wait flag                              |
| i2c_master_transmit     | I2C master transmits data (polling mode)   |
| i2c_master_receive      | I2C master receives data (polling mode)    |
| i2c_slave_transmit      | I2C slave transmits data (polling mode)    |
| i2c_slave_receive       | I2C slave receives data (polling mode)     |
| i2c_master_transmit_int | I2C master transmits data (interrupt mode) |
| i2c_master_receive_int  | I2C master receives data (interrupt mode)  |
| i2c_slave_transmit_int  | I2C slave transmits data (interrupt mode)  |
| i2c_slave_receive_int   | I2C slave receives data (interrupt mode)   |
| i2c_master_transmit_dma | I2C master transmits data (DMA mode)       |
| i2c_master_receive_dma  | I2C master receives data (DMA mode)        |
| i2c_slave_transmit_dma  | I2C slave transmits data (DMA mode)        |
| i2c_slave_receive_dma   | I2C slave receives data (DMA mode)         |

|                           |  |
|---------------------------|--|
| i2c_smbus_master_transmit | SMBus master transmits data (polling mode) |
| i2c_smbus_master_receive  | SMBus master receives data (polling mode)  |
| i2c_smbus_slave_transmit  | SMBus slave transmits data (polling mode)  |
| i2c_smbus_slave_receive   | SMBus slave receives data (polling mode)   |
| i2c_memory_write          | I2C writes data to EEPROM (polling mode)   |
| i2c_memory_write_int      | I2C writes data to EEPROM (interrupt mode) |
| i2c_memory_write_dma      | I2C writes data to EEPROM (DMA mode)       |
| i2c_memory_read           | I2C reads from EEPROM (polling mode)       |
| i2c_memory_read_int       | I2C reads from EEPROM (interrupt mode)     |
| i2c_memory_read_dma       | I2C reads from EEPROM (DMA mode)           |
| i2c_evt_irq_handler       | I2C event interrupt function               |
| i2c_err_irq_handler       | I2C error interrupt function               |
| i2c_dma_tx_irq_handler    | I2C DMA Tx interrupt function              |
| i2c_dma_rx_irq_handler    | I2C DMA Rx interrupt function              |

### 5.15.1 i2c\_reset function

The table below describes the function i2c\_reset.

**Table 390. i2c\_reset function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_reset  |
| Function prototype     | void i2c_reset(i2c_type *i2c_x);   |
| Function description   | Reset all I2C registers to their initial values through CRM (Clock and reset management) |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.              |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | void crm_periph_reset(crm_periph_reset_type value, confirm_state new_state)              |

**Example:**

|                  |
|------------------|
| i2c_reset(I2C1); |
|------------------|

### 5.15.2 i2c\_init function

The table below describes the function i2c\_init.

**Table 391. i2c\_init function**

| Name                 | Description  |
|----------------------|--|
| Function name        | i2c_init   |
| Function prototype   | void i2c_init(i2c_type *i2c_x, uint8_t dfilters, uint32_t clk);  |
| Function description | Set I2C bus speed and digital filter   |
| Input parameter 1    | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.  |
| Input parameter 2    | dfilters: digital filter, ranging from 0x00 to 0x0F<br>When in use, it is recommended to program the digital filter with a maximum value |

| Name                   | Description   |
|------------------------|---|
|                        | to effectively filter disturbance.  |
| Input parameter 3      | clk: timing register (I2C_CLKCTRL) value used to control I2C communication speed. This value can be calculated through “Artery_I2C_Timing_Configuration” defined in <i>AN0091_AT32F435_437_I2C_Application_Note</i> . |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_init(I2C1, 0x0F, 0x80504C4E);
```

### 5.15.3 i2c\_own\_address1\_set function

The table below describes the function `i2c_own_address1_set`.

**Table 392. i2c\_own\_address1\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_own_address1_set</code>  |
| Function prototype     | <code>void i2c_own_address1_set(i2c_type *i2c_x, i2c_address_mode_type mode, uint16_t address);</code> |
| Function description   | Set own address1   |
| Input parameter 1      | mode: Own address 1 address mode<br>Refer to the following “mode” descriptions for details.            |
| Input parameter 2      | address: Own address 1   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**mode**

Own address 1 address mode

I2C\_ADDRESS\_MODE\_7BIT: 7-bit address

I2C\_ADDRESS\_MODE\_10BIT: 10-bit address

**Example:**

```
i2c_own_address1_set(I2C1, I2C_ADDRESS_MODE_7BIT, 0xA0);
```

### 5.15.4 i2c\_own\_address2\_set function

The table below describes the function `i2c_own_address2_set`.

**Table 393. i2c\_own\_address2\_set function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>i2c_own_address2_set</code>   |
| Function prototype   | <code>void i2c_own_address2_set(i2c_type *i2c_x, uint8_t address, i2c_addr2_mask_type mask);</code>   |
| Function description | Set own address 2. The address 2 becomes active only after it is enabled<br>Note: only 7-bit address is supported, not 10-bit address mode. |



| Name                   | Description   |
|------------------------|---|
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.             |
| Input parameter 2      | address: own address 2  |
| Input parameter 3      | mask: own address 2 bit mask<br>Refer to the following "mask" descriptions for details. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**mask**

Own address 2 bit mask

|                   |  |
|-------------------|--|
| I2C_ADDR2_NOMASK: | match address bit [7: 1]                     |
| I2C_ADDR2_MASK01: | match address bit [7: 2] only                |
| I2C_ADDR2_MASK02: | match address bit [7: 3] only                |
| I2C_ADDR2_MASK03: | match address bit [7: 4] only                |
| I2C_ADDR2_MASK04: | match address bit [7: 5] only                |
| I2C_ADDR2_MASK05: | match address bit [7: 6] only                |
| I2C_ADDR2_MASK06: | match address bit [7]                        |
| I2C_ADDR2_MASK07: | All non-I2C reserved addresses would respond |

**Example:**

```
i2c_own_address2_set(I2C1, 0xB0, I2C_ADDR2_NOMASK);
```

### 5.15.5 i2c\_own\_address2\_enable function

The table below describes the function `i2c_own_address2_enable`.

**Table 394. i2c\_own\_address2\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_own_address2_enable</code>   |
| Function prototype     | <code>void i2c_own_address2_enable(i2c_type *i2c_x, confirm_state new_state);</code>   |
| Function description   | Enable own address 2. The address becomes active only after it is enabled.<br>Note that this function should be used in conjunction with the <code>i2c_own_address2_set</code> . |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.  |
| Input parameter 2      | new_state: address 2 status<br>This parameter can be TRUE or FALSE.  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_own_address2_enable(I2C1, TRUE);
```

### 5.15.6 i2c\_smbus\_enable function

The table below describes the function i2c\_smbus\_enable.

**Table 395. i2c\_smbus\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_smbus_enable   |
| Function prototype     | void i2c_smbus_enable(i2c_type *i2c_x, i2c_smbus_mode_type mode, confirm_state new_state); |
| Function description   | Enable SMBus mode. After power-on reset, the default mode is I2C mode.                     |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.                |
| Input parameter 2      | mode: SMBus mode selection<br>Refer to the following "mode" descriptions for details.      |
| Input parameter 3      | new_state: SMBus mode status<br>This parameter can be TRUE or FALSE.                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**mode**

SMBus mode

I2C\_SMBUS\_MODE\_DEVICE: SMBus device

I2C\_SMBUS\_MODE\_HOST: SMBus host

**Example:**

```
i2c_smbus_enable(I2C1, I2C_SMBUS_MODE_DEVICE, TRUE);
```

### 5.15.7 i2c\_enable function

The table below describes the function i2c\_enable.

**Table 396. i2c\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_enable  |
| Function prototype     | void i2c_enable(i2c_type *i2c_x, confirm_state new_state);                  |
| Function description   | Enable I2C peripheral   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Input parameter 2      | new_state: indicates I2C status<br>This parameter can be TRUE or FALSE.     |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_enable(I2C1, TRUE);
```

### 5.15.8 i2c\_clock\_stretch\_enable function

The table below describes the function `i2c_clock_stretch_enable`.

**Table 397. i2c\_clock\_stretch\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_clock_stretch_enable</code>  |
| Function prototype     | <code>void i2c_clock_stretch_enable(i2c_type *i2c_x, confirm_state new_state);</code>  |
| Function description   | <p>Enable clock stretching capability.</p> <p>This function is applicable to slave mode only. In most cases, enabling the clock stretching mode is recommended in order to prevent slave from having no sufficient time to receive or send data due to slow process speed, which causes a loss of data.</p> <p>It should be noted that the host must be able to support clock stretching function before using this mode by slave. For example, some hosts based on IO analog are not equipped with the clock stretching capability.</p> |
| Input parameter 1      | <p><code>i2c_x</code>: selected I2C peripheral</p> <p>This parameter can be I2C1, I2C2 or I2C3.</p>  |
| Input parameter 2      | <p><code>new_state</code>: indicates clock stretching status</p> <p>This parameter can be TRUE or FALSE.</p>   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_clock_stretch_enable(I2C1, TRUE);
```

### 5.15.9 i2c\_ack\_enable function

The table below describes the function `i2c_ack_enable`.

**Table 398. i2c\_ack\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_ack_enable</code>  |
| Function prototype     | <code>void i2c_ack_enable(i2c_type *i2c_x, confirm_state new_state);</code>  |
| Function description   | <p>This function is used to enable ACK or NACK of each byte in master and slave mode. For ACK information on I2C communication protocol, refer to I2C protocol or AT32 reference manual.</p> |
| Input parameter 1      | <p><code>i2c_x</code>: selected I2C peripheral</p> <p>This parameter can be I2C1, I2C2 or I2C3.</p>  |
| Input parameter 2      | <p><code>new_state</code>: indicates ACK response status</p> <p>This parameter can be TRUE or FALSE.</p>   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_ack_enable(I2C1, TRUE);
```

### 5.15.10 i2c\_addr10\_mode\_enable function

The table below describes the function i2c\_addr10\_mode\_enable.

**Table 399. i2c\_addr10\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_addr10_mode_enable  |
| Function prototype     | void i2c_addr10_mode_enable(i2c_type *i2c_x, confirm_state new_state);              |
| Function description   | Enable master transmit 10-bit address mode  |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.         |
| Input parameter 2      | new_state: 10-bit address mode enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_addr10_mode_enable(I2C1, TRUE);
```

### 5.15.11 i2c\_transfer\_addr\_set function

The table below describes the function i2c\_transfer\_addr\_set.

**Table 400. i2c\_transfer\_addr\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_transfer_addr_set   |
| Function prototype     | void i2c_transfer_addr_set(i2c_type *i2c_x, uint16_t address);              |
| Function description   | Set master transfer address (slave address)                                 |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Input parameter 2      | address: slave address  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_transfer_addr_set(I2C1, 0xA0);
```

### 5.15.12 i2c\_transfer\_addr\_get function

The table below describes the function i2c\_transfer\_addr\_get.

**Table 401. i2c\_transfer\_addr\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_transfer_addr_get   |
| Function prototype     | uint16_t i2c_transfer_addr_get(i2c_type *i2c_x);                            |
| Function description   | Get slave address sent from master  |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Output parameter       | NA  |
| Return value           | uint16_t: slave address sent from master                                    |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_transfer_addr_get(I2C1);
```

### 5.15.13 i2c\_transfer\_dir\_set function

The table below describes the function i2c\_transfer\_dir\_set.

**Table 402. i2c\_transfer\_dir\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_transfer_dir_set   |
| Function prototype     | void i2c_transfer_dir_set(i2c_type *i2c_x, i2c_transfer_dir_type i2c_direction);                   |
| Function description   | Set master data transfer direction   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.                        |
| Input parameter 2      | direction: data transfer direction<br>Refer to the following "direction" descriptions for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**direction**

Data transfer direction

I2C\_DIR\_TRANSMIT: Master sends data

I2C\_DIR\_RECEIVE: Master receives data

**Example:**

```
i2c_transfer_dir_set(I2C1, I2C_DIR_TRANSMIT);
```

### 5.15.14 i2c\_transfer\_dir\_get function

The table below describes the function i2c\_transfer\_dir\_get.

**Table 403. i2c\_transfer\_dir\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_transfer_dir_get   |
| Function prototype     | i2c_transfer_dir_type i2c_transfer_dir_get(i2c_type *i2c_x);   |
| Function description   | Get slave data transfer direction  |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.  |
| Output parameter       | NA   |
| Return value           | i2c_transfer_dir_type: slave data transfer direction<br>Refer to the following "i2c_transfer_dir_type" descriptions for details. |
| Required preconditions | NA   |
| Called functions       | NA   |

i2c\_transfer\_dir\_type

Data transfer direction

I2C\_DIR\_TRANSMIT: master sends data and slave receives data

I2C\_DIR\_RECEIVE: master receives data and slave sends data

**Example:**

```
i2c_transfer_dir_get(I2C1);
```

### 5.15.15 i2c\_matched\_addr\_get function

The table below describes the function i2c\_matched\_addr\_get.

**Table 404. i2c\_matched\_addr\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_matched_addr_get  |
| Function prototype     | uint8_t i2c_matched_addr_get(i2c_type *i2c_x);                              |
| Function description   | Get slave address match value   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Output parameter       | NA  |
| Return value           | uint8_t: slave matched address  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_matched_addr_get(I2C1);
```

### 5.15.16 i2c\_auto\_stop\_enable function

The table below describes the function i2c\_auto\_stop\_enable.

**Table 405. i2c\_auto\_stop\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_auto_stop_enable   |
| Function prototype     | void i2c_auto_stop_enable(i2c_type *i2c_x, confirm_state new_state);                         |
| Function description   | Enable auto transmit stop conditions   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.                  |
| Input parameter 2      | new_state: auto transmit stop condition enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_auto_stop_enable(I2C1, TRUE);
```

### 5.15.17 i2c\_reload\_enable function

The table below describes the function i2c\_reload\_enable.

**Table 406. i2c\_reload\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_reload_enable   |
| Function prototype     | void i2c_reload_enable(i2c_type *i2c_x, confirm_state new_state);           |
| Function description   | Enable transmitted data reload mode   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Input parameter 2      | new_state: reload mode enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_reload_enable(I2C1, TRUE);
```

### 5.15.18 i2c\_cnt\_set function

The table below describes the function i2c\_cnt\_set.

**Table 407. i2c\_cnt\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_cnt_set   |
| Function prototype     | void i2c_cnt_set(i2c_type *i2c_x, uint8_t cnt);                             |
| Function description   | Set the number of data to send or receive, ranging from 1 to 255            |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Input parameter 2      | cnt: number of data to send/receive   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_cnt_set(I2C1, 200);
```

### 5.15.19 i2c\_addr10\_header\_enable function

The table below describes the function i2c\_addr10\_header\_enable.

**Table 408. i2c\_addr10\_header\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_addr10_header_enable   |
| Function prototype     | void i2c_addr10_header_enable(i2c_type *i2c_x, confirm_state new_state);                         |
| Function description   | Enable 10-bit address header read timing   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.                      |
| Input parameter 2      | new_state: enable state of auto transmit stop conditions<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_addr10_header_enable(I2C1, TRUE);
```



### 5.15.20 i2c\_general\_call\_enable function

The table below describes the function i2c\_general\_call\_enable.

**Table 409. i2c\_general\_call\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_general_call_enable   |
| Function prototype     | void i2c_general_call_enable(i2c_type *i2c_x, confirm_state new_state);           |
| Function description   | Enable broadcast address. After enabled, broadcast address 0x00 is responded .    |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.       |
| Input parameter 2      | new_state: Broadcast address enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_general_call_enable(I2C1, TRUE);
```

### 5.15.21 i2c\_smbus\_alert\_set function

The table below describes the function i2c\_smbus\_alert\_set.

**Table 410. i2c\_smbus\_alert\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_smbus_alert_set  |
| Function prototype     | void i2c_smbus_alert_set(i2c_type *i2c_x, i2c_smbus_alert_set_type level);               |
| Function description   | Set SMBus alert pin level (high or low)  |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.              |
| Input parameter 2      | level: SMBus alert pin level<br>Refer to the following "level" descriptions for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**level**

SMBus alert pin level

I2C\_SMBUS\_ALERT\_LOW: SMBus alert pin output low

I2C\_SMBUS\_ALERT\_HIGH: SMBus alert pin output high

**Example:**

```
i2c_smbus_alert_set(I2C1, I2C_SMBUS_ALERT_LOW);
```

### 5.15.22 i2c\_slave\_data\_ctrl\_enable function

The table below describes the function `i2c_slave_data_ctrl_enable`.

**Table 411. i2c\_slave\_data\_ctrl\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_slave_data_ctrl_enable</code>  |
| Function prototype     | <code>void i2c_slave_data_ctrl_enable(i2c_type *i2c_x, confirm_state new_state);</code>  |
| Function description   | Enable slave data receive control. This function is used to control ACK or NACK response to each received byte when in slave receive mode. It is usually used for SMBus. |
| Input parameter 1      | <code>i2c_x</code> : selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.  |
| Input parameter 2      | <code>new_state</code> : enable state<br>This parameter can be TRUE or FALSE.  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_slave_data_ctrl_enable(I2C1, FALSE);
```

### 5.15.23 i2c\_pec\_calculate\_enable function

The table below describes the function `i2c_pec_calculate_enable`.

**Table 412. i2c\_pec\_calculate\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_pec_calculate_enable</code>   |
| Function prototype     | <code>void i2c_pec_calculate_enable(i2c_type *i2c_x, confirm_state new_state);</code>     |
| Function description   | Enable PEC calculation  |
| Input parameter 1      | <code>i2c_x</code> : selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Input parameter 2      | <code>new_state</code> : PEC calculation state<br>This parameter can be TRUE or FALSE.    |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_pec_calculate_enable(I2C1, TRUE);
```

### 5.15.24 i2c\_pec\_transmit\_enable function

The table below describes the function i2c\_pec\_transmit\_enable.

**Table 413. i2c\_pec\_transmit\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_pec_transmit_enable  |
| Function prototype     | void i2c_pec_transmit_enable(i2c_type *i2c_x, confirm_state new_state);      |
| Function description   | PEC transmit enable (send/receive PEC)                                       |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.  |
| Input parameter 2      | new_state: PEC transmit enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_pec_transmit_enable(I2C1, TRUE);
```

### 5.15.25 i2c\_pec\_value\_get function

The table below describes the function i2c\_pec\_value\_get.

**Table 414. i2c\_pec\_value\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_pec_value_get   |
| Function prototype     | uint8_t i2c_pec_value_get(i2c_type *i2c_x);                                 |
| Function description   | Get current PEC value   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Output parameter       | uint8_t: current PEC value  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
pec_value = i2c_pec_value_get(I2C1);
```

### 5.15.26 i2c\_timeout\_set function

The table below describes the function `i2c_timeout_set`.

**Table 415. i2c\_timeout\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_timeout_set</code>  |
| Function prototype     | <code>void i2c_timeout_set(i2c_type *i2c_x, uint16_t timeout);</code>                     |
| Function description   | Set SCL line level timeout detect time  |
| Input parameter 1      | <code>i2c_x</code> : selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Input parameter 2      | <code>timeout</code> : timeout value, ranging from 0x0000 to 0x0FFF                       |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_timeout_set(I2C1, 0x0FFF);
```

### 5.15.27 i2c\_timeout\_detcet\_set function

The table below describes the function `i2c_timeout_detcet_set`.

**Table 416. i2c\_timeout\_detcet\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_timeout_detcet_set</code>  |
| Function prototype     | <code>void i2c_timeout_detcet_set(i2c_type *i2c_x, i2c_timeout_detcet_type mode);</code>         |
| Function description   | Set SCL line level timeout detect mode   |
| Input parameter 1      | <code>i2c_x</code> : selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.        |
| Input parameter 2      | <code>mode</code> : level detect mode<br>Refer to the following "mode" descriptions for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**mode**

Level detection mode

`I2C_TIMEOUT_DETCET_HIGH`: High level timeout detect

`I2C_TIMEOUT_DETCET_LOW`: Low level timeout detect

**Example:**

```
i2c_timeout_detcet_set(I2C1, I2C_TIMEOUT_DETCET_HIGH);
```

### 5.15.28 i2c\_timeout\_enable function

The table below describes the function i2c\_timeout\_enable.

**Table 417. i2c\_timeout\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_timeout_enable   |
| Function prototype     | void i2c_timeout_enable(i2c_type *i2c_x, confirm_state new_state);                   |
| Function description   | Enable SCL line level timeout detect   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.          |
| Input parameter 2      | new_state: level timeout detect enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_timeout_enable(I2C1, TRUE);
```

### 5.15.29 i2c\_ext\_timeout\_set function

The table below describes the function i2c\_ext\_timeout\_set.

**Table 418. i2c\_ext\_timeout\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_ext_timeout_set  |
| Function prototype     | void i2c_ext_timeout_set(i2c_type *i2c_x, uint16_t timeout);                       |
| Function description   | Set SCL line cumulative clock stretching timeout value, usually used in SMBus mode |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.        |
| Input parameter 2      | timeout: range from 0x0000 to 0x0FFF   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_ext_timeout_set(I2C1, 0x0FFF);
```

### 5.15.30 i2c\_ext\_timeout\_enable function

The table below describes the function `i2c_ext_timeout_enable`.

**Table 419. i2c\_ext\_timeout\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_ext_timeout_enable</code>   |
| Function prototype     | <code>void i2c_ext_timeout_enable(i2c_type *i2c_x, confirm_state new_state);</code>                               |
| Function description   | Enable SCL line cumulative clock stretching timeout   |
| Input parameter 1      | <code>i2c_x</code> : selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.                         |
| Input parameter 2      | <code>new_state</code> : cumulative clock stretching timeout enable state<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_ext_timeout_enable(I2C1, TRUE);
```

### 5.15.31 i2c\_interrupt\_enable function

The table below describes the function `i2c_interrupt_enable`.

**Table 420. i2c\_interrupt\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_interrupt_enable</code>  |
| Function prototype     | <code>void i2c_interrupt_enable(i2c_type *i2c_x, uint32_t source, confirm_state new_state);</code>   |
| Function description   | I2C interrupt enable   |
| Input parameter 1      | <code>i2c_x</code> : selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.            |
| Input parameter 2      | <code>source</code> : interrupt sources<br>Refer to the following "source" descriptions for details. |
| Input parameter 3      | <code>new_state</code> : interrupt enable state<br>This parameter can be TRUE or FALSE.              |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**source**

Select an interrupt source

- I2C\_TD\_INT: Data transmit interrupt
- I2C\_RD\_INT: Data receive interrupt
- I2C\_ADDR\_INT: Address match interrupt
- I2C\_ACKFIAL\_INT: Acknowledge failure interrupt
- I2C\_STOP\_INT: Stop condition generation complete interrupt

I2C\_TDC\_INT: Data transfer complete interrupt  
 I2C\_ERR\_INT: Error interrupt

**Example:**

```
i2c_interrupt_enable(I2C1, I2C_TD_INT, TRUE);
```

### 5.15.32 i2c\_interrupt\_get function

The table below describes the function i2c\_interrupt\_get.

**Table 421. i2c\_interrupt\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_interrupt_get   |
| Function prototype     | flag_status i2c_interrupt_get(i2c_type *i2c_x, uint16_t source);                      |
| Function description   | Get interrupt enable state  |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.           |
| Input parameter 2      | source: interrupt source<br>Refer to the following "source" descriptions for details. |
| Output parameter       | flag_status: flag status<br>This parameter can be SET or RESET.                       |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**source**

Select an interrupt source

I2C\_TD\_INT: Data transmit interrupt  
 I2C\_RD\_INT: Data receive interrupt  
 I2C\_ADDR\_INT: Address match interrupt  
 I2C\_ACKFIAL\_INT: Acknowledge failure interrupt  
 I2C\_STOP\_INT: Stop condition generation complete interrupt  
 I2C\_TDC\_INT: Data transfer complete interrupt  
 I2C\_ERR\_INT: Error interrupt

**Example:**

```
i2c_interrupt_get(I2C1, I2C_TD_INT, TRUE);
```

### 5.15.33 i2c\_dma\_enable function

The table below describes the function i2c\_dma\_enable.

**Table 422. i2c\_dma\_enable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | i2c_dma_enable   |
| Function prototype   | void i2c_dma_enable(i2c_type *i2c_x, i2c_dma_request_type dma_req, confirm_state new_state); |
| Function description | DMA transfer enable  |
| Input parameter 1    | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.                  |

| Name                   | Description  |
|------------------------|--|
| Input parameter 2      | dma_req: DMA request<br>Refer to the following "dma_req" descriptions for details. |
| Input parameter 3      | new_state: DMA enable state<br>This parameter can be TRUE or FALSE.                |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**dma\_req**

I2C\_DMA\_REQUEST\_TX: DMA data transmit enable

I2C\_DMA\_REQUEST\_RX: DMA data receive enable

**Example:**

```
i2c_dma_enable(I2C1, I2C_DMA_REQUEST_TX, TRUE);
```

### 5.15.34 i2c\_transmit\_set function

The table below describes the function i2c\_transmit\_set.

**Table 423. i2c\_transmit\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_transmit_set  |
| Function prototype     | void i2c_transmit_set(i2c_type *i2c_x, uint16_t address, uint8_t cnt, i2c_reload_stop_mode_type rld_stop, i2c_start_mode_type start); |
| Function description   | Set master transmit. This function is used to start data transfer on bus .  |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.   |
|                        | address: slave address  |
|                        | cnt: count of data to send/receive  |
| Input parameter 2      | rld_stop: reload mode and STOP condition generation mode<br>Refer to the following "rld_stop" descriptions for details.               |
| Input parameter 3      | start: set START condition generation mode<br>Refer to the following "start" descriptions for details.                                |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**rld\_stop**

Reload mode and STOP condition generation mode

I2C\_AUTO\_STOP\_MODE: Auto stop mode (automatically sends STOP condition)

I2C\_SOFT\_STOP\_MODE: Software stop mode (software sends STOP condition, usually RESTART condition)

I2C\_RELOAD\_MODE: Reload mode (when a single transfer >255)

**start**

START condition generation mode

I2C\_WITHOUT\_START: Start sending data, without START, used in reload mode



I2C\_GEN\_START\_READ: Start sending data, with START condition (for master receive data)

I2C\_GEN\_START\_WRITE: Start sending data with START condition (for master transmit data)

**Example:**

```
i2c_transmit_set(I2C1, I2C_AUTO_STOP_MODE, I2C_GEN_START_WRITE);
```

### 5.15.35 i2c\_start\_generate function

The table below describes the function i2c\_start\_generate.

**Table 424. i2c\_start\_generate function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_start_generate  |
| Function prototype     | void i2c_start_generate(i2c_type *i2c_x);                                   |
| Function description   | Generate a START condition (for master)                                     |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_start_generate(I2C1);
```

### 5.15.36 i2c\_stop\_generate function

The table below describes the function i2c\_stop\_generate.

**Table 425. i2c\_stop\_generate function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_stop_generate   |
| Function prototype     | void i2c_stop_generate(i2c_type *i2c_x);                                    |
| Function description   | Generate a STOP condition   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_stop_generate(I2C1);
```

### 5.15.37 i2c\_data\_send function

The table below describes the function `i2c_data_send`.

**Table 426. i2c\_data\_send function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_data_send</code>  |
| Function prototype     | <code>void i2c_data_send(i2c_type *i2c_x, uint8_t data);</code>                           |
| Function description   | Send data   |
| Input parameter 1      | <code>i2c_x</code> : selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Input parameter 2      | <code>data</code> : data to be sent   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_data_send(I2C1, 0x55);
```

### 5.15.38 i2c\_data\_receive function

The table below describes the function `i2c_data_receive`.

**Table 427. i2c\_data\_receive function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_data_receive</code>   |
| Function prototype     | <code>uint8_t i2c_data_receive(i2c_type *i2c_x);</code>                                   |
| Function description   | Receive data  |
| Input parameter 1      | <code>i2c_x</code> : selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3. |
| Output parameter       | <code>uint8_t</code> : data to be received  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
data_value = i2c_data_receive(I2C1);
```

### 5.15.39 i2c\_flag\_get function

The table below describes the function `i2c_flag_get`.

**Table 428. i2c\_flag\_get function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>i2c_flag_get</code>  |
| Function prototype   | <code>flag_status i2c_flag_get(i2c_type *i2c_x, uint32_t flag);</code> |
| Function description | Get flag status  |
| Input parameter 1    | <code>i2c_x</code> : selected I2C peripheral                           |

| Name                   | Description  |
|------------------------|--|
|                        | This parameter can be I2C1, I2C2 or I2C3.  |
| Input parameter 2      | flag: the selected flag<br>Refer to the following “flag” descriptions for details. |
| Output parameter       | NA   |
| Return value           | flag_status: flag status<br>This parameter can be SET or RESET.                    |
| Required preconditions | NA   |
| Called functions       | NA   |

**flag**

This bit is used to select a flag to get its status. Optional parameters are below:

|                   |  |
|-------------------|--|
| I2C_TDBE_FLAG:    | Transmit data register empty flag          |
| I2C_TDIS_FLAG:    | Transmit interrupt status flag             |
| I2C_RDBF_FLAG:    | Receive data buffer full flag              |
| I2C_ADDRF_FLAG:   | Address match flag                         |
| I2C_ACKFAIL_FLAG: | Acknowledge failure flag                   |
| I2C_STOPF_FLAG:   | STOP condition generation complete flag    |
| I2C_TDC_FLAG:     | Data transfer complete flag                |
| I2C_TCRLD_FLAG:   | Transfer complete to wait for loading data |
| I2C_BUSERR_FLAG:  | Bus error flag                             |
| I2C_ARLOST_FLAG:  | Arbitration lost flag                      |
| I2C_OUF_FLAG:     | Overflow or underflow flag                 |
| I2C_PECERR_FLAG:  | PEC RECEIVE ERROR FLAG                     |
| I2C_TMOUT_FLAG:   | SMBus timeout flag                         |
| I2C_ALERTF_FLAG:  | SMBus alert flag                           |
| I2C_BUSYF_FLAG:   | Bus busy flag                              |
| I2C_SDIR_FLAG:    | Slave data transfer direction              |

**Example:**

```
i2c_flag_get(I2C1, I2C_TDIS_FLAG);
```

### 5.15.40 i2c\_flag\_clear function

The table below describes the function i2c\_flag\_clear.

**Table 429. i2c\_flag\_clear function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_flag_clear   |
| Function prototype     | void i2c_flag_clear(i2c_type *i2c_x, uint32_t flag);                               |
| Function description   | Clear flag   |
| Input parameter 1      | i2c_x: selected I2C peripheral<br>This parameter can be I2C1, I2C2 or I2C3.        |
| Input parameter 2      | flag: the selected flag<br>Refer to the following “flag” descriptions for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |

| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**flag**

This bit is used to select a flag, including:

- I2C\_ADDRF\_FLAG: Address match flag
- I2C\_ACKFAIL\_FLAG: Acknowledge failure flag
- I2C\_STOPF\_FLAG: STOP condition generation complete flag
- I2C\_BUSERR\_FLAG: Bus error flag
- I2C\_ARLOST\_FLAG: Arbitration lost flag
- I2C\_OUF\_FLAG: Overflow or underflow flag
- I2C\_PECERR\_FLAG: PEC RECEIVE ERROR FLAG
- I2C\_TMOUF\_FLAG: SMBus timeout flag
- I2C\_ALERTF\_FLAG: SMBus alert flag

**Example:**

```
i2c_flag_clear(I2C1, I2C_ACKFAIL_FLAG);
```

### 5.15.41 i2c\_config function

The table below describes the function `i2c_config`.

**Table 430. i2c\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_config</code>   |
| Function prototype     | <code>void i2c_config(i2c_handle_type* hi2c);</code>  |
| Function description   | I2C initialization function used to initialize I2C. Call the function <code>i2c_lowlevel_init()</code> to initialize I2C peripherals, GPIO, DMA, interrupts and others. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refet to <a href="#">i2c_handle_type</a> .  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | <code>void i2c_lowlevel_init(i2c_handle_type* hi2c);</code>   |

**i2c\_handle\_type\* hi2c**

The `i2c_handle_type` is defined in the `i2c_application.h`.

typedef struct

```
{
    i2c_type          *i2cx;
    uint8_t          *pbuff;
    __IO uint16_t     psize;
    __IO uint16_t     pcount;
    __IO uint32_t     mode;
    __IO uint32_t     timeout;
    __IO uint32_t     status;
    __IO i2c_status_type error_code;
    dma_channel_type *dma_tx_channel;
    dma_channel_type *dma_rx_channel;
    dma_init_type     dma_init_struct;
}
```

}i2c\_handle\_type;

**i2cx**

Select an I2C peripheral from I2C1, I2C2 or I2C3.

**pbuff**

An array of data to be sent or received

**psize**

This bit is used to count the size of bytes in a single transfer when the transfer size is over 255. It is used in internal state machine. Users don't care.

**pcount**

The number of data to be sent or received

**mode**

I2C communication mode. It is used in internal state machine. Users don't care.

**timeout**

Communications timeout

**status**

Transfer status. It is used in internal state machine. Users don't care.

**error\_code**

This bit is used to enumerate error code in the i2c\_status\_type. When a communication error occurred, it logs the corresponding error code.

|                    |   |
|--------------------|---|
| I2C_OK:            | Communication OK                              |
| I2C_ERR_STEP_1:    | Step 1 error                                  |
| I2C_ERR_STEP_2:    | Step 2 error                                  |
| I2C_ERR_STEP_3:    | Step 3 error                                  |
| I2C_ERR_STEP_4:    | Step 4 error                                  |
| I2C_ERR_STEP_5:    | Step 5 error                                  |
| I2C_ERR_STEP_6:    | Step 6 error                                  |
| I2C_ERR_STEP_7:    | Step 7 error                                  |
| I2C_ERR_STEP_8:    | Step 8 error                                  |
| I2C_ERR_STEP_9:    | Step 9 error                                  |
| I2C_ERR_STEP_10:   | Step 10 error                                 |
| I2C_ERR_STEP_11:   | Step 11 error                                 |
| I2C_ERR_STEP_12:   | Step 12 error                                 |
| I2C_ERR_TCRLD:     | Wait for TCRLD timeout                        |
| I2C_ERR_TDC:       | Wait for TDC timeout                          |
| I2C_ERR_ADDR:      | Address send error                            |
| I2C_ERR_STOP:      | STOP condition send error                     |
| I2C_ERR_ACKFAIL:   | Acknowledge error                             |
| I2C_ERR_TIMEOUT:   | Timeout error                                 |
| I2C_ERR_INTERRUPT: | Enter an interrupt when an error event occurs |

**dma\_tx\_channel**

I2C transmit DMA channel

**dma\_rx\_channel**

I2C receive DMA channel

**dma\_init\_struct**

DMA initialization structure

**Example:**

```
i2c_handle_type hi2c;
hi2c.i2cx = I2C1;
i2c_config(&hi2c);
```

### 5.15.42 i2c\_lowlevel\_init function

The table below describes the function `i2c_lowlevel_init`.

**Table 431. i2c\_lowlevel\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_lowlevel_init</code>  |
| Function prototype     | <code>void i2c_lowlevel_init(i2c_handle_type* hi2c);</code>   |
| Function description   | I2C lower-level initialization callback function. It is called in the <code>i2c_config</code> to initialize I2C peripherals, GPIO, DMA, interrupts, etc. It requires users to implement I2C initialization inside the function. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
void i2c_lowlevel_init(i2c_handle_type* hi2c)
{
    if(hi2c->i2cx == I2C1)
    {
        Implement I2C1 initialization
    }
    else if(hi2c->i2cx == I2C2)
    {
        Implement I2C2 initialization
    }
}
```

### 5.15.43 i2c\_wait\_end function

The table below describes the function `i2c_wait_end`.

**Table 432. i2c\_wait\_end function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>i2c_wait_end</code>  |
| Function prototype   | <code>i2c_status_type i2c_wait_end(i2c_handle_type* hi2c, uint32_t timeout);</code>  |
| Function description | Wait for the end of communications. This function is used in DMA and interrupt transfer modes as they are non-blocking functions and can thus be used to wait for the end of transfer. |
| Input parameter 1    | hi2c: <code>i2c_handle_type</code> pointer   |

| Name                   | Description  |
|------------------------|--|
|                        | Refer to <a href="#">i2c_handle_type</a> .                           |
| Input parameter 2      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details. |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```

if (i2c_master_transmit_dma(&hi2c, 0xB0, tx_buf, 8, 0xFFFFFFFF) != I2C_OK)
{
    error_handler(i2c_status);
}

/* wait for the end of transfer */
if(i2c_wait_end(&hi2c, 0xFFFFFFFF) != I2C_OK)
{
    error_handler(i2c_status);
}

```

## 5.15.44 i2c\_wait\_flag function

The table below describes the function i2c\_wait\_flag.

**Table 433. i2c\_wait\_flag function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_wait_flag  |
| Function prototype     | i2c_status_type i2c_wait_flag(i2c_handle_type* hi2c, uint32_t flag, uint32_t event_check, uint32_t timeout)                                    |
| Function description   | Wait for a flag to be set or reset<br>Only BUSFY flag is “wait for a flag to be reset”, and others are “wait for a flag to be set”.            |
| Input parameter 1      | hi2c: i2c_handle_type pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | flag: the selected flag<br>Refer to the following “flag” descriptions for details.   |
| Input parameter 3      | event_check: check if the event has occurred or not while waiting for a flag<br>Refer to the following “event_check” descriptions for details. |
| Input parameter 4      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details.   |
| Required preconditions | NA   |
| Called functions       | NA   |

**flag**

Select a flag to wait for.

- I2C\_TDBE\_FLAG: Transmit data register empty flag
- I2C\_TDIS\_FLAG: Transmit interrupt status flag
- I2C\_RDBF\_FLAG: Receive data buffer full flag
- I2C\_ADDRF\_FLAG: Address match flag
- I2C\_ACKFAIL\_FLAG: Acknowledge failure flag
- I2C\_STOPF\_FLAG: STOP condition generation complete flag
- I2C\_TDC\_FLAG: Data transfer complete flag
- I2C\_TCRLD\_FLAG: Transfer complete to wait for loading data
- I2C\_BUSERR\_FLAG: Bus error flag
- I2C\_ARLOST\_FLAG: Arbitration lost flag
- I2C\_OUF\_FLAG: Overflow or underflow flag
- I2C\_PECERR\_FLAG: PEC receive error flag
- I2C\_TMOUT\_FLAG: SMBus timeout flag
- I2C\_ALERTF\_FLAG: SMBus alert flag
- I2C\_BUSYF\_FLAG: Bus busy flag
- I2C\_SDIR\_FLAG: Slave data transfer direction

**event\_check**

Check if the event has occurred or not while waiting for a flag.

- I2C\_EVENT\_CHECK\_NONE: None
- I2C\_EVENT\_CHECK\_ACKFAIL: Check ACKFAIL event
- I2C\_EVENT\_CHECK\_STOP: Check STOP event

**Example:**

```
i2c_wait_flag(&hi2c, I2C_BUSYF_FLAG, I2C_EVENT_CHECK_NONE, 0xFFFFFFFF);
```

### 5.15.45 i2c\_master\_transmit function

The table below describes the function `i2c_master_transmit`.

**Table 434. i2c\_master\_transmit function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_master_transmit</code>  |
| Function prototype     | <code>i2c_status_type i2c_master_transmit(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code> |
| Function description   | Master sends data (polling mode). This is a blocking function, and so I2C transfer ends after the function is executed.                     |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | address: slave address  |
| Input parameter 3      | pdata: array address of to-be-sent data   |
| Input parameter 4      | size: number of data to be sent   |
| Input parameter 5      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**



```
i2c_master_transmit(&hi2c, 0xB0, tx_buf, 8, 0xFFFFFFFF);
```

## 5.15.46 i2c\_master\_receive function

The table below describes the function `i2c_master_receive`.

**Table 435. i2c\_master\_receive function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_master_receive</code>  |
| Function prototype     | <code>i2c_status_type i2c_master_receive(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code> |
| Function description   | Master receives data (polling mode). This function is a blocking type. After the execution is done, so does I2C transfer.                  |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .   |
| Input parameter 2      | address: slave address   |
| Input parameter 3      | pdata: array address to receive data   |
| Input parameter 4      | size: number of data to receive  |
| Input parameter 5      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_master_receive(&hi2c, 0xB0, rx_buf, 8, 0xFFFFFFFF);
```

## 5.15.47 i2c\_slave\_transmit function

The table below describes the function `i2c_slave_transmit`.

**Table 436. i2c\_slave\_transmit function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_slave_transmit</code>  |
| Function prototype     | <code>i2c_status_type i2c_slave_transmit(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>                           |
| Function description   | Slave sends data (polling mode). This function is a blocking type. In other words, after the function execution is done, so does the I2C transfer. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .   |
| Input parameter 2      | pdata: array address of to-be-sent data  |
| Input parameter 3      | size: number of data to be sent  |
| Input parameter 4      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.   |
| Required preconditions | NA   |

| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**Example:**

```
i2c_slave_transmit(&hi2c, tx_buf, 8, 0xFFFFFFFF);
```

### 5.15.48 i2c\_slave\_receive function

The table below describes the function `i2c_slave_receive`.

**Table 437. i2c\_slave\_receive function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_slave_receive</code>  |
| Function prototype     | <code>i2c_status_type i2c_slave_receive(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>                               |
| Function description   | Slave receives data (polling mode). This function is a blocking type. In other words, after the function execution is done, so does the I2C transfer. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | pdata: array address to receive data  |
| Input parameter 3      | size: number of data to be received   |
| Input parameter 4      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_slave_receive(&hi2c, rx_buf, 8, 0xFFFFFFFF);
```

### 5.15.49 i2c\_master\_transmit\_int function

The table below describes the function `i2c_master_transmit_int`.

**Table 438. i2c\_master\_transmit\_int function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>i2c_master_transmit_int</code>  |
| Function prototype   | <code>i2c_status_type i2c_master_transmit_int(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>   |
| Function description | Master sends data (interrupt mode). This function is a non-blocking type. In other words, after the function execution is done, I2C transfer has not completed yet. In this case, it is possible to call the <code>i2c_wait_end()</code> to wait for the completion of communication. |
| Input parameter 1    | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2    | address: slave address  |
| Input parameter 3    | pdata: array address of data to be sent   |
| Input parameter 4    | size: number of data to be sent   |

| Name                   | Description  |
|------------------------|--|
| Input parameter 5      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details. |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_master_transmit_int(&hi2c, 0xB0, tx_buf, 8, 0xFFFFFFFF);
```

### 5.15.50 i2c\_master\_receive\_int function

The table below describes the function `i2c_master_receive_int`.

**Table 439. i2c\_master\_receive\_int function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_master_receive_int</code>   |
| Function prototype     | <code>i2c_status_type i2c_master_receive_int(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>  |
| Function description   | Master receives data (through interrupt mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call <code>i2c_wait_end()</code> to wait for the end of transfer. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | address: slave address  |
| Input parameter 3      | pdata: array address to receive data  |
| Input parameter 4      | size: number of data to be received   |
| Input parameter 5      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_master_receive_int(&hi2c, 0xB0, rx_buf, 8, 0xFFFFFFFF);
```

### 5.15.51 i2c\_slave\_transmit\_int function

The table below describes the function `i2c_slave_transmit_int`.

**Table 440. i2c\_slave\_transmit\_int function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>i2c_slave_transmit_int</code>  |
| Function prototype   | <code>i2c_status_type i2c_slave_transmit_int(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);</code> |
| Function description | Slave sends data (through interrupt mode). This function operates in non-blocking  |

| Name                   | Description  |
|------------------------|--|
|                        | mode. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call the <code>i2c_wait_end()</code> to wait for the end of transfer. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .   |
| Input parameter 2      | pdata: array address of data to be sent  |
| Input parameter 3      | size: number of data to be sent  |
| Input parameter 4      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_slave_transmit_int(&hi2c, tx_buf, 8, 0xFFFFFFFF);
```

## 5.15.52 i2c\_slave\_receive\_int function

The table below describes the function `i2c_slave_receive_int`.

**Table 441. i2c\_slave\_receive\_int function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_slave_receive_int</code>   |
| Function prototype     | <code>i2c_status_type i2c_slave_receive_int(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>  |
| Function description   | Slave receives data (through interrupt mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call the <code>i2c_wait_end()</code> to wait for the end of transfer. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .   |
| Input parameter 2      | pdata: array address to receive data   |
| Input parameter 3      | size: number of data to be received  |
| Input parameter 4      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_slave_receive_int(&hi2c, rx_buf, 8, 0xFFFFFFFF);
```

### 5.15.53 i2c\_master\_transmit\_dma function

The table below describes the function `i2c_master_transmit_dma`.

**Table 442. i2c\_master\_transmit\_dma function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_master_transmit_dma</code>  |
| Function prototype     | <code>i2c_status_type i2c_master_transmit_dma(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>   |
| Function description   | Slave sends data (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call the <code>i2c_wait_end()</code> to wait for the end of transfer. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | address: slave address  |
| Input parameter 3      | pdata: array address of data to be sent   |
| Input parameter 4      | size: number of data to be sent   |
| Input parameter 5      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_master_transmit_dma(&hi2c, 0xB0, tx_buf, 8, 0xFFFFFFFF);
```

### 5.15.54 i2c\_master\_receive\_dma function

The table below describes the function `i2c_master_receive_dma`.

**Table 443. i2c\_master\_receive\_dma function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>i2c_master_receive_dma</code>   |
| Function prototype   | <code>i2c_status_type i2c_master_receive_dma(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>  |
| Function description | Master receives data (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call the <code>i2c_wait_end()</code> to wait for the end of transfer. |
| Input parameter 1    | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2    | address: slave address  |
| Input parameter 3    | pdata: array address to receive data  |
| Input parameter 4    | size: number of data to be received   |
| Input parameter 5    | timeout: wait timeout   |
| Output parameter     | NA  |

| Name                   | Description  |
|------------------------|--|
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details. |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_master_receive_dma(&hi2c, 0xB0, rx_buf, 8, 0xFFFFFFFF);
```

### 5.15.55 i2c\_slave\_transmit\_dma function

The table below describes the function i2c\_slave\_transmit\_dma.

**Table 444. i2c\_slave\_transmit\_dma function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_slave_transmit_dma   |
| Function prototype     | i2c_status_type i2c_slave_transmit_dma(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);  |
| Function description   | Slave sends data (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer. |
| Input parameter 1      | hi2c: i2c_handle_type pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | pdata: array address of data to be sent  |
| Input parameter 3      | size: number of data to be sent  |
| Input parameter 4      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details.   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_slave_transmit_dma(&hi2c, tx_buf, 8, 0xFFFFFFFF);
```

### 5.15.56 i2c\_slave\_receive\_dma function

The table below describes the function i2c\_slave\_receive\_dma.

**Table 445. i2c\_slave\_receive\_dma function**

| Name                 | Description   |
|----------------------|---|
| Function name        | i2c_slave_receive_dma   |
| Function prototype   | i2c_status_type i2c_slave_receive_dma(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);  |
| Function description | Slave receives data (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer. |

| Name                   | Description   |
|------------------------|---|
| Input parameter 1      | hi2c: i2c_handle_type pointer<br>Refer to <a href="#">i2c_handle_type</a> . |
| Input parameter 2      | pdata: array address to receive data  |
| Input parameter 3      | size: number of data to be received   |
| Input parameter 4      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details.        |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_slave_receive_dma(&hi2c, rx_buf, 8, 0xFFFFFFFF);
```

### 5.15.57 i2c\_smbus\_master\_transmit function

The table below describes the function i2c\_smbus\_master\_transmit.

**Table 446. i2c\_smbus\_master\_transmit function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_smbus_master_transmit  |
| Function prototype     | i2c_status_type i2c_smbus_master_transmit(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);   |
| Function description   | SMBus master sends data (through polling mode). This function is a blocking type. In other words, after the function execution is done, so does the data transfer. It is mainly used for PEC transmission and reception. |
| Input parameter 1      | hi2c: i2c_handle_type pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | address: slave address   |
| Input parameter 3      | pdata: array address of data to be sent  |
| Input parameter 4      | size: number of data to be sent  |
| Input parameter 5      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details.   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
i2c_smbus_master_transmit(&hi2c, 0xB0, tx_buf, 8, 0xFFFFFFFF);
```

### 5.15.58 i2c\_smbus\_master\_receive function

The table below describes the function `i2c_smbus_master_receive`.

**Table 447. i2c\_smbus\_master\_receive function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_smbus_master_receive</code>   |
| Function prototype     | <code>i2c_status_type i2c_smbus_master_receive(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>  |
| Function description   | SMBus master receives data (through polling mode). This function is a blocking type. In other words, after the function execution is done, so does the data transfer. It is mainly used for PEC transmission and reception. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | address: slave address  |
| Input parameter 3      | pdata: array address to receive data  |
| Input parameter 4      | size: number of data to be received   |
| Input parameter 5      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_smbus_master_receive(&hi2c, 0xB0, rx_buf, 8, 0xFFFFFFFF);
```

### 5.15.59 i2c\_smbus\_slave\_transmit function

The table below describes the function `i2c_smbus_slave_transmit`.

**Table 448. i2c\_smbus\_slave\_transmit function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_smbus_slave_transmit</code>   |
| Function prototype     | <code>i2c_status_type i2c_smbus_slave_transmit(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>  |
| Function description   | SMBus slave sends data (through polling mode). This function is a blocking type. In other words, after the function execution is done, so does the data transfer. It is mainly used for PEC transmission and reception. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | pdata: array address of data to be sent   |
| Input parameter 3      | size: number of data to be sent   |
| Input parameter 4      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.  |
| Required preconditions | NA  |



| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**Example:**

```
i2c_smbus_slave_transmit(&hi2c, tx_buf, 8, 0xFFFFFFFF);
```

### 5.15.60 i2c\_smbus\_slave\_receive function

The table below describes the function `i2c_smbus_slave_receive`.

**Table 449. i2c\_smbus\_slave\_receive function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_smbus_slave_receive</code>  |
| Function prototype     | <code>i2c_status_type i2c_smbus_slave_receive(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>   |
| Function description   | SMBus slave receives data (through polling mode). This function is a blocking type. In other words, after the function execution is done, so is data transfer. It is mainly used for PEC transmission and reception |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | pdata: array address to receive data  |
| Input parameter 3      | size: number of data to be received   |
| Input parameter 4      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
i2c_smbus_slave_receive(&hi2c, rx_buf, 8, 0xFFFFFFFF);
```

### 5.15.61 i2c\_memory\_write function

The table below describes the function `i2c_memory_write`.

**Table 450. i2c\_memory\_write function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>i2c_memory_write</code>  |
| Function prototype   | <code>i2c_status_type i2c_memory_write(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code> |
| Function description | Write data to EEPROM (through polling mode). This function is a blocking type. In other words, after the function execution is done, so does the I2C transfer.   |
| Input parameter 1    | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .   |
| Input parameter 2    | mem_address_width: EEPROM memory address width<br>Refer to the following “mem_address_width” descriptions for details.   |
| Input parameter 3    | address: EEPROM address  |

| Name                   | Description  |
|------------------------|--|
| Input parameter 4      | mem_address: EEPROM data memory address                              |
| Input parameter 5      | pdata: array address of data to be sent                              |
| Input parameter 6      | size: number of data to be sent                                      |
| Input parameter 7      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details. |
| Required preconditions | NA   |
| Called functions       | NA   |

**mem\_address\_width**

EEPROM memory address width

I2C\_MEM\_ADDR\_WIDIH\_8: 8-bit address width

I2C\_MEM\_ADDR\_WIDIH\_16: 16-bit address width

**Example:**

```
i2c_memory_write(&hi2c, 0xA0, 0x05, tx_buf, 8, 0xFFFFFFFF);
```

## 5.15.62 i2c\_memory\_write\_int function

The table below describes the function `i2c_memory_write_int`.

**Table 451. i2c\_memory\_write\_int function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_memory_write_int</code>   |
| Function prototype     | <code>i2c_status_type i2c_memory_write_int(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>  |
| Function description   | Write EEPROM (through interrupt mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call the <code>i2c_wait_end()</code> to wait for the end of transfer. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | mem_address_width: EEPROM memory address width<br>Refer to the following "mem_address_width" descriptions for details.  |
| Input parameter 3      | address: EEPROM address   |
| Input parameter 4      | mem_address: EEPROM data memory address   |
| Input parameter 5      | pdata: array address of data to be sent   |
| Input parameter 6      | size: number of data to be sent   |
| Input parameter 7      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**mem\_address\_width**

EEPROM memory address width

I2C\_MEM\_ADDR\_WIDIH\_8: 8-bit address width

I2C\_MEM\_ADDR\_WIDIH\_16: 16-bit address width

**Example:**

```
i2c_memory_write_int(&hi2c, 0xA0, 0x05, tx_buf, 8, 0xFFFFFFFF);
```

### 5.15.63 i2c\_memory\_write\_dma function

The table below describes the function i2c\_memory\_write\_dma.

**Table 452. i2c\_memory\_write\_dma function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_memory_write_dma   |
| Function prototype     | i2c_status_type i2c_memory_write_dma(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);  |
| Function description   | Write EEPROM (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer. |
| Input parameter 1      | hi2c: i2c_handle_type pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | mem_address_width: EEPROM memory address width<br>Refer to the following "mem_address_width" descriptions for details.   |
| Input parameter 3      | address: EEPROM address  |
| Input parameter 4      | mem_address: EEPROM data memory address  |
| Input parameter 5      | pdata: array address of data to be sent  |
| Input parameter 6      | size: number of data to be sent  |
| Input parameter 7      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | i2c_status_type: error code<br>Refer to Section 5.15.41 for details.   |
| Required preconditions | NA   |
| Called functions       | NA   |

**mem\_address\_width**

EEPROM memory address width

I2C\_MEM\_ADDR\_WIDIH\_8: 8-bit address width

I2C\_MEM\_ADDR\_WIDIH\_16: 16-bit address width

**Example:**

```
i2c_memory_write_dma(&hi2c, 0xA0, 0x05, tx_buf, 8, 0xFFFFFFFF);
```

### 5.15.64 i2c\_memory\_read function

The table below describes the function `i2c_memory_read`.

**Table 453. i2c\_memory\_read function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2c_memory_read</code>  |
| Function prototype     | <code>i2c_status_type i2c_memory_read(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code> |
| Function description   | Read EEPROM (through polling mode). This function is a blocking type. In other words, after the function execution is done, so does the data transfer.  |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Input parameter 2      | mem_address_width: EEPROM memory address width<br>Refer to the following "mem_address_width" descriptions for details.  |
| Input parameter 3      | address: EEPROM address   |
| Input parameter 4      | mem_address: EEPROM data memory address   |
| Input parameter 5      | pdata: array address of data to be read   |
| Input parameter 6      | size: number of data to be read   |
| Input parameter 7      | timeout: wait timeout   |
| Output parameter       | NA  |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### **mem\_address\_width**

EEPROM memory address width

`I2C_MEM_ADDR_WIDIH_8`: 8-bit address width

`I2C_MEM_ADDR_WIDIH_16`: 16-bit address width

#### **Example:**

```
i2c_memory_read(&hi2c, 0xA0, 0x05, rx_buf, 8, 0xFFFFFFFF);
```

### 5.15.65 i2c\_memory\_read\_int function

The table below describes the function `i2c_memory_read_int`.

**Table 454. i2c\_memory\_read\_int function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_memory_read_int</code>   |
| Function prototype     | <code>i2c_status_type i2c_memory_read_int(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code>  |
| Function description   | Read EEPROM (through interrupt mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet. So in this case, it is possible to call the <code>i2c_wait_end()</code> to wait for the end of transfer. |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .   |
| Input parameter 2      | mem_address_width: EEPROM memory address width<br>Refer to the following "mem_address_width" descriptions for details.   |
| Input parameter 3      | address: EEPROM address  |
| Input parameter 4      | mem_address: EEPROM data memory address  |
| Input parameter 5      | pdata: array address of data to be read  |
| Input parameter 6      | size: number of data to be read  |
| Input parameter 7      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### mem\_address\_width

EEPROM memory address width

I2C\_MEM\_ADDR\_WIDIH\_8: 8-bit address width

I2C\_MEM\_ADDR\_WIDIH\_16: 16-bit address width

#### Example:

```
i2c_memory_read_int(&hi2c, 0xA0, 0x05, rx_buf, 8, 0xFFFFFFFF);
```

### 5.15.66 i2c\_memory\_read\_dma function

The table below describes the function `i2c_memory_read_dma`.

**Table 455. i2c\_memory\_read\_dma function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>i2c_memory_read_dma</code>  |
| Function prototype   | <code>i2c_status_type i2c_memory_read_dma(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);</code> |
| Function description | Read EEPROM (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I2C transfer has not completed yet.   |

| Name                   | Description  |
|------------------------|--|
|                        | So in this case, it is possible to call the <code>i2c_wait_end()</code> to wait for the end of transfer.               |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> .                               |
| Input parameter 2      | mem_address_width: EEPROM memory address width<br>Refer to the following “mem_address_width” descriptions for details. |
| Input parameter 3      | address: EEPROM address  |
| Input parameter 4      | mem_address: EEPROM data memory address  |
| Input parameter 5      | pdata: array address of data to be read  |
| Input parameter 6      | size: number of data to be read  |
| Input parameter 7      | timeout: wait timeout  |
| Output parameter       | NA   |
| Return value           | <code>i2c_status_type</code> : error code<br>Refer to Section 5.15.41 for details.                                     |
| Required preconditions | NA   |
| Called functions       | NA   |

**mem\_address\_width**

EEPROM memory address width

I2C\_MEM\_ADDR\_WIDIH\_8: 8-bit address width

I2C\_MEM\_ADDR\_WIDIH\_16: 16-bit address width

**Example:**

```
i2c_memory_read_dma(&hi2c, 0xA0, 0x05, rx_buf, 8, 0xFFFFFFFF);
```

## 5.15.67 i2c\_evt\_irq\_handler function

The table below describes the function `i2c_evt_irq_handler`.

**Table 456. i2c\_evt\_irq\_handler function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_evt_irq_handler</code>   |
| Function prototype     | <code>void i2c_evt_irq_handler(i2c_handle_type* hi2c);</code>                            |
| Function description   | Event interrupt function. It is used to handle I2C event interrupt.                      |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> . |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
void I2C1_EVT_IRQHandler(void)
{
    i2c_evt_irq_handler(&hi2c);
}
```

### 5.15.68 i2c\_err\_irq\_handler function

The table below describes the function i2c\_err\_irq\_handler.

**Table 457. i2c\_err\_irq\_handler function**

| Name                   | Description   |
|------------------------|---|
| Function name          | i2c_err_irq_handler   |
| Function prototype     | void i2c_err_irq_handler(i2c_handle_type* hi2c);                            |
| Function description   | Error interruptfunction. It is used to handle I2C error interrupt.          |
| Input parameter 1      | hi2c: i2c_handle_type pointer<br>Refer to <a href="#">i2c_handle_type</a> . |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
void I2C1_ERR_IRQHandler(void)
{
    i2c_err_irq_handler(&hi2c);
}
```

### 5.15.69 i2c\_dma\_tx\_irq\_handler function

The table below describes the function i2c\_dma\_tx\_irq\_handler.

**Table 458. i2c\_dma\_tx\_irq\_handler function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2c_dma_tx_irq_handler   |
| Function prototype     | void i2c_dma_tx_irq_handler(i2c_handle_type* hi2c);                          |
| Function description   | DMA transmit interruptfunction. It is used to handle DMA transmit interrupt. |
| Input parameter 1      | hi2c: i2c_handle_type pointer<br>Refer to <a href="#">i2c_handle_type</a> .  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
void DMA1_Channel6_IRQHandler(void)
{
    i2c_dma_tx_irq_handler(&hi2c);
}
```

### 5.15.70 i2c\_dma\_rx\_irq\_handler function

The table below describes the function `i2c_dma_rx_irq_handler`.

**Table 459. i2c\_dma\_rx\_irq\_handler function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>i2c_dma_rx_irq_handler</code>  |
| Function prototype     | <code>void i2c_dma_rx_irq_handler(i2c_handle_type* hi2c);</code>                         |
| Function description   | DMA receive interrupt function. It is used to handle DMA receive interrupt.              |
| Input parameter 1      | hi2c: <code>i2c_handle_type</code> pointer<br>Refer to <a href="#">i2c_handle_type</a> . |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
void DMA1_Channel7_IRQHandler(void)
{
    i2c_dma_tx_irq_handler(&hi2c);
}
```



## 5.16 Nested vectored interrupt controller (NVIC)

The NVIC register structure NVIC\_Type is defined in the “core\_cm4.h”.

```
/**
 * @brief Structure type to access the Nested Vectored Interrupt Controller (NVIC).
 */
typedef struct
{
    .....
} NVIC_Type;
```

The table below gives a list of the NVIC registers.

**Table 460. Summary of PWC registers**

| Register | Description                         |
|----------|-------------------------------------|
| iser     | Interrupt enable set register       |
| icer     | Interrupt enable clear register     |
| ispr     | Interrupt suspend set register      |
| icpr     | Interrupt suspend clear register    |
| iabr     | Interrupt activate bit register     |
| ip       | Interrupt priority register         |
| stir     | Software trigger interrupt register |

The table below gives a list of NVIC library functions.

**Table 461. Summary of PWC library functions**

| Function name              | Description   |
|----------------------------|---|
| nvic_system_reset          | System software reset   |
| nvic_irq_enable            | NVIC interrupt enable and priority configuration                          |
| nvic_irq_disable           | NVIC interrupt disable  |
| nvic_priority_group_config | NVIC interrupt priority grouping configuration                            |
| nvic_vector_table_set      | NVIC interrupt vector table base address and offset address configuration |
| nvic_lowpower_mode_config  | NVIC low-power mode configuration   |

### 5.16.1 nvic\_system\_reset function

The table below describes the function nvic\_system\_reset.

**Table 462. nvic\_system\_reset function**

| Name                 | Description                  |
|----------------------|------------------------------|
| Function name        | nvic_system_reset            |
| Function prototype   | void nvic_system_reset(void) |
| Function description | System software reset        |
| Input parameter      | NA                           |
| Output parameter     | NA                           |
| Return value         | NA                           |

| Name                   | Description        |
|------------------------|--------------------|
| Required preconditions | NA                 |
| Called functions       | NVIC_SystemReset() |

**Example:**

```
/* system reset */
nvic_system_reset();
```

## 5.16.2 nvic\_irq\_enable function

The table below describes the function nvic\_irq\_enable.

**Table 463. nvic\_irq\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | nvic_irq_enable  |
| Function prototype     | void nvic_irq_enable(IRQn_Type irqn, uint32_t preempt_priority, uint32_t sub_priority)   |
| Function description   | NVIC interrupt enable and priority configuration   |
| Input parameter 1      | irqn: interrupt vector selection<br>Refer to <a href="#">irqn</a> .  |
| Input parameter 2      | preempt_priority: set preemption priority<br>This parameter cannot be greater than the highest preemption priority defined in the NVIC_PRIORITY_GROUP_x. |
| Input parameter 3      | sub_priority: set response priority<br>This parameter cannot be greater than the highest response priority defined in the NVIC_PRIORITY_GROUP_x.         |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NVIC_SetPriority()<br>NVIC_EnableIRQ()   |

**irqn**

The irqn is used to select interrupt vectors, including

- WWDT\_IRQn: Window timer interrupt
- PVM\_IRQn: PVM interrupt linked to EXINT
- .....
- DMA2\_Channel6\_IRQn: DMA2 channel 6 global interrupt
- DMA2\_Channel7\_IRQn: DMA2 channel 7 global interrupt

**Example:**

```
/* enable nvic irq */
nvic_irq_enable(ADC1_2_3_IRQn, 0, 0);
```

### 5.16.3 nvic\_irq\_disable function

The table below describes the function `nvic_irq_disable`.

**Table 464. nvic\_irq\_disable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>nvic_irq_disable</code>   |
| Function prototype     | <code>void nvic_irq_disable(IRQn_Type irqn)</code>                              |
| Function description   | NVIC interruptenable  |
| Input parameter        | <code>irqn</code> : select interrupt vector.<br>Refer to <a href="#">irqn</a> . |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | <code>NVIC_DisableIRQ()</code>  |

**Example:**

```
/* disable nvic irq */
nvic_irq_disable(ADC1_2_3_IRQn);
```

### 5.16.4 nvic\_priority\_group\_config function

The table below describes the function `nvic_priority_group_config`.

**Table 465. nvic\_priority\_group\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>nvic_priority_group_config</code>  |
| Function prototype     | <code>void nvic_priority_group_config(nvic_priority_group_type priority_group)</code>  |
| Function description   | NVIC interrupt priority grouping configuration   |
| Input parameter        | <code>priority_group</code> : select interrupt priority group<br>This parameter can be any enumerated value in the <code>nvic_priority_group_type</code> . |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | <code>NVIC_SetPriorityGrouping()</code>  |

**priority\_group**

The `priority_group` is used to select priority group from the parameters below:

`NVIC_PRIORITY_GROUP_0`:

Priority group 0 (0 bit for preemption priority, and 4 bits for response priority)

`NVIC_PRIORITY_GROUP_1`:

Priority group 1 (1 bit for preemption priority, and 3 bits for response priority)

`NVIC_PRIORITY_GROUP_2`:

Priority group 2 (2 bits for preemption priority, and 2 bits for response priority)

`NVIC_PRIORITY_GROUP_3`:

Priority group 3 (3 bits for preemption priority, and 1 bit for response priority)

`NVIC_PRIORITY_GROUP_4`:

Priority group 3 (4 bits for preemption priority, and 0 bit for response priority)

**Example:**

```
/* config nvic priority group */
nvic_priority_group_config(NVIC_PRIORITY_GROUP_4);
```

### 5.16.5 nvic\_vector\_table\_set function

The table below describes the function `nvic_vector_table_set`.

**Table 466. nvic\_vector\_table\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>nvic_vector_table_set</code>  |
| Function prototype     | <code>void nvic_vector_table_set(uint32_t base, uint32_t offset)</code>   |
| Function description   | Set NVIC interrupt vector table base address and offset address   |
| Input parameter 1      | base: base address of interrupt vector table<br>The base address can be set in RAM or FLASH.  |
| Input parameter 2      | offset: offset address of interrupt vector table<br>This parameter defines the start address of interrupt vector table, so it must be set to a multiple of 0x200. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### base

The base is used to select the base address of interrupt vector table, including:

NVIC\_VECTTAB\_RAM: Interrupt vector table base address is located in RAM

NVIC\_VECTTAB\_FLASH: Interrupt vector table base address is located in FLASH

#### Example:

```
/* config vector table offset */
nvic_vector_table_set(NVIC_VECTTAB_FLASH, 0x4000);
```

### 5.16.6 nvic\_lowpower\_mode\_config function

The table below describes the function `nvic_lowpower_mode_config`.

**Table 467. nvic\_lowpower\_mode\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>nvic_lowpower_mode_config</code>  |
| Function prototype     | <code>void nvic_lowpower_mode_config(nvic_lowpower_mode_type lp_mode, confirm_state new_state)</code>                       |
| Function description   | Configure NVIC low-power mode   |
| Input parameter 1      | lp_mode: select low-power modes<br>This parameter can be any enumerated value in the <code>nvic_lowpower_mode_type</code> . |
| Input parameter 2      | new_state: indicates the pre-configured status of battery powered domain<br>This parameter can be TRUE or FALSE.            |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**lp\_mode**

The lp\_mode is used to select low-power modes, including

NVIC\_LP\_SEVONPEND:

Send wakeup event upon interrupt suspend (this option is usually used in conjunction with WFE)

NVIC\_LP\_SLEEPDEEP:

Deepsleep mode control bit (enable or disable core clock)

NVIC\_LP\_SLEEPONEXIT:

Sleep mode entry when system leaves the lowest-priority interrupt

**Example:**

```
/* enable sleep-on-exit feature */  
nvic_lowpower_mode_config(NVIC_LP_SLEEPONEXIT, TRUE);
```

## 5.17 Power controller (PWC)

The PWC register structure `pwc_type` is defined in the “`at32f435_437_pwc.h`”.

```
/**
 * @brief type define pwc register all
 */
typedef struct
{
    .....
} pwc_type;
```

The table below gives a list of the PWC registers.

**Table 468. Summary of PWC registers**

| Register             | Description                   |
|----------------------|-------------------------------|
| <code>ctrl</code>    | Power control register        |
| <code>ctrlsts</code> | Power control/status register |
| <code>ldoov</code>   | LDO calibration register      |

The table below gives a list of PWC library functions.

**Table 469. Summary of PWC library functions**

| Function name                                  | Description                                       |
|--|---|
| <code>pwc_reset</code>                         | Reset PWC registers to their reset values         |
| <code>pwc_battery_powered_domain_access</code> | Enable battery powered domain access              |
| <code>pwc_pvm_level_select</code>              | Select PVM threshold                              |
| <code>pwc_power_voltage_monitor_enable</code>  | Enable voltage monitor                            |
| <code>pwc_wakeup_pin_enable</code>             | Enable standby-mode wakeup pin                    |
| <code>pwc_flag_clear</code>                    | Clear flag  |
| <code>pwc_flag_get</code>                      | Get flag status                                   |
| <code>pwc_sleep_mode_enter</code>              | Enter Sleep mode                                  |
| <code>pwc_deep_sleep_mode_enter</code>         | Enter Deepsleep mode                              |
| <code>pwc_voltage_regulate_set</code>          | Select voltage regulator status in Deepsleep mode |
| <code>pwc_standby_mode_enter</code>            | Enter Standby mode                                |

### 5.17.1 `pwc_reset` function

The table below describes the function `pwc_reset`.

**Table 470. `pwc_reset` function**

| Name                 | Description                                   |
|----------------------|---|
| Function name        | <code>pwc_reset</code>                        |
| Function prototype   | <code>void pwc_reset(void)</code>             |
| Function description | Reset all PWC registers to their reset values |
| Input parameter      | NA  |
| Output parameter     | NA  |
| Return value         | NA  |

| Name                   | Description        |
|------------------------|--------------------|
| Required preconditions | NA                 |
| Called functions       | crm_periph_reset() |

**Example:**

```
/* deinitialize pwc */
pwc_reset();
```

### 5.17.2 pwc\_battery\_powered\_domain\_access function

The table below describes the function pwc\_battery\_powered\_domain\_access.

**Table 471. pwc\_battery\_powered\_domain\_access function**

| Name                   | Description  |
|------------------------|--|
| Function name          | pwc_battery_powered_domain_access  |
| Function prototype     | void pwc_battery_powered_domain_access(confirm_state new_state)  |
| Function description   | Battery powered domain access enable   |
| Input parameter        | new_state: indicates the pre-configured status of battery powered domain<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable the battery-powered domain write operations */
pwc_battery_powered_domain_access(TRUE);
```

*Note: Access to battery powered domain (such as, RTC) is allowed only after enabling it through this function.*

### 5.17.3 pwc\_pvm\_level\_select function

The table below describes the function pwc\_pvm\_level\_select.

**Table 472. pwc\_pvm\_level\_select function**

| Name                   | Description  |
|------------------------|--|
| Function name          | pwc_pvm_level_select   |
| Function prototype     | void pwc_pvm_level_select(pwc_pvm_voltage_type pvm_voltage)  |
| Function description   | Select PVM threshold   |
| Input parameter        | pvm_voltage: indicates the selected PVM threshold<br>This parameter can be any enumerated value in the pwc_pvm_voltage_type. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**pvm\_voltage**

The pvm\_voltage is used to select a PVM threshold from the optional parameters below:

PWC\_PVM\_VOLTAGE\_2V3: PVM threshold is 2.3 V

PWC\_PVM\_VOLTAGE\_2V4: PVM threshold is 2.4 V

PWC\_PVM\_VOLTAGE\_2V5: PVM threshold is 2.5 V  
 PWC\_PVM\_VOLTAGE\_2V6: PVM threshold is 2.6 V  
 PWC\_PVM\_VOLTAGE\_2V7: PVM threshold is 2.7 V  
 PWC\_PVM\_VOLTAGE\_2V8: PVM threshold is 2.8 V  
 PWC\_PVM\_VOLTAGE\_2V9: PVM threshold is 2.9 V

**Example:**

```
/* set the threshold voltage to 2.9v */
pwc_pvm_level_select(PWC_PVM_VOLTAGE_2V9);
```

### 5.17.4 pwc\_power\_voltage\_monitor\_enable function

The table below describes the function pwc\_power\_voltage\_monitor\_enable.

**Table 473. pwc\_power\_voltage\_monitor\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | pwc_power_voltage_monitor_enable  |
| Function prototype     | void pwc_power_voltage_monitor_enable(confirm_state new_state)                                |
| Function description   | Enable power voltage monitor (PVM)  |
| Input parameter        | new_state: indicates the pre-configured status of PVM<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable power voltage monitor */
pwc_power_voltage_monitor_enable(TRUE);
```

### 5.17.5 pwc\_wakeup\_pin\_enable function

The table below describes the function pwc\_wakeup\_pin\_enable.

**Table 474. pwc\_wakeup\_pin\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | pwc_wakeup_pin_enable   |
| Function prototype     | void pwc_wakeup_pin_enable(uint32_t pin_num, confirm_state new_state)   |
| Function description   | Enable Standby wakeup pin   |
| Input parameter 1      | pin_num: select a standby wakeup pin<br>This parameter can be any pin that is capable of waking up from Standby mode. |
| Input parameter 2      | new_state: indicates the pre-configured status of Standby wakeup pins<br>This parameter can be TRUE or FALSE.         |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**pin\_num**

The pin\_num is used to select Standby-mode wakeup pin, including



PWC\_WAKEUP\_PIN\_1: Standby wakeup pin 1 (corresponding GPIO is PA0)

PWC\_WAKEUP\_PIN\_2: Standby wakeup pin 2 (corresponding GPIO is PC13)

**Example:**

```
/* enable wakeup pin - pa0 */
pwc_wakeup_pin_enable(PWC_WAKEUP_PIN_1, TRUE);
```

### 5.17.6 pwc\_flag\_clear function

The table below describes the function pwc\_flag\_clear.

**Table 475. pwc\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | pwc_flag_clear  |
| Function prototype     | void pwc_flag_clear(uint32_t pwc_flag)                              |
| Function description   | Clear flag  |
| Input parameter        | pwc_flag: to-be-cleared flag<br>Refer to <a href="#">pwc_flag</a> . |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**pwc\_flag**

The pwc\_flag is used to select a flag from the optional parameters below:

PWC\_WAKEUP\_FLAG: Standby wakeup event

PWC\_STANDBY\_FLAG: Standby mode entry flag

PWC\_PVM\_OUTPUT\_FLAG: PVM output flag (this parameter cannot be cleared by software)

**Example:**

```
/* wakeup event flag clear */
pwc_flag_clear(PWC_WAKEUP_FLAG);
```

### 5.17.7 pwc\_flag\_get function

The table below describes the function pwc\_flag\_get.

**Table 476. pwc\_flag\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | pwc_flag_get   |
| Function prototype     | flag_status pwc_flag_get(uint32_t pwc_flag)                    |
| Function description   | Get flag status  |
| Input parameter        | pwc_flag: select a flag<br>Refer to <a href="#">pwc_flag</a> . |
| Output parameter       | NA   |
| Return value           | flag_status: indicates flag status<br>Return SET or RESET.     |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* check if wakeup event flag is set*/
if(pwc_flag_get(PWC_WAKEUP_FLAG) != RESET)
```

### 5.17.8 pwc\_sleep\_mode\_enter function

The table below describes the function pwc\_sleep\_mode\_enter.

**Table 477. pwc\_sleep\_mode\_enter function**

| Name                   | Description  |
|------------------------|--|
| Function name          | pwc_sleep_mode_enter   |
| Function prototype     | void pwc_sleep_mode_enter(pwc_sleep_enter_type pwc_sleep_enter)  |
| Function description   | Enter Sleep mode   |
| Input parameter        | pwc_sleep_enter: select a command to enter Sleep mode<br>This parameter can be any enumerated value in the pwc_sleep_enter_type. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **pwc\_sleep\_enter**

The pwc\_sleep\_enter is used to select a command to enter Sleep mode from the optional parameters below:

PWC\_SLEEP\_ENTER\_WFI:           Enter Sleep mode by WFI  
PWC\_SLEEP\_ENTER\_WFE:           Enter Sleep mode by WFE

#### **Example:**

```
/* enter sleep mode */
pwc_sleep_mode_enter(PWC_SLEEP_ENTER_WFI);
```

### 5.17.9 pwc\_deep\_sleep\_mode\_enter function

The table below describes the function pwc\_deep\_sleep\_mode\_enter.

**Table 478. pwc\_deep\_sleep\_mode\_enter function**

| Name                   | Description  |
|------------------------|--|
| Function name          | pwc_deep_sleep_mode_enter  |
| Function prototype     | void pwc_deep_sleep_mode_enter(pwc_deep_sleep_enter_type pwc_deep_sleep_enter)   |
| Function description   | Enter Deepsleep mode   |
| Input parameter        | pwc_deep_sleep_enter: select a command to enter Deepsleep mode<br>This parameter can be any enumerated value in the pwc_deep_sleep_enter_type. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **pwc\_deep\_sleep\_enter**

The pwc\_deep\_sleep\_enter is used to select a command to enter Deepsleep mode, including:

PWC\_DEEP\_SLEEP\_ENTER\_WFI:       Enter Deepsleep mode WFI  
PWC\_DEEP\_SLEEP\_ENTER\_WFE:       Enter Deepsleep mode WFE

**Example:**

```
/* enter deep sleep mode */
pwc_deep_sleep_mode_enter(PWC_DEEP_SLEEP_ENTER_WFI);
```

### 5.17.10 pwc\_voltage\_regulate\_set function

The table below describes the function pwc\_voltage\_regulate\_set.

**Table 479. pwc\_voltage\_regulate\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | pwc_voltage_regulate_set  |
| Function prototype     | void pwc_voltage_regulate_set(pwc_regulator_type pwc_regulator)   |
| Function description   | Select the status of voltage regulator in Deepsleep mode  |
| Input parameter        | pwc_regulator: select voltage regulator status<br>This parameter can be any enumerated value in the pwc_regulator_type. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**pwc\_regulator**

The pwc\_regulator is used to select the status of voltage regulator from the optional parameters below:

PWC\_REGULATOR\_ON: Voltage regulator ON in Deepsleep mode

PWC\_REGULATOR\_LOW\_POWER: Voltage regulator low-power mode in Deepsleep mode

**Example:**

```
/* congfig the voltage regulator mode */
pwc_voltage_regulate_set(PWC_REGULATOR_LOW_POWER);
```

### 5.17.11 pwc\_standby\_mode\_enter function

The table below describes the function pwc\_standby\_mode\_enter.

**Table 480. pwc\_standby\_mode\_enter function**

| Name                   | Description                       |
|------------------------|-----------------------------------|
| Function name          | pwc_standby_mode_enter            |
| Function prototype     | void pwc_standby_mode_enter(void) |
| Function description   | Enter Standby mode                |
| Input parameter        | NA                                |
| Output parameter       | NA                                |
| Return value           | NA                                |
| Required preconditions | NA                                |
| Called functions       | NA                                |

**Example:**

```
/* enter standbymode */
pwc_standby_mode_enter();
```

## 5.18 Qud-SPI interface (QSPI)

The QSPI register structure `qspi_type` is defined in the “`at32f435_437_qspi.h`”.

```
/**
 * @brief type define qspi register all
 */
typedef struct
{
    ...
} qspi_type;
```

The table below gives a list of the QSPI registers.

**Table 481. Summary of QSPI registers**

| Register                | Description             |
|-------------------------|-------------------------|
| <code>cmd_w0</code>     | Command word 0          |
| <code>cmd_w1</code>     | Command word 1          |
| <code>cmd_w2</code>     | Command word 2          |
| <code>cmd_w3</code>     | Command word 3          |
| <code>ctrl</code>       | Control register        |
| <code>actr</code>       | AC timing register      |
| <code>fifosts</code>    | FIFO status register    |
| <code>ctrl2</code>      | Control register 2      |
| <code>cmdsts</code>     | Command status register |
| <code>rsts</code>       | Read status register    |
| <code>fsize</code>      | Flash size register     |
| <code>xip cmd_w0</code> | XIP command word 0      |
| <code>xip cmd_w1</code> | XIP command word 1      |
| <code>xip cmd_w2</code> | XIP command word 2      |
| <code>xip cmd_w3</code> | XIP command word 3      |
| <code>rev</code>        | Revision register       |
| <code>dt</code>         | Data port register      |

The table below gives a list of QSPI library functions.

**Table 482. Summary of QSPI library functions**

| Function name                          | Description                                |
|--|--|
| <code>qspi_encryption_enable</code>    | QSPI encryption enable                     |
| <code>qspi_sck_mode_set</code>         | Configure QSPI clock mode                  |
| <code>qspi_clk_division_set</code>     | Configure QSPI clock division              |
| <code>qspi_xip_cache_bypass_set</code> | Enable QSPI XIP port cache bypass          |
| <code>qspi_interrupt_enable</code>     | Enable QSPI interrupt                      |
| <code>qspi_flag_get</code>             | Get QSPI flag                              |
| <code>qspi_flag_clear</code>           | Clear QSPI flag                            |
| <code>qspi_dma_rx_threshold_set</code> | Configure QSPI DMA receive FIFO threshold  |
| <code>qspi_dma_tx_threshold_set</code> | Configure QSPI DMA transmit FIFO threshold |

| Function name           | Description  |
|-------------------------|--|
| qspi_dma_enable         | Enable QSPI DMA  |
| qspi_busy_config        | Configure the offset of QSPI busy bit in the status register |
| qspi_xip_enable         | QSPI XIP port enable   |
| qspi_cmd_operation_kick | Start QSPI command operation                                 |
| qspi_xip_init           | QSPI XIP port initialization                                 |
| qspi_byte_read          | QSPI byte read   |
| qspi_half_word_read     | QSPI half-word read  |
| qspi_word_read          | QSPI word read   |
| qspi_word_write         | QSPI word write  |
| qspi_half_word_write    | QSPI half-word write   |
| qspi_byte_write         | QSPI byte write  |

### 5.18.1 qspi\_encryption\_enable function

The table below describes the function qspi\_encryption\_enable

**Table 483. qspi\_encryption\_enable function function**

| Name                   | Description  |
|------------------------|--|
| Function name          | qspi_encryption_enable   |
| Function prototype     | void qspi_encryption_enable(qspi_type* qspi_x, confirm_state new_state);               |
| Function description   | Enable QSPI encryption. This function is called only when QSPI is in the command port. |
| Input parameter 1      | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2.              |
| Input parameter 2      | new_state: encryption status<br>This parameter can be TRUE or FALSE.                   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

|   |
|---|
| <pre>qspi_encryption_enable(QSPI1, TRUE);</pre> |
|---|

### 5.18.2 qspi\_sck\_mode\_set function

The table below describes the function qspi\_sck\_mode\_set.

**Table 484. qspi\_sck\_mode\_set function**

| Name                 | Description   |
|----------------------|---|
| Function name        | qspi_sck_mode_set   |
| Function prototype   | void qspi_sck_mode_set(qspi_type* qspi_x, qspi_clk_mode_type new_mode);   |
| Function description | Configure QSPI clock mode   |
| Input parameter 1    | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2    | new_mode: clock mode  |
| Output parameter     | NA  |

| Name                   | Description |
|------------------------|-------------|
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**qspi\_clk\_mode\_type**

QSPI\_SCK\_MODE\_0: QSPI clock mode 0

QSPI\_SCK\_MODE\_3: QSPI clock mode 3

**Example:**

```
qspi_sck_mode_set(QSPI1, QSPI_SCK_MODE_0);
```

### 5.18.3 qspi\_clk\_division\_set function

The table below describes the function qspi\_clk\_division\_set.

**Table 485. qspi\_clk\_division\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | qspi_clk_division_set  |
| Function prototype     | void qspi_clk_division_set(qspi_type* qspi_x, qspi_clk_div_type new_clkdiv); |
| Function description   | Configure QSPI clock division  |
| Input parameter 1      | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2.    |
| Input parameter 2      | new_clkdiv: clock division   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**qspi\_clk\_div\_type**

QSPI\_CLK\_DIV\_2: Divided by 2

QSPI\_CLK\_DIV\_4: Divided by 4

QSPI\_CLK\_DIV\_6: Divided by 6

QSPI\_CLK\_DIV\_8: Divided by 8

QSPI\_CLK\_DIV\_3: Divided by 3

QSPI\_CLK\_DIV\_5: Divided by 5

QSPI\_CLK\_DIV\_10: Divided by 10

QSPI\_CLK\_DIV\_12: Divided by 12

**Example:**

```
qspi_clk_division_set(QSPI1, QSPI_CLK_DIV_2);
```

### 5.18.4 qspi\_xip\_cache\_bypass\_set function

The table below describes the function qspi\_xip\_cache\_bypass\_set.

**Table 486. qspi\_xip\_cache\_bypass\_set function**

| Name                 | Description   |
|----------------------|---|
| Function name        | qspi_xip_cache_bypass_set   |
| Function prototype   | void qspi_xip_cache_bypass_set(qspi_type* qspi_x, confirm_state new_state); |
| Function description | Configure QSPI XIP port cache bypass  |

| Name                   | Description   |
|------------------------|---|
| Input parameter 1      | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2      | new_state: bypass status<br>This parameter can be TRUE or FALSE.          |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
qspi_xip_cache_bypass_set(QSPI1, TRUE);
```

### 5.18.5 qspi\_interrupt\_enable function

The table below describes the function qspi\_interrupt\_enable.

**Table 487. qspi\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | qspi_interrupt_enable   |
| Function prototype     | void qspi_interrupt_enable(qspi_type* qspi_x, confirm_state new_state);   |
| Function description   | Configure QSPI interrupts   |
| Input parameter 1      | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2      | new_state: interrupt status<br>This parameter can be TRUE or FALSE.       |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
qspi_interrupt_enable(QSPI1, TRUE);
```

### 5.18.6 qspi\_flag\_get function

The table below describes the function qspi\_flag\_get.

**Table 488. qspi\_flag\_get function**

| Name                 | Description   |
|----------------------|---|
| Function name        | qspi_flag_get   |
| Function prototype   | flag_status qspi_flag_get(qspi_type* qspi_x, uint32_t flag);              |
| Function description | Get flag status   |
| Input parameter 1    | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2    | flag: flag selection  |
| Output parameter     | NA  |
| Return value         | flag_status: flag status<br>Return SET or RESET.                          |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

**qspi\_flag**

Get a QSPI status flag

QSPI\_CMDSTS\_FLAG: QSPI command complete flag

QSPI\_RXFIFORDY\_FLAG: QSPI receive FIFO ready flag

QSPI\_TXFIFORDY\_FLAG: QSPI transmit FIFO ready flag

**Example:**

```
flag_status status;
status = qspi_flag_get(QSPI_CMDSTS_FLAG);
```

### 5.18.7 qspi\_flag\_clear function

The table below describes the function qspi\_flag\_clear.

**Table 489. qspi\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | qspi_flag_clear   |
| Function prototype     | void qspi_flag_clear(qspi_type* qspi_x, uint32_t flag);                   |
| Function description   | Clear flag  |
| Input parameter 1      | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2      | flag: to-be-cleared flag  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**qspi\_flag**

Clear the QSPI status flag

QSPI\_CMDSTS\_FLAG: QSPI command complete flag

**Example:**

```
qspi_flag_clear(QSPI_CMDSTS_FLAG);
```

### 5.18.8 qspi\_dma\_rx\_threshold\_set function

The table below describes the function qspi\_dma\_rx\_threshold\_set.

**Table 490. qspi\_dma\_rx\_threshold\_set function**

| Name                 | Description   |
|----------------------|---|
| Function name        | qspi_dma_rx_threshold_set   |
| Function prototype   | void qspi_dma_rx_threshold_set(qspi_type* qspi_x, qspi_dma_fifo_thod_type new_threshold); |
| Function description | Set QSPI DMA receive FIFO threshold   |
| Input parameter 1    | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2.                 |
| Input parameter 2    | new_threshold: threshold  |



| Name                   | Description |
|------------------------|-------------|
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**qspi\_dma\_fifo\_thod\_type**

Configure a QSPI DMA FIFO threshold

QSPI\_DMA\_FIFO\_THOD\_WORD08: QSPI DMA FIFO 8 WORDs

QSPI\_DMA\_FIFO\_THOD\_WORD16: QSPI DMA FIFO 16 WORDs

QSPI\_DMA\_FIFO\_THOD\_WORD32: QSPI DMA FIFO 32 WORDs

**Example:**

```
qspi_dma_rx_threshold_set(QSPI_DMA_FIFO_THOD_WORD08);
```

### 5.18.9 qspi\_dma\_tx\_threshold\_set function

The table below describes the function `qspi_dma_tx_threshold_set`.

**Table 491. qspi\_dma\_tx\_threshold\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>qspi_dma_tx_threshold_set</code>   |
| Function prototype     | <code>void qspi_dma_tx_threshold_set(qspi_type* qspi_x, qspi_dma_fifo_thod_type new_threshold);</code> |
| Function description   | Configure QSPI DMA transmit FIFO threshold   |
| Input parameter 1      | <code>qspi_x</code> : selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2.                |
| Input parameter 2      | <code>new_threshold</code> : threshold<br>Refer to <a href="#">qspi_dma_fifo_thod_type</a> .           |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
qspi_dma_tx_threshold_set(QSPI_DMA_FIFO_THOD_WORD08);
```

### 5.18.10 qspi\_dma\_enable function

The table below describes the function `qspi_dma_enable`.

**Table 492. qspi\_dma\_enable function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>qspi_dma_enable</code>  |
| Function prototype   | <code>void qspi_dma_enable(qspi_type* qspi_x, confirm_state new_state);</code>          |
| Function description | Enable QSPI interrupts  |
| Input parameter 1    | <code>qspi_x</code> : selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2    | <code>new_state</code> : DMA status<br>This parameter can be TRUE or FALSE.             |

| Name                   | Description |
|------------------------|-------------|
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

```
qspi_dma_enable(QSPI1, TRUE);
```

### 5.18.11 qspi\_busy\_config function

The table below describes the function qspi\_busy\_config.

**Table 493. qspi\_busy\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | qspi_busy_config  |
| Function prototype     | void qspi_busy_config(qspi_type* qspi_x, qspi_busy_pos_type busy_pos);    |
| Function description   | Configure the offset of QSPI busy bit in the status register              |
| Input parameter 1      | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2      | busy_pos: offset  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**qspi\_busy\_pos\_type**

- QSPI\_BUSY\_OFFSET\_0: Busy bit offset 0
- QSPI\_BUSY\_OFFSET\_1: Busy bit offset 1
- QSPI\_BUSY\_OFFSET\_2: Busy bit offset 2
- QSPI\_BUSY\_OFFSET\_3: Busy bit offset 3
- QSPI\_BUSY\_OFFSET\_4: Busy bit offset 4
- QSPI\_BUSY\_OFFSET\_5: Busy bit offset 5
- QSPI\_BUSY\_OFFSET\_6: Busy bit offset 6
- QSPI\_BUSY\_OFFSET\_7: Busy bit offset 7

**Example:**

```
qspi_busy_config(QSPI1, QSPI_BUSY_OFFSET_0);
```

### 5.18.12 qspi\_xip\_enable function

The table below describes the function qspi\_xip\_enable.

**Table 494. qspi\_xip\_enable function**

| Name                 | Description   |
|----------------------|---|
| Function name        | qspi_xip_enable   |
| Function prototype   | void qspi_xip_enable(qspi_type* qspi_x, confirm_state new_state);         |
| Function description | Enable QSPI XIP port  |
| Input parameter 1    | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |

| Name                   | Description  |
|------------------------|--|
| Input parameter 2      | new_state: XIP port status<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
qspi_xip_enable(QSPI1, TRUE);
```

### 5.18.13 qspi\_cmd\_operation\_kick function

The table below describes the function `qspi_cmd_operation_kick`.

**Table 495. qspi\_cmd\_operation\_kick function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>qspi_cmd_operation_kick</code>  |
| Function prototype     | <code>void qspi_cmd_operation_kick(qspi_type* qspi_x, qspi_cmd_type* qspi_cmd_struct);</code> |
| Function description   | Start QSPI command operation  |
| Input parameter 1      | <code>qspi_x</code> : selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2.       |
| Input parameter 2      | <code>qspi_cmd_struct</code> : command structure pointer                                      |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**qspi\_cmd\_type structure**

The `qspi_cmd_type` is defined in the `at32f435_437_qspi.h`.

typedef struct

```
{
    confirm_state          pe_mode_enable;
    uint8_t                pe_mode_operate_code;
    uint8_t                instruction_code;
    qspi_cmd_inslen_type   instruction_length;
    uint32_t               address_code;
    qspi_cmd_adrlen_type   address_length;
    uint32_t               data_counter;
    uint8_t               second_dummy_cycle_num;
    qspi_operate_mode_type operation_mode;
    qspi_read_status_conf_type read_status_config;
    confirm_state          read_status_enable;
    confirm_state          write_data_enable;
} qspi_cmd_type;
```

**pe\_mode\_enable**

Enable performance enhance mode according to the selected QSPI peripheral.

TRUE: Performance enhance mode enabled

FALSE: Performance enhance mode disabled

**pe\_mode\_operate\_code**

Performance enhance mode operate code, dependent on the selected QSPI peripheral.

**instruction\_code**

Command instruction code

**instruction\_length**

Command instruction code length

QSPI\_CMD\_INSLEN\_0\_BYTE: No instruction code

QSPI\_CMD\_INSLEN\_1\_BYTE: 1-byte instruction code

QSPI\_CMD\_INSLEN\_2\_BYTE: 2-byte instruction code

**address\_code**

Address code

**address\_length**

Address length

QSPI\_CMD\_ADRLLEN\_0\_BYTE: No address

QSPI\_CMD\_ADRLLEN\_1\_BYTE: 1-byte address

QSPI\_CMD\_ADRLLEN\_2\_BYTE: 2-byte address

QSPI\_CMD\_ADRLLEN\_3\_BYTE: 3-byte address

QSPI\_CMD\_ADRLLEN\_4\_BYTE: 4-byte address

**data\_counter**

Number of data

**second\_dummy\_cycle\_num**

Number of the second dummy cycle, ranging from 0 to 32

**operation\_mode**

Operation mode

QSPI\_OPERATE\_MODE\_111: qspi serial mode

QSPI\_OPERATE\_MODE\_112: qspi dual mode

QSPI\_OPERATE\_MODE\_114: qspi quad mode

QSPI\_OPERATE\_MODE\_122: qspi dual i/o mode

QSPI\_OPERATE\_MODE\_144: qspi quad i/o mode

QSPI\_OPERATE\_MODE\_222: qspi instruction 2-bit mode

QSPI\_OPERATE\_MODE\_444: qspi instruction 4-bit mode(qpi)

**read\_status\_config**

QSPI\_RSTSC\_HW\_AUTO: Read by hardware automatically

QSPI\_RSTSC\_SW\_ONCE: Read by software for once

**read\_status\_enable**

Enable read status

TRUE: Enable

FALSE: Disbale

**write\_data\_enable**

Enable write data

TRUE: Enable

FALSE: Disable

**Example:**

```
esmt32m_cmd_erase_config(&esmt32m_cmd_config, sec_addr);
```

```
qspi_cmd_operation_kick(QSPI1, &esmt32m_cmd_config);
```

## 5.18.14 qspi\_xip\_init function

The table below describes the function qspi\_xip\_init.

**Table 496. qspi\_xip\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | qspi_xip_init   |
| Function prototype     | void qspi_xip_init(qspi_type* qspi_x, qspi_xip_type* xip_init_struct);    |
| Function description   | Initialize QSPI XIP port  |
| Input parameter 1      | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2      | xip_init_struct: initialization structure pointer                         |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### qspi\_xip\_type structure

The qspi\_xip\_type is defined in the at32f435\_437\_qspi.h.

typedef struct

```
{
    uint8_t          read_instruction_code;
    qspi_xip_addrlen_type read_address_length;
    qspi_operate_mode_type read_operation_mode;
    uint8_t          read_second_dummy_cycle_num;
    uint8_t          write_instruction_code;
    qspi_xip_addrlen_type write_address_length;
    qspi_operate_mode_type write_operation_mode;
    uint8_t          write_second_dummy_cycle_num;
    qspi_xip_write_sel_type write_select_mode;
    uint8_t          write_time_counter;
    uint8_t          write_data_counter;
    qspi_xip_read_sel_type read_select_mode;
    uint8_t          read_time_counter;
    uint8_t          read_data_counter;
} qspi_xip_type;
```

### read\_instruction\_code

Read command instruction code

### read\_address\_length

Read command address length

QSPI\_XIP\_ADDRLEN\_3\_BYTE: 3-byte address

QSPI\_XIP\_ADDRLEN\_4\_BYTE: 4-byte address

### read\_operation\_mode

Read command operation mode

QSPI\_OPERATE\_MODE\_111: qspi serial mode

QSPI\_OPERATE\_MODE\_112: qspi dual mode

QSPI\_OPERATE\_MODE\_114: qspi quad mode  
 QSPI\_OPERATE\_MODE\_122: qspi dual i/o mode  
 QSPI\_OPERATE\_MODE\_144: qspi quad i/o mode  
 QSPI\_OPERATE\_MODE\_222: qspi instruction 2-bit mode  
 QSPI\_OPERATE\_MODE\_444: qspi instruction 4-bit mode(qpi)

**read\_second\_dummy\_cycle\_num**

Number of read command second dummy cycle, ranging from 0 to 32

**write\_instruction\_code**

Write command instruction code

**write\_address\_length**

Write command address length

QSPI\_XIP\_ADDRLEN\_3\_BYTE: 3-byte address

QSPI\_XIP\_ADDRLEN\_4\_BYTE: 4-byte address

**write\_operation\_mode**

Write command operation mode

QSPI\_OPERATE\_MODE\_111: qspi serial mode

QSPI\_OPERATE\_MODE\_112: qspi dual mode

QSPI\_OPERATE\_MODE\_114: qspi quad mode

QSPI\_OPERATE\_MODE\_122: qspi dual i/o mode

QSPI\_OPERATE\_MODE\_144: qspi quad i/o mode

QSPI\_OPERATE\_MODE\_222: qspi instruction 2-bit mode

QSPI\_OPERATE\_MODE\_444: qspi instruction 4-bit mode(qpi)

**write\_second\_dummy\_cycle\_num**

Number of write command second dummy cycle, ranging from 0 to 32

**write\_select\_mode**

Write command mode selection

QSPI\_XIPW\_SEL\_MODED: Mode D

QSPI\_XIPW\_SEL\_MODET: Mode T

**write\_time\_counter**

Number of clock in write command mode T

**write\_data\_counter**

Number of data in write command mode D

**read\_select\_mode**

Read command mode selection

QSPI\_XIPW\_SEL\_MODED: Mode D

QSPI\_XIPW\_SEL\_MODET: Mode T

**read\_time\_counter**

Number of clock in read command mode T

**read\_data\_counter**

Number of data in read command mode T

**Example:**

```

/* initial xip */
xip_init_ly68l6400_config(&ly68l6400_xip_init);
qspi_xip_init(QSPI1, &ly68l6400_xip_init);
  
```

### 5.18.15 qspi\_byte\_read function

The table below describes the function qspi\_byte\_read.

**Table 497. qspi\_byte\_read function**

| Name                   | Description   |
|------------------------|---|
| Function name          | qspi_byte_read  |
| Function prototype     | uint8_t qspi_byte_read(qspi_type* qspi_x);                                |
| Function description   | Read data in bytes  |
| Input parameter        | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Output parameter       | NA  |
| Return value           | Return the data value.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
uint8_t data;
data = qspi_byte_read(QSPI1);
```

### 5.18.16 qspi\_half\_word\_read function

The table below describes the function qspi\_half\_word\_read.

**Table 498. qspi\_half\_word\_read function**

| Name                   | Description   |
|------------------------|---|
| Function name          | qspi_half_word_read   |
| Function prototype     | uint16_t qspi_half_word_read(qspi_type* qspi_x);                          |
| Function description   | Read data in half-words.  |
| Input parameter        | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Output parameter       | NA  |
| Return value           | Return the data value.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
uint16_t data;
data = qspi_half_word_read(QSPI1);
```

### 5.18.17 qspi\_word\_read function

The table below describes the function qspi\_word\_read

**Table 499. qspi\_word\_read function**

| Name                   | Description   |
|------------------------|---|
| Function name          | qspi_word_read  |
| Function prototype     | uint32_t qspi_word_read(qspi_type* qspi_x);                               |
| Function description   | Read data in words.   |
| Input parameter        | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Output parameter       | NA  |
| Return value           | Return the data value.  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
uint32_t data;
data = qspi_word_read(QSPI1);
```

### 5.18.18 qspi\_word\_write function

The table below describes the function qspi\_word\_write.

**Table 500. qspi\_word\_write function**

| Name                   | Description   |
|------------------------|---|
| Function name          | qspi_word_write   |
| Function prototype     | void qspi_word_write(qspi_type* qspi_x, uint32_t value);                  |
| Function description   | Write data in words.  |
| Input parameter 1      | qspi_x: selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2      | value: the to-be-written data   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
qspi_word_write(QSPI1, 0x12345678);
```



### 5.18.19 qspi\_half\_word\_write function

The table below describes the function `qspi_half_word_write`.

**Table 501. qspi\_half\_word\_write function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>qspi_half_word_write</code>   |
| Function prototype     | <code>void qspi_half_word_write(qspi_type* qspi_x, uint16_t value);</code>              |
| Function description   | Write data in half-words.   |
| Input parameter 1      | <code>qspi_x</code> : selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2      | value: the to-be-written data   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
qspi_half_word_write(QSPI1, 0x1234);
```

### 5.18.20 qspi\_byte\_write function

The table below describes the function `qspi_byte_write`.

**Table 502. qspi\_byte\_write function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>qspi_byte_write</code>  |
| Function prototype     | <code>void qspi_byte_write(qspi_type* qspi_x, uint8_t value);</code>                    |
| Function description   | Write data in bytes.  |
| Input parameter 1      | <code>qspi_x</code> : selected QSPI peripheral<br>This parameter can be QSPI1 or QSPI2. |
| Input parameter 2      | value: the to-be-written data   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
qspi_byte_write(QSPI1, 0x12);
```

## 5.19 System configuration controller (SCFG)

The SCFG register structure `scfg_type` is defined in the “`at32f435_437_scfg.h`”.

```
/**
 * @brief type define scfg register all
 */
typedef struct
{
    ...
} scfg_type;
```

The table below gives a list of the SCFG registers.

**Table 503. Summary of SCFG registers**

| Register                  | Description                                      |
|---------------------------|--|
| <code>scfg_cfg1</code>    | SCFG configuration register 1                    |
| <code>scfg_cfg2</code>    | SCFG configuration register 2                    |
| <code>scfg_exintc1</code> | SCFG external interrupt configuration register 1 |
| <code>scfg_exintc2</code> | SCFG external interrupt configuration register 2 |
| <code>scfg_exintc3</code> | SCFG external interrupt configuration register 3 |
| <code>scfg_exintc4</code> | SCFG external interrupt configuration register 4 |
| <code>scfg_uhdrv</code>   | SCFG ultra-high drive capability register        |

The table below gives a list of the SCFG library functions.

**Table 504. Summary of SCFG library functions**

| Function name                              | Description                                      |
|--|--|
| <code>scfg_reset</code>                    | SCFG reset                                       |
| <code>scfg_xmc_mapping_swap_set</code>     | Configure XMC address mapping swap               |
| <code>scfg_infrared_config</code>          | Infrared configuration                           |
| <code>scfg_mem_map_set</code>              | Configure memory address mapping                 |
| <code>scfg_emac_interface_set</code>       | Configure EMAC interface                         |
| <code>scfg_exint_line_config</code>        | Configure external interrupt line                |
| <code>scfg_pins_ultra_driven_enable</code> | Pin ultra-high current sinking capability enable |

### 5.19.1 `scfg_reset` function

The table below describes the function `scfg_reset`.

**Table 505. `scfg_reset` function**

| Name                 | Description                         |
|----------------------|-------------------------------------|
| Function name        | <code>scfg_reset</code>             |
| Function prototype   | <code>void scfg_reset(void);</code> |
| Function description | Reset SCFG                          |
| Input parameter      | NA                                  |
| Output parameter     | NA                                  |
| Return value         | NA                                  |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

|               |
|---------------|
| scfg_reset(); |
|---------------|

### 5.19.2 scfg\_xmc\_mapping\_swap\_set function

The table below describes the function scfg\_xmc\_mapping\_swap\_set.

**Table 506. scfg\_xmc\_mapping\_swap\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | scfg_xmc_mapping_swap_set                                    |
| Function prototype     | void scfg_xmc_mapping_swap_set(scfg_xmc_swap_type xmc_swap); |
| Function description   | Configure XMC address mapping swap                           |
| Input parameter        | xmc_swap: mapping swap parameter                             |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**scfg\_xmc\_swap\_type**

- SCFG\_XMC\_SWAP\_NONE: No XMC address mapping swap
- SCFG\_XMC\_SWAP\_MODE1: XMC address mapping swap mode 1
- SCFG\_XMC\_SWAP\_MODE2: XMC address mapping swap mode 2
- SCFG\_XMC\_SWAP\_MODE3: XMC address mapping swap mode 3

**Example:**

|   |
|---|
| scfg_xmc_mapping_swap_set(SCFG_XMC_SWAP_MODE1); |
|---|

### 5.19.3 scfg\_infrared\_config function

The table below describes the function scfg\_infrared\_config.

**Table 507. scfg\_infrared\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | scfg_infrared_config   |
| Function prototype     | void scfg_infrared_config(scfg_ir_source_type source, scfg_ir_polarity_type polarity); |
| Function description   | Infrared configuration   |
| Input parameter 1      | source: Infrared modulation envelope signal source selection                           |
| Input parameter 2      | polarity: Infrared output polarity selection   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**scfg\_ir\_source\_type**

Infrared modulation envelope signal source selection

- SCFG\_IR\_SOURCE\_TMR10: TMR10

SCFG\_IR\_SOURCE\_USART1: USART1  
 SCFG\_IR\_SOURCE\_USART2: USART2

**scfg\_ir\_polarity\_type**

Infrared output polarity selection

SCFG\_IR\_POLARITY\_NO\_AFFECTE: Infrared output is not inversed

SCFG\_IR\_POLARITY\_REVERSE: Infrared output is inversed

**Example:**

```
scfg_infrared_config(SCFG_IR_SOURCE_TMR10, SCFG_IR_POLARITY_NO_AFFECTE);
```

### 5.19.4 scfg\_mem\_map\_set function

The table below describes the function scfg\_mem\_map\_set.

**Table 508. scfg\_mem\_map\_set function**

| Name                   | Description                                       |
|------------------------|---|
| Function name          | scfg_mem_map_set                                  |
| Function prototype     | void scfg_mem_map_set(scfg_mem_map_type mem_map); |
| Function description   | Configure memory mapping at 0x00000000            |
| Input parameter        | mem_map: memory address mapping selection         |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**scfg\_mem\_map\_type**

Memory address mapping type

SCFG\_MEM\_MAP\_MAIN\_MEMORY: Main Flash memory mapped at 0x00000000

SCFG\_MEM\_MAP\_BOOT\_MEMORY: Bootloader mapped at 0x00000000

SCFG\_MEM\_MAP\_XMC\_BANK1: XMC bank1 mapped at 0x00000000

SCFG\_MEM\_MAP\_INTERNAL\_SRAM: Embedded SRAM mapped at 0x00000000

SCFG\_MEM\_MAP\_XMC\_SDRAM\_BANK1: XMC SDRAM bank1 mapped at 0x00000000

**Example:**

```
scfg_mem_map_set(SCFG_MEM_MAP_BOOT_MEMORY);
```

### 5.19.5 scfg\_emac\_interface\_set function

The table below describes the function scfg\_emac\_interface\_set.

**Table 509. scfg\_emac\_interface\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | scfg_emac_interface_set                                      |
| Function prototype     | void scfg_emac_interface_set(scfg_emac_interface_type mode); |
| Function description   | Configure EMAC interface                                     |
| Input parameter        | mode: EMAC interface type                                    |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**scfg\_emac\_interface\_type**

EMAC interface type

SCFG\_EMAC\_SELECT\_MII: MII

SCFG\_EMAC\_SELECT\_RMII: RMII

**Example:**

```
scfg_emac_interface_set(SCFG_EMAC_SELECT_MII);
```

### 5.19.6 scfg\_exint\_line\_config function

The table below describes the function scfg\_exint\_line\_config.

**Table 510. scfg\_exint\_line\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | scfg_exint_line_config  |
| Function prototype     | void scfg_exint_line_config(scfg_port_source_type port_source, scfg_pins_source_type pin_source); |
| Function description   | Configure external interrupt line   |
| Input parameter 1      | port_source: port source selection  |
| Input parameter 2      | pin_source: pin source selection  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**scfg\_port\_source\_type**

SCFG\_PORT\_SOURCE\_GPIOA: GPIOA

SCFG\_PORT\_SOURCE\_GPIOB: GPIOB

SCFG\_PORT\_SOURCE\_GPIOC: GPIOC

SCFG\_PORT\_SOURCE\_GPIOD: GPIOD

SCFG\_PORT\_SOURCE\_GPIOE: GPIOE

SCFG\_PORT\_SOURCE\_GPIOF: GPIOF

SCFG\_PORT\_SOURCE\_GPIOG: GPIOG

SCFG\_PORT\_SOURCE\_GPIOH: GPIOH

**scfg\_pins\_source\_type**

SCFG\_PINS\_SOURCE0: pin 0

SCFG\_PINS\_SOURCE1: pin 1

SCFG\_PINS\_SOURCE2: pin 2

.....

SCFG\_PINS\_SOURCE13: pin 13

SCFG\_PINS\_SOURCE14: pin 14

SCFG\_PINS\_SOURCE15: pin 15

**Example:**

```
scfg_exint_line_config(SCFG_PORT_SOURCE_GPIOA, SCFG_PINS_SOURCE1);
```

### 5.19.7 scfg\_pins\_ultra\_driven\_enable function

The table below describes the function `scfg_pins_ultra_driven_enable`.

**Table 511. scfg\_pins\_ultra\_driven\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>scfg_pins_ultra_driven_enable</code>   |
| Function prototype     | <code>void scfg_pins_ultra_driven_enable(scfg_ultra_driven_pins_type value, confirm_state new_state);</code> |
| Function description   | Enable pin ultra-high current sinking capability   |
| Input parameter 1      | value: pin selection   |
| Input parameter 2      | new_state: interrupt status<br>This parameter can be TRUE or FALSE.  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**scfg\_ultra\_driven\_pins\_type**

- SCFG\_ULTRA\_DRIVEN\_PB3: PB3
- SCFG\_ULTRA\_DRIVEN\_PB9: PB9
- SCFG\_ULTRA\_DRIVEN\_PB10: PB10
- SCFG\_ULTRA\_DRIVEN\_PD12: PD12
- SCFG\_ULTRA\_DRIVEN\_PD13: PD13
- SCFG\_ULTRA\_DRIVEN\_PD14: PD14
- SCFG\_ULTRA\_DRIVEN\_PD15: PD15
- SCFG\_ULTRA\_DRIVEN\_PF14: PF14
- SCFG\_ULTRA\_DRIVEN\_PF15: PF15

**Example:**

```
scfg_pins_ultra_driven_enable(SCFG_ULTRA_DRIVEN_PB3, TRUE);
```

## 5.20 SDIO interface (SDIO)

The SDIO register structure `crm_type` is defined in the “`at32f435_437_sdio.h`”.

```
/**
 * @brief type define sdio register all
 */
typedef struct
{
    ...
} sdio_type;
```

The table below gives a list of the SDIO registers.

**Table 512. Summary of SDIO registers**

| Register             | Description               |
|----------------------|---------------------------|
| <code>pwrctrl</code> | Power control register    |
| <code>clkctrl</code> | Clock control register    |
| <code>arg</code>     | Argument register         |
| <code>cmd</code>     | Command register          |
| <code>rspcmd</code>  | Command response register |
| <code>rsp1</code>    | Response register 1       |
| <code>rsp2</code>    | Response register 2       |
| <code>rsp3</code>    | Response register 3       |
| <code>rsp4</code>    | Response register 4       |
| <code>dtm r</code>   | Data timer register       |
| <code>dtlen</code>   | Data length register      |
| <code>dtctrl</code>  | Data control register     |
| <code>dtcntr</code>  | Data counter register     |
| <code>sts</code>     | Status register           |
| <code>intclr</code>  | Clear interrupt register  |
| <code>inten</code>   | Interrupt mask register   |
| <code>bufcntr</code> | BUF counter register      |
| <code>buf</code>     | Data BUF register         |

The table below gives a list of the SDIO library functions.

**Table 513. Summary of SDIO library functions**

| Function name                              | Description  |
|--|--|
| <code>sdio_reset</code>                    | Reset SDIO peripheral registers and control status |
| <code>sdio_power_set</code>                | Configure controller power status                  |
| <code>sdio_power_status_get</code>         | Get controller power status                        |
| <code>sdio_clock_config</code>             | Configure clock parameters                         |
| <code>sdio_bus_width_config</code>         | Configure bus width                                |
| <code>sdio_clock_bypass</code>             | Enable clock bypass mode                           |
| <code>sdio_power_saving_mode_enable</code> | Enable controller power-saving mode                |

|                                   |   |
|-----------------------------------|---|
| sdio_flow_control_enable          | Enable flow control mode  |
| sdio_clock_enable                 | Enable clock  |
| sdio_dma_enable                   | Enable DMA  |
| sdio_interrupt_enable             | Enable interrupts   |
| sdio_flag_get                     | Get the flag  |
| sdio_flag_clear                   | Clear the flag  |
| sdio_command_config               | Configure command argument                                      |
| sdio_command_state_machine_enable | Enable command state machine                                    |
| sdio_command_response_get         | Get response command index                                      |
| sdio_response_get                 | Get card command response                                       |
| sdio_data_config                  | Configure data paramters  |
| sdio_data_state_machine_enable    | Enable data state machine                                       |
| sdio_data_counter_get             | Get the counter of to-be-sent data                              |
| sdio_data_read                    | Read one-WORD data from the receive FIFO                        |
| sdio_buffer_counter_get           | Get the counter of data to be written into BUF or read from BUF |
| sdio_data_write                   | Write one-WORD data to the transmit FIFO                        |
| sdio_read_wait_mode_set           | Configure read wait mode  |
| sdio_read_wait_start              | Read wait start   |
| sdio_read_wait_stop               | Read wait stop  |
| sdio_io_function_enable           | Enable IO function mode   |
| sdio_io_suspend_command_set       | Enable suspend command in IO function mode                      |

### 5.20.1 sdio\_reset function

The table below describes the function sdio\_reset.

**Table 514. sdio\_reset function**

| Name                   | Description  |
|------------------------|--|
| Function name          | sdio_reset   |
| Function prototype     | void sdio_reset(sdio_type *sdio_x);                |
| Function description   | Reset SDIO peripheral registers and control status |
| Input parameter 1      | sdio_x: selected SDIO peripheral, such as SDIO1    |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* resetsdio */
sdio_reset(SDIO1);
```



## 5.20.2 sdio\_power\_set function

The table below describes the function `sdio_power_set`.

**Table 515. sdio\_power\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>sdio_power_set</code>   |
| Function prototype     | <code>void sdio_power_set(sdio_type *sdio_x, sdio_power_state_type power_state);</code> |
| Function description   | Configure the controller power status   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                           |
| Input parameter 2      | <code>power_state</code> : controller power status                                      |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### **power\_state**

Controller power status

SDIO\_POWER\_ON: Power ON

SDIO\_POWER\_OFF: Power OFF

### **Example:**

```
/* sdio power on */
sdio_power_set(SDIO1, SDIO_POWER_ON);
```

## 5.20.3 sdio\_power\_status\_get function

The table below describes the function `sdio_power_status_get`.

**Table 516. sdio\_power\_status\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_power_status_get</code>   |
| Function prototype     | <code>sdio_power_state_type sdio_power_status_get(sdio_type *sdio_x);</code> |
| Function description   | Get the controller power status  |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | <code>sdio_power_state_type</code> : controller power status                 |
| Required preconditions | NA   |
| Called functions       | NA   |

### **Example:**

```
/* check power status */
if(sdio_power_status_get(SDIO1) == SDIO_POWER_OFF)
{
    return SD_REQ_NOT_APPLICABLE;
}
```

## 5.20.4 sdio\_clock\_config function

The table below describes the function `sdio_clock_config`.

**Table 517. sdio\_clock\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>sdio_clock_config</code>  |
| Function prototype     | <code>void sdio_clock_config(sdio_type *sdio_x, uint16_t clk_div, sdio_edge_phase_type clk_edg);</code> |
| Function description   | Configure clock parameters  |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1   |
| Input parameter 2      | <code>clk_div</code> : clock division, ranging from 0 to 0x3FF  |
| Input parameter 2      | <code>clk_edg</code> : clock edge configuration   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### **clk\_edg**

Clock edge selection

SDIO\_CLOCK\_EDGE\_RISING: Clock rising edge

SDIO\_CLOCK\_EDGE\_FALLING: Clock falling edge

### **Example:**

```
/* config sdio clock divide and edge phase */
sdio_clock_config(SDIO1, 0x2, SDIO_CLOCK_EDGE_FALLING);
```

## 5.20.5 sdio\_bus\_width\_config function

The table below describes the function `sdio_bus_width_config`.

**Table 518. sdio\_bus\_width\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_bus_width_config</code>   |
| Function prototype     | <code>void sdio_bus_width_config(sdio_type *sdio_x, sdio_bus_width_type width);</code> |
| Function description   | Configure bus width  |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                          |
| Input parameter 2      | <code>width</code> : selected bus width  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### **width**

Data bus width selection

SDIO\_BUS\_WIDTH\_D1: 1-bit data bus width

SDIO\_BUS\_WIDTH\_D4: 4-bit data bus width

SDIO\_BUS\_WIDTH\_D8: 8-bit data bus width

### **Example:**

```
/* config sdio bus width */
```

```
sdio_bus_width_config(SDIOx, SDIO_BUS_WIDTH_D1);
```

## 5.20.6 sdio\_clock\_bypass function

The table below describes the function `sdio_clock_bypass`.

**Table 519. sdio\_clock\_bypass function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_clock_bypass</code>   |
| Function prototype     | <code>void sdio_clock_bypass(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Enable clock bypass mode   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                    |
| Input parameter 2      | <code>new_state</code> : new state; enabled (TRUE) or disabled (FALSE)           |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* disable clock bypass */
sdio_clock_bypass(SDIO1, FALSE);
```

## 5.20.7 sdio\_power\_saving\_mode\_enable function

The table below describes the function `sdio_power_saving_mode_enable`.

**Table 520. sdio\_power\_saving\_mode\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_power_saving_mode_enable</code>   |
| Function prototype     | <code>void sdio_power_saving_mode_enable(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Enable controller power-saving mode  |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                                |
| Input parameter 2      | <code>new_state</code> : new state, enabled (TRUE) or disabled (FALSE)                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* disable power saving mode */
sdio_power_saving_mode_enable(SDIO1, FALSE);
```

## 5.20.8 sdio\_flow\_control\_enable function

The table below describes the function `sdio_flow_control_enable`.

**Table 521. sdio\_flow\_control\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>sdio_flow_control_enable</code>   |
| Function prototype     | <code>void sdio_flow_control_enable(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Enable flow control mode  |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                           |
| Input parameter 2      | <code>new_state</code> : new state, enabled (TRUE) or disabled (FALSE)                  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* disable flow control */
sdio_flow_control_enable(SDIO1, FALSE);
```

## 5.20.9 sdio\_clock\_enable function

The table below describes the function `sdio_clock_enable`.

**Table 522. sdio\_clock\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_clock_enable</code>   |
| Function prototype     | <code>void sdio_clock_enable(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Enable clock   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                    |
| Input parameter 2      | <code>new_state</code> : new state, enabled (TRUE) or disabled (FALSE)           |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable to output sdio_ck */
sdio_clock_enable(SDIO1, TRUE);
```

## 5.20.10 sdio\_dma\_enable function

The table below describes the function `sdio_dma_enable`.

**Table 523. sdio\_dma\_enable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>sdio_dma_enable</code>   |
| Function prototype   | <code>void sdio_dma_enable(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description | Enable DMA   |

| Name                   | Description  |
|------------------------|--|
| Input parameter 1      | sdio_x: selected SDIO peripheral, such as SDIO1          |
| Input parameter 2      | new_state: new state, enabled (TRUE) or disabled (FALSE) |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable sdio dma */
sdio_dma_enable(SDIO1, TRUE);
```

## 5.20.11 sdio\_interrupt\_enable function

The table below describes the function sdio\_interrupt\_enable.

**Table 524. crm\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | sdio_interrupt_enable   |
| Function prototype     | void sdio_interrupt_enable(sdio_type *sdio_x, uint32_t int_opt, confirm_state new_state); |
| Function description   | Enable interrupts   |
| Input parameter 1      | sdio_x: selected SDIO peripheral, such as SDIO1   |
| Input parameter 2      | int_opt: selected interrupt type  |
| Input parameter 3      | new_state: new state, enabled (TRUE) or disabled (FALSE)                                  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**int\_opt**

Interrupt type selection

|                         |                                     |
|-------------------------|-------------------------------------|
| SDIO_CMDFAIL_INT:       | Command CRC fail interrupt          |
| SDIO_DTFAIL_INT:        | Data CRC fail interrupt             |
| SDIO_CMDCMDTIMEOUT_INT: | Command timeout interrupt           |
| SDIO_DTTIMEOUT_INT:     | Data timeout interrupt              |
| SDIO_TXERRU_INT:        | TxBUF underrun error interrupt      |
| SDIO_RXERRO_INT:        | RxBUF overrun error interrupt       |
| SDIO_CMDRSPCMPL_INT:    | Command response received interrupt |
| SDIO_CMDCMPL_INT:       | Command sent interrupt              |
| SDIO_DTCMP_INT:         | Data end interrupt                  |
| SDIO_SBITERR_INT:       | Start bit error interrupt           |
| SDIO_DTBLKCMPL_INT:     | Data block end interrupt            |
| SDIO_DOCMD_INT:         | Command acting interrupt            |
| SDIO_DOTX_INT:          | Data transmit acting interrupt      |
| SDIO_DORX_INT:          | Data receive acting interrupt       |
| SDIO_TXBUFH_INT:        | TxBUF half empty interrupt          |
| SDIO_RXBUFH_INT:        | RxBUF half empty interrupt          |

|                  |                                   |
|------------------|-----------------------------------|
| SDIO_TXBUFF_INT: | TxBUF full interrupt              |
| SDIO_RXBUFF_INT: | RxBUF full interrupt              |
| SDIO_TXBUFE_INT: | TxBUF empty interrupt             |
| SDIO_RXBUFE_INT: | RxBUF empty interrupt             |
| SDIO_TXBUF_INT:  | Data available in TxBUF interrupt |
| SDIO_RXBUF_INT:  | Data available in RxBUF interrupt |
| SDIO_SDIOIF_INT: | SD I/O mode received interrupt    |

**Example:**

```

/* disable interrupt*/
sdio_interrupt_enable(SDIO1, (SDIO_DTFAIL_INT | SDIO_DTTIMEOUT_INT | \
                             SDIO_DTCMP_INT | SDIO_TXBUFH_INT | SDIO_RXBUFH_INT | \
                             SDIO_TXERRU_INT| SDIO_RXERRO_INT | SDIO_SBITERR_INT), FALSE);

```

### 5.20.12 sdio\_flag\_get function

The table below describes the function sdio\_flag\_get.

**Table 525. sdio\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | sdio_flag_get   |
| Function prototype     | flag_status sdio_flag_get(sdio_type *sdio_x, uint32_t flag);    |
| Function description   | Get the flag  |
| Input parameter 1      | sdio_x: selected SDIO peripheral, such as SDIO1                 |
| Input parameter 2      | flag: selected interrupt type                                   |
| Output parameter       | NA  |
| Return value           | flag_status: flag status<br>This parameter can be SET or RESET. |
| Required preconditions | NA  |
| Called functions       | NA  |

**flag**

Flag selection

|                       |                                   |
|-----------------------|-----------------------------------|
| SDIO_CMDFAIL_FLAG:    | Command CRC fail interrupt flag   |
| SDIO_DTFAIL_FLAG:     | Data CRC fail interrupt flag      |
| SDIO_CMDTIMEOUT_FLAG: | Command timeout flag              |
| SDIO_DTTIMEOUT_FLAG:  | Data timeout flag                 |
| SDIO_TXERRU_FLAG:     | TxBUF overrun error flag          |
| SDIO_RXERRO_FLAG:     | RxBUF overrun error flag          |
| SDIO_CMDRSPCMPL_FLAG: | Command response received flag    |
| SDIO_CMDCMPL_FLAG:    | Command sent flag                 |
| SDIO_DTCMP_FLAG:      | Data transfer complete flag       |
| SDIO_SBITERR_FLAG:    | Start bit error flag              |
| SDIO_DTBLKCMPL_FLAG:  | Data block transfer complete flag |
| SDIO_DOCMD_FLAG:      | Command acting flag               |
| SDIO_DOTX_FLAG:       | Data transmit acting flag         |
| SDIO_DORX_FLAG:       | Data receive acting flag          |
| SDIO_TXBUFH_FLAG:     | TxBUF half-empty flag             |
| SDIO_RXBUFH_FLAG:     | RxBUF half-empty flag             |

|                   |                              |
|-------------------|------------------------------|
| SDIO_TXBUFF_FLAG: | TxBUF full flag              |
| SDIO_RXBUFF_FLAG: | RxBUF full flag              |
| SDIO_TXBUFE_FLAG: | TxBUF empty flag             |
| SDIO_RXBUFE_FLAG: | RxBUF empty flag             |
| SDIO_TXBUF_FLAG:  | Data available in TxBUF flag |
| SDIO_RXBUF_FLAG:  | Data available in RxBUF flag |
| SDIO_SDIOIF_FLAG: | SD I/O mode received flag    |

**Example:**

```

/* check dtimeout flag */
if(sdio_flag_get(SDIOx, SDIO_DTIMEOUT_FLAG) != RESET)
{
}

```

### 5.20.13 sdio\_flag\_clear function

The table below describes the function sdio\_flag\_clear.

**Table 526. sdio\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | sdio_flag_clear   |
| Function prototype     | void sdio_flag_clear(sdio_type *sdio_x, uint32_t flag); |
| Function description   | Clear flag  |
| Input parameter 1      | sdio_x: selected SDIO peripheral, such as SDIO1         |
| Input parameter 2      | flag: selected interrupt type                           |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**flag**

Flag selection

|                          |                                   |
|--------------------------|-----------------------------------|
| SDIO_CMDFAIL_FLAG:       | Command CRC fail flag             |
| SDIO_DTFAIL_FLAG:        | Data CRC fail flag                |
| SDIO_CMDCMDTIMEOUT_FLAG: | Command timeout flag              |
| SDIO_DDTIMEOUT_FLAG:     | Data timeout flag                 |
| SDIO_TXERRU_FLAG:        | TxBUF underrun error flag         |
| SDIO_RXERRO_FLAG:        | RxBUF overrun error flag          |
| SDIO_CMDRSPCMPL_FLAG:    | Command response received flag    |
| SDIO_CMDCMPL_FLAG:       | Command transfer complete flag    |
| SDIO_DTCMP_FLAG:         | Data transfer complete flag       |
| SDIO_SBITERR_FLAG:       | Start bit error flag              |
| SDIO_DTBLKCMPL_FLAG:     | Data block transfer complete flag |
| SDIO_SDIOIF_FLAG:        | SD I/O mode received flag         |

**Example:**

```

/* clear flags */
#define SDIO_STATIC_FLAGS ((uint32_t)0x000005FF)
sdio_flag_clear(SDIO1, SDIO_STATIC_FLAGS);

```

## 5.20.14 sdio\_command\_config function

The table below describes the function `sdio_command_config`.

**Table 527. sdio\_command\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>sdio_command_config</code>  |
| Function prototype     | <code>void sdio_command_config(sdio_type *sdio_x, sdio_command_struct_type *command_struct);</code> |
| Function description   | Configure command argument  |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                                       |
| Input parameter 2      | <code>command_struct</code> : <code>sdio_command_struct_type</code> pointer                         |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### **command\_struct**

The `sdio_command_struct_type` is defined in the `at32f435_437_sdio.h`.

typedef struct

```
{
    uint32_t          argument;
    uint8_t           cmd_index;
    sdio_reponse_type  rsp_type;
    sdio_wait_type    wait_type;
} sdio_command_struct_type;
```

### **argument**

Command argument is sent to a card as part of a command. It is dependent on the command type.

### **cmd\_index**

Command index

### **rsp\_type**

Response type, dependent on the command type, including:

```
SDIO_RESPONSE_NO:      No response
SDIO_RESPONSE_SHORT:   Short response
SDIO_RESPONSE_LONG:    Long response
```

### **wait\_type**

Wait type, dependent on the command type, including:

```
SDIO_WAIT_FOR_NO:      No wait
SDIO_WAIT_FOR_INT:     Wait for interrupt request
SDIO_WAIT_FOR_PEND:    Wait for end of transfer
```

### **Example:**

```
/* send cmd16, set block length */
sdio_command_struct_type sdio_command_init_struct;
sdio_command_init_struct.argument = (uint32_t)8;
sdio_command_init_struct.cmd_index = SD_CMD_SET_BLOCKLEN;
sdio_command_init_struct.rsp_type = SDIO_RESPONSE_SHORT;
sdio_command_init_struct.wait_type = SDIO_WAIT_FOR_NO;
/* sdio command config */
```



```
sdio_command_config(SDIOx, &sdio_command_init_struct);
```

## 5.20.15 sdio\_command\_state\_machine\_enable function

The table below describes the function `sdio_command_state_machine_enable`.

**Table 528. sdio\_command\_state\_machine\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_command_state_machine_enable</code>   |
| Function prototype     | <code>void sdio_command_state_machine_enable(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Enable command state machine   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                                    |
| Input parameter 2      | <code>new_state</code> : new state, enabled (TRUE) or disabled (FALSE)                           |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable ccsd */
sdio_command_state_machine_enable(SDIO1, TRUE);
```

## 5.20.16 sdio\_command\_response\_get function

The table below describes the function `sdio_command_response_get`.

**Table 529. sdio\_command\_response\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_command_response_get</code>                             |
| Function prototype     | <code>uint8_t sdio_command_response_get(sdio_type *sdio_x);</code> |
| Function description   | Get response command index   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1      |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | <code>uint8_t</code> : response command index                      |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* get response of command index */
uint8_t rsp_cmd = 0;
rsp_cmd = sdio_command_response_get(SDIO1);
```

## 5.20.17 sdio\_response\_get function

The table below describes the function `sdio_response_get`

**Table 530. sdio\_response\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_response_get</code>   |
| Function prototype     | <code>uint32_t sdio_response_get(sdio_type *sdio_x, sdio_rsp_index_type reg_index);</code> |
| Function description   | Get card command response  |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                              |
| Input parameter 2      | <code>reg_index</code> : response register number (1/2/3/4)                                |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### **reg\_div**

Response register selection

SDIO\_RSP1\_INDEX: Response register 1

SDIO\_RSP2\_INDEX: Response register 2

SDIO\_RSP3\_INDEX: Response register 3

SDIO\_RSP4\_INDEX: Response register 4

### **Example:**

```
/* get response register1 */
response = sdio_response_get(SDIO1, SDIO_RSP1_INDEX);
```

## 5.20.18 sdio\_data\_config function

The table below describes the function `sdio_data_config`.

**Table 531. sdio\_data\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_data_config</code>  |
| Function prototype     | <code>void sdio_data_config(sdio_type *sdio_x, sdio_data_struct_type *data_struct);</code> |
| Function description   | Configure data parameters  |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                              |
| Input parameter 2      | <code>data_struct</code> : <code>sdio_data_struct_type</code> pointer                      |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### **data\_struct**

The `sdio_data_struct_type` is defined in the `at32f435_437_sdio.h`.

typedef struct

```
{
    uint32_t          timeout;
    uint32_t          data_length;
    sdio_block_size_type block_size;
```

```

sdio_transfer_mode_type      transfer_mode;
sdio_transfer_direction_type  transfer_direction;
} sdio_data_struct_type;

```

### timeout

Data transfer timeout, with the bus clock as the counting base

### data\_length

Length of the to-be-sent data

### block\_size

Block size, including

|                              |           |
|------------------------------|-----------|
| SDIO_DATA_BLOCK_SIZE_1B:     | 1-bit     |
| SDIO_DATA_BLOCK_SIZE_2B:     | 2-bit     |
| SDIO_DATA_BLOCK_SIZE_4B:     | 4-bit     |
| SDIO_DATA_BLOCK_SIZE_8B:     | 8-bit     |
| SDIO_DATA_BLOCK_SIZE_16B:    | 16-bit    |
| SDIO_DATA_BLOCK_SIZE_32B:    | 32-bit    |
| SDIO_DATA_BLOCK_SIZE_64B:    | 64-bit    |
| SDIO_DATA_BLOCK_SIZE_128B:   | 128-bit   |
| SDIO_DATA_BLOCK_SIZE_256B:   | 256-bit   |
| SDIO_DATA_BLOCK_SIZE_512B:   | 512-bit   |
| SDIO_DATA_BLOCK_SIZE_1024B:  | 1024-bit  |
| SDIO_DATA_BLOCK_SIZE_2048B:  | 2048-bit  |
| SDIO_DATA_BLOCK_SIZE_4096B:  | 4096-bit  |
| SDIO_DATA_BLOCK_SIZE_8192B:  | 8192-bit  |
| SDIO_DATA_BLOCK_SIZE_16384B: | 16384-bit |

### transfer\_mode

Data transfer mode selection

|                            |                 |
|----------------------------|-----------------|
| SDIO_DATA_BLOCK_TRANSFER:  | Data block mode |
| SDIO_DATA_STREAM_TRANSFER: | Stream mode     |

### transfer\_direction

Data transfer direction selection

|                                   |                    |
|-----------------------------------|--------------------|
| SDIO_DATA_TRANSFER_TO_CARD:       | Controller-to-card |
| SDIO_DATA_TRANSFER_TO_CONTROLLER: | Card-to-controller |

### Example:

```

sdio_data_struct_type sdio_data_init_struct;
sdio_data_init_struct.block_size = SDIO_DATA_BLOCK_SIZE_512B;
sdio_data_init_struct.data_length = 8 ;
sdio_data_init_struct.timeout = SD_DATATIMEOUT ;
sdio_data_init_struct.transfer_direction = SDIO_DATA_TRANSFER_TO_CARD;
sdio_data_init_struct.transfer_mode = SDIO_DATA_BLOCK_TRANSFER;
/* config sdio data */
sdio_data_config(SDIO1, &sdio_data_init_struct);

```

### 5.20.19 sdio\_data\_state\_machine\_enable function

The table below describes the function `sdio_data_state_machine_enable`.

**Table 532. sdio\_data\_state\_machine\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>sdio_data_state_machine_enable</code>   |
| Function prototype     | <code>void sdio_data_state_machine_enable(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Enable data state machine   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                                 |
| Input parameter 2      | <code>new_state</code> : new state; enabled (TRUE) or disabled (FALSE)                        |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable dcsn */
sdio_data_state_machine_enable(SDIO1, TRUE);
```

### 5.20.20 sdio\_data\_counter\_get function

The table below describes the function `sdio_data_counter_get`.

**Table 533. sdio\_data\_counter\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>sdio_data_counter_get</code>                              |
| Function prototype     | <code>uint32_t sdio_data_counter_get(sdio_type *sdio_x);</code> |
| Function description   | Get the counter of to-be-sent data                              |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1   |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | <code>uint32_t</code> : the counter of to-be-sent data          |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* get data counter */
uint32_t count = 0;
count = sdio_data_counter_get(SDIO1);
```

### 5.20.21 sdio\_data\_read function

The table below describes the function `sdio_data_read`.

**Table 534. sdio\_data\_read function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>sdio_data_read</code>                                   |
| Function prototype     | <code>uint32_t sdio_data_read(sdio_type *sdio_x);</code>      |
| Function description   | Read one-WORD data from the receive FIFO                      |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1 |
| Input parameter 2      | NA  |
| Input parameter 3      | NA  |
| Output parameter       | NA  |
| Return value           | <code>uint32_t</code> : one-WORD data                         |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* read data */
uint32_t data = 0;
data = sdio_data_read(SDIO1);

```

### 5.20.22 sdio\_buffer\_counter\_get function

The table below describes the function `sdio_buffer_counter_get`.

**Table 535. sdio\_buffer\_counter\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>sdio_buffer_counter_get</code>                              |
| Function prototype     | <code>uint32_t sdio_buffer_counter_get(sdio_type *sdio_x);</code> |
| Function description   | Get the counter of data to be written into BUF or read from BUF   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1     |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* get buffer count */
uint32_t count = 0;
count = sdio_buffer_counter_get(SDIO1);

```

### 5.20.23 sdio\_data\_write function

The table below describes the function `sdio_data_write`

**Table 536. sdio\_data\_write function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_data_write</code>   |
| Function prototype     | <code>void sdio_data_write(sdio_type *sdio_x, uint32_t data);</code> |
| Function description   | Write one-WORD data to the transmit FIFO                             |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1        |
| Input parameter 2      | NA   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* write data */
uint32_t data = 0x11223344;
sdio_data_write(SDIO1, data);
```

### 5.20.24 sdio\_read\_wait\_mode\_set function

The table below describes the function `sdio_read_wait_mode_set`.

**Table 537. sdio\_read\_wait\_mode\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_read_wait_mode_set</code>   |
| Function prototype     | <code>void sdio_read_wait_mode_set(sdio_type *sdio_x, sdio_read_wait_mode_type mode);</code> |
| Function description   | Configure read wait mode   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                                |
| Input parameter 2      | <code>mode</code> : read wait mode   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**mode**

`SDIO_READ_WAIT_CONTROLLED_BY_D2`: Read wait is controlled by DATA Line2

`SDIO_READ_WAIT_CONTROLLED_BY_CK`: Read wait is controlled by clock line

**Example:**

```
/* config read wait mode */
sdio_read_wait_mode_set(SDIO1, SDIO_READ_WAIT_CONTROLLED_BY_D2);
```

### 5.20.25 sdio\_read\_wait\_start function

The table below describes the function `sdio_read_wait_start`.

**Table 538. sdio\_read\_wait\_start function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>sdio_read_wait_start</code>   |
| Function prototype     | <code>void sdio_read_wait_start(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Read wait start   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                       |
| Input parameter 2      | <code>new_state</code> : new state, enabled (TRUE) or disabled (FALSE)              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

Calling this function indicates start of read wait; when this function is called to disable wait state, it indicates that no action occurs.

**Example:**

```
/* start read wait mode */
sdio_read_wait_start (SDIO1, TRUE);
```

### 5.20.26 sdio\_read\_wait\_stop function

The table below describes the function `sdio_read_wait_stop`.

**Table 539. sdio\_read\_wait\_stop function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_read_wait_stop</code>   |
| Function prototype     | <code>void sdio_read_wait_stop(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Read wait stop   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                      |
| Input parameter 2      | <code>new_state</code> : new state, enabled (TRUE) or disabled (FALSE)             |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

Calling this function indicates stop of read wait; when this function is called to disable wait state, it indicates that the read wait is in progress.

**Example:**

```
/* stop read wait mode */
sdio_read_wait_stop (SDIO1, TRUE);
```

## 5.20.27 sdio\_io\_function\_enable function

The table below describes the function `sdio_io_function_enable`.

**Table 540. sdio\_io\_function\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_io_function_enable</code>   |
| Function prototype     | <code>void sdio_io_function_enable(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Enable IO function mode  |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                          |
| Input parameter 2      | <code>new_state</code> : new state, enabled (TRUE) or disabled (FALSE)                 |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable sdio IO mode */
sdio_io_function_enable (SDIO1, TRUE);
```

## 5.20.28 sdio\_io\_suspend\_command\_set function

The table below describes the function `sdio_io_suspend_command_set`.

**Table 541. sdio\_io\_suspend\_command\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>sdio_io_suspend_command_set</code>   |
| Function prototype     | <code>void sdio_io_suspend_command_set(sdio_type *sdio_x, confirm_state new_state);</code> |
| Function description   | Enable suspend command in IO function mode   |
| Input parameter 1      | <code>sdio_x</code> : selected SDIO peripheral, such as SDIO1                              |
| Input parameter 2      | <code>new_state</code> : new state, enabled (TRUE) or disabled (FALSE)                     |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* send suspend command */
sdio_io_suspend_command_set (SDIO1, TRUE);
```



## 5.21 Serial peripheral interface (SPI)/I<sup>2</sup>S

The SPI register structure spi\_type is defined in the “at32f435\_437\_spi.h”.

```
/**
 * @brief type define spi register all
 */
typedef struct
{
    ...
} spi_type;
```

The table below gives a list of the SPI registers.

**Table 542. Summary of SPI registers**

| Registers | Description                    |
|-----------|--------------------------------|
| ctrl1     | SPI control register 1         |
| ctrl2     | SPI control register 2         |
| sts       | SPI status register            |
| dt        | SPI data register              |
| cpoly     | SPI CRC register               |
| rcrc      | SPI RxCRC register             |
| tcrc      | SPI TxCRC register             |
| i2sctrl   | SPI_I2S configuration register |
| i2sclkp   | SPI_I2S prescaler register     |

The table below gives a list of the SPI library functions.

**Table 543. Summary of SPI library functions**

| Function name                      | Description  |
|------------------------------------|--|
| spi_i2s_reset                      | Reset SPI/I <sup>2</sup> S registers to their reset values             |
| spi_default_para_init              | Configure the SPI initialization structure with an initial value       |
| spi_init                           | Initialize SPI   |
| spi_ti_mode_enable                 | SPI TI mode enable   |
| spi_crc_next_transmit              | Next data transfer is CRC command                                      |
| spi_crc_polynomial_set             | SPI CRC polynomial configuration                                       |
| spi_crc_polynomial_get             | Get SPI CRC polynomial   |
| spi_crc_enable                     | Enable SPI CRC   |
| spi_crc_value_get                  | Get CRC result of SPI receive/transmit                                 |
| spi_hardware_cs_output_enable      | Enable hardware CS output  |
| spi_software_cs_internal_level_set | Set software CS internal level   |
| spi_frame_bit_num_set              | Set the number of frame bits   |
| spi_half_duplex_direction_set      | Set transfer direction of single-wire bidirectional half-duplex mode   |
| spi_enable                         | Enable SPI   |
| i2s_default_para_init              | Set an initial value for the I <sup>2</sup> S initialization structure |
| i2s_init                           | Initialize I <sup>2</sup> S  |
| i2s_enable                         | Enable I <sup>2</sup> S  |

|                                |  |
|--------------------------------|--|
| spi_i2s_interrupt_enable       | Enable SPI/I <sup>2</sup> S interrupts   |
| spi_i2s_dma_transmitter_enable | Enable SPI/I <sup>2</sup> S DMA transmit |
| spi_i2s_dma_receiver_enable    | Enable SPI/I <sup>2</sup> S DMA receive  |
| spi_i2s_data_transmit          | SPI/I <sup>2</sup> S transmits data      |
| spi_i2s_data_receive           | SPI/I <sup>2</sup> S receives data       |
| spi_i2s_flag_get               | Get SPI/I <sup>2</sup> S flag            |
| spi_i2s_flag_clear             | Clear SPI/I <sup>2</sup> S flag          |

### 5.21.1 spi\_i2s\_reset function

The table below describes the function spi\_i2s\_reset.

**Table 544. spi\_i2s\_reset function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_i2s_reset   |
| Function prototype     | void spi_i2s_reset(spi_type *spi_x);  |
| Function description   | Reset SPI/I <sup>2</sup> S registers to their reset values  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4, I2S2EXT or I2S3EXT. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | crm_periph_reset();   |

**Example:**

```
spi_i2s_reset(SPI1);
```

### 5.21.2 spi\_default\_para\_init function

The table below describes the function spi\_default\_para\_init.

**Table 545. spi\_default\_para\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | spi_default_para_init  |
| Function prototype     | void spi_default_para_init(spi_init_type* spi_init_struct);                |
| Function description   | Set an initial value for the SPI initialization structure                  |
| Input parameter 1      | spi_init_struct: <i>spi_init_type</i> pointer                              |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | It is necessary to define a variable of the spi_init_type before starting. |
| Called functions       | NA   |

**Example:**

```
spi_init_type spi_init_struct;
spi_default_para_init(&spi_init_struct);
```

### 5.21.3 spi\_init function

The table below describes the function spi\_init.

**Table 546. spi\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_init  |
| Function prototype     | void spi_init(spi_type* spi_x, spi_init_type* spi_init_struct);                   |
| Function description   | Initialize SPI  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4. |
| Input parameter 2      | spi_init_struct: <a href="#">spi_init_type</a> pointer                            |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | It is necessary to define a variable of the spi_init_type before starting.        |
| Called functions       | NA  |

The spi\_init\_type is defined in the at32f435\_437\_spi.h.

typedef struct

```
{
    spi_transmission_mode_type    transmission_mode;
    spi_master_slave_mode_type    master_slave_mode;
    spi_mclk_freq_div_type        mclk_freq_division;
    spi_first_bit_type            first_bit_transmission;
    spi_frame_bit_num_type        frame_bit_num;
    spi_clock_polarity_type        clock_polarity;
    spi_clock_phase_type          clock_phase;
    spi_cs_mode_type              cs_mode_selection;
} spi_init_type;
```

#### **spi\_transmission\_mode**

SPI transmission mode

SPI\_TRANSMIT\_FULL\_DUPLEX: Two-wire unidirectional full-duplex mode  
 SPI\_TRANSMIT\_SIMPLEX\_RX: Two-wire unidirectional receive-only mode  
 SPI\_TRANSMIT\_HALF\_DUPLEX\_RX: Single-wire bidirectional receive-only mode  
 SPI\_TRANSMIT\_HALF\_DUPLEX\_TX: Single-wire bidirectional transmit-only mode

#### **master\_slave\_mode**

Master/slave mode selection

SPI\_MODE\_SLAVE: Slave mode  
 SPI\_MODE\_MASTER: Master mode

#### **mclk\_freq\_division**

Frequency division factor selection

SPI\_MCLK\_DIV\_2: Divided by 2  
 SPI\_MCLK\_DIV\_3: Divided by 3  
 SPI\_MCLK\_DIV\_4: Divided by 4  
 SPI\_MCLK\_DIV\_8: Divided by 8

SPI\_MCLK\_DIV\_16: Divided by 16  
 SPI\_MCLK\_DIV\_32: Divided by 32  
 SPI\_MCLK\_DIV\_64: Divided by 64  
 SPI\_MCLK\_DIV\_128: Divided by 128  
 SPI\_MCLK\_DIV\_256: Divided by 256  
 SPI\_MCLK\_DIV\_512: Divided by 512  
 SPI\_MCLK\_DIV\_1024: Divided by 1024

**first\_bit\_transmission**

SPI MSB-first/LSB-first selection

SPI\_FIRST\_BIT\_MSB: MSB-first

SPI\_FIRST\_BIT\_LSB: LSB-first

**frame\_bit\_num**

Set the number of bits in a frame

SPI\_FRAME\_8BIT: 8-bit data in a frame

SPI\_FRAME\_16BIT: 16-bit data in a frame

**clock\_polarity**

Select clock polarity

SPI\_CLOCK\_POLARITY\_LOW: Clock output low in idle state

SPI\_CLOCK\_POLARITY\_HIGH: Clock output high in idle state

**clock\_phase**

Select clock phase

SPI\_CLOCK\_PHASE\_1EDGE: Sample on the first clock edge

SPI\_CLOCK\_PHASE\_2EDGE: Sample on the second clock edge

**cs\_mode\_selection**

Select CS mode

SPI\_CS\_HARDWARE\_MODE: Hardware CS mode

SPI\_CS\_SOFTWARE\_MODE: Software CS mode

**Example:**

```

spi_init_type spi_init_struct;
spi_default_para_init(&spi_init_struct);
spi_init_struct.transmission_mode = SPI_TRANSMIT_FULL_DUPLEX;
spi_init_struct.master_slave_mode = SPI_MODE_MASTER;
spi_init_struct.mclk_freq_division = SPI_MCLK_DIV_8;
spi_init_struct.first_bit_transmission = SPI_FIRST_BIT_MSB;
spi_init_struct.frame_bit_num = SPI_FRAME_16BIT;
spi_init_struct.clock_polarity = SPI_CLOCK_POLARITY_LOW;
spi_init_struct.clock_phase = SPI_CLOCK_PHASE_2EDGE;
spi_init_struct.cs_mode_selection = SPI_CS_SOFTWARE_MODE;
spi_init(SPI1, &spi_init_struct);
  
```

### 5.21.4 spi\_ti\_mode\_enable function

The table below describes the function spi\_ti\_mode\_enable.

**Table 547. spi\_ti\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_ti_mode_enable  |
| Function prototype     | void spi_ti_mode_enable(spi_type* spi_x, confirm_state new_state);                |
| Function description   | Enable SPI TI mode  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4. |
| Input parameter 2      | new_state: Enable or disable<br>This parameter can be FALSE or TRUE.              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* spi ti mode enable */
spi_ti_mode_enable (SPI1, TRUE);
```

### 5.21.5 spi\_crc\_next\_transmit function

The table below describes the function spi\_crc\_next\_transmit.

**Table 548. spi\_crc\_next\_transmit function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_crc_next_transmit   |
| Function prototype     | void spi_crc_next_transmit(spi_type* spi_x);                                      |
| Function description   | The next data to be sent is CRC command   |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
spi_crc_next_transmit (SPI1);
```

## 5.21.6 spi\_crc\_polynomial\_set function

The table below describes the function spi\_crc\_polynomial\_set.

**Table 549. spi\_crc\_polynomial\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_crc_polynomial_set  |
| Function prototype     | void spi_crc_polynomial_set(spi_type* spi_x, uint16_t crc_poly);                  |
| Function description   | Set SPI CRC polynomial  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4. |
| Input parameter 2      | crc_poly: CRC polynomial<br>Range: 0x0000~0xFFFF                                  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/*set spi crc polynomial value */
spi_crc_polynomial_set (SPI1, 0x07);
```

## 5.21.7 spi\_crc\_polynomial\_get function

The table below describes the function spi\_crc\_polynomial\_get.

**Table 550. spi\_crc\_polynomial\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_crc_polynomial_get  |
| Function prototype     | uint16_t spi_crc_polynomial_get(spi_type* spi_x);                               |
| Function description   | Get SPI CRC polynomial  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4. |
| Output parameter       | NA  |
| Return value           | CRC polynomial<br>Range: 0x0000~0xFFFF  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/*get spi crc polynomial value */
uint16_t crc_poly;
crc_poly = spi_crc_polynomial_get (SPI1);
```

### 5.21.8 spi\_crc\_enable function

The table below describes the function spi\_crc\_enable.

**Table 551. spi\_crc\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_crc_enable  |
| Function prototype     | void spi_crc_enable(spi_type* spi_x, confirm_state new_state);                    |
| Function description   | Enable SPI CRC  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4. |
| Input parameter 2      | new_state: enable or disable<br>This parameter can be FALSE or TRUE.              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* spi crc enable */
spi_crc_enable (SPI1, TRUE);
```

### 5.21.9 spi\_crc\_value\_get function

The table below describes the function spi\_crc\_value\_get.

**Table 552. spi\_crc\_value\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | spi_crc_value_get  |
| Function prototype     | uint16_t spi_crc_value_get(spi_type* spi_x, spi_crc_direction_type crc_direction); |
| Function description   | Get SPI receive/transmit CRC result  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4.  |
| Input parameter 2      | <i>crc_direction</i> : Select receive/transmit CRC                                 |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**spi\_crc\_direction**

Select receive/transmit CRC

SPI\_CRC\_RX: Receive CRC

SPI\_CRC\_TX: Transmit CRC

**Example:**

```
/* get spi rx & tx crc enable */
uint16_t spi_rx_crc, spi_tx_crc;
spi_rx_crc = spi_crc_value_get (SPI1, SPI_CRC_RX);
```

```
spi_tx_crc = spi_crc_value_get(SPI1, SPI_CRC_TX);
```

### 5.21.10 spi\_hardware\_cs\_output\_enable function

The table below describes the function spi\_hardware\_cs\_output\_enable.

**Table 553. spi\_hardware\_cs\_output\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_hardware_cs_output_enable   |
| Function prototype     | void spi_hardware_cs_output_enable(spi_type* spi_x, confirm_state new_state);     |
| Function description   | Enable hardware CS output   |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4. |
| Input parameter 2      | new_state: enable or disable<br>This parameter can be FALSE or TRUE.              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | This setting is applicable to SPI master mode only.                               |
| Called functions       | NA  |

**Example:**

```
/* enable the hardware cs output */
spi_hardware_cs_output_enable (SPI1, TRUE);
```

### 5.21.11 spi\_software\_cs\_internal\_level\_set function

The table below describes the function spi\_software\_cs\_internal\_level\_set.

**Table 554. spi\_software\_cs\_internal\_level\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | spi_software_cs_internal_level_set   |
| Function prototype     | void spi_software_cs_internal_level_set(spi_type* spi_x, spi_software_cs_level_type level);  |
| Function description   | Set software CS internal level   |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4.  |
| Input parameter 2      | <i>level</i> : set software CS internal level  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | 1. This setting is applicable to software CS mode only<br>2. In master mode, the "level" value must be "SPI_SWCS_INTERNAL_LEVEL_HIGH". |
| Called functions       | NA   |

**level**

Set software CS internal level

SPI\_SWCS\_INTERNAL\_LEVEL\_LOW:            Software CS internal low level



SPI\_SWCS\_INTERNAL\_LEVEL\_HIGHT:      Software CS internal high level

**Example:**

```
/* set the internal level high */
spi_software_cs_internal_level_set(SPI1, SPI_SWCS_INTERNAL_LEVEL_HIGHT);
```

### 5.21.12 spi\_frame\_bit\_num\_set function

The table below describes the function spi\_frame\_bit\_num\_set.

**Table 555. spi\_frame\_bit\_num\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_frame_bit_num_set   |
| Function prototype     | void spi_frame_bit_num_set(spi_type* spi_x, spi_frame_bit_num_type bit_num);      |
| Function description   | Set the number of bits in a frame   |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4. |
| Input parameter 2      | <i>bit_num</i> : Set the number of bits in a frame                                |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**bit\_num**

Set the number of bits in a frame

SPI\_FRAME\_8BIT:      8-bit data in a frame

SPI\_FRAME\_16BIT:    16-bit data in a frame

**Example:**

```
/* set the data frame bit num as 8 */
spi_frame_bit_num_set(SPI1, SPI_FRAME_8BIT);
```

### 5.21.13 spi\_half\_duplex\_direction\_set function

The table below describes the function spi\_half\_duplex\_direction\_set.

**Table 556. spi\_half\_duplex\_direction\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_half_duplex_direction_set   |
| Function prototype     | void spi_half_duplex_direction_set(spi_type* spi_x,<br>spi_half_duplex_direction_type direction); |
| Function description   | Set the transfer direction of single-wire bidirectional half-duplex mode                          |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4.                 |
| Input parameter 2      | <i>direction</i> : transfer direction   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | This setting is applicable to the single-wire bidirectional half-duplex mode only.                |
| Called functions       | NA  |

**direction**

Transfer direction

SPI\_HALF\_DUPLEX\_DIRECTION\_RX: Receive

SPI\_HALF\_DUPLEX\_DIRECTION\_TX: Transmit

**Example:**

```
/* set the data transmission direction as transmit */
spi_half_duplex_direction_set(SPI1, SPI_HALF_DUPLEX_DIRECTION_TX);
```

### 5.21.14 spi\_enable function

The table below describes the function spi\_enable.

**Table 557. spi\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_enable  |
| Function prototype     | void spi_enable(spi_type* spi_x, confirm_state new_state);                        |
| Function description   | Enable SPI  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4. |
| Input parameter 2      | new_state: enable or disable<br>This parameter can be FALSE or TRUE.              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable spi */
spi_enable(SPI1, TRUE);
```

### 5.21.15 i2s\_default\_para\_init function

The table below describes the function i2s\_default\_para\_init.

**Table 558. i2s\_default\_para\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | i2s_default_para_init  |
| Function prototype     | void i2s_default_para_init(i2s_init_type* i2s_init_struct);                |
| Function description   | Set an initial value for the I <sup>2</sup> S initialization structure     |
| Input parameter 1      | i2s_init_struct: <a href="#">spi_i2s_flag</a> pointer                      |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | It is necessary to define a variable of the i2s_init_type before starting. |
| Called functions       | NA   |

**Example:**

```
i2s_init_type i2s_init_struct;
```

```
i2s_default_para_init (&i2s_init_struct);
```

## 5.21.16 i2s\_init function

The table below describes the function `i2s_init`.

**Table 559. i2s\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>i2s_init</code>   |
| Function prototype     | <code>void i2s_init(spi_type* spi_x, i2s_init_type* i2s_init_struct);</code>                                      |
| Function description   | Initialize I <sup>2</sup> S   |
| Input parameter 1      | <code>spi_x</code> : selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4, I2S2EXT or I2S3EXT. |
| Input parameter 2      | <code>i2s_init_struct</code> : <a href="#">spi_i2s_flag</a> pointer   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | It is necessary to define a variable of the <code>i2s_init_type</code> before starting.                           |
| Called functions       | NA  |

The `i2s_init_type` is defined in the `at32f435_437_spi.h`.

typedef struct

```
{
    i2s_operation_mode_type      operation_mode;
    i2s_audio_protocol_type      audio_protocol;
    i2s_audio_sampling_freq_type audio_sampling_freq;
    i2s_data_channel_format_type data_channel_format;
    i2s_clock_polarity_type      clock_polarity;
    confirm_state                 mclk_output_enable;
}
```

} `i2s_init_type`;

### **operation\_mode**

I<sup>2</sup>S transfer mode

```
I2S_MODE_SLAVE_TX:      I2S slave transmit
I2S_MODE_SLAVE_RX:      I2S slave receive
I2S_MODE_MASTER_TX:     I2S master transmit
I2S_MODE_MASTER_RX:     I2S master receive
```

### **audio\_protocol**

I<sup>2</sup>S audio protocol standards

```
I2S_AUDIO_PROTOCOL_PHILLIPS:      Phillips
I2S_AUDIO_PROTOCOL_MSB:           MSB aligned (left-aligned)
I2S_AUDIO_PROTOCOL_LSB:           LSB aligned (right-aligned)
I2S_AUDIO_PROTOCOL_PCM_SHORT:     PCM short frame synchronization
I2S_AUDIO_PROTOCOL_PCM_LONG:      PCM long frame synchronization
```

### **audio\_sampling\_freq**

I<sup>2</sup>S audio sampling frequency

```
I2S_AUDIO_FREQUENCY_DEFAULT:
```

Kept at its reset value (sampling frequency changes with SCLK)

|                              |                                |
|------------------------------|--------------------------------|
| I2S_AUDIO_FREQUENCY_8K:      | I2S sampling frequency 8K      |
| I2S_AUDIO_FREQUENCY_11_025K: | I2S sampling frequency 11.025K |
| I2S_AUDIO_FREQUENCY_16K:     | I2S sampling frequency 16K     |
| I2S_AUDIO_FREQUENCY_22_05K:  | I2S sampling frequency 22.05K  |
| I2S_AUDIO_FREQUENCY_32K:     | I2S sampling frequency 32K     |
| I2S_AUDIO_FREQUENCY_44_1K:   | I2S sampling frequency 44.1K   |
| I2S_AUDIO_FREQUENCY_48K:     | I2S sampling frequency 48K     |
| I2S_AUDIO_FREQUENCY_96K:     | I2S sampling frequency 96K     |
| I2S_AUDIO_FREQUENCY_192K:    | I2S sampling frequency 192K    |

**data\_channel\_format**

I2S data/channel bits format

|                               |                             |
|-------------------------------|-----------------------------|
| I2S_DATA_16BIT_CHANNEL_16BIT: | 16-bit data, 16-bit channel |
| I2S_DATA_16BIT_CHANNEL_32BIT: | 16-bit data, 32-bit channel |
| I2S_DATA_24BIT_CHANNEL_32BIT: | 24-bit data, 32-bit channel |
| I2S_DATA_32BIT_CHANNEL_32BIT: | 32-bit data, 32-bit channel |

**clock\_polarity**

I2S clock polarity

|                          |                                 |
|--------------------------|---------------------------------|
| I2S_CLOCK_POLARITY_LOW:  | Clock output low in idle state  |
| I2S_CLOCK_POLARITY_HIGH: | Clock output high in idle state |

**mclk\_output\_enable**

Enable mclk clock output

This parameter can be FALSE or TRUE.

**Example:**

```
i2s_init_type i2s_init_struct;
i2s_default_para_init(&i2s_init_struct);
i2s_init_struct.audio_protocol = I2S_AUDIO_PROTOCOL_PHILLIPS;
i2s_init_struct.data_channel_format = I2S_DATA_16BIT_CHANNEL_32BIT;
i2s_init_struct.mclk_output_enable = FALSE;
i2s_init_struct.audio_sampling_freq = I2S_AUDIO_FREQUENCY_48K;
i2s_init_struct.clock_polarity = I2S_CLOCK_POLARITY_LOW;
i2s_init_struct.operation_mode = I2S_MODE_MASTER_TX;
i2s_init(SPI2, &i2s_init_struct);
```

### 5.21.17 i2s\_enable function

The table below describes the function i2s\_enable.

**Table 560. i2s\_enable function**

| Name                 | Description   |
|----------------------|---|
| Function name        | i2s_enable  |
| Function prototype   | void i2s_enable(spi_type* spi_x, confirm_state new_state);                        |
| Function description | Enable I2S  |
| Input parameter 1    | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3 or SPI4. |
| Input parameter 2    | new_state: enable or disable<br>This parameter can be FALSE or TRUE.              |

| Name                   | Description |
|------------------------|-------------|
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

```
/* enable i2s*/
i2s_enable(SPI1, TRUE);
```

### 5.21.18 spi\_i2s\_interrupt\_enable function

The table below describes the function spi\_i2s\_interrupt\_enable.

**Table 561. spi\_i2s\_interrupt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_i2s_interrupt_enable  |
| Function prototype     | void spi_i2s_interrupt_enable(spi_type* spi_x, uint32_t spi_i2s_int, confirm_state new_state);      |
| Function description   | Enable SPI/I <sup>2</sup> S interrupts  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4, I2S2EXT or I2S3EXT. |
| Input parameter 2      | <a href="#">spi_i2s_int</a> : SPI interrupt selection   |
| Input parameter 3      | new_state: enable or disable<br>This parameter can be FALSE or TRUE.                                |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**spi\_i2s\_int**

SPI/I<sup>2</sup>S interrupt selection

SPI\_I2S\_ERROR\_INT:

SPI/I<sup>2</sup>S error interrupts (including CRC error, overflow error, underflow error and mode error)

SPI\_I2S\_RDBF\_INT: Receive data buffer full

SPI\_I2S\_TDBE\_INT: Transmit data buffer empty

**Example:**

```
/* enable the specified spi/i2s interrupts */
spi_i2s_interrupt_enable(SPI1, SPI_I2S_ERROR_INT);
spi_i2s_interrupt_enable(SPI1, SPI_I2S_RDBF_INT);
spi_i2s_interrupt_enable(SPI1, SPI_I2S_TDBE_INT);
```

### 5.21.19 spi\_i2s\_dma\_transmitter\_enable function

The table below describes the function spi\_i2s\_dma\_transmitter\_enable.

**Table 562. spi\_i2s\_dma\_transmitter\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_i2s_dma_transmitter_enable  |
| Function prototype     | void spi_i2s_dma_transmitter_enable(spi_type* spi_x, confirm_state new_state);                      |
| Function description   | Enable SPI/I <sup>2</sup> S DMA transmitter   |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4, I2S2EXT or I2S3EXT. |
| Input parameter 2      | new_state: enable or disable<br>This parameter can be FALSE or TRUE.                                |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable spi transmitter dma */
spi_i2s_dma_transmitter_enable (SPI1, TRUE);
```

### 5.21.20 spi\_i2s\_dma\_receiver\_enable function

The table below describes the function spi\_i2s\_dma\_receiver\_enable.

**Table 563. spi\_i2s\_dma\_receiver\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_i2s_dma_receiver_enable   |
| Function prototype     | void spi_i2s_dma_receiver_enable(spi_type* spi_x, confirm_state new_state);                         |
| Function description   | Enable SPI/I <sup>2</sup> S DMA receiver  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4, I2S2EXT or I2S3EXT. |
| Input parameter 2      | new_state: enable or disable<br>This parameter can be FALSE or TRUE.                                |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable spi dma transmitter */
spi_i2s_dma_transmitter_enable (SPI1, TRUE);
```

## 5.21.21 spi\_i2s\_data\_transmit function

The table below describes the function spi\_i2s\_data\_transmit.

**Table 564. spi\_i2s\_data\_transmit function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_i2s_data_transmit   |
| Function prototype     | void spi_i2s_data_transmit(spi_type* spi_x, uint16_t tx_data);  |
| Function description   | SPI/I <sup>2</sup> S sends data   |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4, I2S2EXT or I2S3EXT.                             |
| Input parameter 2      | tx_data: data to be sent<br>Value range (for 8-bit in a frame): 0x00~0xFF<br>Value range (for 16-bit in a frame): 0x0000~0xFFFF |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* spi data transmit */
uint16_t tx_data = 0x6666;
spi_i2s_data_transmit (SPI1, tx_data);
```

## 5.21.22 spi\_i2s\_data\_receive function

The table below describes the function spi\_i2s\_data\_receive.

**Table 565. spi\_i2s\_data\_receive function**

| Name                   | Description   |
|------------------------|---|
| Function name          | spi_i2s_data_receive  |
| Function prototype     | uint16_t spi_i2s_data_receive(spi_type* spi_x);   |
| Function description   | SPI/I <sup>2</sup> S receives data  |
| Input parameter 1      | spi_x: selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4, I2S2EXT or I2S3EXT.                             |
| Output parameter       | rx_data: data to receive<br>Value range (for 8-bit in a frame): 0x00~0xFF<br>Value range (for 16-bit in a frame): 0x0000~0xFFFF |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* spi data receive */
uint16_t rx_data = 0;
rx_data = spi_i2s_data_receive (SPI1);
```

### 5.21.23 spi\_i2s\_flag\_get function

The table below describes the function `spi_i2s_flag_get`.

**Table 566. spi\_i2s\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>spi_i2s_flag_get</code>   |
| Function prototype     | <code>flag_status spi_i2s_flag_get(spi_type* spi_x, uint32_t spi_i2s_flag);</code>                                |
| Function description   | Get SPI/I <sup>2</sup> S flag   |
| Input parameter 1      | <code>spi_x</code> : selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4, I2S2EXT or I2S3EXT. |
| Input parameter 2      | <code>spi_i2s_flag</code> : flag selection<br>Refer to “ <code>spi_i2s_flag</code> ” description for details.     |
| Output parameter       | NA  |
| Return value           | <code>flag_status</code> : flag status<br>This parameter can be SET or RESET.                                     |
| Required preconditions | NA  |
| Called functions       | NA  |

#### spi\_i2s\_flag

SPI/I<sup>2</sup>S is used to select a flag from the optional parameters below:

|                                   |   |
|-----------------------------------|---|
| <code>SPI_I2S_RDBF_FLAG</code> :  | SPI/I <sup>2</sup> S receive data buffer full           |
| <code>SPI_I2S_TDBE_FLAG</code> :  | SPI/I <sup>2</sup> S transmit data buffer empty         |
| <code>I2S_ACS_FLAG</code> :       | I2S audio channel state (indicating left/right channel) |
| <code>I2S_TUERR_FLAG</code> :     | I2S transmitter underload error                         |
| <code>SPI_CCERR_FLAG</code> :     | SPI CRC error   |
| <code>SPI_MMERR_FLAG</code> :     | SPI master mode error                                   |
| <code>SPI_I2S_ROERR_FLAG</code> : | SPI/I <sup>2</sup> S receive overflow error             |
| <code>SPI_I2S_BF_FLAG</code> :    | SPI/I <sup>2</sup> S busy                               |
| <code>SPI_CSPAS_FLAG</code> :     | SPI CS pulse error                                      |

#### Example:

```
/* get receive data buffer full flag */
flag_status status;
status = spi_i2s_flag_get(SPI1, SPI_I2S_RDBF_FLAG);
```

### 5.21.24 spi\_i2s\_flag\_clear function

The table below describes the function `spi_i2s_flag_clear`.

**Table 567. spi\_i2s\_flag\_clear function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>spi_i2s_flag_clear</code>   |
| Function prototype   | <code>void spi_i2s_flag_clear(spi_type* spi_x, uint32_t spi_i2s_flag)</code>                                      |
| Function description | Clear SPI/I <sup>2</sup> S flag   |
| Input parameter 1    | <code>spi_x</code> : selected SPI peripheral<br>This parameter can be SPI1, SPI2, SPI3, SPI4, I2S2EXT or I2S3EXT. |
| Input parameter 2    | <code>spi_i2s_flag</code> : to-be-cleared flag  |



| Name                   | Description                                      |
|------------------------|--|
|                        | Refer to “spi_i2s_flag” description for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### spi\_i2s\_flag:

SPI/I<sup>2</sup>S is used for flag selection, including:

- SPI\_I2S\_RDBF\_FLAG: SPI/I<sup>2</sup>S receive data buffer full
- I2S\_TUERR\_FLAG: I2S transmitter underload error
- SPI\_CCERR\_FLAG: SPI CRC error
- SPI\_MMERR\_FLAG: SPI master mode error
- SPI\_I2S\_ROERR\_FLAG: SPI/I<sup>2</sup>S receive overflow error
- SPI\_CSPAS\_FLAG: SPI CS pulse error

*Note: The SPI\_I2S\_TDBE\_FLAG (SPI/I2S transmit data buffer empty) ,I2S\_ACS\_FLAG (I2S audio channel state) and SPI\_I2S\_BF\_FLAG (SPI/I2S busy) are all set and cleared by hardware to indicate communication state, without the intervention of software.*

### Example:

```
/* clear receive data buffer full flag */
spi_i2s_flag_clear(SPI1, SPI_I2S_RDBF_FLAG);
```

## 5.22 SysTick

The SysTick register structure SysTick\_Type is defined in the “core\_cm4.h”.

```
typedef struct
{
    ...
} SysTick_Type;
```

The table below gives a list of SysTick registers.

**Table 568. Summary of SysTick registers**

| Register | Description                    |
|----------|--------------------------------|
| ctrl     | Control status register        |
| load     | Reload value register          |
| val      | Current counter value register |
| calib    | Calibration register           |

The table below gives a list of SysTick library functions.

**Table 569. Summary of SysTick library functions**

| Function name               | Description   |
|-----------------------------|---|
| systick_clock_source_config | Configure SysTick clock sources                       |
| SysTick_Config              | Configure SysTick counter reload value and interrupts |

### 5.22.1 systick\_clock\_source\_config function

The table below describes the function systick\_clock\_source\_config.

**Table 570. systick\_clock\_source\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | systick_clock_source_config   |
| Function prototype     | void systick_clock_source_config(systick_clock_source_type source); |
| Function description   | Configure SysTick clock source                                      |
| Input parameter 1      | source: systick clock source  |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**source**

SYSTICK\_CLOCK\_SOURCE\_AHBCLK\_DIV8: AHB/8 as SysTick clock

SYSTICK\_CLOCK\_SOURCE\_AHBCLK\_NODIV: AHB as SysTick clock

**Example:**

```
/* config systick clock source */
systick_clock_source_config(SYSTICK_CLOCK_SOURCE_AHBCLK_NODIV);
```

## 5.22.2 SysTick\_Config function

The table below describes the function SysTick\_Config.

**Table 571. SysTick\_Config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | SysTick_Config   |
| Function prototype     | uint32_t SysTick_Config(uint32_t ticks);                               |
| Function description   | Configure SysTick counter reload value and enable interrupt            |
| Input parameter 1      | ticks: SysTick counter interrupt reload value                          |
| Input parameter 2      |  |
| Output parameter       | NA   |
| Return value           | Return the setting status of this function, success (0) or failure (1) |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```

/* config systick reload value and enable interrupt*/
SysTick_Config(1000);
    
```

## 5.23 Timer (TMR)

The TMR register structure `tmr_type` is defined in the “`at32f435_437_tmr.h`”.

```
/**
 * @brief type define tmr register all
 */
typedef struct
{

} tmr_type;
```

The table below gives a list of TMR registers.

**Table 572. Summary of TMR registers**

| Register             | Description                       |
|----------------------|-----------------------------------|
| <code>ctrl1</code>   | TMR control register 1            |
| <code>ctrl2</code>   | TMR control register 2            |
| <code>stctrl</code>  | TMR slave timer control register  |
| <code>iden</code>    | TMR DMA/interrupt enable register |
| <code>ists</code>    | TMR interrupt status register     |
| <code>swevt</code>   | TMR software event register       |
| <code>cm1</code>     | TMR channel mode register 1       |
| <code>cm2</code>     | TMR channel mode register 2       |
| <code>cctrl</code>   | TMR channel control register      |
| <code>cval</code>    | TMR counter value register        |
| <code>div</code>     | TMR division register             |
| <code>pr</code>      | TMR period register               |
| <code>rpr</code>     | TMR repetition period register    |
| <code>c1dt</code>    | TMR channel 1 data register       |
| <code>c2dt</code>    | TMR channel 2 data register       |
| <code>c3dt</code>    | TMR channel 3 data register       |
| <code>c4dt</code>    | TMR channel 4 data register       |
| <code>brk</code>     | TMR break register                |
| <code>dmactrl</code> | TMR DMA control register          |
| <code>dmatd</code>   | TMR DMA data register             |
| <code>rmp</code>     | TMR channel input remap register  |
| <code>cm3</code>     | TMR channel mode register 3       |
| <code>c5dt</code>    | TMR channel 5 data register       |

The table below gives a list of TMR library functions.

**Table 573. Summary of TMR library functions**

| Function name                   | Description                        |
|---------------------------------|------------------------------------|
| <code>tmr_reset</code>          | TMR is reset by CRM reset register |
| <code>tmr_counter_enable</code> | Enable or disable TMR counter      |

|                                    |   |
|------------------------------------|---|
| tmr_output_default_para_init       | Initialize TMR output default parameter           |
| tmr_input_default_para_init        | Initialize TMR input default parameter            |
| tmr_brkdt_default_para_init        | Initialize TMR brkdt default parameter            |
| tmr_base_init                      | Initialize TMR period and division                |
| tmr_clock_source_div_set           | Set TMR clock source frequency division factor    |
| tmr_cnt_dir_set                    | Set TMR counter direction                         |
| tmr_repetition_counter_set         | Set repetition period register value              |
| tmr_counter_value_set              | Set TMR counter value                             |
| tmr_counter_value_get              | Get TMR counter value                             |
| tmr_div_value_set                  | Set TMR division value                            |
| tmr_div_value_get                  | Get TMR division value                            |
| tmr_output_channel_config          | Configure TMR output channel                      |
| tmr_output_channel_mode_select     | Select TMR output channel mode                    |
| tmr_period_value_set               | Set TMR period value                              |
| tmr_period_value_get               | Get TMR period value                              |
| tmr_channel_value_set              | Set TMR channel value                             |
| tmr_channel_value_get              | Get TMR channel value                             |
| tmr_period_buffer_enable           | Enable or disable TMR periodic buffer             |
| tmr_output_channel_buffer_enable   | Enable or disable TMR output channel buffer       |
| tmr_output_channel_immediately_set | TMR output channel enable immediately             |
| tmr_output_channel_switch_set      | Set TMR output channel switch                     |
| tmr_one_cycle_mode_enable          | Enable or disable TMR one-cycle mode              |
| tmr_32_bit_function_enable         | Enable or disable TMR 32-bit function (plus mode) |
| tmr_overflow_request_source_set    | Select TMR overflow event source                  |
| tmr_overflow_event_disable         | Enable or disable TMR overflow event generation   |
| tmr_input_channel_init             | Initialize TMR input channel                      |
| tmr_channel_enable                 | Enable or disable TMR channel                     |
| tmr_input_channel_filter_set       | Set TMR input channel filter                      |
| tmr_pwm_input_config               | Configure TMR pwm input                           |
| tmr_channel1_input_select          | Select TMR channel 1 input                        |
| tmr_input_channel_divider_set      | Set TMR input channel divider                     |
| tmr_primary_mode_select            | Select TMR master mode                            |
| tmr_sub_mode_select                | Select TMR slave timer mode                       |
| tmr_channel_dma_select             | Select TMR channel DMA request source             |
| tmr_hall_select                    | Select TMR hall mode                              |
| tmr_channel_buffer_enable          | Enable or disable TMR channel buffer              |
| tmr_trgout2_enable                 | Enable or disable TMR trigger output 2 signal     |
| tmr_trigger_input_select           | Select TMR slave timer trigger input              |
| tmr_sub_sync_mode_set              | Set TMR slave timer synchronization mode          |
| tmr_dma_request_enable             | Enable or disable TMR DMA request                 |
| tmr_interrupt_enable               | Enable or disable TMR interrupt                   |
| tmr_flag_get                       | Get TMR flag                                      |
| tmr_flag_clear                     | Clear TMR flag                                    |
| tmr_event_sw_trigger               | Software trigger TMR event                        |
| tmr_output_enable                  | Enable or disable TMR output                      |

|                                 |                                  |
|---------------------------------|----------------------------------|
| tmr_internal_clock_set          | Set TMR internal clock           |
| tmr_output_channel_polarity_set | Set TMR output channel polarity  |
| tmr_external_clock_config       | Set TMR external clock           |
| tmr_external_clock_mode1_config | Set TMR external clock mode 1    |
| tmr_external_clock_mode2_config | Set TMR external clock mode 2    |
| tmr_encoder_mode_config         | Set TMR encoder mode             |
| tmr_force_output_set            | Set TMR forced output            |
| tmr_dma_control_config          | Set TMR DMA control              |
| tmr_brkdt_config                | Set TMR break mode and dead-time |
| tmr_iremap_config               | Set TMR internal remap           |

### 5.23.1 tmr\_reset function

The table below describes the function tmr\_reset.

**Table 574. tmr\_reset function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_reset  |
| Function prototype     | void tmr_reset(tmr_type *tmr_x);   |
| Function description   | TMR is reset by CRM reset register   |
| Input parameter        | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | crm_periph_reset();  |

**Example:**

|                  |
|------------------|
| tmr_reset(TMR1); |
|------------------|

### 5.23.2 tmr\_counter\_enable function

The table below describes the function tmr\_counter\_enable.

**Table 575. tmr\_counter\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_counter_enable   |
| Function prototype     | void tmr_counter_enable(tmr_type *tmr_x, confirm_state new_state);   |
| Function description   | Enable or disable TMR counter  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | new_state: indicates counter status, ON (TRUE) or OFF (FALSE)  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
tmr_counter_enable(TMR1, TRUE);
```

### 5.23.3 tmr\_output\_default\_para\_init function

The table below describes the function tmr\_output\_default\_para\_init.

**Table 576. tmr\_output\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | tmr_output_default_para_init  |
| Function prototype     | void tmr_output_default_para_init(tmr_output_config_type *tmr_output_struct); |
| Function description   | Initialize tmr output default parameters                                      |
| Input parameter        | tmr_output_struct: tmr_output_config_type pointer                             |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The table below describes the default values of members of the tmr\_output\_struct.

**Table 577. tmr\_output\_struct default values**

| Member           | Default value          |
|------------------|------------------------|
| oc_mode          | TMR_OUTPUT_CONTROL_OFF |
| oc_idle_state    | FALSE                  |
| occ_idle_state   | FALSE                  |
| oc_polarity      | TMR_OUTPUT_ACTIVE_HIGH |
| occ_polarity     | TMR_OUTPUT_ACTIVE_HIGH |
| oc_output_state  | FALSE                  |
| occ_output_state | FALSE                  |

**Example:**

```
tmr_output_config_type tmr_output_struct;
tmr_output_default_para_init(&tmr_output_struct);
```

### 5.23.4 tmr\_input\_default\_para\_init function

The table below describes the function tmr\_input\_default\_para\_init.

**Table 578. tmr\_input\_default\_para\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_input_default_para_init  |
| Function prototype     | void tmr_input_default_para_init(tmr_input_config_type *tmr_input_struct); |
| Function description   | Initialize TMR input default parameters                                    |
| Input parameter        | tmr_input_struct: tmr_input_config_type pointer                            |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

The table below describes the default values of members of the tmr\_input\_struct.

**Table 579. tmr\_input\_struct default values**

| Member                | Default values               |
|-----------------------|------------------------------|
| input_channel_select  | TMR_SELECT_CHANNEL_1         |
| input_polarity_select | TMR_INPUT_RISING_EDGE        |
| input_mapped_select   | TMR_CC_CHANNEL_MAPPED_DIRECT |
| input_filter_value    | 0x0                          |

**Example:**

```
tmr_input_config_type tmr_input_struct;
tmr_input_default_para_init(&tmr_input_struct);
```

### 5.23.5 tmr\_brkdt\_default\_para\_init function

The table below describes the function tmr\_brkdt\_default\_para\_init.

**Table 580. tmr\_brkdt\_default\_para\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_brkdt_default_para_init  |
| Function prototype     | void tmr_brkdt_default_para_init(tmr_brkdt_config_type *tmr_brkdt_struct); |
| Function description   | Initialize TMR brkdt default parameters                                    |
| Input parameter        | tmr_brkdt_struct: tmr_brkdt_config_type pointer                            |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

The table below describes the default values of members of tmr\_brkdt\_struct.

**Table 581. tmr\_brkdt\_struct default values**

| Member             | Default value            |
|--------------------|--------------------------|
| deadtime           | 0x0                      |
| brk_polarity       | TMR_BRK_INPUT_ACTIVE_LOW |
| wp_level           | TMR_WP_OFF               |
| auto_output_enable | FALSE                    |
| fcsoen_state       | FALSE                    |
| fcsodis_state      | FALSE                    |
| brk_enable         | FALSE                    |

**Example:**

```
tmr_brkdt_config_type tmr_brkdt_struct;
tmr_brkdt_default_para_init(&tmr_brkdt_struct);
```



### 5.23.6 tmr\_base\_init function

The table below describes the function `tmr_base_init`.

**Table 582. tmr\_base\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_base_init</code>   |
| Function prototype     | <code>void tmr_base_init(tmr_type* tmr_x, uint32_t tmr_pr, uint32_t tmr_div);</code>   |
| Function description   | Initialize TMR period and frequency division   |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>tmr_pr</code> : timer period value, 0x0000~0xFFFF for 16-bit timer, and 0x0000_0000~0xFFFF_FFFF for 32-bit timer   |
| Input parameter 3      | <code>tmr_div</code> : timer division value, 0x0000~0xFFFF   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
tmr_base_init(TMR1, 0xFFFF, 0xFFFF);
```

### 5.23.7 tmr\_clock\_source\_div\_set function

The table below describes the function `tmr_clock_source_div_set`.

**Table 583. tmr\_clock\_source\_div\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_clock_source_div_set</code>  |
| Function prototype     | <code>void tmr_clock_source_div_set(tmr_type *tmr_x, tmr_clock_division_type tmr_clock_div);</code>  |
| Function description   | Set TMR clock source division  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>tmr_clock_div</code> : TMR clock source division factor  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_clock\_div**

Select TMR clock source frequency division factor

- TMR\_CLOCK\_DIV1: Divided by 1
- TMR\_CLOCK\_DIV2: Divided by 2
- TMR\_CLOCK\_DIV4: Divided by 4

**Example:**

```
tmr_clock_source_div_set(TMR1, TMR_CLOCK_DIV4);
```

### 5.23.8 tmr\_cnt\_dir\_set function

The table below describes the function `tmr_cnt_dir_set`.

**Table 584. tmr\_cnt\_dir\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_cnt_dir_set</code>   |
| Function prototype     | <code>void tmr_cnt_dir_set(tmr_type *tmr_x, tmr_count_mode_type tmr_cnt_dir);</code>   |
| Function description   | Set TMR counter direction  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>tmr_cnt_dir</code> : timer counting direction  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

`tmr_cnt_dir`

Select timer counting direction

TMR\_COUNT\_UP: Up counting

TMR\_COUNT\_DOWN: Down counting

TMR\_COUNT\_TWO\_WAY\_1: Center-aligned mode (up/down counting) 1

TMR\_COUNT\_TWO\_WAY\_2: Center-aligned mode (up/down counting) 2

TMR\_COUNT\_TWO\_WAY\_3: Center-aligned mode (up/down counting) 3

**Example:**

```
tmr_cnt_dir_set(TMR1, TMR_COUNT_UP);
```

### 5.23.9 tmr\_repetition\_counter\_set function

The table below describes the function `tmr_repetition_counter_set`.

**Table 585. tmr\_repetition\_counter\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>tmr_repetition_counter_set</code>   |
| Function prototype     | <code>void tmr_repetition_counter_set(tmr_type *tmr_x, uint8_t tmr_rpr_value);</code>       |
| Function description   | Set repetition period register (rpr)  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR8 or TMR20. |
| Input parameter 2      | <code>tmr_rpr_value</code> : timer repetition period value, ranging from 0x00 to 0xFF       |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
tmr_repetition_counter_set(TMR1, 0x10);
```

### 5.23.10 tmr\_counter\_value\_set function

The table below describes the function `tmr_counter_value_set`.

**Table 586. tmr\_counter\_value\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_counter_value_set</code>   |
| Function prototype     | <code>void tmr_counter_value_set(tmr_type *tmr_x, uint32_t tmr_cnt_value);</code>  |
| Function description   | Set TMR counter value  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>tmr_cnt_value</code> : timer counter value, 0x0000~0xFFFF for 16-bit timer, and 0x0000_0000~0xFFFF_FFFF for 32-timer   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
tmr_counter_value_set(TMR1, 0xFFFF);
```

### 5.23.11 tmr\_counter\_value\_get function

The table below describes the function `tmr_counter_value_get`.

**Table 587. tmr\_counter\_value\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_counter_value_get</code>   |
| Function prototype     | <code>uint32_t tmr_counter_value_get(tmr_type *tmr_x);</code>  |
| Function description   | Get TMR counter value  |
| Input parameter        | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Output parameter       | NA   |
| Return value           | Timer counter value  |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
uint32_t counter_value;
counter_value = tmr_counter_value_get(TMR1);
```

### 5.23.12 tmr\_div\_value\_set function

The table below describes the function `tmr_div_value_set`.

**Table 588. tmr\_div\_value\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_div_value_set</code>   |
| Function prototype     | <code>void tmr_div_value_set(tmr_type *tmr_x, uint32_t tmr_div_value);</code>  |
| Function description   | Set TMR frequency division value   |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_div_value: timer frequency division value, 0x0000~0xFFFF for 16-bit timer and 0x0000_0000~0xFFFF_FFFF for 32-bit timer                                 |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
tmr_div_value_set(TMR1, 0xFFFF);
```

### 5.23.13 tmr\_div\_value\_get function

The table below describes the function `tmr_div_value_get`.

**Table 589. tmr\_div\_value\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_div_value_get</code>   |
| Function prototype     | <code>uint32_t tmr_div_value_get(tmr_type *tmr_x);</code>  |
| Function description   | Get TMR frequency division value   |
| Input parameter        | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Output parameter       | NA   |
| Return value           | Timer frequency division value   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
uint32_t div_value;
div_value = tmr_div_value_get(TMR1);
```

### 5.23.14 tmr\_output\_channel\_config function

The table below describes the function `tmr_output_channel_config`.

**Table 590. tmr\_output\_channel\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_output_channel_config</code>   |
| Function prototype     | <code>void tmr_output_channel_config(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_output_config_type *tmr_output_struct);</code>                |
| Function description   | Configure TMR output channel   |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>tmr_channel</code> : timer channel   |
| Input parameter 3      | <code>tmr_output_struct</code> : <code>tmr_output_config_type</code> pointer   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **tmr\_channel**

Set a TMR channel

|                                     |           |
|-------------------------------------|-----------|
| <code>TMR_SELECT_CHANNEL_1</code> : | Channel 1 |
| <code>TMR_SELECT_CHANNEL_2</code> : | Channel 2 |
| <code>TMR_SELECT_CHANNEL_3</code> : | Channel 3 |
| <code>TMR_SELECT_CHANNEL_4</code> : | Channel 4 |
| <code>TMR_SELECT_CHANNEL_5</code> : | Channel 5 |

#### **tmr\_output\_config\_type structure**

The `tmr_output_config_type` is defined in the `at32f435_437_tmr.h`.

typedef struct

```
{
    tmr_output_control_mode_type    oc_mode;
    confirm_state                   oc_idle_state;
    confirm_state                   occ_idle_state;
    tmr_output_polarity_type        oc_polarity;
    tmr_output_polarity_type        occ_polarity;
    confirm_state                   oc_output_state;
    confirm_state                   occ_output_state;
} tmr_output_config_type;
```

#### **oc\_mode**

Set output channel mode, that is, to configure channel original signals (CxORAW)

|  |   |
|--|---|
| <code>TMR_OUTPUT_CONTROL_OFF</code> :        | Disconnect channel output (CxOUT) from CxORAW |
| <code>TMR_OUTPUT_CONTROL_HIGH</code> :       | CxORAW high                                   |
| <code>TMR_OUTPUT_CONTROL_LOW</code> :        | CxORAW low                                    |
| <code>TMR_OUTPUT_CONTROL_SWITCH</code> :     | Switch CxORAW level                           |
| <code>TMR_OUTPUT_CONTROL_FORCE_LOW</code> :  | CxORAW forced low                             |
| <code>TMR_OUTPUT_CONTROL_FORCE_HIGH</code> : | CxORAW forced high                            |
| <code>TMR_OUTPUT_CONTROL_PWM_MODE_A</code> : | PWM mode A                                    |

TMR\_OUTPUT\_CONTROL\_PWM\_MODE\_B: PWM mode B

**oc\_idle\_state**

Set output channel idle state.

FALSE: Output channel idle state is 0

TRUE: Output channel idle state is 1

**occ\_idle\_state**

Set complementary output channel idle state.

FALSE: Complementary output channel idle state is 0

TRUE: Complementary output channel idle state is 1

**oc\_polarity**

Set the polarity of output channels.

TMR\_OUTPUT\_ACTIVE\_HIGH: Active high

TMR\_OUTPUT\_ACTIVE\_LOW: Active low

**occ\_polarity**

Set the polarity of complementary output channels.

TMR\_OUTPUT\_ACTIVE\_HIGH: Active high

TMR\_OUTPUT\_ACTIVE\_LOW: Active low

**oc\_output\_state**

Set the state of output channels.

FALSE: Output channel OFF

TRUE: Output channel ON

**occ\_output\_state**

Set the state of complementary output channels.

FALSE: Complementary output channel OFF

TRUE: Complementary output channel ON

**Example:**

```

tmr_output_config_type tmr_output_struct;
tmr_output_struct.oc_mode = TMR_OUTPUT_CONTROL_OFF;
tmr_output_struct.oc_output_state = TRUE;
tmr_output_struct.oc_polarity = TMR_OUTPUT_ACTIVE_HIGH;
tmr_output_struct.oc_idle_state = TRUE;
tmr_output_struct.occ_output_state = TRUE;
tmr_output_struct.occ_polarity = TMR_OUTPUT_ACTIVE_HIGH;
tmr_output_struct.occ_idle_state = TRUE;
tmr_output_channel_config(TMR1, TMR_SELECT_CHANNEL_1, &tmr_output_struct);
    
```

### 5.23.15 tmr\_output\_channel\_mode\_select function

The table below describes the function tmr\_output\_channel\_mode\_select.

**Table 591. tmr\_output\_channel\_mode\_select function**

| Name                 | Description  |
|----------------------|--|
| Function name        | tmr_output_channel_mode_select   |
| Function prototype   | void tmr_output_channel_mode_select(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_output_control_mode_type oc_mode); |
| Function description | Select TMR output channel mode   |
| Input parameter 1    | tmr_x: selected TMR peripheral.  |

| Name                   | Description   |
|------------------------|---|
|                        | This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_channel: timer channel  |
| Input parameter 3      | oc_mode: output mode  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**tmr\_channel**

Select a TMR channel.

|                       |                 |
|-----------------------|-----------------|
| TMR_SELECT_CHANNEL_1: | Timer channel 1 |
| TMR_SELECT_CHANNEL_2: | Timer channel 2 |
| TMR_SELECT_CHANNEL_3: | Timer channel 3 |
| TMR_SELECT_CHANNEL_4: | Timer channel 4 |
| TMR_SELECT_CHANNEL_5: | Timer channel 5 |

**oc\_mode**

Set output channel mode, that is, to configure channel original signals (CxORAW)

|                                |  |
|--------------------------------|--|
| TMR_OUTPUT_CONTROL_OFF:        | Disconnect channel output (CxOUT) fromCxORAW |
| TMR_OUTPUT_CONTROL_HIGH:       | CxORAW high                                  |
| TMR_OUTPUT_CONTROL_LOW:        | CxORAW low                                   |
| TMR_OUTPUT_CONTROL_SWITCH:     | Switch CxORAW level                          |
| TMR_OUTPUT_CONTROL_FORCE_LOW:  | CxORAW forced low                            |
| TMR_OUTPUT_CONTROL_FORCE_HIGH: | CxORAW forced high                           |
| TMR_OUTPUT_CONTROL_PWM_MODE_A: | PWM mode A                                   |
| TMR_OUTPUT_CONTROL_PWM_MODE_B: | PWM mode B                                   |

**Example:**

```
tmr_output_channel_mode_select(TMR1, TMR_SELECT_CHANNEL_1, TMR_OUTPUT_CONTROL_SWITCH);
```

## 5.23.16 tmr\_period\_value\_set function

The table below describes the function tmr\_period\_value\_set.

**Table 592. tmr\_period\_value\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_period_value_set   |
| Function prototype     | void tmr_period_value_set(tmr_type *tmr_x, uint32_t tmr_pr_value);   |
| Function description   | Set TMR period value   |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_pr_value: timer period value, 0x0000~0xFFFF for 16-bit timer and 0x0000_0000~0xFFFF_FFFF for 32-bit timer  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |

| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**Example:**

```
tmr_period_value_set(TMR1,0xFFFF);
```

### 5.23.17 tmr\_period\_value\_get function

The table below describes the function tmr\_period\_value\_get.

**Table 593. tmr\_period\_value\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_period_value_get   |
| Function prototype     | uint32_t tmr_period_value_get(tmr_type *tmr_x);  |
| Function description   | Get TMR period value   |
| Input parameter        | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Output parameter       | NA   |
| Return value           | Timer period value   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
uint32_t pr_value;  
pr_value = tmr_period_value_get(TMR1);
```

### 5.23.18 tmr\_channel\_value\_set function

The table below describes the function tmr\_channel\_value\_set.

**Table 594. tmr\_channel\_value\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_channel_value_set  |
| Function prototype     | void tmr_channel_value_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, uint32_t tmr_channel_value);                                  |
| Function description   | Set TMR channel value  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_channel: timer channel   |
| Input parameter 3      | tmr_channel_value: timer channel value, 0x0000~0xFFFF for 16-bit timer and 0x0000_0000~0xFFFF_FFFF for 32-bit timer                            |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_channel**

Set TMR channel



TMR\_SELECT\_CHANNEL\_1: Timer channel 1  
 TMR\_SELECT\_CHANNEL\_2: Timer channel 2  
 TMR\_SELECT\_CHANNEL\_3: Timer channel 3  
 TMR\_SELECT\_CHANNEL\_4: Timer channel 4  
 TMR\_SELECT\_CHANNEL\_5: Timer channel 5

**Example:**

```
tmr_channel_value_set(TMR1, TMR_SELECT_CHANNEL_1, 0xFFFF);
```

### 5.23.19 tmr\_channel\_value\_get function

The table below describes the function `tmr_channel_value_get`.

**Table 595. tmr\_channel\_value\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_channel_value_get</code>   |
| Function prototype     | <code>uint32_t tmr_channel_value_get(tmr_type *tmr_x, tmr_channel_select_type tmr_channel);</code>   |
| Function description   | Get TMR channel value  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>tmr_channel</code> : timer channel   |
| Output parameter       | Timer channel value  |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_channel**

Set TMR channel

TMR\_SELECT\_CHANNEL\_1: Timer channel 1  
 TMR\_SELECT\_CHANNEL\_2: Timer channel 2  
 TMR\_SELECT\_CHANNEL\_3: Timer channel 3  
 TMR\_SELECT\_CHANNEL\_4: Timer channel 4  
 TMR\_SELECT\_CHANNEL\_5: Timer channel 5

**Example:**

```
uint32_t ch_value;  
ch_value = tmr_channel_value_get(TMR1, TMR_SELECT_CHANNEL_1);
```

### 5.23.20 tmr\_period\_buffer\_enable function

The table below describes the function `tmr_period_buffer_enable`.

**Table 596. tmr\_period\_buffer\_enable function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>tmr_period_buffer_enable</code>   |
| Function prototype   | <code>void tmr_period_buffer_enable(tmr_type *tmr_x, confirm_state new_state);</code> |
| Function description | Enable or disable TMR period buffer   |
| Input parameter 1    | <code>tmr_x</code> : selected TMR peripheral.   |

| Name                   | Description   |
|------------------------|---|
|                        | This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | new_state: indicates the status of period buffer.<br>It can be Enable (TRUE) or Disable (FALSE).                        |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
tmr_period_buffer_enable(TMR1, TRUE);
```

### 5.23.21 tmr\_output\_channel\_buffer\_enable function

The table below describes the function tmr\_output\_channel\_buffer\_enable.

**Table 597. tmr\_output\_channel\_buffer\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_output_channel_buffer_enable   |
| Function prototype     | void tmr_output_channel_buffer_enable(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, confirm_state new_state);                          |
| Function description   | Enable or disable TMR output channel buffer  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_channel: timer channel   |
| Input parameter 3      | new_state: indicates the status of output channel buffer.<br>It can be Enable (TRUE) or Disable (FALSE).                                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_channel**

Select a TMR channel.

TMR\_SELECT\_CHANNEL\_1: Timer channel 1  
 TMR\_SELECT\_CHANNEL\_2: Timer channel 2  
 TMR\_SELECT\_CHANNEL\_3: Timer channel 3  
 TMR\_SELECT\_CHANNEL\_4: Timer channel 4  
 TMR\_SELECT\_CHANNEL\_5: Timer channel 5

**Example:**

```
tmr_output_channel_buffer_enable(TMR1, TMR_SELECT_CHANNEL_1, TRUE);
```

### 5.23.22 tmr\_output\_channel\_immediately\_set function

The table below describes the function `tmr_output_channel_immediately_set`.

**Table 598. tmr\_output\_channel\_immediately\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_output_channel_immediately_set</code>  |
| Function prototype     | <code>void tmr_output_channel_immediately_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, confirm_state new_state);</code>                         |
| Function description   | Enable TMR output channel immediately  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>tmr_channel</code> : timer channel   |
| Input parameter 3      | <code>new_state</code> : indicates the status of output channel enable.<br>It can be Enable (TRUE) or Disable (FALSE).                                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### tmr\_channel

Select a TMR channel.

|                                     |                 |
|-------------------------------------|-----------------|
| <code>TMR_SELECT_CHANNEL_1</code> : | Timer channel 1 |
| <code>TMR_SELECT_CHANNEL_2</code> : | Timer channel 2 |
| <code>TMR_SELECT_CHANNEL_3</code> : | Timer channel 3 |
| <code>TMR_SELECT_CHANNEL_4</code> : | Timer channel 4 |
| <code>TMR_SELECT_CHANNEL_5</code> : | Timer channel 5 |

#### Example:

```
tmr_output_channel_immediately_set(TMR1, TMR_SELECT_CHANNEL_1, TRUE);
```

### 5.23.23 tmr\_output\_channel\_switch\_set function

The table below describes the function `tmr_output_channel_switch_set`.

**Table 599. tmr\_output\_channel\_switch\_set function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>tmr_output_channel_switch_set</code>   |
| Function prototype   | <code>void tmr_output_channel_switch_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, confirm_state new_state);</code>                              |
| Function description | Set TMR output channel switch  |
| Input parameter 1    | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2    | <code>tmr_channel</code> : timer channel   |
| Input parameter 3    | <code>new_state</code> : indicates the status of output channel switch.<br>It can be Enable (TRUE) or Disable (FALSE).                                       |
| Output parameter     | NA   |

| Name                   | Description |
|------------------------|-------------|
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**tmr\_channel**

Select a TMR channel.

|                       |                 |
|-----------------------|-----------------|
| TMR_SELECT_CHANNEL_1: | Timer channel 1 |
| TMR_SELECT_CHANNEL_2: | Timer channel 2 |
| TMR_SELECT_CHANNEL_3: | Timer channel 3 |
| TMR_SELECT_CHANNEL_4: | Timer channel 4 |
| TMR_SELECT_CHANNEL_5: | Timer channel 5 |

**Example:**

```
tmr_output_channel_switch_set(TMR1, TMR_SELECT_CHANNEL_1, TRUE);
```

### 5.23.24 tmr\_one\_cycle\_mode\_enable function

The table below describes the function `tmr_one_cycle_mode_enable`.

**Table 600. tmr\_one\_cycle\_mode\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_one_cycle_mode_enable</code>   |
| Function prototype     | <code>void tmr_one_cycle_mode_enable(tmr_type *tmr_x, confirm_state new_state);</code>   |
| Function description   | Enable or disable TMR one-cycle mode   |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>new_state</code> : indicates the status of one-cycle mode.<br>It can be Enable (TRUE) or Disable (FALSE).  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
tmr_one_cycle_mode_enable(TMR1, TRUE);
```

### 5.23.25 tmr\_32\_bit\_function\_enable function

The table below describes the function `tmr_32_bit_function_enable`.

**Table 601. tmr\_32\_bit\_function\_enable function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>tmr_32_bit_function_enable</code>   |
| Function prototype   | <code>void tmr_32_bit_function_enable(tmr_type *tmr_x, confirm_state new_state);</code> |
| Function description | Enable or disable TMR 32-bit mode (plus mode)   |
| Input parameter 1    | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR2 or TMR5.    |
| Input parameter 2    | <code>new_state</code> : the status of 32-bit mode                                      |

| Name                   | Description                                 |
|------------------------|---|
|                        | It can be Enable (TRUE) or Disable (FALSE). |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
tmr_32_bit_function_enable(TMR2, TRUE);
```

### 5.23.26 tmr\_overflow\_request\_source\_set function

The table below describes the function tmr\_overflow\_request\_source\_set.

**Table 602. tmr\_overflow\_request\_source\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_overflow_request_source_set  |
| Function prototype     | void tmr_overflow_request_source_set(tmr_type *tmr_x, confirm_state new_state);  |
| Function description   | Select TMR overflow event sources  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | new_state: indicates the overflow event source   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**new\_state**

Select an overflow event source

FALSE: Counter overflow, OVFSWTR being set, overflow event from slave mode timer controller

TRUE: Counter overflow only

**Example:**

```
tmr_overflow_request_source_set(TMR1, TRUE);
```

### 5.23.27 tmr\_overflow\_event\_disable function

The table below describes the function tmr\_overflow\_event\_disable.

**Table 603. tmr\_overflow\_event\_disable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | tmr_overflow_event_disable   |
| Function prototype   | void tmr_overflow_event_disable(tmr_type *tmr_x, confirm_state new_state);   |
| Function description | Enable or disable TMR overflow event generation  |
| Input parameter 1    | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2    | new_state: indicates the status of overflow event generation   |

| Name                   | Description |
|------------------------|-------------|
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**new\_state**

Select the status of overflow event generation

FALSE: Enable overflow event generation, which can be generated from the following

- Counter overflow
- Set OVFSWTR=1
- Overflow event from slave mode timer controller

TRUE: Disable overflow event generation

**Example:**

```
tmr_overflow_event_disable(TMR1, TRUE);
```

### 5.23.28 tmr\_input\_channel\_init function

The table below describes the function tmr\_input\_channel\_init.

**Table 604. tmr\_input\_channel\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_input_channel_init   |
| Function prototype     | void tmr_input_channel_init(tmr_type *tmr_x, tmr_input_config_type *input_struct, tmr_channel_input_divider_type divider_factor);              |
| Function description   | Initialize TMR input channel   |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | input_struct: tmr_input_config_type pointer  |
| Input parameter 3      | divider_factor: input channel frequency division factor  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_input\_config\_type structure**

The tmr\_input\_config\_type is defined in the at32f435\_437\_tmr.h.

typedef struct

```
{
    tmr_channel_select_type      input_channel_select;
    tmr_input_polarity_type      input_polarity_select;
    tmr_input_direction_mapped_type  input_mapped_select;
    uint8_t                      input_filter_value;
} tmr_input_config_type;
```

**input\_channel\_select**

Select a TMR input channel

TMR\_SELECT\_CHANNEL\_1: Timer channel 1

TMR\_SELECT\_CHANNEL\_2: Timer channel 2  
 TMR\_SELECT\_CHANNEL\_3: Timer channel 3  
 TMR\_SELECT\_CHANNEL\_4: Timer channel 4

**input\_polarity\_select**

Select the polarity of input channels.

TMR\_INPUT\_RISING\_EDGE: Rising edge  
 TMR\_INPUT\_FALLING\_EDGE: Falling edge  
 TMR\_INPUT\_BOTH\_EDGE: Both edges (rising edge and falling edge)

**input\_mapped\_select**

Select input channel mapping

TMR\_CC\_CHANNEL\_MAPPED\_DIRECT:  
 TMR input channels 1, 2, 3 and 4 are linked to C1IRAW, C2IRAW, C3IRAW and C4IRAW respectively

TMR\_CC\_CHANNEL\_MAPPED\_INDIRECT:  
 TMR input channels 1, 2, 3 and 4 are linked to C2IRAW, C1IRAW, C4IRAW and C3IRAW respectively

TMR\_CC\_CHANNEL\_MAPPED\_STI:  
 TMR input channel is mapped on STI

**input\_filter\_value**

Select an input channel filter value, ranging from 0x00 to 0x0F

**divider\_factor**

Select input channel frequency division factor

TMR\_CHANNEL\_INPUT\_DIV\_1: Divided by 1  
 TMR\_CHANNEL\_INPUT\_DIV\_2: Divided by 2  
 TMR\_CHANNEL\_INPUT\_DIV\_4: Divided by 4  
 TMR\_CHANNEL\_INPUT\_DIV\_8: Divided by 8

**Example:**

```

tmr_input_config_type tmr_input_config_struct;
tmr_input_config_struct.input_channel_select = TMR_SELECT_CHANNEL_2;
tmr_input_config_struct.input_mapped_select = TMR_CC_CHANNEL_MAPPED_DIRECT;
tmr_input_config_struct.input_polarity_select = TMR_INPUT_RISING_EDGE;
tmr_input_config_struct.input_filter_value = 0x00;
tmr_input_channel_init(TMR1, &tmr_input_config_struct, TMR_CHANNEL_INPUT_DIV_1);
    
```

### 5.23.29 tmr\_channel\_enable function

The table below describes the function tmr\_channel\_enable.

**Table 605. tmr\_channel\_enable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | tmr_channel_enable   |
| Function prototype   | void tmr_channel_enable(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, confirm_state new_state);  |
| Function description | Enable or disable TMR channels   |
| Input parameter 1    | tmr_x: selected TMR peripheral.<br><br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |

| Name                   | Description  |
|------------------------|--|
| Input parameter 2      | tmr_channel: timer channel   |
| Input parameter 3      | new_state: indicates the status of timer channel.<br>It can be Enable (TRUE) or Disable (FALSE). |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_channel**

Set TMR channel

|                        |                         |
|------------------------|-------------------------|
| TMR_SELECT_CHANNEL_1:  | Timer channel 1         |
| TMR_SELECT_CHANNEL_1C: | Complementary channel 1 |
| TMR_SELECT_CHANNEL_2:  | Timer channel 2         |
| TMR_SELECT_CHANNEL_2C: | Complementary channel 2 |
| TMR_SELECT_CHANNEL_3:  | Timer channel 3         |
| TMR_SELECT_CHANNEL_3C: | Complementary channel 3 |
| TMR_SELECT_CHANNEL_4:  | Timer channel 4         |

**Example:**

```
tmr_channel_enable(TMR1, TMR_SELECT_CHANNEL_1, TRUE);
```

### 5.23.30 tmr\_input\_channel\_filter\_set function

The table below describes the function tmr\_input\_channel\_filter\_set.

**Table 606. tmr\_input\_channel\_filter\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_input_channel_filter_set   |
| Function prototype     | void tmr_input_channel_filter_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, uint16_t filter_value);                                |
| Function description   | Set TMR input channel filter   |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_channel: timer channel   |
| Input parameter 3      | filter_value: set channel filter value, 0x00~0x0F  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_channel**

Select a TMR channel

|                       |                 |
|-----------------------|-----------------|
| TMR_SELECT_CHANNEL_1: | Timer channel 1 |
| TMR_SELECT_CHANNEL_2: | Timer channel 2 |
| TMR_SELECT_CHANNEL_3: | Timer channel 3 |
| TMR_SELECT_CHANNEL_4: | Timer channel 4 |

**Example:**



```
tmr_input_channel_filter_set(TMR1, TMR_SELECT_CHANNEL_1, 0x0F);
```

### 5.23.31 tmr\_pwm\_input\_config function

The table below describes the function `tmr_pwm_input_config`.

**Table 607. tmr\_pwm\_input\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_pwm_input_config</code>  |
| Function prototype     | <code>void tmr_pwm_input_config(tmr_type *tmr_x, tmr_input_config_type *input_struct, tmr_channel_input_divider_type divider_factor);</code>                 |
| Function description   | Configure TMR pwm input  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>input_struct</code> : <code>tmr_input_config_type</code> pointer   |
| Input parameter 3      | <code>divider_factor</code> : input channel frequency division factor  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **input\_struct**

`tmr_input_config_type` pointer; refer to [tmr\\_input\\_config\\_type](#) for details.

#### **divider\_factor**

Select input channel frequency division factor

TMR\_CHANNEL\_INPUT\_DIV\_1: Divided by 1

TMR\_CHANNEL\_INPUT\_DIV\_2: Divided by 2

TMR\_CHANNEL\_INPUT\_DIV\_4: Divided by 4

TMR\_CHANNEL\_INPUT\_DIV\_8: Divided by 8

#### **Example:**

```
tmr_input_config_type tmr_ic_init_structure;
tmr_ic_init_structure.input_filter_value = 0;
tmr_ic_init_structure.input_channel_select = TMR_SELECT_CHANNEL_2;
tmr_ic_init_structure.input_mapped_select = TMR_CC_CHANNEL_MAPPED_DIRECT;
tmr_ic_init_structure.input_polarity_select = TMR_INPUT_RISING_EDGE;
tmr_pwm_input_config(TMR1, &tmr_ic_init_structure, TMR_CHANNEL_INPUT_DIV_1);
```

### 5.23.32 tmr\_channel1\_input\_select function

The table below describes the function `tmr_channel1_input_select`.

**Table 608. tmr\_channel1\_input\_select function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>tmr_channel1_input_select</code>   |
| Function prototype   | <code>void tmr_channel1_input_select(tmr_type *tmr_x, tmr_channel1_input_connected_type ch1_connect);</code> |
| Function description | Select TMR channel 1 input   |

| Name                   | Description   |
|------------------------|---|
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8 or TMR20. |
| Input parameter 2      | ch1_connect: channel 1 input selection  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**ch1\_connect**

Select channel 1 input

TMR\_CHANNEL1\_CONNECTED\_C1IRAW: CH1 pin is connected to C1IRAW

TMR\_CHANNEL1\_2\_3\_CONNECTED\_C1IRAW\_XOR: Connect XOR results of CH1, CH2 and CH3 pins to C1IRAW

**Example:**

```
tmr_channel1_input_select(TMR1, TMR_CHANNEL1_2_3_CONNECTED_C1IRAW_XOR);
```

### 5.23.33 tmr\_input\_channel\_divider\_set function

The table below describes the function tmr\_input\_channel\_divider\_set.

**Table 609. tmr\_input\_channel\_divider\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_input_channel_divider_set  |
| Function prototype     | void tmr_input_channel_divider_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_channel_input_divider_type divider_factor);       |
| Function description   | Set TMR input channel divider  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_channel: timer channel   |
| Input parameter 3      | divider_factor: input channel frequency division factor  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_channel**

Select a TMR channel.

TMR\_SELECT\_CHANNEL\_1: Timer channel 1

TMR\_SELECT\_CHANNEL\_2: Timer channel 2

TMR\_SELECT\_CHANNEL\_3: Timer channel 3

TMR\_SELECT\_CHANNEL\_4: Timer channel 4

**divider\_factor**

Select input channel frequency division factor

TMR\_CHANNEL\_INPUT\_DIV\_1: Divided by 1

TMR\_CHANNEL\_INPUT\_DIV\_2: Divided by 2

TMR\_CHANNEL\_INPUT\_DIV\_4: Divided by 4

TMR\_CHANNEL\_INPUT\_DIV\_8: Divided by 8

**Example:**

```
tmr_input_channel_divider_set(TMR1, TMR_SELECT_CHANNEL_1, TMR_CHANNEL_INPUT_DIV_2);
```

### 5.23.34 tmr\_primary\_mode\_select function

The table below describes the function tmr\_primary\_mode\_select

**Table 610. tmr\_primary\_mode\_select function**

| Name                   | Description   |
|------------------------|---|
| Function name          | tmr_primary_mode_select   |
| Function prototype     | void tmr_primary_mode_select(tmr_type *tmr_x, tmr_primary_select_type primary_mode);                              |
| Function description   | Select TMR primary(master) mode   |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8 or TMR20. |
| Input parameter 2      | primary_mode: master mode   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**primary\_mode**

Select primary mode, that is, master timer output signal selection

- TMR\_PRIMARY\_SEL\_RESET: Reset
- TMR\_PRIMARY\_SEL\_ENABLE: Enable
- TMR\_PRIMARY\_SEL\_OVERFLOW: Overflow
- TMR\_PRIMARY\_SEL\_COMPARE: Compare pulse
- TMR\_PRIMARY\_SEL\_C1ORAW: C1ORAW
- TMR\_PRIMARY\_SEL\_C2ORAW: C2ORAW
- TMR\_PRIMARY\_SEL\_C3ORAW: C3ORAW
- TMR\_PRIMARY\_SEL\_C4ORAW: C4ORAW

**Example:**

```
tmr_primary_mode_select(TMR1, TMR_PRIMARY_SEL_RESET);
```

### 5.23.35 tmr\_sub\_mode\_select function

The table below describes the function tmr\_sub\_mode\_select.

**Table 611. tmr\_sub\_mode\_select function**

| Name                 | Description  |
|----------------------|--|
| Function name        | tmr_sub_mode_select  |
| Function prototype   | void tmr_sub_mode_select(tmr_type *tmr_x, tmr_sub_mode_select_type sub_mode);                            |
| Function description | Select TMR slave timer mode  |
| Input parameter 1    | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR12 |

| Name                   | Description                |
|------------------------|----------------------------|
|                        | or TMR20.                  |
| Input parameter 2      | sub_mode: slave timer mode |
| Output parameter       | NA                         |
| Return value           | NA                         |
| Required preconditions | NA                         |
| Called functions       | NA                         |

**primary\_mode**

Select slave timer modes.

|                                |                  |
|--------------------------------|------------------|
| TMR_SUB_MODE_DIABLE:           | Disable          |
| TMR_SUB_ENCODER_MODE_A:        | Encoder mode A   |
| TMR_SUB_ENCODER_MODE_B:        | Encoder mode B   |
| TMR_SUB_ENCODER_MODE_C:        | Encoder mode C   |
| TMR_SUB_RESET_MODE:            | Reset            |
| TMR_SUB_HANG_MODE:             | Suspend          |
| TMR_SUB_TRIGGER_MODE:          | Trigger          |
| TMR_SUB_EXTERNAL_CLOCK_MODE_A: | External clock A |

**Example:**

```
tmr_sub_mode_select(TMR1, TMR_SUB_HANG_MODE);
```

### 5.23.36 tmr\_channel\_dma\_select function

The table below describes the function tmr\_channel\_dma\_select.

**Table 612. tmr\_channel\_dma\_select function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_channel_dma_select   |
| Function prototype     | void tmr_channel_dma_select(tmr_type *tmr_x, tmr_dma_request_source_type cc_dma_select);                           |
| Function description   | Select TMR channel DMA request source  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR12 or TMR20. |
| Input parameter 2      | cc_dma_select: TMR channel DMA request source  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**cc\_dma\_select**

Select DMA request source for TMR channels

|                              |  |
|------------------------------|--|
| TMR_DMA_REQUEST_BY_CHANNEL:  | DMA request upon a channel event (CxIF = 1)    |
| TMR_DMA_REQUEST_BY_OVERFLOW: | DMA request upon an overflow event (OVFIF = 1) |

**Example:**

```
tmr_channel_dma_select(TMR1, TMR_DMA_REQUEST_BY_OVERFLOW);
```

### 5.23.37 tmr\_hall\_select function

The table below describes the function tmr\_hall\_select.

**Table 613. tmr\_hall\_select function**

| Name                   | Description   |
|------------------------|---|
| Function name          | tmr_hall_select   |
| Function prototype     | void tmr_hall_select(tmr_type *tmr_x, confirm_state new_state);               |
| Function description   | Select TMR hall mode  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR8 or TMR20. |
| Input parameter 2      | new_state: indicates the status of TMR hall mode                              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**new\_state**

Select the status of TMR hall mode in order to refresh channel control bit

FALSE: Refresh channel control bit through HALL

TRUE: Refresh channel control bit through HALL or the rising edge of TRGIN

**Example:**

```
tmr_hall_select(TMR1, TRUE);
```

### 5.23.38 tmr\_channel\_buffer\_enable function

The table below describes the function tmr\_channel\_buffer\_enable.

**Table 614. tmr\_channel\_buffer\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | tmr_channel_buffer_enable   |
| Function prototype     | void tmr_channel_buffer_enable(tmr_type *tmr_x, confirm_state new_state);                             |
| Function description   | Enable or disable TMR channel buffer  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR8 or TMR20.                         |
| Input parameter 2      | new_state: indicates the status of TMR channel buffer.<br>It can be Enable (TRUE) or Disable (FALSE). |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
tmr_channel_buffer_enable(TMR1, TRUE);
```

### 5.23.39 tmr\_trgout2\_enable function

The table below describes the function tmr\_trgout2\_enable.

**Table 615. tmr\_trgout2\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_trgout2_enable   |
| Function prototype     | void tmr_trgout2_enable(tmr_type *tmr_x, confirm_state new_state);   |
| Function description   | Enable or disable TMR trigger output2 signal   |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR8 or TMR20.                                  |
| Input parameter 2      | new_state: indicates the status of TMR trigger output 2 signal.<br>It can be Enable (TRUE) or Disable (FALSE). |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
tmr_trgout2_enable(TMR1, TRUE);
```

### 5.23.40 tmr\_trigger\_input\_select function

The table below describes the function tmr\_trigger\_input\_select.

**Table 616. tmr\_trigger\_input\_select function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_trigger_input_select   |
| Function prototype     | void tmr_trigger_input_select(tmr_type *tmr_x, sub_tmr_input_sel_type trigger_select);                             |
| Function description   | Select TMR slave timer trigger input   |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR12 or TMR20. |
| Input parameter 2      | trigger_select: TMR slave timer trigger input  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**trigger\_select**

select TMR slave timer trigger input.

- TMR\_SUB\_INPUT\_SEL\_IS0: Internal input 0
- TMR\_SUB\_INPUT\_SEL\_IS1: Internal input 1
- TMR\_SUB\_INPUT\_SEL\_IS2: Internal input 2
- TMR\_SUB\_INPUT\_SEL\_IS3: Internal input 3
- TMR\_SUB\_INPUT\_SEL\_C1INC: C1IRAW input detection
- TMR\_SUB\_INPUT\_SEL\_C1DF1: Filter input channel 1
- TMR\_SUB\_INPUT\_SEL\_C2DF2: Filter input channel 2

TMR\_SUB\_INPUT\_SEL\_EXTIN: External input channel EXT

**Example:**

```
tmr_trigger_input_select(TMR1, TMR_SUB_INPUT_SEL_IS0);
```

### 5.23.41 tmr\_sub\_sync\_mode\_set function

The table below describes the function tmr\_sub\_sync\_mode\_set.

**Table 617. tmr\_sub\_sync\_mode\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_sub_sync_mode_set  |
| Function prototype     | void tmr_sub_sync_mode_set(tmr_type *tmr_x, confirm_state new_state);  |
| Function description   | Set TMR slave timer synchronization mode   |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR12 or TMR20.     |
| Input parameter 2      | new_state: indicates the status of TMR slave timer synchronization mode<br>It can be Enable (TRUE) or Disable (FALSE). |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
tmr_sub_sync_mode_set(TMR1, TRUE);
```

### 5.23.42 tmr\_dma\_request\_enable function

The table below describes the function tmr\_dma\_request\_enable.

**Table 618. tmr\_dma\_request\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_dma_request_enable   |
| Function prototype     | void tmr_dma_request_enable(tmr_type *tmr_x, tmr_dma_request_type dma_request, confirm_state new_state);   |
| Function description   | Enable or disable TMR DMA request  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | dma_request: DMA request   |
| Input parameter 3      | new_state: indicates the status of DMA request<br>It can be Enable (TRUE) or Disable (FALSE).  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**dma\_request**

Select a DMA request

|                           |                            |
|---------------------------|----------------------------|
| TMR_OVERFLOW_DMA_REQUEST: | Overflow event DMA request |
| TMR_C1_DMA_REQUEST:       | Channel 1 DMA request      |
| TMR_C2_DMA_REQUEST:       | Channel 2 DMA request      |
| TMR_C3_DMA_REQUEST:       | Channel 3 DMA request      |
| TMR_C4_DMA_REQUEST:       | Channel 4 DMA request      |
| TMR_HALL_DMA_REQUEST:     | HALL event DMA request     |
| TMR_TRIGGER_DMA_REQUEST:  | Trigger event DMA request  |

**Example:**

```
tmr_dma_request_enable(TMR1, TMR_OVERFLOW_DMA_REQUEST, TRUE);
```

### 5.23.43 tmr\_interrupt\_enable function

The table below describes the function tmr\_interrupt\_enable.

**Table 619. tmr\_interrupt\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_interrupt_enable   |
| Function prototype     | void tmr_interrupt_enable(tmr_type *tmr_x, uint32_t tmr_interrupt, confirm_state new_state);   |
| Function description   | Enable or disable TMR interrupts   |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_interrupt: TMR interrupts  |
| Input parameter 3      | new_state: indicates the status of TMR interrupts<br>It can be Enable (TRUE) or Disable (FALSE).   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_interrupt**

Select a TMR interrupt

|                  |                           |
|------------------|---------------------------|
| TMR_OVF_INT:     | Overflow event interrupt  |
| TMR_C1_INT:      | Channel 1 event interrupt |
| TMR_C2_INT:      | Channel 2 event interrupt |
| TMR_C3_INT:      | Channel 3 event interrupt |
| TMR_C4_INT:      | Channel 4 event interrupt |
| TMR_HALL_INT:    | HALL event interrupt      |
| TMR_TRIGGER_INT: | Trigger event interrupt   |
| TMR_BRK_INT:     | Break event interrupt     |

**Example:**

```
tmr_interrupt_enable(TMR1, TMR_OVF_INT, TRUE);
```



### 5.23.44 tmr\_flag\_get function

The table below describes the function `tmr_flag_get`.

**Table 620. tmr\_flag\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_flag_get</code>  |
| Function prototype     | <code>flag_status_tmr_flag_get(tmr_type *tmr_x, uint32_t tmr_flag);</code>   |
| Function description   | Get flag status  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>tmr_flag</code> : flag selection<br>Refer to the “ <code>tmr_flag</code> ” description for details.  |
| Output parameter       | NA   |
| Return value           | <code>flag_status</code> : status of flag<br>Return SET or RESET.  |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **tmr\_flag**

This is used for flag selection, including

|                                      |                          |
|--------------------------------------|--------------------------|
| <code>TMR_OVF_FLAG</code> :          | Overflow interrupt flag  |
| <code>TMR_C1_FLAG</code> :           | Channel 1 interrupt flag |
| <code>TMR_C2_FLAG</code> :           | Channel 2 interrupt flag |
| <code>TMR_C3_FLAG</code> :           | Channel 3 interrupt flag |
| <code>TMR_C4_FLAG</code> :           | Channel 4 interrupt flag |
| <code>TMR_C5_FLAG</code> :           | Channel 5 interrupt flag |
| <code>TMR_HALL_FLAG</code> :         | HALL interrupt flag      |
| <code>TMR_TRIGGER_FLAG</code> :      | Trigger interrupt flag   |
| <code>TMR_BRK_FLAG</code> :          | Break interrupt flag     |
| <code>TMR_C1_RECAPTURE_FLAG</code> : | Channel 1 recapture flag |
| <code>TMR_C2_RECAPTURE_FLAG</code> : | Channel 2 recapture flag |
| <code>TMR_C3_RECAPTURE_FLAG</code> : | Channel 3 recapture flag |
| <code>TMR_C4_RECAPTURE_FLAG</code> : | Channel 4 recapture flag |

#### **Example:**

```
if(tmr_flag_get(TMR1, TMR_OVF_FLAG) != RESET)
```

### 5.23.45 tmr\_flag\_clear function

The table below describes the function `tmr_flag_clear`.

**Table 621. tmr\_flag\_clear function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>tmr_flag_clear</code>   |
| Function prototype   | <code>void tmr_flag_clear(tmr_type *tmr_x, uint32_t tmr_flag);</code> |
| Function description | Clear flag  |
| Input parameter 1    | <code>tmr_x</code> : selected TMR peripheral.                         |

| Name                   | Description   |
|------------------------|---|
|                        | This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_flag: flag selection<br>Refer to the “tmr_flag” description for details.  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
tmr_flag_clear(TMR1, TMR_OVF_FLAG);
```

### 5.23.46 tmr\_event\_sw\_trigger function

The table below describes the function tmr\_event\_sw\_trigger

**Table 622. tmr\_event\_sw\_trigger function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_event_sw_trigger   |
| Function prototype     | void tmr_event_sw_trigger(tmr_type *tmr_x, tmr_event_trigger_type tmr_event);  |
| Function description   | Software triggers TMR event  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR6, TMR7, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_event: select a TMR event  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_event**

Set TMR events triggered by software

|                      |                 |
|----------------------|-----------------|
| TMR_OVERFLOW_SWTRIG: | Overflow event  |
| TMR_C1_SWTRIG:       | Channel 1 event |
| TMR_C2_SWTRIG:       | Channel 2 event |
| TMR_C3_SWTRIG:       | Channel 3 event |
| TMR_C4_SWTRIG:       | Channel 4 event |
| TMR_HALL_SWTRIG:     | HALL event      |
| TMR_TRIGGER_SWTRIG:  | Trigger event   |
| TMR_BRK_SWTRIG:      | Break event     |

**Example:**

```
tmr_event_sw_trigger(TMR1, TMR_OVERFLOW_SWTRIG);
```

### 5.23.47 tmr\_output\_enable function

The table below describes the function tmr\_output\_enable.

**Table 623. tmr\_output\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | tmr_output_enable   |
| Function prototype     | void tmr_output_enable(tmr_type *tmr_x, confirm_state new_state);             |
| Function description   | Enable or disable TMR output  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR8 or TMR20. |
| Input parameter 2      | new_state: TMR output status<br>It can be Enable (TRUE) or Disable (FALSE).   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
tmr_output_enable(TMR1, TRUE);
```

### 5.23.48 tmr\_internal\_clock\_set function

The table below describes the function tmr\_internal\_clock\_set.

**Table 624. tmr\_internal\_clock\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | tmr_internal_clock_set   |
| Function prototype     | void tmr_internal_clock_set(tmr_type *tmr_x);  |
| Function description   | Set TMR internal clock   |
| Input parameter        | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR12 or TMR20. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
tmr_internal_clock_set(TMR1);
```

### 5.23.49 tmr\_output\_channel\_polarity\_set function

The table below describes the function tmr\_output\_channel\_polarity\_set.

**Table 625. tmr\_output\_channel\_polarity\_set function**

| Name               | Description   |
|--------------------|---|
| Function name      | tmr_output_channel_polarity_set   |
| Function prototype | void tmr_output_channel_polarity_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_polarity_active_type oc_polarity); |

| Name                   | Description  |
|------------------------|--|
| Function description   | Set TMR output channel polarity  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | tmr_channel: timer channel   |
| Input parameter 3      | oc_polarity: output channel polarity   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_channel**

Select a TMR channel.

|                        |                         |
|------------------------|-------------------------|
| TMR_SELECT_CHANNEL_1:  | Timer channel 1         |
| TMR_SELECT_CHANNEL_1C: | Complementary channel 1 |
| TMR_SELECT_CHANNEL_2:  | Timer channel 2         |
| TMR_SELECT_CHANNEL_2C: | Complementary channel 2 |
| TMR_SELECT_CHANNEL_3:  | Timer channel 3         |
| TMR_SELECT_CHANNEL_3C: | Complementary channel 3 |
| TMR_SELECT_CHANNEL_4:  | Timer channel 4         |

**oc\_polarity**

Select TMR channel polarity.

|                           |             |
|---------------------------|-------------|
| TMR_POLARITY_ACTIVE_HIGH: | Active high |
| TMR_POLARITY_ACTIVE_LOW:  | Active low  |

**Example:**

```
tmr_output_channel_polarity_set(TMR1, TMR_SELECT_CHANNEL_1, TMR_POLARITY_ACTIVE_HIGH);
```

### 5.23.50 tmr\_external\_clock\_config function

The table below describes the function tmr\_external\_clock\_config.

**Table 626. tmr\_external\_clock\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | tmr_external_clock_config   |
| Function prototype     | void tmr_external_clock_config(tmr_type *tmr_x, tmr_external_signal_divider_type es_divide, tmr_external_signal_polarity_type es_polarity, uint16_t es_filter); |
| Function description   | Configure TMR external clock  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8 or TMR20.   |
| Input parameter 2      | es_divide: external signal frequency division factor  |
| Input parameter 3      | es_polarity: external signal polarity   |
| Input parameter 4      | es_filter: external signal filter value, 0x00~0x0F  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**es\_divide**

Set TMR external signal frequency division factor

TMR\_ES\_FREQUENCY\_DIV\_1: Divided by 1

TMR\_ES\_FREQUENCY\_DIV\_2: Divided by 2

TMR\_ES\_FREQUENCY\_DIV\_4: Divided by 4

TMR\_ES\_FREQUENCY\_DIV\_8: Divided by 8

**es\_polarity**

Select TMR external signal polarity

TMR\_ES\_POLARITY\_NON\_INVERTED: High or rising edge

TMR\_ES\_POLARITY\_INVERTED: Low or falling edge

**Example:**

```
tmr_external_clock_config(TMR1, TMR_ES_FREQUENCY_DIV_1, TMR_ES_POLARITY_INVERTED, 0x0F);
```

### 5.23.51 tmr\_external\_clock\_mode1\_config function

The table below describes the function `tmr_external_clock_mode1_config`.

**Table 627. tmr\_external\_clock\_mode1\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_external_clock_mode1_config</code>   |
| Function prototype     | <code>void tmr_external_clock_mode1_config(tmr_type *tmr_x, tmr_external_signal_divider_type es_divide, tmr_external_signal_polarity_type es_polarity, uint16_t es_filter);</code> |
| Function description   | Configure TMR external clock mode 1 (corresponding to external mode A in the reference manual)   |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8 or TMR20.  |
| Input parameter 2      | <code>es_divide</code> : external signal frequency division factor   |
| Input parameter 3      | <code>es_polarity</code> : external signal polarity  |
| Input parameter 4      | <code>es_filter</code> : external signal filter value, 0x00~0x0F   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**es\_divide**

Set TMR external signal frequency division factor, refer to [es\\_divide](#) for details.

**es\_polarity**

Set TMR external signal polarity, refer to [es\\_polarity](#) for details.

**Example:**

```
tmr_external_clock_mode1_config(TMR1, TMR_ES_FREQUENCY_DIV_1, TMR_ES_POLARITY_INVERTED, 0x0F);
```

### 5.23.52 tmr\_external\_clock\_mode2\_config function

The table below describes the function `tmr_external_clock_mode2_config`.

**Table 628. tmr\_external\_clock\_mode2\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_external_clock_mode2_config</code>   |
| Function prototype     | <code>void tmr_external_clock_mode2_config(tmr_type *tmr_x, tmr_external_signal_divider_type es_divide, tmr_external_signal_polarity_type es_polarity, uint16_t es_filter);</code> |
| Function description   | Configure TMR external clock mode 2 (corresponding to external mode B in the reference manual)   |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8 or TMR20.  |
| Input parameter 2      | <code>es_divide</code> : external signal frequency division factor   |
| Input parameter 3      | <code>es_polarity</code> : external signal polarity  |
| Input parameter 4      | <code>es_filter</code> : external signal filter value, 0x00~0x0F   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **es\_divide**

Set TMR external signal frequency division factor, refer to [es\\_divide](#) for details.

#### **es\_polarity**

Set TMR external signal polarity, refer to [es\\_polarity](#) for details.

#### **Example:**

```
tmr_external_clock_mode2_config(TMR1, TMR_ES_FREQUENCY_DIV_1, TMR_ES_POLARITY_INVERTED, 0x0F);
```

### 5.23.53 tmr\_encoder\_mode\_config function

The table below describes the function `tmr_encoder_mode_config`.

**Table 629. tmr\_encoder\_mode\_config function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>tmr_encoder_mode_config</code>  |
| Function prototype   | <code>void tmr_encoder_mode_config(tmr_type *tmr_x, tmr_encoder_mode_type encoder_mode, tmr_input_polarity_type ic1_polarity, tmr_input_polarity_type ic2_polarity);</code> |
| Function description | Configure TMR encoder mode  |
| Input parameter 1    | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8 or TMR20.   |
| Input parameter 2    | <code>encoder_mode</code> : encoder mode  |
| Input parameter 3    | <code>ic1_polarity</code> : input channel 1 polarity  |
| Input parameter 4    | <code>ic2_polarity</code> : input channel 2 polarity  |
| Output parameter     | NA  |
| Return value         | NA  |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

**encoder\_mode**

Select a TMR encoder mode

TMR\_ENCODER\_MODE\_A: Encoder mode A

TMR\_ENCODER\_MODE\_B: Encoder mode B

TMR\_ENCODER\_MODE\_C: Encoder mode C

**ic1\_polarity**

Select TMR input channel 1 polarity

TMR\_INPUT\_RISING\_EDGE: Rising edge

TMR\_INPUT\_FALLING\_EDGE: Falling edge

TMR\_INPUT\_BOTH\_EDGE: Both edges (Rising edge and Falling edge)

**ic2\_polarity**

Select TMR input channel 2 polarity

TMR\_INPUT\_RISING\_EDGE: Rising edge

TMR\_INPUT\_FALLING\_EDGE: Falling edge

TMR\_INPUT\_BOTH\_EDGE: Both edges (Rising edge and Falling edge)

**Example:**

```
tmr_encoder_mode_config(TMR1, TMR_ENCODER_MODE_A, TMR_INPUT_RISING_EDGE,
TMR_INPUT_RISING_EDGE);
```

## 5.23.54 tmr\_force\_output\_set function

The table below describes the function `tmr_force_output_set`.

**Table 630. tmr\_force\_output\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_force_output_set</code>  |
| Function prototype     | <code>void tmr_force_output_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_force_output_type force_output);</code>                            |
| Function description   | Set TMR forced output  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8, TMR9, TMR10, TMR11, TMR12, TMR13, TMR14 or TMR20. |
| Input parameter 2      | <code>tmr_channel</code> : timer channel   |
| Input parameter 3      | <code>force_output</code> : forced output level  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**tmr\_channel**

Select a TMR channel

TMR\_SELECT\_CHANNEL\_1: Timer channel 1

TMR\_SELECT\_CHANNEL\_2: Timer channel 2

TMR\_SELECT\_CHANNEL\_3: Timer channel 3

TMR\_SELECT\_CHANNEL\_4: Timer channel 4  
 TMR\_SELECT\_CHANNEL\_5: Timer channel 5

**force\_output**

Forced output level of output channels

TMR\_FORCE\_OUTPUT\_HIGH: CxORAW forced high  
 TMR\_FORCE\_OUTPUT\_LOW: CxORAW forced low

**Example:**

```
tmr_force_output_set(TMR1, TMR_SELECT_CHANNEL_1, TMR_FORCE_OUTPUT_HIGH);
```

### 5.23.55 tmr\_dma\_control\_config function

The table below describes the function `tmr_dma_control_config`.

**Table 631. tmr\_dma\_control\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>tmr_dma_control_config</code>  |
| Function prototype     | <code>void tmr_dma_control_config(tmr_type *tmr_x, tmr_dma_transfer_length_type dma_length, tmr_dma_address_type dma_base_address);</code> |
| Function description   | Configure TMR DMA control  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR1, TMR2, TMR3, TMR4, TMR5, TMR8 or TMR20.                        |
| Input parameter 2      | <code>dma_length</code> : DMA transfer length  |
| Input parameter 3      | <code>dma_base_address</code> : DMA transfer offset address  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**dma\_length**

Set DAM transfer bytes, including

TMR\_DMA\_TRANSFER\_1BYTE: 1 byte  
 TMR\_DMA\_TRANSFER\_2BYTES: 2 bytes  
 TMR\_DMA\_TRANSFER\_3BYTES: 3 bytes

...

TMR\_DMA\_TRANSFER\_17BYTES: 17 bytes  
 TMR\_DMA\_TRANSFER\_18BYTES: 18 bytes

**dma\_base\_address**

Set DMA transfer offset address, starting from TMR control register 1, including

- TMR\_CTRL1\_ADDRESS
- TMR\_CTRL2\_ADDRESS
- TMR\_STCTRL\_ADDRESS
- TMR\_IDEN\_ADDRESS
- TMR\_ISTS\_ADDRESS
- TMR\_SWEVT\_ADDRESS
- TMR\_CM1\_ADDRESS
- TMR\_CM2\_ADDRESS
- TMR\_CCTRL\_ADDRESS
- TMR\_CVAL\_ADDRESS



TMR\_DIV\_ADDRESS  
TMR\_PR\_ADDRESS  
TMR\_RPR\_ADDRESS  
TMR\_C1DT\_ADDRESS  
TMR\_C2DT\_ADDRESS  
TMR\_C3DT\_ADDRESS  
TMR\_C4DT\_ADDRESS  
TMR\_BRK\_ADDRESS  
TMR\_DMACTRL\_ADDRESS

**Example:**

```
tmr_dma_control_config(TMR1, TMR_DMA_TRANSFER_8BYTES, TMR_CTRL1_ADDRESS);
```

### 5.23.56 tmr\_brkdt\_config function

The table below describes the function tmr\_brkdt\_config.

**Table 632. tmr\_brkdt\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | tmr_brkdt_config  |
| Function prototype     | void tmr_brkdt_config(tmr_type *tmr_x, tmr_brkdt_config_type *brkdt_struct);  |
| Function description   | Configure TMR break mode and dead time  |
| Input parameter 1      | tmr_x: selected TMR peripheral.<br>This parameter can be TMR1, TMR8 or TMR20. |
| Input parameter 2      | brkdt_struct: tmr_brkdt_config_type pointer                                   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**tmr\_brkdt\_config\_type structure**

The tmr\_brkdt\_config\_type is defined in the at32f435\_437\_tmr.h.

typedef struct

```
{
    uint8_t            deadtime;
    tmr_brk_polarity_type brk_polarity;
    tmr_wp_level_type wp_level;
    confirm_state      auto_output_enable;
    confirm_state      fcsoen_state;
    confirm_state      fcsodis_state;
    confirm_state      brk_enable;
} tmr_brkdt_config_type;
```

**deadtime**

Set dead time, ranging from 0x00 to 0xFF

**brk\_polarity**

Select break input polarity

TMR\_BRK\_INPUT\_ACTIVE\_LOW: Active low

TMR\_BRK\_INPUT\_ACTIVE\_HIGH: Active high

**wp\_level**

Set write protection level

TMR\_WP\_OFF: Write protection OFF

TMR\_WP\_LEVEL\_3:

Level 3 write protection, protecting the bits below:

- TMRx\_BRK: DTC, BRKEN, BRKV and AOEN
- TMRx\_CTRL2: CxIOS and CxCIOS

TMR\_WP\_LEVEL\_2:

Level 2 write protection, protecting the bits below in addition to level-3 protected bits:

- TMRx\_CCTRL: CxP and CxCP
- TMRx\_BRK: FCSODIS and FCSOEN

TMR\_WP\_LEVEL\_1:

Level 1 write protection, protecting the bits below in addition to level-2 protected bits:

- TMRx\_CMx: CxOCTRL and CxOBEN

**auto\_output\_enable**

Enable auto output, Enable (TRUE) or Disable (FALSE)

**fcsoen\_state**

Indicates the frozen status when main output is ON. It is used to configure the status of complementary output channels when timer is OFF and output is enabled (OEN=1).

FALSE: Disable CxOUT/CxCOUT output

TRUE: Enable CxOUT/CxCOUT output, inactive level

**fcsodis\_state**

Indicates the frozen status when main output is OFF. It is used to configure the status of complementary output channels when timer is OFF and output is disabled (OEN=0).

FALSE: Disable CxOUT/CxCOUT output

TRUE: Enable CxOUT/CxCOUT output, idle level

**brk\_enable**

Enable break feature, Enable (TRUE) or Disable (FALSE).

**Example:**

```

tmr_brkdt_config_type tmr_brkdt_config_struct;
tmr_brkdt_config_struct.brk_enable = TRUE;
tmr_brkdt_config_struct.auto_output_enable = TRUE;
tmr_brkdt_config_struct.deadtime = 0;
tmr_brkdt_config_struct.fcsodis_state = TRUE;
tmr_brkdt_config_struct.fcsoen_state = TRUE;
tmr_brkdt_config_struct.brk_polarity = TMR_BRK_INPUT_ACTIVE_HIGH;
tmr_brkdt_config_struct.wp_level = TMR_WP_OFF;
tmr_brkdt_config(TMR1, &tmr_brkdt_config_struct);
    
```

## 5.23.57 tmr\_iremap\_config function

The table below describes the function `tmr_iremap_config`.

**Table 633. tmr\_iremap\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>tmr_iremap_config</code>  |
| Function prototype     | <code>void tmr_iremap_config(tmr_type *tmr_x, tmr_input_remap_type input_remap);</code> |
| Function description   | Set TMR internal remapping  |
| Input parameter 1      | <code>tmr_x</code> : selected TMR peripheral.<br>This parameter can be TMR2 or TMR5.    |
| Input parameter 2      | <code>input_remap</code> : TMR input channel remap to be configured                     |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### **input\_remap**

Set TMR2 internal trigger 1 remapping and TMR5 channel 4 input remapping .

TMR2\_TMR8TRGOUT\_TMR5\_GPIO:

TMR2 is connected to TMR8\_TRGO output, and TMR5 is connected to GPIO

TMR2\_PTP\_TMR5\_ERTCCLK:

TMR2 is connected to Ethernet PTP output, and TMR5 is connected to LICK

TMR2\_OTG1FS\_TMR5\_LEXT:

TMR2 is connected to OTG1\_FS\_SOF, and TMR5 is connected to LEXT

TMR2\_OTG2FS\_TMR5\_ERTC:

TMR2 is connected to OTG2\_FS\_SOF, and TMR5 is connected to ERTC wakeup interrupt

### **Example:**

```
tmr_iremap_config(TMR2, TMR2_TMR8TRGOUT_TMR5_GPIO);
```

## 5.24 Universal synchronous/asynchronous receiver/transmitter (USART)

The USART register structure `usart_type` is defined in the “at32f435\_437\_usart.h”.

```
/**
 * @brief type define usart register all
 */
typedef struct
{
    ...
} usart_type;
```

The table below gives a list of USART registers.

**Table 634. Summary of USART registers**

| Register | Description                     |
|----------|---------------------------------|
| sts      | Status register                 |
| dt       | Data register                   |
| baudr    | Baud rate register              |
| ctrl1    | Control register 1              |
| ctrl2    | Control register 2              |
| ctrl3    | Control register 3              |
| gdiv     | Guard time and divider register |

The table below gives a list of USART library functions.

**Table 635. Summary of USART library functions**

| Function name                              | Description                                       |
|--|---|
| <code>usart_reset</code>                   | Reset USART peripheral registers                  |
| <code>usart_init</code>                    | Set baud rate, data bits and stop bits            |
| <code>usart_parity_selection_config</code> | Parity selection                                  |
| <code>usart_enable</code>                  | Enable USART peripherals                          |
| <code>usart_transmitter_enable</code>      | Enable USART transmitter                          |
| <code>usart_receiver_enable</code>         | Enable USART receiver                             |
| <code>usart_clock_config</code>            | Set clock polarity and phases for synchronization |
| <code>usart_clock_enable</code>            | Set clock output for synchronization              |
| <code>usart_interrupt_enable</code>        | Enable interrupts                                 |
| <code>usart_dma_transmitter_enable</code>  | Enable DMA transmitter                            |
| <code>usart_dma_receiver_enable</code>     | Enable DMA receiver                               |
| <code>usart_wakeup_id_set</code>           | Set wakeup ID                                     |
| <code>usart_wakeup_mode_set</code>         | Set wakeup mode                                   |
| <code>usart_receiver_mute_enable</code>    | Enable receiver mute mode                         |
| <code>usart_break_bit_num_set</code>       | Set break frame length                            |
| <code>usart_lin_mode_enable</code>         | Enable LIN mode                                   |
| <code>usart_data_transmit</code>           | Data transmit                                     |

|                                     |   |
|-------------------------------------|---|
| usart_data_receive                  | Data receive  |
| usart_break_send                    | Send break frame  |
| usart_smartcard_guard_time_set      | Set smartcard guard time  |
| usart_irda_smartcard_division_set   | Set infrared and smartcard division                                       |
| usart_smartcard_mode_enable         | Enable smartcard mode   |
| usart_smartcard_nack_set            | Enable smartcard NACK   |
| usart_single_line_halfduplex_select | Enable single-wire half-duplexmode  |
| usart_irda_mode_enable              | Enable infrared mode  |
| usart_irda_low_power_enable         | Enable infrared low-power mode  |
| usart_hardware_flow_control_set     | Enable hardware flow control  |
| usart_flag_get                      | Get flag  |
| usart_flag_clear                    | Clear flag  |
| usart_rs485_delay_time_config       | Set latency for starting or ending consecutive data transmission in RS485 |
| usart_transmit_receive_pin_swap     | Swap transmit/receive pins  |
| usart_id_bit_num_set                | Set ID bit count  |
| usart_de_polarity_set               | DE signal polarity selection  |
| usart_rs485_mode_enable             | RS485 mode enable   |

### 5.24.1 usart\_reset function

The table below describes the function usart\_reset.

**Table 636. usart\_reset function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_reset   |
| Function prototype     | void usart_reset(usart_type* usart_x);                                  |
| Function description   | Reset USART peripheral registers  |
| Input parameter 1      | usart_x: selected peripherals.<br>It can be USART1, USART2 or USART3... |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | crm_periph_reset  |

**Example:**

```
/* reset usart1 */
usart_reset(USART1);
```

## 5.24.2 usart\_init function

The table below describes the function usart\_init.

**Table 637. usart\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_init  |
| Function prototype     | void usart_init(usart_type* usart_x, uint32_t baud_rate, usart_data_bit_num_type data_bit, usart_stop_bit_num_type stop_bit); |
| Function description   | Set baud rate, data bits and stop bits.   |
| Input parameter 1      | usart_x: selected peripherals.<br>It can be USART1, USART2 or USART3...   |
| Input parameter 2      | baud_rate: baud rate for serial interfaces  |
| Input parameter 3      | data_bit: data bit width for serial interfaces  |
| Input parameter 4      | stop_bit: stop bit width for serial interfaces  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | This operation can be allowed only when external low-speed clock is disabled.   |
| Called functions       | NA  |

### data\_bit

Select data bit size for serial interface communication

USART\_DATA\_8BITS: 8-bit

USART\_DATA\_9BITS: 9-bit

### stop\_bit

Select stop bit size for serial interface communication

USART\_STOP\_1\_BIT: 1-bit

USART\_STOP\_0\_5\_BIT: 0.5-bit

USART\_STOP\_2\_BIT: 2-bit

USART\_STOP\_1\_5\_BIT: 1.5-bit

### Example:

```
/* configure uart param */
usart_init(USART1, 115200, USART_DATA_8BITS, USART_STOP_1_BIT);
```

## 5.24.3 usart\_parity\_selection\_config function

The table below describes the function usart\_parity\_selection\_config.

**Table 638. usart\_parity\_selection\_config function**

| Name                 | Description  |
|----------------------|--|
| Function name        | usart_parity_selection_config  |
| Function prototype   | void usart_parity_selection_config(usart_type* usart_x, usart_parity_selection_type parity); |
| Function description | Parity selection   |
| Input parameter 1    | usart_x: selected peripheral.<br>It can be USART1, USART2 or USART3...                       |
| Input parameter 2    | parity: parity mode for serial interface communication                                       |
| Output parameter     | NA   |

| Name                   | Description |
|------------------------|-------------|
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**parity**

Select parity mode for serial interface communication

USART\_PARITY\_NONE: No parity

USART\_PARITY\_EVEN: Even

USART\_PARITY\_ODD: Odd

**Example:**

```
/* config usart even parity */
usart_parity_selection_config(USART1, USART_PARITY_EVEN);
```

### 5.24.4 usart\_enable function

The table below describes the function usart\_enable.

**Table 639. usart\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | usart_enable   |
| Function prototype     | void usart_enable(usart_type* usart_x, confirm_state new_state);       |
| Function description   | Enable USART   |
| Input parameter 1      | usart_x: selected peripheral.<br>It can be USART1, USART2 or USART3... |
| Input parameter 2      | new_state: Enable (TRUE) and disable (FALSE)                           |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable usart1 */
usart_enable(USART1, TRUE);
```

### 5.24.5 usart\_transmitter\_enable function

The table below describes the function usart\_transmitter\_enable.

**Table 640. usart\_transmitter\_enable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | usart_transmitter_enable   |
| Function prototype   | void usart_transmitter_enable(usart_type* usart_x, confirm_state new_state); |
| Function description | Enable USART transmitter   |
| Input parameter 1    | usart_x: selected peripheral.<br>It can be USART1, USART2 or USART3...       |
| Input parameter 2    | new_state: Enable (TRUE) and disable (FALSE)                                 |
| Output parameter     | NA   |
| Return value         | NA   |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

```
/* enable usart1 transmitter */
usart_transmitter_enable(USART1, TRUE);
```

### 5.24.6 usart\_receiver\_enable function

The table below describes the function usart\_receiver\_enable.

**Table 641. usart\_receiver\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_receiver_enable   |
| Function prototype     | void usart_receiver_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable USART receiver   |
| Input parameter 1      | usart_x: selected peripheral.<br>It can be USART1, USART2 or USART3...    |
| Input parameter 2      | new_state: Enable (TRUE) and disable (FALSE)                              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable usart1 receiver */
usart_receiver_enable(USART1, TRUE);
```

### 5.24.7 usart\_clock\_config function

The table below describes the function usart\_clock\_config.

**Table 642. usart\_clock\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_clock_config  |
| Function prototype     | void usart_clock_config(usart_type* usart_x, usart_clock_polarity_type clk_pol, usart_clock_phase_type clk pha, usart_lbc_type clk_lb); |
| Function description   | Configure clock polarity and phase for synchronization feature  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...   |
| Input parameter 2      | clk_pol: clock polarity for synchronization   |
| Input parameter 3      | clk pha: clock phase for synchronization  |
| Input parameter 4      | clk_lb: selects whether to output clock on the last bit (upper bit) of data sent through synchronization feature                        |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**clk\_pol**



Clock polarity selection

USART\_CLOCK\_POLARITY\_LOW: Low

USART\_CLOCK\_POLARITY\_HIGH: High

**clk\_pha**

Clock phase selection

USART\_CLOCK\_PHASE\_1EDGE: 1<sup>st</sup> edge

USART\_CLOCK\_PHASE\_2EDGE: 2<sup>nd</sup> edge

**clk\_lb**

Select whether to output clock on the last bit of data

USART\_CLOCK\_LAST\_BIT\_NONE: No clock output

USART\_CLOCK\_LAST\_BIT\_OUTPUT: Clock output

**Example:**

```
/* config synchronous mode */
usart_clock_config(USART1, USART_CLOCK_POLARITY_HIGH, USART_CLOCK_PHASE_2EDGE,
USART_CLOCK_LAST_BIT_OUTPUT);
```

### 5.24.8 usart\_clock\_enable function

The table below describes the function usart\_clock\_enable.

**Table 643. usart\_clock\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | usart_clock_enable   |
| Function prototype     | void usart_clock_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable clock output  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...    |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                            |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable clock */
usart_clock_enable(USART1, TRUE);
```

### 5.24.9 usart\_interrupt\_enable function

The table below describes the function usart\_interrupt\_enable.

**Table 644. usart\_interrupt\_enable function**

| Name                 | Description  |
|----------------------|--|
| Function name        | usart_interrupt_enable   |
| Function prototype   | void usart_interrupt_enable(usart_type* usart_x, uint32_t usart_int, confirm_state new_state); |
| Function description | Enable interrupts  |
| Input parameter 1    | usart_x: selected peripheral. It can be USART1, USART2 or USART3...                            |
| Input parameter 2    | usart_int: interrupt type  |

| Name                   | Description                                 |
|------------------------|---|
| Input parameter 3      | new_state: enable (TRUE) or disable (FALSE) |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**usart\_int**

Select a peripheral interrupt

|                  |                            |
|------------------|----------------------------|
| USART_IDLE_INT:  | Bus idle                   |
| USART_RDBF_INT:  | Receive data buff full     |
| USART_TDC_INT:   | Transmit data complete     |
| USART_TDBE_INT:  | Transmit data buff empty   |
| USART_PERR_INT:  | Parity error               |
| USART_BF_INT:    | Break frame receive        |
| USART_ERR_INT:   | Error interrupt            |
| USART_CTSCF_INT: | CTS (Clear To Send) change |

**Example:**

```
/* enable usart1 transmit complete interrupt*/
usart_interrupt_enable (USART1, USART_TDC_INT, TRUE);
```

### 5.24.10 usart\_dma\_transmitter\_enable function

The table below describes the function usart\_dma\_transmitter\_enable.

**Table 645. usart\_dma\_transmitter\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | usart_dma_transmitter_enable   |
| Function prototype     | void usart_dma_transmitter_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable DMA transmitter   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...              |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                                      |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable dma transmitter*/
usart_dma_transmitter_enable (USART1, TRUE);
```

### 5.24.11 usart\_dma\_receiver\_enable function

The table below describes the function usart\_dma\_receiver\_enable.

**Table 646. usart\_dma\_receiver\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_dma_receiver_enable   |
| Function prototype     | void usart_dma_receiver_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable DMA receiver   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...           |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                                   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable dma receiver */
usart_dma_receiver_enable (USART1, TRUE);
```

### 5.24.12 usart\_wakeup\_id\_set function

The table below describes the function usart\_wakeup\_id\_set.

**Table 647. usart\_wakeup\_id\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_wakeup_id_set   |
| Function prototype     | void usart_wakeup_id_set(usart_type* usart_x, uint8_t usart_id);    |
| Function description   | Set wakeup ID   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3... |
| Input parameter 2      | usart_id: wakeup ID   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* config wakeup id */
usart_wakeup_id_set (USART1, 0x88);
```

### 5.24.13 usart\_wakeup\_mode\_set function

The table below describes the function usart\_wakeup\_mode\_set.

**Table 648. usart\_wakeup\_mode\_set function**

| Name               | Description  |
|--------------------|--|
| Function name      | usart_wakeup_mode_set  |
| Function prototype | void usart_wakeup_mode_set(usart_type* usart_x, usart_wakeup_mode_type wakeup_mode); |

| Name                   | Description   |
|------------------------|---|
| Function description   | Set wakeup mode   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3... |
| Input parameter 2      | wakeup_mode: wakeup mode  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**wakeup\_mode**

Set wakeup mode to wake up from silent state

USART\_WAKEUP\_BY\_IDLE\_FRAME:           Woke up by idle frame

USART\_WAKEUP\_BY\_MATCHING\_ID:        Woke up by ID matching

**Example:**

```
/* config usart1 wakeup mode */
usart_wakeup_mode_set(USART1, USART_WAKEUP_BY_MATCHING_ID);
```

### 5.24.14 usart\_receiver\_mute\_enable function

The table below describes the function usart\_receiver\_mute\_enable.

**Table 649. usart\_receiver\_mute\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | usart_receiver_mute_enable   |
| Function prototype     | void usart_receiver_mute_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable USART receiver mute mode  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...            |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                                    |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* config receiver mute */
usart_receiver_mute_enable(USART1, TRUE);
```

### 5.24.15 usart\_break\_bit\_num\_set function

The table below describes the function usart\_break\_bit\_num\_set.

**Table 650. usart\_break\_bit\_num\_set function**

| Name                 | Description  |
|----------------------|--|
| Function name        | usart_break_bit_num_set  |
| Function prototype   | void usart_break_bit_num_set(usart_type* usart_x, usart_break_bit_num_type break_bit); |
| Function description | Set USART break frame length   |
| Input parameter 1    | usart_x: selected peripheral. It can be USART1, USART2 or USART3...                    |
| Input parameter 2    | break_bit: break frame length type   |

| Name                   | Description |
|------------------------|-------------|
| Output parameter       | NA          |
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**break\_bit**

Set break frame length

USART\_BREAK\_10BITS: 10 bits

USART\_BREAK\_11BITS: 11 bits

**Example:**

```
/* config break frame length 10bits */
usart_break_bit_num_set(USART1, USART_BREAK_10BITS);
```

### 5.24.16 usart\_lin\_mode\_enable function

The table below describes the function usart\_lin\_mode\_enable.

**Table 651. usart\_lin\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_lin_mode_enable   |
| Function prototype     | void usart_lin_mode_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable LIN mode   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...       |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                               |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable usart1 lin mode */
usart_lin_mode_enable (USART1, TRUE);
```

### 5.24.17 usart\_data\_transmit function

The table below describes the function usart\_data\_transmit.

**Table 652. usart\_data\_transmit function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_data_transmit   |
| Function prototype     | void usart_data_transmit(usart_type* usart_x, uint16_t data);       |
| Function description   | Transmit data   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3... |
| Input parameter 2      | data: data to send  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* transmit data */
uint16_t data = 0x88;
usart_data_transmit(USART1, data);

```

## 5.24.18 usart\_data\_receive function

The table below describes the function usart\_data\_receive.

**Table 653. usart\_data\_receive function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_data_receive  |
| Function prototype     | uint16_t usart_data_receive(usart_type* usart_x);                   |
| Function description   | Receive data  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3... |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | uint16_t: return the received data                                  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* receive data */
uint16_t data = 0;
data = usart_data_receive(USART1);

```

## 5.24.19 usart\_break\_send function

The table below describes the function usart\_break\_send.

**Table 654. usart\_break\_send function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_break_send  |
| Function prototype     | void usart_break_send(usart_type* usart_x);                         |
| Function description   | Send break frame  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3... |
| Input parameter 2      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* send break frame */
usart_break_send(USART1);

```

## 5.24.20 usart\_smartcard\_guard\_time\_set function

The table below describes the function usart\_smartcard\_guard\_time\_set.

**Table 655. usart\_smartcard\_guard\_time\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_smartcard_guard_time_set  |
| Function prototype     | void usart_smartcard_guard_time_set(usart_type* usart_x, uint8_t guard_time_val); |
| Function description   | Set smartcard guard time  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...               |
| Input parameter 2      | guard_time_val: guard time, 0x00~0xFF   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* usart guard time set to 2 bit */
usart_smartcard_guard_time_set(USART1, 0x2);
```

## 5.24.21 usart\_irda\_smartcard\_division\_set function

The table below describes the function usart\_irda\_smartcard\_division\_set.

**Table 656. usart\_irda\_smartcard\_division\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_irda_smartcard_division_set   |
| Function prototype     | void usart_irda_smartcard_division_set(usart_type* usart_x, uint8_t div_val); |
| Function description   | Infrared and smartcard frequency division settings                            |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...           |
| Input parameter 2      | div_val: division value   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* usart clock set to (apbclk / (2 * 20)) */
usart_irda_smartcard_division_set(USART1, 20);
```

### 5.24.22 usart\_smartcard\_mode\_enable function

The table below describes the function usart\_smartcard\_mode\_enable.

**Table 657. usart\_smartcard\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_smartcard_mode_enable   |
| Function prototype     | void usart_smartcard_mode_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable smartcode mode   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...             |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                                     |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable the smartcard mode */
usart_smartcard_mode_enable(USART1, TRUE);
```

### 5.24.23 usart\_smartcard\_nack\_set function

The table below describes the function usart\_smartcard\_nack\_set.

**Table 658. usart\_smartcard\_nack\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | usart_smartcard_nack_set   |
| Function prototype     | void usart_smartcard_nack_set(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable smartcard NACK  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...          |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                                  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable the nack transmission */
usart_smartcard_nack_set(USART1, TRUE);
```



### 5.24.24 usart\_single\_line\_halfduplex\_select function

The table below describes the function usart\_single\_line\_halfduplex\_select.

**Table 659. usart\_single\_line\_halfduplex\_select function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_single_line_halfduplex_select   |
| Function prototype     | void usart_single_line_halfduplex_select(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable single-wire half-duplex mode   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...                     |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable halfduplex */
usart_single_line_halfduplex_select(USART1, TRUE);
```

### 5.24.25 usart\_irda\_mode\_enable function

The table below describes the function usart\_irda\_mode\_enable.

**Table 660. usart\_irda\_mode\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | usart_irda_mode_enable   |
| Function prototype     | void usart_irda_mode_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable infrared mode   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...        |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                                |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* enable irda mode */
usart_irda_mode_enable(USART1, TRUE);
```

## 5.24.26 usart\_irda\_low\_power\_enable function

The table below describes the function usart\_irda\_low\_power\_enable.

**Table 661. usart\_irda\_low\_power\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_irda_low_power_enable   |
| Function prototype     | void usart_irda_low_power_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | Enable infrared low-power mode  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...             |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                                     |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable irda lowpower mode */
usart_irda_low_power_enable (USART1, TRUE);
```

## 5.24.27 usart\_hardware\_flow\_control\_set function

The table below describes the function usart\_hardware\_flow\_control\_set.

**Table 662. usart\_hardware\_flow\_control\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_hardware_flow_control_set   |
| Function prototype     | void usart_hardware_flow_control_set(usart_type* usart_x, usart_hardware_flow_control_type flow_state); |
| Function description   | Set peripheral hardware flow control  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...                                     |
| Input parameter 2      | flow_state: flow control type   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**flow\_state**

USART\_HARDWARE\_FLOW\_NONE: No hardware flow control  
 USART\_HARDWARE\_FLOW\_RTS: RTS  
 USART\_HARDWARE\_FLOW\_CTS: CTS  
 USART\_HARDWARE\_FLOW\_RTS\_CTS: RTS and CTS

**Example:**

```
/* hardware flow set none */
usart_hardware_flow_control_set (USART1, USART_HARDWARE_FLOW_NONE);
```

## 5.24.28 usart\_flag\_get function

The table below describes the function usart\_flag\_get.

**Table 663. usart\_flag\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_flag_get  |
| Function prototype     | flag_status usart_flag_get(usart_type* usart_x, uint32_t flag);     |
| Function description   | Get flag status   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3... |
| Input parameter 2      | flag: flag  |
| Output parameter       | NA  |
| Return value           | flag_status: SET or RESET   |
| Required preconditions | NA  |
| Called functions       | NA  |

### flag

|                   |                                 |
|-------------------|---------------------------------|
| USART_CTSCF_FLAG: | CTS (Clear To Send) change flag |
| USART_BFF_FLAG:   | Break frame receive flag        |
| USART_TDBE_FLAG:  | Transmit buff empty flag        |
| USART_TDC_FLAG:   | Transmit complete flag          |
| USART_RDBF_FLAG:  | Receive data buff full flag     |
| USART_IDLEF_FLAG: | Idle frame flag                 |
| USART_ROERR_FLAG: | Receive overflow flag           |
| USART_NERR_FLAG:  | Noise error flag                |
| USART_FERR_FLAG:  | Frame error flag                |
| USART_PERR_FLAG:  | Parity error flag               |

### Example:

```
/* wait data transmit complete flag */
while(usart_flag_get(USART1, USART_TDC_FLAG) == RESET);
```

## 5.24.29 usart\_flag\_clear function

The table below describes the function usart\_flag\_clear.

**Table 664. usart\_flag\_clear function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_flag_clear  |
| Function prototype     | void usart_flag_clear(usart_type* usart_x, uint32_t flag);          |
| Function description   | Clear flag  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3... |
| Input parameter 2      | flag: flag  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### flag

|                   |                                 |
|-------------------|---------------------------------|
| USART_CTSCF_FLAG: | CTS (Clear To Send) change flag |
|-------------------|---------------------------------|

USART\_BFF\_FLAG: Break frame receive flag  
 USART\_TDC\_FLAG: Transmit complete flag  
 USART\_RDBF\_FLAG: Receive data buff full flag

**Example:**

```

/* clear data transmit complete flag */
usart_flag_clear(USART1, USART_TDC_FLAG);
  
```

### 5.24.30 usart\_rs485\_delay\_time\_config function

The table below describes the function usart\_rs485\_delay\_time\_config.

**Table 665. usart\_rs485\_delay\_time\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_rs485_delay_time_config   |
| Function prototype     | void usart_rs485_delay_time_config(usart_type* usart_x, uint8_t start_delay_time, uint8_t complete_delay_time);   |
| Function description   | Delay time for setting and clearing data valid signal for continuous data transmission in RS485 mode  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...   |
| Input parameter 2      | start_delay_time: After the first data is written in continuous transmit mode, data valid signal is set and "start_delay_time" is inserted before sending data. The time unit is 1/16 baud rate period. |
| Input parameter 3      | complete_delay_time: After the last data is sent in continuous transmit mode, the "complete_delay_time" is inserted before clearing data valid signal. The time unit is 1/16 baud rate period.          |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```

/* config rs485 delaytime */
usart_rs485_delay_time_config(USART1, 2, 2);
  
```

### 5.24.31 usart\_transmit\_receive\_pin\_swap function

The table below describes the function usart\_transmit\_receive\_pin\_swap.

**Table 666. usart\_transmit\_receive\_pin\_swap function**

| Name                 | Description   |
|----------------------|---|
| Function name        | usart_transmit_receive_pin_swap   |
| Function prototype   | void usart_transmit_receive_pin_swap(usart_type* usart_x, confirm_state new_state); |
| Function description | Swap transmit/receive pins  |
| Input parameter 1    | usart_x: selected peripheral. It can be USART1, USART2 or USART3...                 |
| Input parameter 2    | new_state: enable (TRUE) or disable (FALSE)   |
| Output parameter     | NA  |
| Return value         | NA  |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

**Example:**

```
/* enable tx/rx swap */
usart_transmit_receive_pin_swap(USART1, TRUE);
```

### 5.24.32 usart\_id\_bit\_num\_set function

The table below describes the function usart\_id\_bit\_num\_set.

**Table 667. usart\_id\_bit\_num\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_id_bit_num_set  |
| Function prototype     | void usart_id_bit_num_set(usart_type* usart_x, usart_identification_bit_num_type id_bit_num); |
| Function description   | Set ID bit number   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...                           |
| Input parameter 2      | id_bit_num: ID bit number   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**id\_bit\_num**

USART\_ID\_FIXED\_4\_BIT: 4-bit ID  
 USART\_ID\_RELATED\_DATA\_BIT: Current data bit - 1

**Example:**

```
/* config ID bit width */
usart_id_bit_num_set(USART1, USART_ID_FIXED_4_BIT);
```

### 5.24.33 usart\_de\_polarity\_set function

The table below describes the function usart\_de\_polarity\_set.

**Table 668. usart\_de\_polarity\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | usart_de_polarity_set  |
| Function prototype     | void usart_de_polarity_set(usart_type* usart_x, usart_de_polarity_type de_polarity); |
| Function description   | DE signal polarityselection  |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...                  |
| Input parameter 2      | de_polarity: DE signal polarity  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**de\_polarity**

USART\_DE\_POLARITY\_HIGH: DE signal active high

USART\_DE\_POLARITY\_LOW: DE signal active low

**Example:**

```
/* config DE polarity */
usart_de_polarity_set(USART1, USART_DE_POLARITY_HIGH);
```

### 5.24.34 usart\_rs485\_mode\_enable function

The table below describes the function usart\_rs485\_mode\_enable.

**Table 669. usart\_rs485\_mode\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | usart_rs485_mode_enable   |
| Function prototype     | void usart_rs485_mode_enable(usart_type* usart_x, confirm_state new_state); |
| Function description   | RS485 mode enable   |
| Input parameter 1      | usart_x: selected peripheral. It can be USART1, USART2 or USART3...         |
| Input parameter 2      | new_state: enable (TRUE) or disable (FALSE)                                 |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/* enable rs485 mode */
usart_rs485_mode_enable (USART1, TRUE);
```

## 5.25 Watchdog timer (WDT)

The WDT register structure `wdt_type` is defined in the “`at32f435_437_wdt.h`”.

```
/**
 * @brief type define wdt register all
 */
typedef struct
{

} wdt_type;
```

The table below gives a list of WDT registers.

**Table 670. Summary of WDT registers**

| Register         | Description      |
|------------------|------------------|
| <code>cmd</code> | Command register |
| <code>div</code> | Divider register |
| <code>rl</code>  | Reload register  |
| <code>sts</code> | Status register  |
| <code>win</code> | Window register  |

The table below gives a list of WDT library functions.

**Table 671. Summary WDT library functions**

| Function name                          | Description   |
|--|---|
| <code>wdt_enable</code>                | Enable watchdog   |
| <code>wdt_counter_reload</code>        | Reload counter  |
| <code>wdt_reload_value_set</code>      | Set reload value  |
| <code>wdt_divider_set</code>           | Set division value  |
| <code>wdt_register_write_enable</code> | Unlock WDT_DIV, WDT_RLD and WDT_WIN register write protection |
| <code>wdt_flag_get</code>              | Get flag  |
| <code>wdt_window_counter_set</code>    | Set window value  |

### 5.25.1 `wdt_enable` function

The table below describes the function `wdt_enable`.

**Table 672. `wdt_enable` function**

| Name                   | Description                         |
|------------------------|-------------------------------------|
| Function name          | <code>wdt_enable</code>             |
| Function prototype     | <code>void wdt_enable(void);</code> |
| Function description   | Enable watchdog                     |
| Input parameter 1      | NA                                  |
| Output parameter       | NA                                  |
| Return value           | NA                                  |
| Required preconditions | NA                                  |

| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**Example:**

```
wdt_enable();
```

### 5.25.2 wdt\_counter\_reload function

The table below describes the function wdt\_counter\_reload.

**Table 673. wdt\_counter\_reload function**

| Name                   | Description                    |
|------------------------|--------------------------------|
| Function name          | wdt_counter_reload             |
| Function prototype     | void wdt_counter_reload(void); |
| Function description   | Reload counter                 |
| Input parameter 1      | NA                             |
| Output parameter       | NA                             |
| Return value           | NA                             |
| Required preconditions | NA                             |
| Called functions       | NA                             |

**Example:**

```
wdt_counter_reload();
```

### 5.25.3 wdt\_reload\_value\_set function

The table below describes the function wdt\_reload\_value\_set.

**Table 674. wdt\_reload\_value\_set function**

| Name                   | Description                                       |
|------------------------|---|
| Function name          | wdt_reload_value_set                              |
| Function prototype     | void wdt_reload_value_set(uint16_t reload_value); |
| Function description   | Set reload value                                  |
| Input parameter 1      | reload_value: reload value, 0x000~0xFFFF          |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
wdt_reload_value_set(0xFFFF);
```



### 5.25.4 wdt\_divider\_set function

The table below describes the function wdt\_divider\_set.

**Table 675. wdt\_divider\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | wdt_divider_set  |
| Function prototype     | void wdt_divider_set(wdt_division_type division);  |
| Function description   | Set division value   |
| Input parameter 1      | division: watchdog division value<br>Refer to the following "division" descriptions for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### division

Select watchdog division value

|                  |                |
|------------------|----------------|
| WDT_CLK_DIV_4:   | Divided by 4   |
| WDT_CLK_DIV_8:   | Divided by 8   |
| WDT_CLK_DIV_16:  | Divided by 16  |
| WDT_CLK_DIV_32:  | Divided by 32  |
| WDT_CLK_DIV_64:  | Divided by 64  |
| WDT_CLK_DIV_128: | Divided by 128 |
| WDT_CLK_DIV_256: | Divided by 256 |

#### Example:

```
wdt_divider_set(WDT_CLK_DIV_4);
```

### 5.25.5 wdt\_register\_write\_enable function

The table below describes the function wdt\_register\_write\_enable.

**Table 676. wdt\_register\_write\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | wdt_register_write_enable   |
| Function prototype     | void wdt_register_write_enable( confirm_state new_state);                           |
| Function description   | Unlock WDT_DIV, WDT_RLD and WDT_WIN write protection                                |
| Input parameter 1      | new_state: unlock register write protection<br>This parameter can be TRUE or FALSE. |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### Example:

```
wdt_register_write_enable(TRUE);
```

## 5.25.6 wdt\_flag\_get function

The table below describes the function wdt\_flag\_get.

**Table 677. wdt\_flag\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | wdt_flag_get   |
| Function prototype     | flag_status wdt_flag_get(uint16_t wdt_flag);                         |
| Function description   | Get flag status  |
| Input parameter 1      | flag: flag selection<br>Refer to the “flag” description for details. |
| Output parameter       | NA   |
| Return value           | flag_status: flag status<br>Return SET or RESET.                     |
| Required preconditions | NA   |
| Called functions       | NA   |

### flag

This is used for flag selection, including

WDT\_DIVF\_UPDATE\_FLAG: Division value update complete

WDT\_RLDF\_UPDATE\_FLAG: Reload value update complete

WDT\_WINF\_UPDATE\_FLAG: Window value update complete

### Example:

```
wdt_flag_get(WDT_DIVF_UPDATE_FLAG);
```

## 5.25.7 wdt\_window\_counter\_set function

The table below describes the function wdt\_window\_counter\_set.

**Table 678. wdt\_window\_counter\_set function**

| Name                   | Description                                       |
|------------------------|---|
| Function name          | wdt_window_counter_set                            |
| Function prototype     | void wdt_window_counter_set(uint16_t window_cnt); |
| Function description   | Set window value                                  |
| Input parameter 1      | window_cnt: window value, 0x000~0xFF              |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

### Example:

```
wdt_window_counter_set(0x7FF);
```

## 5.26 Window watchdog timer (WWDT)

The WWDT register structure `wwdt_type` is defined in the “`at32f435_437_wwdt.h`”.

```
/**
 * @brief type define wwdt register all
 */
typedef struct
{

} wwdt_type;
```

The table below gives a list of WWDT registers.

**Table 679. Summary of WWDT registers**

| Register | Description            |
|----------|------------------------|
| ctrl     | Control register       |
| cfg      | Configuration register |
| sts      | Status register        |

The table below gives a list of WWDT library functions.

**Table 680. Summary of WWDT library functions**

| Function name                        | Description                         |
|--------------------------------------|-------------------------------------|
| <code>wwdt_reset</code>              | Reset window watchdog registers     |
| <code>wwdt_divider_set</code>        | Set divider                         |
| <code>wwdt_flag_clear</code>         | Clear reload counter interrupt flag |
| <code>wwdt_enable</code>             | Enable WWDT                         |
| <code>wwdt_interrupt_enable</code>   | Enable reload counter interrupt     |
| <code>wwdt_flag_get</code>           | Get flag                            |
| <code>wwdt_counter_set</code>        | Set counter value                   |
| <code>wwdt_window_counter_set</code> | Set window value                    |

### 5.26.1 `wwdt_reset` function

The table below describes the function `wwdt_reset`.

**Table 681. `wwdt_reset` function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>wwdt_reset</code>   |
| Function prototype     | <code>void wwdt_reset(void);</code>   |
| Function description   | Reset window watchdog registers to their initial values                                   |
| Input parameter 1      | NA  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | <code>void crm_periph_reset(crm_periph_reset_type value, confirm_state new_state);</code> |

**Example:**

```
wwdt_reset();
```

## 5.26.2 wwdt\_divider\_set function

The table below describes the function `wwdt_divider_set`.

**Table 682. wwdt\_divider\_set function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>wwdt_divider_set</code>  |
| Function prototype     | <code>void wwdt_divider_set(wwdt_division_type division);</code>                             |
| Function description   | Set divider  |
| Input parameter 1      | division: WWDT division value<br>Refer to the following "division" descriptions for details. |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**division**

Select WWDT division value

WWDT\_PCLK1\_DIV\_4096: Divided by 4096

WWDT\_PCLK1\_DIV\_8192: Divided by 8192

WWDT\_PCLK1\_DIV\_16384: Divided by 16384

WWDT\_PCLK1\_DIV\_32768: Divided by 32768

**Example:**

```
wwdt_divider_set(WWDT_PCLK1_DIV_4096);
```

## 5.26.3 wwdt\_enable function

The table below describes the function `wwdt_enable`.

**Table 683. wwdt\_enable function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>wwdt_enable</code>                                      |
| Function prototype     | <code>void wwdt_enable(uint8_t wwdt_cnt);</code>              |
| Function description   | Enable WWDT   |
| Input parameter 1      | <code>wwdt_cnt</code> : WWDT counter initial value, 0x40~0x7F |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
wwdt_enable(0x7F);
```

### 5.26.4 wwdt\_interrupt\_enable function

The table below describes the function wwdt\_interrupt\_enable.

**Table 684. wwdt\_interrupt\_enable function**

| Name                   | Description                       |
|------------------------|-----------------------------------|
| Function name          | wwdt_interrupt_enable             |
| Function prototype     | void wwdt_interrupt_enable(void); |
| Function description   | Enable reload counter interrupt   |
| Input parameter 1      | NA                                |
| Output parameter       | NA                                |
| Return value           | NA                                |
| Required preconditions | NA                                |
| Called functions       | NA                                |

**Example:**

```
wwdt_interrupt_enable();
```

### 5.26.5 wwdt\_counter\_set function

The table below describes the function wwdt\_counter\_set.

**Table 685. wwdt\_counter\_set function**

| Name                   | Description                              |
|------------------------|--|
| Function name          | wwdt_counter_set                         |
| Function prototype     | void wwdt_counter_set(uint8_t wwdt_cnt); |
| Function description   | Set counter value                        |
| Input parameter 1      | wwdt_cnt: WWDT counter value, 0x40~0x7F  |
| Output parameter       | NA                                       |
| Return value           | NA                                       |
| Required preconditions | NA                                       |
| Called functions       | NA                                       |

**Example:**

```
wwdt_counter_set(0x7F);
```

### 5.26.6 wwdt\_window\_counter\_set function

The table below describes the function wwdt\_window\_counter\_set.

**Table 686. wwdt\_window\_counter\_set function**

| Name                   | Description                                       |
|------------------------|---|
| Function name          | wwdt_window_counter_set                           |
| Function prototype     | void wwdt_window_counter_set(uint8_t window_cnt); |
| Function description   | Set window value                                  |
| Input parameter 1      | wwdt_cnt: WWDT window value, 0x40~0x7F            |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |

| Name             | Description |
|------------------|-------------|
| Called functions | NA          |

**Example:**

|   |
|---|
| <code>wwdt_window_counter_set(0x6F);</code> |
|---|

## 5.26.7 wwdt\_flag\_get function

The table below describes the function `wwdt_flag_get`.

**Table 687. wwdt\_flag\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>wwdt_flag_get</code>                                     |
| Function prototype     | <code>flag_status wwdt_flag_get(void);</code>                  |
| Function description   | Get reload counter interrupt flag                              |
| Input parameter 1      | NA   |
| Output parameter       | NA   |
| Return value           | <code>flag_status</code> : flag status<br>Return SET or RESET. |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

|                               |
|-------------------------------|
| <code>wwdt_flag_get();</code> |
|-------------------------------|

## 5.26.8 wwdt\_flag\_clear function

The table below describes the function `wwdt_flag_clear`.

**Table 688. wwdt\_flag\_clear function**

| Name                   | Description                              |
|------------------------|--|
| Function name          | <code>wwdt_flag_clear</code>             |
| Function prototype     | <code>void wwdt_flag_clear(void);</code> |
| Function description   | Clear reload counter interrupt flag      |
| Input parameter 1      | NA                                       |
| Output parameter       | NA                                       |
| Return value           | NA                                       |
| Required preconditions | NA                                       |
| Called functions       | NA                                       |

**Example:**

|                                 |
|---------------------------------|
| <code>wwdt_flag_clear();</code> |
|---------------------------------|

## 5.27 External memory controller (XMC)

For XMC bank1 chip-select control register and timing register, their register structure `xmc_bank1_ctrl_tmg_reg_type` is defined in the “`at32f435_437_xmc.h`”.

```
/**
 * @brief type define xmc bank1 ctrl and tmg register
 */
typedef struct
{
    ...
} xmc_bank1_ctrl_tmg_reg_type;
```

XMC bank1 write timing register structure `xmc_bank1_tmgwr_reg_type` is defined in the “`at32f435_437_xmc.h`”.

```
/**
 * @brief type define xmc bank1 tmgwr register
 */
typedef struct
{
    ...
} xmc_bank1_tmgwr_reg_type;
```

XMC bank1 register structure `xmc_bank1_type` is defined in the “`at32f435_437_xmc.h`”.

```
/**
 * @brief xmc bank1 registers
 */
typedef struct
{
    ...
} xmc_bank1_type;
```

XMC bank2 register structure `xmc_bank2_type` is defined in the “`at32f435_437_xmc.h`”.

```
/**
 * @brief xmc bank2 registers
 */
typedef struct
{
    ...
} xmc_bank2_type;
```

XMC bank3 register structure `xmc_bank3_type` is defined in the “`at32f435_437_xmc.h`”.

```
/**
 * @brief xmc bank3 registers
```

```

*/
typedef struct
{
    ...

} xmc_bank3_type;

```

XMC bank4 register structure `xmc_bank4_type` is defined in the “at32f435\_437\_xmc.h”.

```

/**
 * @brief xmc bank4 registers
 */
typedef struct
{
    ...

} xmc_bank4_type;

```

XMC sdram register structure `xmc_sdram_type` is defined in the “at32f435\_437\_xmc.h”.

```

/**
 * @brief xmc sdram type
 */
typedef struct
{
    ...

} xmc_sdram_type

```

The table below gives a list of XMC registers.

**Table 689. Summary of XMC registers**

| Register                  | Description                                   |
|---------------------------|---|
| <code>xmc_bk1ctrl1</code> | SRAM/NOR Flash chip select control register 1 |
| <code>xmc_bk1tmg1</code>  | SRAM/NOR Flash chip select timing register 1  |
| <code>xmc_bk1ctrl2</code> | SRAM/NOR Flash chip select control register 2 |
| <code>xmc_bk1tmg2</code>  | SRAM/NOR Flash chip select timing register 2  |
| <code>xmc_bk1ctrl3</code> | SRAM/NOR Flash chip select control register 3 |
| <code>xmc_bk1tmg3</code>  | SRAM/NOR Flash chip select timing register 3  |
| <code>xmc_bk1ctrl4</code> | SRAM/NOR Flash chip select control register 4 |
| <code>xmc_bk1tmg4</code>  | SRAM/NOR Flash chip select timing register 4  |
| <code>xmc_bk2ctrl</code>  | Nand Flash control register 2                 |
| <code>xmc_bk2is</code>    | Interrupt enable and FIFO status register 2   |
| <code>xmc_bk2tmgrg</code> | Regular memory timing register 2              |
| <code>xmc_bk2tmgsp</code> | Special memory timing register 2              |
| <code>xmc_bk2ecc</code>   | ECC value register 2                          |
| <code>xmc_bk3ctrl</code>  | Nand Flash control register 3                 |
| <code>xmc_bk3is</code>    | Interrupt enable and FIFO status register 3   |
| <code>xmc_bk3tmgrg</code> | Regular memory timing register 3              |



| Register      | Description                                 |
|---------------|---|
| xmc_bk3tmgsp  | Special memory timing register 3            |
| xmc_bk3ecc    | ECC value register 3                        |
| xmc_bk4ctrl   | PC card control register                    |
| xmc_bk4is     | Interrupt enable and FIFO status register 4 |
| xmc_bk4tmgcm  | Common memory timing register 4             |
| xmc_bk4tmgat  | Attribute memory timing register 4          |
| xmc_bk4tmgio  | IO space timing register 4                  |
| xmc_bk1tmgwr1 | SRAM/NOR Flash write timing register 1      |
| xmc_bk1tmgwr2 | SRAM/NOR Flash write timing register 2      |
| xmc_bk1tmgwr3 | SRAM/NOR Flash write timing register 3      |
| xmc_bk1tmgwr4 | SRAM/NOR Flash write timing register 4      |
| xmc_ext1      | SRAM/NOR Flash extra timing register 1      |
| xmc_ext2      | SRAM/NOR Flash extra timing register 2      |
| xmc_ext3      | SRAM/NOR Flash extra timing register 3      |
| xmc_ext4      | SRAM/NOR Flash extra timing register 4      |
| sdram_ctrl1   | SDRAM control register 1                    |
| sdram_ctrl2   | SDRAM control register 2                    |
| sdram_tm1     | SDRAM timing register 1                     |
| sdram_tm2     | SDRAM timing register 2                     |
| sdram_cmd     | SDRAM command register                      |
| sdram_rcnt    | SDRAM refresh timer register                |
| sdram_sts     | SDRAM status register                       |

The table below gives a list of XMC library functions.

**Table 690. Summary of XMC library functions**

| Function name                        | Description  |
|--------------------------------------|--|
| xmc_nor_sram_reset                   | Reset nor/sram controller  |
| xmc_nor_sram_init                    | Initialize nor/sram controller   |
| xmc_nor_sram_timing_config           | Configure nor/sram controller timing   |
| xmc_norsram_default_para_init        | Initialize paramters in xmc_nor_sram_init_struct   |
| xmc_norsram_timing_default_para_init | Initialize paramters in xmc_rw_timing_struct and xmc_w_timing_struct                       |
| xmc_nor_sram_enable                  | Enable nor/sram controller   |
| xmc_ext_timing_config                | Configure nor/sram extension controller  |
| xmc_nand_reset                       | Reset nand controller  |
| xmc_nand_init                        | Initialize nand controller   |
| xmc_nand_timing_config               | Configure nand controller timing   |
| xmc_nand_default_para_init           | Initialize paramters in xmc_nand_init_struct   |
| xmc_nand_timing_default_para_init    | Initialize paramters in xmc_common_spacetiming_struct and xmc_attribute_spacetiming_struct |
| xmc_nand_enable                      | Enable nand controller   |
| xmc_nand_ecc_enable                  | Enable nand controller ECC feature   |
| xmc_ecc_get                          | Get ECC value  |
| xmc_interrupt_enable                 | Enable XMC controller interrupt  |

|                                     |  |
|-------------------------------------|--|
| xmc_flag_status_get                 | Get XMC controller interruptflag   |
| xmc_flag_clear                      | Clear XMC controller interrupt   |
| xmc_pccard_reset                    | Reset pccard controller  |
| xmc_pccard_init                     | Initialize pccard controller   |
| xmc_pccard_timing_config            | Configure pccard controller timing   |
| xmc_pccard_default_para_init        | Initialize parameters in xmc_pccard_init_struct  |
| xmc_pccard_timing_default_para_init | Initialize parameters in xmc_common_spacetiming_struct, xmc_attribute_spacetiming_struct and xmc_iospace_timing_struct |
| xmc_pccard_enable                   | Enable pccard controller   |
| xmc_sdram_reset                     | Reset sdram bank controller  |
| xmc_sdram_init                      | Initialize sdram bank controller   |
| xmc_sdram_default_para_init         | Initialize parameters in xmc_sdram_init_struct and xmc_sdram_timing_struct   |
| xmc_sdram_cmd                       | Send sdram command   |
| xmc_sdram_status_get                | Get sdram bank status  |
| xmc_sdram_refresh_counter_set       | Configure sdram auto refresh counter   |
| xmc_sdram_auto_refresh_set          | Set auto refresh times   |

### 5.27.1 xmc\_nor\_sram\_reset function

The table below describes the function xmc\_nor\_sram\_reset.

**Table 691. xmc\_nor\_sram\_reset function**

| Name                   | Description   |
|------------------------|---|
| Function name          | xmc_nor_sram_reset  |
| Function prototype     | void xmc_nor_sram_reset(xmc_nor_sram_subbank_type xmc_subbank); |
| Function description   | Reset nor/sram controller                                       |
| Input parameter 1      | xmc_subbank: selected subbank                                   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### xmc\_subbank

Select a subbank.

|                      |              |
|----------------------|--------------|
| XMC_BANK1_NOR_SRAM1: | xmc_subbank1 |
| XMC_BANK1_NOR_SRAM2: | xmc_subbank2 |
| XMC_BANK1_NOR_SRAM3: | xmc_subbank3 |
| XMC_BANK1_NOR_SRAM4: | xmc_subbank4 |

Example:

```
/* resetnor/sram subbank1 */
xmc_nor_sram_reset(XMC_BANK1_NOR_SRAM1);
```

## 5.27.2 xmc\_nor\_sram\_init function

The table below describes the function `xmc_nor_sram_init`.

**Table 692. xmc\_nor\_sram\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>xmc_nor_sram_init</code>   |
| Function prototype     | <code>void xmc_nor_sram_init(xmc_norsram_init_type* xmc_norsram_init_struct);</code> |
| Function description   | Initialize nor/sram controller   |
| Input parameter 1      | <code>xmc_norsram_init_struct</code> : <code>xmc_norsram_init_type</code> pointer    |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### **xmc\_norsram\_init\_type struct**

The `xmc_norsram_init_type` is defined in the `at32f435_437_xmc.h`.

typedef struct

```

{
    xmc_nor_sram_subbank_type    subbank;
    xmc_data_addr_mux_type      data_addr_mux;
    xmc_memory_type             device;
    xmc_data_width_type         bus_type;
    xmc_burst_access_mode_type  burst_mode_enable;
    xmc_asyn_wait_type          asynwait_enable;
    xmc_wait_signal_polarity_type wait_signal_lv;
    xmc_wrap_mode_type          wrapped_mode_enable;
    xmc_wait_timing_type        wait_signal_config;
    xmc_write_operation_type     write_enable;
    xmc_wait_signal_type         wait_signal_enable;
    xmc_extended_mode_type      write_timing_enable;
    xmc_write_burst_type        write_burst_syn;
} xmc_norsram_init_type;

```

### **subbank**

Select a subbank

```

XMC_BANK1_NOR_SRAM1:    xmc subbank1
XMC_BANK1_NOR_SRAM2:    xmc subbank2
XMC_BANK1_NOR_SRAM3:    xmc subbank3
XMC_BANK1_NOR_SRAM4:    xmc subbank4

```

### **data\_addr\_mux**

Define whether the lower 16 bits of the xmc address line is multiplexed with data line or not.

```

XMC_DATA_ADDR_MUX_DISABLE:    Not multiplexed
XMC_DATA_ADDR_MUX_ENABLE:     Multiplexed

```

### **Device**

Select an external memory device

```

XMC_DEVICE_SRAM:    sram

```

XMC\_DEVICE\_PSRAM: psram  
 XMC\_DEVICE\_NOR: nor

**bus\_type**

xmc data bus bit width

XMC\_BUSTYPE\_8\_BITS: 8-bit data bus  
 XMC\_BUSTYPE\_16\_BITS: 16-bit data bus

**burst\_mode\_enable**

Enable or disable burst mode

XMC\_BURST\_MODE\_DISABLE: Burst mode disabled  
 XMC\_BURST\_MODE\_ENABLE: Burst mode enabled

**asynwait\_enable**

Enable or disable wait signals during asynchronous transmission

XMC\_ASYNC\_WAIT\_DISABLE: Disabled  
 XMC\_ASYNC\_WAIT\_ENABLE: Enabled

**wait\_signal\_lv**

Select the polarity of wait signals. It is used to set the polarity of NWAIT signal in synchronous mode

XMC\_WAIT\_SIGNAL\_LEVEL\_LOW: Active low  
 XMC\_WAIT\_SIGNAL\_LEVEL\_HIGH: Active high

**wrapped\_mode\_enable**

In synchronous mode, this bit is used to define whether the XMC controller will or not split a not-aligned AHB access into two accesses.

XMC\_WRAPPED\_MODE\_DISABLE: Direct wrapped burst mode is disabled  
 XMC\_WRAPPED\_MODE\_ENABLE: Direct wrapped burst mode is enabled

**wait\_signal\_config**

Wait timing configuration, valid only in synchronous mode

XMC\_WAIT\_SIGNAL\_SYN\_BEFORE: NWAIT signal is active one data cycle before wait state  
 XMC\_WAIT\_SIGNAL\_SYN\_DURING : NWAIT signal is active during wait state

**write\_enable**

Write enable bit

XMC\_WRITE\_OPERATION\_DISABLE: Write operation is disabled  
 XMC\_WRITE\_OPERATION\_ENABLE: Write operation is enabled

**wait\_signal\_enable**

Wait signal enable bit during synchronous transmission

XMC\_WAIT\_SIGNAL\_DISABLE: NWAIT signal disabled  
 XMC\_WAIT\_SIGNAL\_ENABLE: NWAIT signal enabled

**write\_timing\_enable**

Wait timing enable bit. Read memory and write memory operate at different timings. In other words, SRAM/NOR write timing register (XMC\_BKxTMGWR) is released.

XMC\_WRITE\_TIMING\_DISABLE: Read and write timings are the same  
 XMC\_WRITE\_TIMING\_ENABLE: Read and write timings are different

**write\_burst\_syn**

Write burst enable bit

XMC\_WRITE\_BURST\_SYN\_DISABLE: Write operation is performed in asynchronous mode  
 XMC\_WRITE\_BURST\_SYN\_ENABLE: Write operation is performed in synchronous mode

**Example:**

```
xmc_norsram_init_type xmc_norsram_init_struct;
```

|  |                                |
|--|--------------------------------|
| xmc_norsram_init_struct.subbank              | = XMC_BANK1_NOR_SRAM1;         |
| xmc_norsram_init_struct.data_addr_mux_enable | = XMC_DATA_ADDR_MUX_ENABLE;    |
| xmc_norsram_init_struct.device               | = XMC_DEVICE_PSRAM;            |
| xmc_norsram_init_struct.bus_type             | = XMC_BUSTYPE_16_BITS;         |
| xmc_norsram_init_struct.burst_mode_enable    | = XMC_BURST_MODE_DISABLE;      |
| xmc_norsram_init_struct.asynwait_enable      | = XMC_ASYN_WAIT_DISABLE;       |
| xmc_norsram_init_struct.wait_signal_lv       | = XMC_WAIT_SIGNAL_LEVEL_LOW;   |
| xmc_norsram_init_struct.wrapped_mode_enable  | = XMC_WRAPPED_MODE_DISABLE;    |
| xmc_norsram_init_struct.wait_signal_config   | = XMC_WAIT_SIGNAL_SYN_BEFORE;  |
| xmc_norsram_init_struct.write_enable         | = XMC_WRITE_OPERATION_ENABLE;  |
| xmc_norsram_init_struct.wait_signal_enable   | = XMC_WAIT_SIGNAL_DISABLE;     |
| xmc_norsram_init_struct.write_burst_syn      | = XMC_WRITE_BURST_SYN_DISABLE; |
| xmc_norsram_init_struct.write_timing_enable  | = XMC_WRITE_TIMING_DISABLE;    |
| xmc_nor_sram_init(&xmc_norsram_init_struct); |                                |

### 5.27.3 xmc\_nor\_sram\_timing\_config function

The table below describes the function xmc\_nor\_sram\_reset.

**Table 693.xmc\_nor\_sram\_timing\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | xmc_nor_sram_timing_config   |
| Function prototype     | void xmc_nor_sram_timing_config(xmc_norsram_timing_init_type* xmc_rw_timing_struct, xmc_norsram_timing_init_type* xmc_w_timing_struct);                                |
| Function description   | Configure nor/sram controller timing   |
| Input parameter 1      | xmc_rw_timing_struct: xmc_norsram_timing_init_type pointer.<br>This structure is used to configure read and write timings when a separate write timing is not enabled. |
| Input parameter 2      | xmc_w_timing_struct: xmc_norsram_timing_init_type pointer.<br>This structure is used to configure write timings when a separate write timing is enabled.               |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### xmc\_norsram\_timing\_init\_type struct

The xmc\_norsram\_timing\_init\_type is defined in the at32f435\_437\_xmc.h.

typedef struct

```
{
    xmc_nor_sram_subbank_type    subbank;
    xmc_extended_mode_type      write_timing_enable;
    uint32_t                    addr_setup_time;
    uint32_t                    addr_hold_time;
    uint32_t                    data_setup_time;
    uint32_t                    bus_latency_time;
    uint32_t                    clk_psc;
```

```
uint32_t          data_latency_time;
xmc_access_mode_type mode;
} xmc_norsram_timing_init_type;
```

## subbank

Select a subbank to reset

```
XMC_BANK1_NOR_SRAM1:  xmc subbank1
XMC_BANK1_NOR_SRAM2:  xmc subbank2
XMC_BANK1_NOR_SRAM3:  xmc subbank3
XMC_BANK1_NOR_SRAM4:  xmc subbank4
```

## write\_timing\_enable

Wait timing enable bit. Read memory and write memory operate at different timings. In other words, SRAM/NOR write timing register (XMC\_BKxTMGWR) is released.

XMC\_WRITE\_TIMING\_DISABLE: Read and write timings are the same

XMC\_WRITE\_TIMING\_ENABLE: Read and write timings are different

## addr\_setup\_time

Address setup time

```
0000:  0 HCLK clock cycle added
0001:  1 HCLK clock cycle added
.....
1111:  15 HCLK clock cycles added
```

## addr\_hold\_time

Address hold time

```
0000:  0 HCLK clock cycle added
0001:  1 HCLK clock cycle added
.....
1111:  15 HCLK clock cycles added
```

## data\_setup\_time

Data setup time

```
0000:  0 HCLK clock cycle added
0001:  1 HCLK clock cycle added
.....
1111:  15 HCLK clock cycles added
```

## bus\_latency\_time

Bus latency time. In order to avoid conflicts on data bus, in multiplexed mode or synchronous mode, the XMC controller inserts latency time into data bus after a single read operation.

```
0000:  1 HCLK clock cycle added
0001:  2 HCLK clock cycle added
.....
1111:  16 HCLK clock cycles added
```

## clk\_psc

Clock frequency division factor. Valid only in synchronous mode. It is used to define the clock frequency of the XMC\_CLK.

```
0000:  Reserved
0001:  XMC_CLK cycles= 2xHCLK clock cycles
0010:  XMC_CLK cycles= 3xHCLK clock cycles
```

.....  
 1111: XMC\_CLK cycles= 16xHCLK clock cycles

**data\_latency\_time**

Data latency time. Valid only in synchronous mode.

0000: 0 XMC\_CLK clock cycle added  
 0001: 1 XMC\_CLK clock cycle added

.....  
 1111: 15 XMC\_CLK clock cycles added

**Mode**

Asynchronous access mode selection bit. Valid only when the RWTD bit is enabled.

- 00: Mode A
- 01: Mode B
- 10: Mode C
- 11: Mode D

**Example:**

```
xmc_norsram_timing_init_type rw_timing_struct,w_timing_struct;

rw_timing_struct.subbank      = XMC_BANK1_NOR_SRAM1;
rw_timing_struct.mode         = XMC_ACCESS_MODE_A;
rw_timing_struct.write_timing_enable = XMC_WRITE_TIMING_DISABLE;
rw_timing_struct.addr_hold_time   = 0x08;
rw_timing_struct.addr_setup_time  = 0x09;
rw_timing_struct.data_setup_time  = 0x0F;
rw_timing_struct.data_latency_time = 0x0;
rw_timing_struct.bus_latency_time = 0x0;
rw_timing_struct.clk_psc         = 0x0;

w_timing_struct.subbank      = XMC_BANK1_NOR_SRAM1;
w_timing_struct.mode         = XMC_ACCESS_MODE_A;
w_timing_struct.write_timing_enable = XMC_WRITE_TIMING_DISABLE;
w_timing_struct.addr_hold_time   = 0x08;
w_timing_struct.addr_setup_time  = 0x09;
w_timing_struct.data_setup_time  = 0x0F;
w_timing_struct.data_latency_time = 0x0;
w_timing_struct.bus_latency_time = 0x0;
w_timing_struct.clk_psc         = 0x0;

xmc_nor_sram_timing_config(&rw_timing_struct,&w_timing_struct);
```

### 5.27.4 xmc\_norsram\_default\_para\_init function

The table below describes the function xmc\_norsram\_default\_para\_init.

**Table 694. xmc\_norsram\_default\_para\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | xmc_norsram_default_para_init  |
| Function prototype     | void xmc_norsram_default_para_init(xmc_norsram_init_type* xmc_nor_sram_init_struct); |
| Function description   | Initialize paramters in xmc_nor_sram_init_struct                                     |
| Input parameter 1      | xmc_nor_sram_init_struct: xmc_norsram_init_type pointer                              |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

The table below describes the default values of members in xmc\_nor\_sram\_init\_struct.

**Table 695.xmc\_nor\_sram\_init\_struct default values**

| Member              | Default value               |
|---------------------|-----------------------------|
| subbank             | XMC_BANK1_NOR_SRAM1         |
| data_addr_muxiplex  | XMC_DATA_ADDR_MUX_ENABLE    |
| device              | XMC_DEVICE_SRAM             |
| bus_type            | XMC_BUSTYPE_8_BITS          |
| burst_mode_enable   | XMC_BURST_MODE_DISABLE      |
| asynwait_enable     | XMC_ASYNC_WAIT_DISABLE      |
| wait_signal_lv      | XMC_WAIT_SIGNAL_LEVEL_LOW   |
| wrapped_mode_enable | XMC_WRAPPED_MODE_DISABLE    |
| wait_signal_config  | XMC_WAIT_SIGNAL_SYN_BEFORE  |
| write_enable        | XMC_WRITE_OPERATION_ENABLE  |
| wait_signal_enable  | XMC_WAIT_SIGNAL_ENABLE      |
| write_timing_enable | XMC_WRITE_TIMING_DISABLE    |
| write_burst_syn     | XMC_WRITE_BURST_SYN_DISABLE |

**Example:**

```
xmc_norsram_init_type xmc_norsram_init_struct;
/* fill each xmc_nor_sram_init_struct member with its default value */
xmc_norsram_default_para_init(&xmc_norsram_init_struct);
```

### 5.27.5 xmc\_norsram\_timing\_default\_para\_init function

The table below describes the function xmc\_norsram\_timing\_default\_para\_init.

**Table 696.xmc\_norsram\_timing\_default\_para\_init function**

| Name               | Description   |
|--------------------|---|
| Function name      | xmc_norsram_timing_default_para_init  |
| Function prototype | void xmc_norsram_timing_default_para_init(xmc_norsram_timing_init_type* xmc_rw_timing_struct, xmc_norsram_timing_init_type* xmc_w_timing_struct); |



| Name                   | Description   |
|------------------------|---|
| Function description   | Initialize parameters in <code>xmc_rw_timing_struct</code> and <code>xmc_w_timing_struct</code>   |
| Input parameter 1      | <code>xmc_rw_timing_struct</code> : <code>xmc_norsram_timing_init_type</code> pointer<br><code>xmc_w_timing_struct</code> : <code>xmc_norsram_timing_init_type</code> pointer |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The table below describes the default values of members in `xmc_rw_timing_struct` and `xmc_w_timing_struct`.

**Table 697. `xmc_rw_timing_struct` and `xmc_w_timing_struct` default values**

| Member                           | Default value                         |
|----------------------------------|---------------------------------------|
| <code>subbank</code>             | <code>XMC_BANK1_NOR_SRAM1</code>      |
| <code>write_timing_enable</code> | <code>XMC_WRITE_TIMING_DISABLE</code> |
| <code>addr_setup_time</code>     | <code>0xF</code>                      |
| <code>addr_hold_time</code>      | <code>0xF</code>                      |
| <code>data_setup_time</code>     | <code>0xFF</code>                     |
| <code>bus_latency_time</code>    | <code>0xF</code>                      |
| <code>clk_psc</code>             | <code>0xF</code>                      |
| <code>data_latency_time</code>   | <code>0xF</code>                      |
| <code>mode</code>                | <code>XMC_ACCESS_MODE_A</code>        |

**Example:**

```
xmc_norsram_timing_init_type rw_timing_struct, w_timing_struct;
/* fill each xmc_rw_timing_struct and xmc_w_timing_struct member with its default value */
xmc_norsram_timing_default_para_init(&xmc_rw_timing_struct, &xmc_w_timing_struct);
```

### 5.27.6 `xmc_nor_sram_enable` function

The table below describes the function `xmc_nor_sram_enable`.

**Table 698. `xmc_nor_sram_enable` function**

| Name                 | Description  |
|----------------------|--|
| Function name        | <code>xmc_nor_sram_enable</code>   |
| Function prototype   | <code>void xmc_nor_sram_enable(xmc_nor_sram_subbank_type xmc_subbank, confirm_state new_state);</code> |
| Function description | Enable nor/sram controller   |
| Input parameter 1    | <code>xmc_subbank</code> : selected xmc subbank  |
| Input parameter 2    | <code>new_state</code> : enable or disable controller  |
| Output parameter     | NA   |

| Name                   | Description |
|------------------------|-------------|
| Return value           | NA          |
| Required preconditions | NA          |
| Called functions       | NA          |

**xmc\_subbank**

Select a subbank to enable

XMC\_BANK1\_NOR\_SRAM1: xmc subbank1  
 XMC\_BANK1\_NOR\_SRAM2: xmc subbank2  
 XMC\_BANK1\_NOR\_SRAM3: xmc subbank3  
 XMC\_BANK1\_NOR\_SRAM4: xmc subbank4

**new\_state**

FALSE: Disable controller

TRUE: Enable controller

**Example:**

```
/* enable xmc bank1_sram bank */
xmc_nor_sram_enable(XMC_BANK1_NOR_SRAM1, TRUE);
```

### 5.27.7 xmc\_ext\_timing\_config function

The table below describes the function xmc\_ext\_timing\_config.

**Table 699. xmc\_ext\_timing\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | xmc_ext_timing_config   |
| Function prototype     | void xmc_ext_timing_config(xmc_nor_sram_subbank_type xmc_sub_bank, uint16_t w2w_timing, uint16_t r2r_timing); |
| Function description   | Configure nor/sram extension controller   |
| Input parameter 1      | xmc_subbank: selected xmc subbank   |
| Input parameter 2      | w2w_timing: bus turnaround phase duration between two consecutive write operations.                           |
| Input parameter 3      | r2r_timing: bus turnaround phase duration between two consecutive read operations.                            |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**xmc\_subbank**

Select a subbank to reset

XMC\_BANK1\_NOR\_SRAM1: xmc subbank1  
 XMC\_BANK1\_NOR\_SRAM2: xmc subbank2  
 XMC\_BANK1\_NOR\_SRAM3: xmc subbank3  
 XMC\_BANK1\_NOR\_SRAM4: xmc subbank4

**w2w\_timing**

This is used to define the bus turnaround phase duration between two consecutive write operations.

00000000: 1 HCLK clock cycle inserted between two consecutive write operations

00000001: 2 HCLK clock cycles inserted between two consecutive write operations

.....

00001000: 9 HCLK clock cycles (default value) inserted between two consecutive write operations  
 .....  
 11111111: 256 HCLK clock cycles inserted between two consecutive write operations

**r2r\_timing**

This is used to define the bus turnaround phase duration between two consecutive read operations.

00000000: 1 HCLK clock cycle inserted between two consecutive read operations  
 00000001: 2 HCLK clock cycles inserted between two consecutive read operations  
 .....  
 00001000: 9 HCLK clock cycles (default value) inserted between two consecutive read operations  
 .....  
 11111111: 256 HCLK clock cycles inserted between two consecutive read operations

**Example:**

```
/* bus turnaround phase for consecutive read duration and consecutive write duration */
xmc_ext_timing_config(XMC_BANK1_NOR_SRAM1, 0x08, 0x08);
```

### 5.27.8 xmc\_nand\_reset function

The table below describes the function xmc\_nand\_reset.

**Table 700. xmc\_nand\_reset function**

| Name                   | Description  |
|------------------------|--|
| Function name          | xmc_nand_reset   |
| Function prototype     | void xmc_nand_reset(xmc_class_bank_type xmc_bank);           |
| Function description   | Reset nand controller  |
| Input parameter 1      | xmc_bank: selected nand controller; it can be XMC_BANK2_NAND |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* reset nand flash */
xmc_nand_reset(XMC_BANK2_NAND);
```

### 5.27.9 xmc\_nand\_init function

The table below describes the function xmc\_nand\_init.

**Table 701. xmc\_nand\_init function**

| Name                 | Description   |
|----------------------|---|
| Function name        | xmc_nand_init   |
| Function prototype   | void xmc_nand_init(xmc_nand_init_type* xmc_nand_init_struct); |
| Function description | Initialize nand controller                                    |
| Input parameter 1    | xmc_nand_init_struct: xmc_nand_init_type pointer              |
| Output parameter     | NA  |
| Return value         | NA  |

| Name                   | Description |
|------------------------|-------------|
| Required preconditions | NA          |
| Called functions       | NA          |

### **xmc\_nand\_init\_type struct**

The xmc\_nand\_init\_type is defined in the at32f435\_437\_xmc.h.

typedef struct

```

{
    xmc_class_bank_type      nand_bank;
    xmc_nand_wait_type      wait_enable;
    xmc_data_width_type     bus_type;
    xmc_ecc_enable_type     ecc_enable;
    xmc_ecc_pagesize_type   ecc_pagesize;
    uint32_t                delay_time_cycle;
    uint32_t                delay_time_ar;
} xmc_nand_init_type;

```

### **Nand\_bank**

Select a nand\_bank controller

XMC\_BANK2\_NAND: bank2 NAND controller

XMC\_BANK3\_NAND: bank3 NAND controller

### **wait\_enable**

Wait enable bit. It is used to enable NAND Flash memory block wait feature.

XMC\_WAIT\_OPERATION\_DISABLE: Disabled

XMC\_WAIT\_OPERATION\_ENABLE: Enabled

### **bus\_type**

External memory data width. It is used to define the external NAND Flash data bus width.

XMC\_BUSTYPE\_8\_BITS: 8-bit data bus

XMC\_BUSTYPE\_16\_BITS: 16-bit data bus

### **ecc\_enable**

Define xmc data bus bit width

XMC\_BUSTYPE\_8\_BITS: 8-bit data bus

XMC\_BUSTYPE\_16\_BITS: 16-bit data bus

### **ecc\_pagesize**

ECC page size

000: 256 bytes

001: 512 bytes

010: 1024 bytes

011: 2048 bytes

100: 4096 bytes

101: 8192 bytes

### **delay\_time\_cycle**

Delay time of CLE to RE (from CLE falling edge to RE falling edge)

0000: 1 HCLK clock cycle

.....

1111: 16 HCLK clock cycles

**delay\_time\_ar**

Delay time of ALE to RE (from ALE falling edge to RE falling edge)

0000: 1 HCLK clock cycle

.....

1111: 16 HCLK clock cycles

**Example:**

```
xmc_nand_init_type nand_init_struct;
nand_init_struct.nand_bank = XMC_BANK2_NAND;
nand_init_struct.wait_enable = XMC_WAIT_OPERATION_DISABLE;
nand_init_struct.bus_type = XMC_BUSTYPE_8_BITS;
nand_init_struct.ecc_enable = XMC_ECC_OPERATION_DISABLE;
nand_init_struct.ecc_pagesize = XMC_ECC_PAGESIZE_2048_BYTES;
nand_init_struct.delay_time_cycle = 0x10;
nand_init_struct.delay_time_ar = 0x10;
/* xmc nand flash configuration */
xmc_nand_init(&nand_init_struct);
```

### 5.27.10 xmc\_nand\_timing\_config function

The table below describes the function xmc\_nand\_timing\_config.

**Table 702. xmc\_nand\_timing\_config function**

| Name                   | Description   |
|------------------------|---|
| Function name          | xmc_nand_timing_config  |
| Function prototype     | void xmc_nand_timing_config(xmc_nand_timinginit_type* xmc_common_spacetiming_struct, xmc_nand_timinginit_type* xmc_attribute_spacetiming_struct); |
| Function description   | Configure nand controller timing  |
| Input parameter 1      | xmc_common_spacetiming_struct: xmc_nand_timinginit_type pointer.<br>It indicates regular memory timing parameters.                                |
| Input parameter 2      | xmc_attribute_spacetiming_struct: xmc_nand_timinginit_type pointer.<br>It indicates special memory timing parameters.                             |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**xmc\_nand\_timinginit\_type struct**

The xmc\_nand\_timinginit\_type is defined in the at32f435\_437\_xmc.h.

typedef struct

```
{
    xmc_class_bank_type    class_bank;
    uint32_t               mem_setup_time;
    uint32_t               mem_wait_time;
    uint32_t               mem_hold_time;
```

```
uint32_t          mem_hiz_time;
} xmc_nand_timinginit_type;
```

### class\_bank

Select a nand flash bank

XMC\_BANK2\_NAND

XMC\_BANK3\_NAND

### mem\_setup\_time

Regular memory setup time. It defines the address setup time when access to NAND Flash in a regular memory.

00000000: 0 HCLK clock cycle is inserted

00000001: 1 HCLK clock cycle is inserted

.....

11111111: 255 HCLK clock cycles are inserted

### mem\_waite\_time

Regular memory wait time. It specifies the regular memory wait time when the XMC\_NWE and XMC\_NOE are low.

00000000: 0 HCLK clock cycle is inserted

00000001: 1 HCLK clock cycle is inserted

.....

11111111: 255 HCLK clock cycles are inserted

### mem\_hold\_time

Regular memory hold time. defines the databus hold time when access to NAND Flash in a regular memory.

00000000: Reserved

00000001: 1 HCLK clock cycle is inserted

.....

11111111: 255 HCLK clock cycles are inserted

### mem\_hiz\_time

Regular memory databus High resistance time. defines the databus high resistance duration when write access to NAND Flash is started in a regular space.

00000000: 0 HCLK clock cycle is inserted

00000001: 1 HCLK clock cycle is inserted

.....

11111111: 255 HCLK clock cycles are inserted

### Example:

```
xmc_regular_spacetimingstruct.class_bank = XMC_BANK2_NAND;
xmc_regular_spacetimingstruct.mem_setup_time = 254;
xmc_regular_spacetimingstruct.mem_hiz_time = 254;
xmc_regular_spacetimingstruct.mem_hold_time = 254;
xmc_regular_spacetimingstruct.mem_waite_time = 254;
xmc_nand_timing_config(&xmc_regular_spacetimingstruct, &xmc_regular_spacetimingstruct);
```

### 5.27.11 xmc\_nand\_default\_para\_init function

The table below describes the function `xmc_nand_default_para_init`.

**Table 703. xmc\_nand\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>xmc_nand_default_para_init</code>   |
| Function prototype     | <code>void xmc_nand_default_para_init(xmc_nand_init_type* xmc_nand_init_struct);</code> |
| Function description   | Initialize parameters in <code>xmc_nand_init_struct</code>                              |
| Input parameter 1      | <code>xmc_nand_init_struct</code> : <code>xmc_nand_init_type</code> pointer             |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The table below describes the default values of members `xmc_nand_init_struct`.

**Table 704. xmc\_nand\_init\_struct default values**

| Member                        | Default value                           |
|-------------------------------|---|
| <code>nand_bank</code>        | <code>XMC_BANK2_NAND</code>             |
| <code>wait_enable</code>      | <code>XMC_WAIT_OPERATION_DISABLE</code> |
| <code>bus_type</code>         | <code>XMC_BUSTYPE_8_BITS</code>         |
| <code>ecc_enable</code>       | <code>XMC_ECC_OPERATION_DISABLE</code>  |
| <code>ecc_pagesize</code>     | <code>XMC_ECC_PAGESIZE_256_BYTES</code> |
| <code>delay_time_cycle</code> | <code>0x0</code>                        |
| <code>delay_time_ar</code>    | <code>0x0</code>                        |

**Example:**

```
/* fill each nand_init_struct member with its default value */
xmc_nand_default_para_init(&nand_init_struct);
```

### 5.27.12 xmc\_nand\_timing\_default\_para\_init function

The table below describes the function `xmc_nand_timing_default_para_init`.

**Table 705. xmc\_nand\_timing\_default\_para\_init function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>xmc_nand_timing_default_para_init</code>  |
| Function prototype   | <code>void xmc_nand_timing_default_para_init(xmc_nand_timinginit_type* xmc_common_spacetiming_struct, xmc_nand_timinginit_type* xmc_attribute_spacetiming_struct);</code>                   |
| Function description | Initialize parameters in <code>xmc_common_spacetiming_struct</code> and <code>xmc_attribute_spacetiming_struct</code>   |
| Input parameter 1    | <code>xmc_common_spacetiming_struct</code> : <code>xmc_nand_timinginit_type</code> pointer<br><code>xmc_attribute_spacetiming_struct</code> : <code>xmc_nand_timinginit_type</code> pointer |
| Output parameter     | NA  |
| Return value         | NA  |
| Required             | NA  |

| Name             | Description |
|------------------|-------------|
| preconditions    |             |
| Called functions | NA          |

The table below describes the default values of members `xmc_rw_timing_struct`, `xmc_common_spacetime_struct` and `xmc_w_timing_struct`, `xmc_attribute_spacetime_struct`.

**Table 706. `xmc_common_spacetime_struct` and `xmc_attribute_spacetime_struct` default values**

| Member                      | Default values              |
|-----------------------------|-----------------------------|
| <code>class_bank</code>     | <code>XMC_BANK2_NAND</code> |
| <code>mem_hold_time</code>  | <code>0xFC</code>           |
| <code>mem_wait_time</code>  | <code>0xFC</code>           |
| <code>mem_setup_time</code> | <code>0xFC</code>           |
| <code>mem_hiz_time</code>   | <code>0xFC</code>           |

**Example:**

```
xmc_nand_timinginit_type xmc_regular_spacetimestruct;
/* fill each xmc_regular_spacetimestruct member with its default value */
xmc_nand_timing_default_para_init(&xmc_regular_spacetimestruct, &xmc_regular_spacetimestruct);
```

### 5.27.13 `xmc_nand_enable` function

The table below describes the function `xmc_nand_enable`.

**Table 707. `xmc_nand_enable` function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>xmc_nand_enable</code>  |
| Function prototype     | <code>void xmc_nand_enable(xmc_class_bank_type xmc_bank, confirm_state new_state);</code> |
| Function description   | Enable nand flash controller  |
| Input parameter 1      | <code>xmc_bank</code> : selected xmc bank   |
| Input parameter 2      | <code>new_state</code> : enable or disable controller                                     |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**`xmc_bank`**

Select an XMC bank

`XMC_BANK2_NAND`

`XMC_BANK3_NAND`

**`new_state`**

FALSE: Disable controller

TRUE: Enable controller

**Example:**

```
/* xmc nand bank enable*/
xmc_nand_enable(XMC_BANK2_NAND, TRUE);
```



### 5.27.14 xmc\_nand\_ecc\_enable function

The table below describes the function xmc\_nand\_ecc\_enable.

**Table 708. xmc\_nand\_ecc\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | xmc_nand_ecc_enable  |
| Function prototype     | void xmc_nand_ecc_enable(xmc_class_bank_type xmc_bank, confirm_state new_state); |
| Function description   | Enable nand flash controller ECC feature   |
| Input parameter 1      | xmc_bank: selected xmc bank  |
| Input parameter 2      | new_state: enable or disable controller ECC feature                              |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **xmc\_bank**

Select an XMC bank

XMC\_BANK2\_NAND

XMC\_BANK3\_NAND

#### **new\_state**

FALSE: Disable controller ECC feature

TRUE: Enable controller ECC feature

#### **Example:**

```
/* calculate ecc value while transmitting */
xmc_nand_ecc_enable(XMC_BANK2_NAND, TRUE);
```

### 5.27.15 xmc\_ecc\_get function

The table below describes the function xmc\_ecc\_get.

**Table 709. xmc\_ecc\_get function**

| Name                   | Description   |
|------------------------|---|
| Function name          | xmc_ecc_get   |
| Function prototype     | uint32_t xmc_ecc_get(xmc_class_bank_type xmc_bank); |
| Function description   | Get nand flash controller ECC value                 |
| Input parameter 1      | xmc_bank: selected xmc bank                         |
| Output parameter       | NA  |
| Return value           | ECC value   |
| Required preconditions | NA  |
| Called functions       | NA  |

#### **xmc\_bank**

Select an XMC bank

XMC\_BANK2\_NAND

XMC\_BANK3\_NAND

#### **Example:**

```
/* get ecc value */
xmc_ecc_get(XMC_BANK2_NAND, TRUE);
```

### 5.27.16 xmc\_interrupt\_enable function

The table below describes the function `xmc_interrupt_enable`.

**Table 710. xmc\_interrupt\_enable function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>xmc_interrupt_enable</code>  |
| Function prototype     | <code>void xmc_interrupt_enable(xmc_class_bank_type xmc_bank, xmc_interrupt_sources_type xmc_int, confirm_state new_state);</code> |
| Function description   | Enable xmc controller interrupts   |
| Input parameter 1      | <code>xmc_bank</code> : selected xmc bank  |
| Input parameter 2      | <code>xmc_int</code> : interrupt selection   |
| Input parameter 3      | <code>new_state</code> : enable or disable interrupt   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

#### **xmc\_bank**

Select a bank

`XMC_BANK2_NAND`

`XMC_BANK3_NAND`

`XMC_BANK4_PCCARD`

`XMC_BANK5_6_SDRAM`

#### **xmc\_int**

`XMC_INT_RISING_EDGE`: XMC rising edge detection interrupt

`XMC_INT_LEVEL`: XMC high level detection interrupt

`XMC_INT_FALLING_EDGE`: XMC falling edge detection interrupt

`XMC_INT_ERR`: XMC error interrupt

#### **new\_state**

`FALSE`: Disable interrupt

`TRUE`: Enable interrupt

#### **Example:**

```
/* xmc rising edge detection interrupt enable */
xmc_interrupt_enable(XMC_BANK2_NAND, XMC_INT_RISING_EDGE, TRUE);
```

### 5.27.17 xmc\_flag\_status\_get function

The table below describes the function `xmc_flag_status_get`.

**Table 711. xmc\_flag\_status\_get function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>xmc_flag_status_get</code>  |
| Function prototype   | <code>flag_status xmc_flag_status_get(xmc_class_bank_type xmc_bank, xmc_interrupt_flag_type xmc_flag);</code> |
| Function description | Get XMC flag  |

| Name                   | Description   |
|------------------------|---|
| Input parameter 1      | xmc_bank: selected xmc bank                           |
| Input parameter 2      | xmc_flag: flag selection                              |
| Output parameter       | NA  |
| Return value           | flag_status: indicates whether the flag is set or not |
| Required preconditions | NA  |
| Called functions       | NA  |

**xmc\_bank**

select a bank

XMC\_BANK2\_NAND

XMC\_BANK3\_NAND

XMC\_BANK4\_PCCARD

XMC\_BANK5\_6\_SDRAM

**xmc\_flag**

xmc\_flag is used to select a flag, including:

XMC\_RISINGEDGE\_FLAG: Rising edge

XMC\_LEVEL\_FLAG: High level

XMC\_FALLINGEDGE\_FLAG: Falling edge

XMC\_FEMPT\_FLAG: FIFO empty

XMC\_BUSY\_FLAG: Busy

XMC\_ERR\_FLAG: Error

**flag\_status**

RESET: The corresponding flag is reset

SET: The corresponding flag is set

**Example:**

```
if(xmc_flag_status_get(XMC_BANK2_NAND, XMC_RISINGEDGE_FLAG) != RESET)
{
    .....
}
```

## 5.27.18 xmc\_flag\_clear function

The table below describes the function xmc\_flag\_clear.

**Table 712. xmc\_flag\_clear function**

| Name                   | Description  |
|------------------------|--|
| Function name          | xmc_flag_clear   |
| Function prototype     | void xmc_flag_clear(xmc_class_bank_type xmc_bank, xmc_interrupt_flag_type xmc_flag); |
| Function description   | Clear flag   |
| Input parameter 1      | xmc_bank: selected xmc bank  |
| Input parameter 2      | xmc_flag: to-be-cleared flag   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**xmc\_bank**

Select a bank

XMC\_BANK2\_NAND

XMC\_BANK3\_NAND

XMC\_BANK4\_PCCARD

XMC\_BANK5\_6\_SDRAM

**xmc\_flag**

xmc\_flag is used to select a flag, including:

XMC\_RISINGEDGE\_FLAG: Rising edge

XMC\_LEVEL\_FLAG: High level

XMC\_FALLINGEDGE\_FLAG: Falling edge

XMC\_FEMPT\_FLAG: FIFO empty

XMC\_BUSY\_FLAG: Busy

XMC\_ERR\_FLAG: Error

**Example:**

```

if(xmc_flag_status_get(XMC_BANK2_NAND, XMC_RISINGEDGE_FLAG) != RESET)
{
    .....
    xmc_flag_clear(XMC_BANK2_NAND, XMC_RISINGEDGE_FLAG);
}
    
```

### 5.27.19 xmc\_pccard\_reset function

The table below describes the function xmc\_pccard\_reset.

**Table 713. xmc\_pccard\_reset function**

| Name                   | Description                  |
|------------------------|------------------------------|
| Function name          | xmc_pccard_reset             |
| Function prototype     | void xmc_pccard_reset(void); |
| Function description   | Reset pccard controller      |
| Input parameter        | NA                           |
| Output parameter       | NA                           |
| Return value           | NA                           |
| Required preconditions | NA                           |
| Called functions       | NA                           |

**Example:**

```

/* resetpccard */
xmc_pccard_reset();
    
```

### 5.27.20 xmc\_pccard\_init function

The table below describes the function xmc\_pccard\_init.

**Table 714. xmc\_pccard\_init function**

| Name               | Description   |
|--------------------|---|
| Function name      | xmc_pccard_init   |
| Function prototype | void xmc_pccard_init(xmc_pccard_init_type* xmc_pccard_init_struct); |

| Name                   | Description  |
|------------------------|--|
| Function description   | Initialize pccard controller                         |
| Input parameter 1      | xmc_pccard_init_struct: xmc_pccard_init_type pointer |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### xmc\_pccard\_init\_type struct

The xmc\_pccard\_init\_type is defined in the at32f435\_437\_xmc.h.

typedef struct

```
{
    xmc_nand_pccard_wait_type    enable_wait;
    uint32_t                    delay_time_cr;
    uint32_t                    delay_time_ar;
} xmc_pccard_init_type;
```

### enable\_wait

Wait enable bit. It is used to enable PC card memory block wait feature.

XMC\_WAIT\_OPERATION\_DISABLE: Disable

XMC\_WAIT\_OPERATION\_ENABLE: Enable

### delay\_time\_cr

Delay time of CLE to RE (from CLE falling edge to RE falling edge)

0000: 1 HCLKclock cycle

.....

1111: 16 HCLK clock cycles

### delay\_time\_ar

Delay time of ALE to RE (from ALE falling edge to RE falling edge)

0000: 1 HCLK clock cycle

.....

1111: 16 HCLK clock cycles

### Example:

```
xmc_pccard_init_type xmc_pccard_init_struct;
xmc_pccard_init_struct.enable_wait=XMC_WAIT_OPERATION_DISABLE;
xmc_pccard_init_struct.delay_time_cr=0xF;
xmc_pccard_init_struct.delay_time_ar=0xF;
/* xmc pccard configuration */
xmc_pccard_init(&xmc_pccard_init_struct);
```

## 5.27.21 xmc\_pccard\_timing\_config function

The table below describes the function `xmc_pccard_timing_config`.

**Table 715. xmc\_nand\_pccard\_config function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>xmc_pccard_timing_config</code>  |
| Function prototype     | <code>void xmc_pccard_timing_config(xmc_nand_pccard_timinginit_type* xmc_common_spacetiming_struct, xmc_nand_pccard_timinginit_type* xmc_attribute_spacetiming_struct, xmc_nand_pccard_timinginit_type* xmc_iospace_timing_struct);</code> |
| Function description   | Configure pccard controller timing   |
| Input parameter 1      | <code>xmc_common_spacetiming_struct</code> : <code>xmc_nand_pccard_timinginit_type</code> pointer<br>It indicates regular memory timing parameters.  |
| Input parameter 2      | <code>xmc_attribute_spacetiming_struct</code> : <code>xmc_nand_pccard_timinginit_type</code> pointer<br>It indicates special memory timing parameters.   |
| Input parameter 3      | <code>xmc_iospace_timing_struct</code> : <code>xmc_nand_pccard_timinginit_type</code> pointer<br>It indicates special memory timing parameters.  |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

### **xmc\_nand\_pccard\_timinginit\_type struct**

The `xmc_nand_pccard_timinginit_type` is defined in the `at32f435_437_xmc.h`.

typedef struct

```
{
    xmc_class_bank_type    class_bank;
    uint32_t               mem_setup_time;
    uint32_t               mem_waite_time;
    uint32_t               mem_hold_time;
    uint32_t               mem_hiz_time;
} xmc_nand_pccard_timinginit_type;
```

### **class\_bank**

NAND flash bank selection

`XMC_BANK4_PCCARD`

### **mem\_setup\_time**

Regular memory setup time. It defines the address setup time during access operation in a regular memory.

00000000: 0 HCLK clock cycle is inserted

00000001: 1 HCLK clock cycle is inserted

.....

11111111: 255 HCLK clock cycles are inserted

### **mem\_waite\_time**

Regular memory wait time. It defines the regular memory wait time when the XMC\_NWE and XMC\_NOE are low.

00000000: 0 HCLK clock cycle is inserted

00000001: 1 HCLK clock cycle is inserted

.....

11111111: 255 HCLK clock cycles are inserted

### mem\_hold\_time

Regular memory hold time. It defines the databus hold time during access operation in a regular memory.

00000000: Reserved

00000001: 1 HCLK clock cycle is inserted

.....

11111111: 255 HCLK clock cycles are inserted

### mem\_hiz\_time

Regular memory databus High resistance time. It defines the databus high resistance duration when write access to PC card is started in a regular space.

00000000: 0 HCLK clock cycle is inserted

00000001: 1 HCLK clock cycle is inserted

.....

11111111: 255 HCLK clock cycles are inserted

### Example:

```
xmc_nand_pccard_timinginit_type xmc_common_spacetiming_struct, xmc_attribute_spacetiming_struct,
xmc_iospace_timing_struct;
xmc_common_spacetiming_struct.class_bank = XMC_BANK4_PCCARD;
xmc_common_spacetiming_struct.mem_setup_time = 254;
xmc_common_spacetiming_struct.mem_hiz_time = 254;
xmc_common_spacetiming_struct.mem_hold_time = 254;
xmc_common_spacetiming_struct.mem_waite_time = 254;

xmc_attribute_spacetiming_struct.class_bank = XMC_BANK4_PCCARD;
xmc_attribute_spacetiming_struct.mem_setup_time = 254;
xmc_attribute_spacetiming_struct.mem_hiz_time = 254;
xmc_attribute_spacetiming_struct.mem_hold_time = 254;
xmc_attribute_spacetiming_struct.mem_waite_time = 254;

xmc_iospace_timing_struct.class_bank = XMC_BANK4_PCCARD;
xmc_iospace_timing_struct.mem_setup_time = 254;
xmc_iospace_timing_struct.mem_hiz_time = 254;
xmc_iospace_timing_struct.mem_hold_time = 254;
xmc_iospace_timing_struct.mem_waite_time = 254;

xmc_pccard_timing_config (&xmc_common_spacetiming_struct, &xmc_attribute_spacetiming_struct, &
xmc_iospace_timing_struct);
```

## 5.27.22 xmc\_pccard\_default\_para\_init function

The table below describes the function `xmc_pccard_default_para_init`.

**Table 716. xmc\_pccard\_default\_para\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>xmc_pccard_default_para_init</code>   |
| Function prototype     | <code>void xmc_pccard_default_para_init(xmc_pccard_init_type* xmc_pccard_init_struct);</code> |
| Function description   | Initialize parameters in <code>xmc_pccard_init_struct</code>                                  |
| Input parameter 1      | <code>xmc_pccard_init_struct</code> : <code>xmc_pccard_init_type</code> pointer               |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

The table below describes the default values of members `xmc_nand_init_struct`.

**Table 717.xmc\_pccard\_init\_struct default values**

| Member                     | Default value                           |
|----------------------------|---|
| <code>enable_wait</code>   | <code>XMC_WAIT_OPERATION_DISABLE</code> |
| <code>delay_time_ar</code> | <code>0x0</code>                        |
| <code>delay_time_cr</code> | <code>0x0</code>                        |

**Example:**

```
/* fill each xmc_pccard_init_struct member with its default value */
xmc_pccard_default_para_init(&xmc_pccard_init_struct);
```

## 5.27.23 xmc\_pccard\_timing\_default\_para\_init function

The table below describes the function `xmc_pccard_timing_default_para_init`.

**Table 718. xmc\_pccard\_timing\_default\_para\_init function**

| Name                 | Description   |
|----------------------|---|
| Function name        | <code>xmc_pccard_timing_default_para_init</code>  |
| Function prototype   | <code>void xmc_pccard_timing_default_para_init(xmc_nand_pccard_timinginit_type* xmc_common_spacetiming_struct, xmc_nand_pccard_timinginit_type* xmc_attribute_spacetiming_struct, xmc_nand_pccard_timinginit_type* xmc_iospace_timing_struct);</code> |
| Function description | Initialize parameters in <code>xmc_common_spacetiming_struct</code> , <code>xmc_attribute_spacetiming_struct</code> and <code>xmc_iospace_timing_struct</code>  |
| Input parameter 1    | <code>xmc_common_spacetiming_struct</code> : <code>xmc_nand_pccard_timinginit_type</code> pointer   |
| Input parameter 2    | <code>xmc_attribute_spacetiming_struct</code> : <code>xmc_nand_pccard_timinginit_type</code> pointer  |
| Input parameter 3    | <code>xmc_iospace_timing_struct</code> : <code>xmc_nand_pccard_timinginit_type</code> pointer   |
| Output parameter     | NA  |
| Return value         | NA  |
| Required             | NA  |



| Name             | Description |
|------------------|-------------|
| preconditions    |             |
| Called functions | NA          |

The table below describes the default values of members `xmc_common_spacetime_struct`, `xmc_attribute_spacetime_struct` and `xmc_iospace_timing_struct`.

**Table 719. `xmc_common_spacetime_struct` and `xmc_attribute_spacetime_struct` default values**

| Member                      | Default value                 |
|-----------------------------|-------------------------------|
| <code>class_bank</code>     | <code>XMC_BANK4_PCCARD</code> |
| <code>mem_hold_time</code>  | <code>0xFC</code>             |
| <code>mem_wait_time</code>  | <code>0xFC</code>             |
| <code>mem_setup_time</code> | <code>0xFC</code>             |
| <code>mem_hiz_time</code>   | <code>0xFC</code>             |

**Example:**

```
xmc_pccard_timinginit_type xmc_regular_spacetime_struct;
/* fill each xmc_regular_spacetime_struct member with its default value */
xmc_pccard_timing_default_para_init(&xmc_regular_spacetime_struct, &xmc_regular_spacetime_struct, &xmc_regular_spacetime_struct);
```

## 5.27.24 `xmc_pccard_enable` function

The table below describes the function `xmc_pccard_enable`.

**Table 720. `xmc_pccard_enable` function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>xmc_pccard_enable</code>                                |
| Function prototype     | <code>void xmc_pccard_enable(confirm_state new_state);</code> |
| Function description   | Enable pccard controller                                      |
| Input parameter 1      | <code>new_state</code> : enable or disable                    |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**new\_state**

FALSE: Disable controller

TRUE: Enable controller

**Example:**

```
/* xmc pccard bank enable*/
xmc_pccard_enable(TRUE);
```

### 5.27.25 xmc\_sdram\_reset function

The table below describes the function xmc\_sdram\_reset.

**Table 721. xmc\_sdram\_reset function**

| Name                   | Description   |
|------------------------|---|
| Function name          | xmc_sdram_reset                                     |
| Function prototype     | void xmc_sdram_reset(xmc_sdram_bank_type xmc_bank); |
| Function description   | Reset sdram bank controller                         |
| Input parameter 1      | xmc_bank: selected sdram bank                       |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### xmc\_bank

XMC\_SDRAM\_BANK1: SDRAM bank1

XMC\_SDRAM\_BANK2: SDRAM bank2

#### Example:

```
/* xmc sdram bank reset*/
xmc_sdram_reset(XMC_SDRAM_BANK1);
```

### 5.27.26 xmc\_sdram\_init function

The table below describes the function xmc\_sdram\_init.

**Table 722. xmc\_sdram\_init function**

| Name                   | Description   |
|------------------------|---|
| Function name          | xmc_sdram_init  |
| Function prototype     | void xmc_sdram_init(xmc_sdram_init_type *xmc_sdram_init_struct,<br>xmc_sdram_timing_type *xmc_sdram_timing_struct); |
| Function description   | Initialize sdram bank   |
| Input parameter 1      | xmc_sdram_init_struct: xmc_sdram_init_type pointer  |
| Input parameter 2      | xmc_sdram_timing_struct: xmc_sdram_timing_type pointer  |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

#### xmc\_sdram\_init\_struct

The xmc\_sdram\_init\_type is defined in the at32f435\_437\_xmc.h.

typedef struct

```
{
    xmc_sdram_bank_type          sdram_bank;
    xmc_sdram_inbk_type         internel_banks;
    xmc_sdram_clkdiv_type       clkdiv;
    uint8_t                     write_protection;
    uint8_t                     burst_read;
```

```

uint8_t          read_delay;
xmc_sdram_column_type column_address;
xmc_sdram_row_type row_address;
xmc_sdram_cas_type cas;
xmc_sdram_width_type width;
} xmc_sdram_init_type;

```

### **sdram\_bank**

Select a sdram bank

XMC\_SDRAM\_BANK1: sdram bank1

XMC\_SDRAM\_BANK2: sdram bank2

### **internal\_banks**

number of banks supported by sdram device

XMC\_INBK\_2: 2 internal banks

XMC\_INBK\_4: 4 internal banks

### **clkdiv**

Set sdram clock division

XMC\_NO\_CLK: sdram clock disabled

XMC\_CLKDIV\_2: Divided by 2

XMC\_CLKDIV\_3: Divided by 3

XMC\_CLKDIV\_4: Divided by 4

### **write\_protection**

Enable/disable sdram write protection

TRUE: Enable sdram write protection

FALSE: Disable sdram write protection

### **burst\_read**

Enable/disable sdram consecutive read operations

TRUE: Enable sdram consecutive read operations

FALSE: Disable sdram consecutive read operations

### **read\_delay**

Set read delay feature

XMC\_READ\_DELAY\_0: 0 HCLK clock cycle delay

XMC\_READ\_DELAY\_1: 1 HCLK clock cycle delay

XMC\_READ\_DELAY\_2: 2 HCLK clock cycles delay

### **column\_address**

Number of column address

XMC\_COLUMN\_8: 8 bits

XMC\_COLUMN\_9: 9 bits

XMC\_COLUMN\_10: 10 bits

XMC\_COLUMN\_11: 11 bits

### **row\_address**

Number of row address

XMC\_ROW\_11: 11 bits

XMC\_ROW\_12: 12 bits

XMC\_ROW\_13: 13 bits

### **cas**

CAS latency

XMC\_CAS\_1: 1 cycle

XMC\_CAS\_2: 2 cycles

XMC\_CAS\_3: 3 cycles

**width**

Data bus width

XMC\_MEM\_WIDTH\_8: 8-bit

XMC\_MEM\_WIDTH\_16: 16-bit

**xmc\_sdram\_timing\_struct**

The xmc\_sdram\_timing\_type is defined in the at32f435\_437\_xmc.h.

**tmrdr**

Delay between a load mode register command and an activate or refresh command in number

XMC\_DELAY\_CYCLE\_1: 1 cycle

XMC\_DELAY\_CYCLE\_2: 2 cycles

.....

XMC\_DELAY\_CYCLE\_15: 15 cycles

XMC\_DELAY\_CYCLE\_16: 16 cycles

**txsr**

Exit self-refresh to active delay

XMC\_DELAY\_CYCLE\_1: 1 cycle

XMC\_DELAY\_CYCLE\_2: 2 cycles

.....

XMC\_DELAY\_CYCLE\_15: 15 cycles

XMC\_DELAY\_CYCLE\_16: 16 cycles

**tras**

Self-refresh time

XMC\_DELAY\_CYCLE\_1: 1 cycle

XMC\_DELAY\_CYCLE\_2: 2 cycles

.....

XMC\_DELAY\_CYCLE\_15: 15 cycles

XMC\_DELAY\_CYCLE\_16: 16 cycles

**trc**

Refresh to active delay

XMC\_DELAY\_CYCLE\_1: 1 cycle

XMC\_DELAY\_CYCLE\_2: 2 cycles

.....

XMC\_DELAY\_CYCLE\_15: 15 cycles

XMC\_DELAY\_CYCLE\_16: 16 cycles

**twr**

Delay between a write command and a precharge command

XMC\_DELAY\_CYCLE\_1: 1 cycle

XMC\_DELAY\_CYCLE\_2: 2 cycles

.....

XMC\_DELAY\_CYCLE\_15: 15 cycles

XMC\_DELAY\_CYCLE\_16: 16 cycles

**trp**

Delay between a precharge command and active command

XMC\_DELAY\_CYCLE\_1: 1 cycle

XMC\_DELAY\_CYCLE\_2: 2 cycles

.....

XMC\_DELAY\_CYCLE\_15: 15 cycles

XMC\_DELAY\_CYCLE\_16: 16 cycles

**trcd**

Delay between an active command and a write/read command

XMC\_DELAY\_CYCLE\_1: 1 cycle

XMC\_DELAY\_CYCLE\_2: 2 cycles

.....

XMC\_DELAY\_CYCLE\_15: 15 cycles

XMC\_DELAY\_CYCLE\_16: 16 cycles

**Example:**

```
xmc_sdram_init_type sdram_init_struct;
xmc_sdram_timing_type sdram_timing_struct;
/*-- xmc configuration -----*/
xmc_sdram_default_para_init(&sdram_init_struct,&sdram_timing_struct);
sdram_init_struct.sdram_bank          = XMC_SDRAM_BANK1;
sdram_init_struct.internal_banks      = XMC_INBK_4;
sdram_init_struct.clkdiv               = XMC_CLKDIV_3;
sdram_init_struct.write_protection    = FALSE;
sdram_init_struct.burst_read           = FALSE;
sdram_init_struct.read_delay           = XMC_READ_DELAY_1;
sdram_init_struct.column_address      = XMC_COLUMN_9;
sdram_init_struct.row_address          = XMC_ROW_13;
sdram_init_struct.cas                  = XMC_CAS_3;
sdram_init_struct.width                = XMC_MEM_WIDTH_16;

sdram_timing_struct.tmrdr              = XMC_DELAY_CYCLE_2;
sdram_timing_struct.txsr               = XMC_DELAY_CYCLE_11;
sdram_timing_struct.tras               = XMC_DELAY_CYCLE_7;
sdram_timing_struct.trc                = XMC_DELAY_CYCLE_9;
sdram_timing_struct.twr                = XMC_DELAY_CYCLE_2;
sdram_timing_struct.trp                = XMC_DELAY_CYCLE_3;
sdram_timing_struct.trcd               = XMC_DELAY_CYCLE_3;
xmc_sdram_init(&sdram_init_struct,&sdram_timing_struct);
```

### 5.27.27 xmc\_sdrām\_default\_para\_init function

The table below describes the function `xmc_sdrām_default_para_init`.

**Table 723. xmc\_sdrām\_default\_para\_init function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>xmc_sdrām_default_para_init</code>   |
| Function prototype     | <code>void xmc_sdrām_default_para_init(xmc_sdrām_init_type *xmc_sdrām_init_struct, xmc_sdrām_timing_type *xmc_sdrām_timing_struct);</code> |
| Function description   | Initialize parameters in <code>xmc_sdrām_init_struct</code> and <code>xmc_sdrām_timing_struct</code>                                       |
| Input parameter 1      | sdrām controller initialization parameters.<br>Refer to <a href="#">xmc_sdrām_init_struct</a> for details.                                 |
| Input parameter 2      | sdrām timing parameters<br>Refer to <a href="#">xmc_sdrām_timing_struct</a> for details.   |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
xmc_sdrām_init_type sdrām_init_struct;
xmc_sdrām_timing_type sdrām_timing_struct;
xmc_sdrām_default_para_init(&sdrām_init_struct, &sdrām_timing_struct);
```

### 5.27.28 xmc\_sdrām\_cmd function

The table below describes the function `xmc_sdrām_cmd`.

**Table 724. xmc\_sdrām\_cmd function**

| Name                   | Description   |
|------------------------|---|
| Function name          | <code>xmc_sdrām_cmd</code>  |
| Function prototype     | <code>void xmc_sdrām_cmd(xmc_sdrām_cmd_type *xmc_sdrām_cmd_struct);</code>  |
| Function description   | Send sdrām command  |
| Input parameter 1      | <code>xmc_sdrām_cmd_struct</code> : <code>xmc_sdrām_cmd_type</code> pointer |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**xmc\_sdrām\_cmd\_struct**

`xmc_sdrām_cmd_type` is defined in the `at32f435_437_xmc.h`.

**cmd**

Command sent to sdrām device

- XMC\_CMD\_NORMAL: Normal mode
- XMC\_CMD\_CLK: Clock configuration enable
- XMC\_CMD\_PRECHARG\_ALL: Precharge all banks
- XMC\_CMD\_AUTO\_REFRESH: : Auto refresh
- XMC\_CMD\_LOAD\_MODE: Load mode register

XMC\_CMD\_SELF\_REFRESH: Self-refresh  
 XMC\_CMD\_POWER\_DOWN: Power-down command

**cmd\_banks**

Select a sdram bank

XMC\_CMD\_BANK1: Command sent to sdram bank1  
 XMC\_CMD\_BANK2: Command sent to sdram bank1  
 XMC\_CMD\_BANK1\_2: Command sent to sdram bank1 and bank2

**auto\_refresh**

Auto-refresh times

0: 1 auto-refresh cycle  
 1: 2 auto-refresh cycles

.....

14: 15 auto-refresh cycles

**data**

Mode register data

**Example:**

```
xmc_sdram_cmd_type sdram_cmd_struct;
sdram_cmd_struct.cmd          = XMC_CMD_CLK;
sdram_cmd_struct.auto_refresh = 1;
sdram_cmd_struct.cmd_banks   = XMC_CMD_BANK1;
sdram_cmd_struct.data        = 0;
xmc_sdram_cmd(&sdram_cmd_struct);
```

## 5.27.29 xmc\_sdram\_status\_get function

The table below describes the function `xmc_sdram_status_get`.

**Table 725. xmc\_sdram\_status\_get function**

| Name                   | Description  |
|------------------------|--|
| Function name          | <code>xmc_sdram_status_get</code>  |
| Function prototype     | <code>uint32_t xmc_sdram_status_get(xmc_sdram_bank_type xmc_bank);</code>                |
| Function description   | Get sdram bank status  |
| Input parameter 1      | <code>xmc_bank</code> : selected sdram bank  |
| Output parameter       | NA   |
| Return value           | Return the current status.<br>Refer to <a href="#">xmc_bank_status_type</a> for details. |
| Required preconditions | NA   |
| Called functions       | NA   |

**xmc\_bank**

Select a sdram bank

XMC\_SDRAM\_BANK1: sdram bank1  
 XMC\_SDRAM\_BANK2: sdram bank2

**xmc\_bank\_status\_type**

XMC\_STATUS\_NORMAL: normal mode  
 XMC\_STATUS\_SELF\_REFRESH: self-refresh mode

XMC\_STATUS\_POWER\_DOWN: power-down mode

**Example:**

```
/* get sdram status */
xmc_sdram_status_get(XMC_SDRAM_BANK1)
```

### 5.27.30 xmc\_sdram\_refresh\_counter\_set function

The table below describes the function xmc\_sdram\_refresh\_counter\_set.

**Table 726. xmc\_sdram\_refresh\_counter\_set function**

| Name                   | Description   |
|------------------------|---|
| Function name          | xmc_sdram_refresh_counter_set                         |
| Function prototype     | void xmc_sdram_refresh_counter_set(uint32_t counter); |
| Function description   | Set sdram auto-refresh counter                        |
| Input parameter 1      | counter: auto-refresh counter value                   |
| Output parameter       | NA  |
| Return value           | NA  |
| Required preconditions | NA  |
| Called functions       | NA  |

**Example:**

```
/*set refresh counter */
xmc_sdram_refresh_counter_set(1105);
```

### 5.27.31 xmc\_sdram\_auto\_refresh\_set function

The table below describes the function xmc\_sdram\_auto\_refresh\_set.

**Table 727. xmc\_sdram\_auto\_refresh\_set function**

| Name                   | Description                                      |
|------------------------|--|
| Function name          | xmc_sdram_auto_refresh_set                       |
| Function prototype     | void xmc_sdram_auto_refresh_set(uint32_t number) |
| Function description   | Set sdram software auto-refresh times            |
| Input parameter 1      | number: auto-refresh times                       |
| Output parameter       | NA   |
| Return value           | NA   |
| Required preconditions | NA   |
| Called functions       | NA   |

**Example:**

```
/* set 8 times auto refresh */
xmc_sdram_auto_refresh_set(8);
```



## 6 Precautions

### 6.1 Device model replacement

While replacing the device part number in an existing project or demo with another one, it is necessary to check the macro definitions corresponding to the device defined in Table 1 before replacement. The subsequent sections give a detailed description of how to replace a device in KEIL and IAR environments (Just taking the at32f403avg7 as an example as other devices share similar operations).

There are two steps to get this happen:

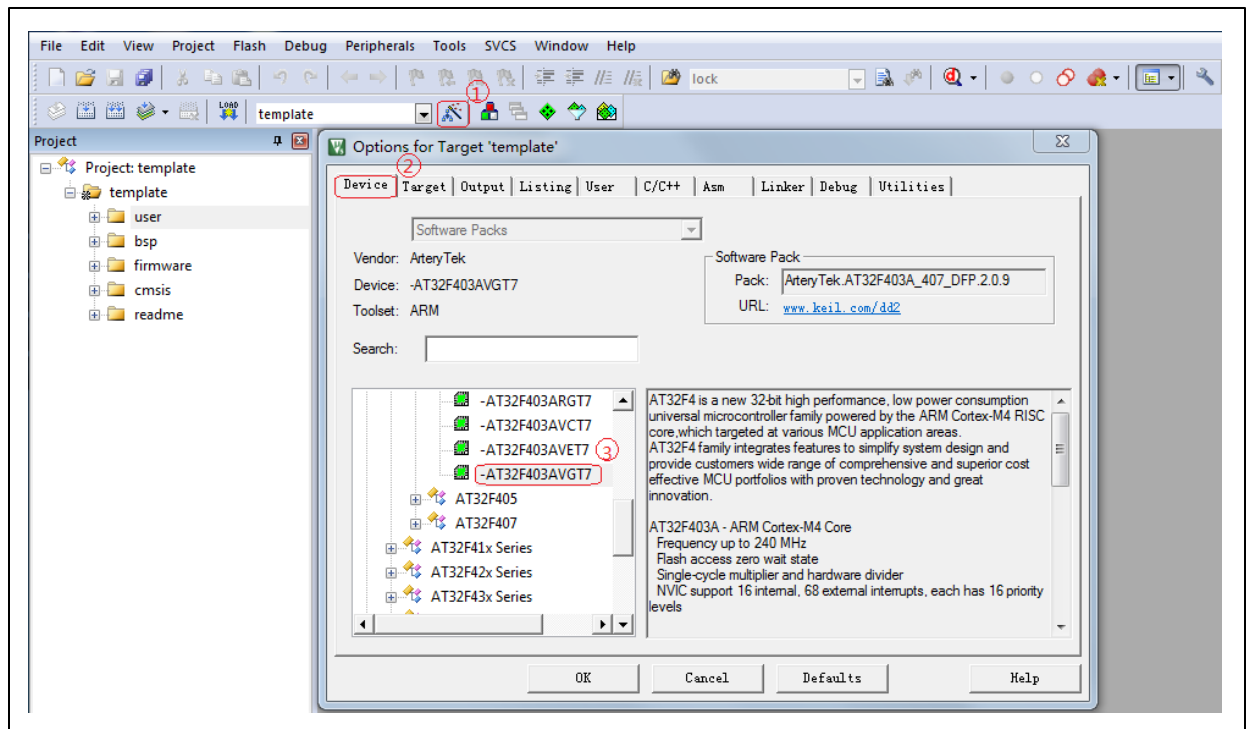
1. By changing device
2. By changing macro definition

#### 6.1.1 KEIL environment

Follow the steps and illustration below for device replacement in Keil environment.

- ① Click on magic wand “Options for Target”
- ② Click on “Device”
- ③ Select the desired device part number

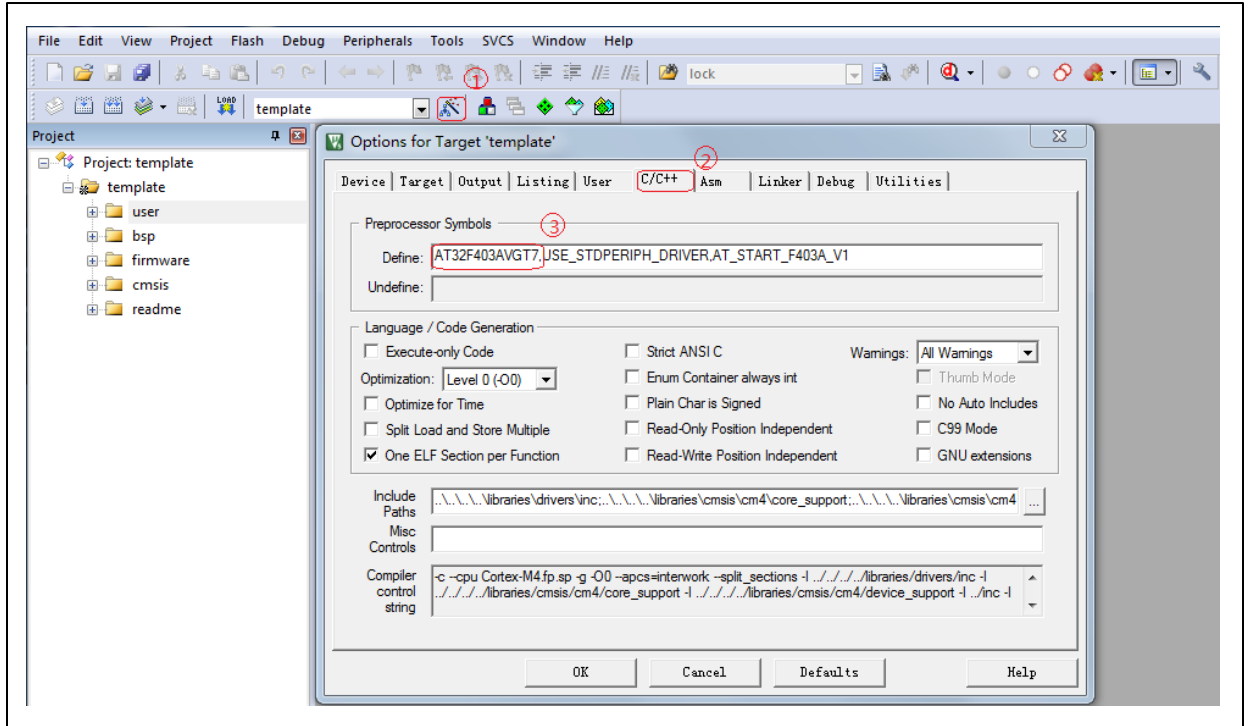
**Figure 29. Change device part number in Keil**



Follow the steps and illustration below to change macro definition.

- ① Click on magic wand “Options for Target”
- ② Click on “C/C++”
- ③ Delete the original macro definition in “Define” box, and write the desired one corresponding to the selected device part number based on Table 1.

Figure 30. Change macro definition in Keil

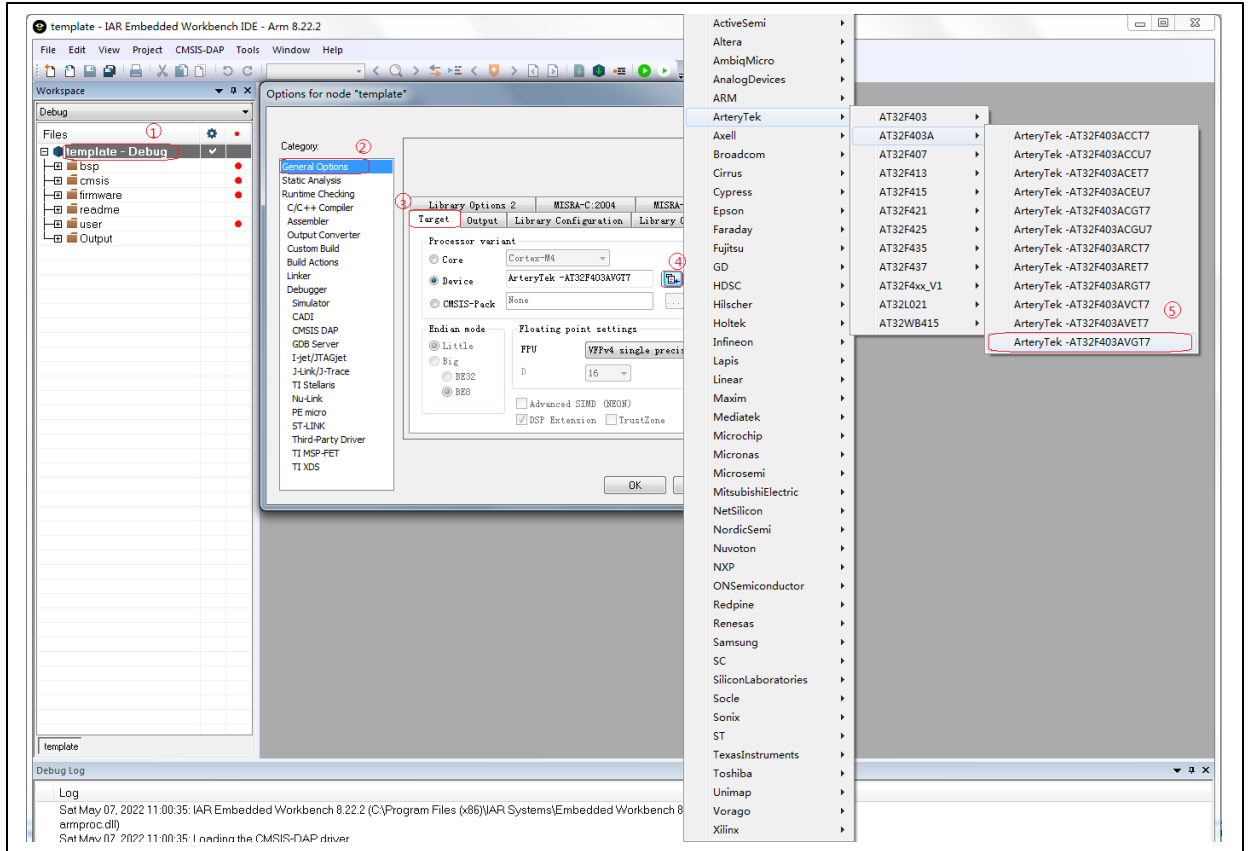


## 6.1.2 IAR environment

Follow the steps and illustration below for device replacement in IAR environment

- ① Right click on the file name, and select “Options...”
- ② Select “General Options”
- ③ Select “Target”
- ④ Click on the check box
- ⑤ Select the desired device part number

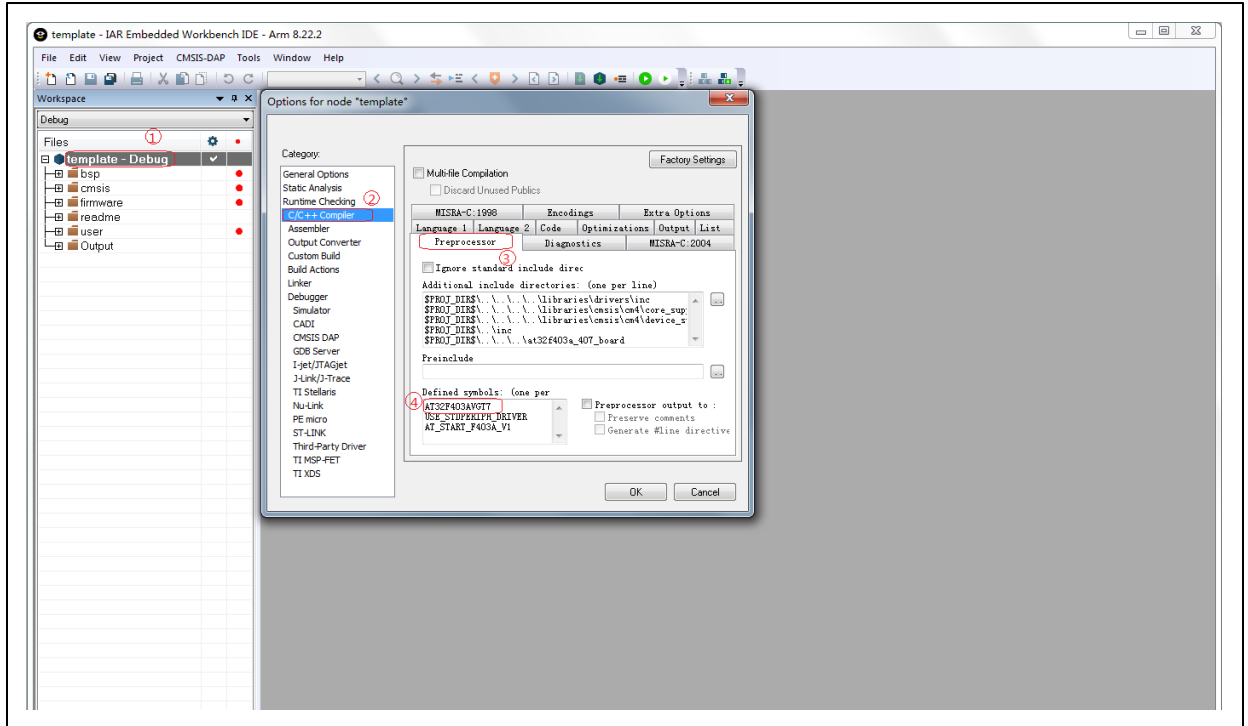
Figure 31. Change device part number in IAR



Follow the steps and illustration below to change macro definition in IAR environment.

- ① Right click on the file name, and select “Options...”
- ② Select “C/C++ Compiler”
- ③ Click on “Preprocessor”
- ④ Delete the original macro definition in “Defined symbols” column, and write the desired one corresponding to the selected device part number based on Table 1.

Figure 32. Change macro definition in IAR



## 6.2 Unable to identify IC by JLink software in Keil

In special circumstances, the Keil project compiled by an engineer is unknown to the J-Link software even if it can be compiled by other engineers and identified by ICP software. For example, some warnings like below will be displayed.

Figure 33. Error warning 1

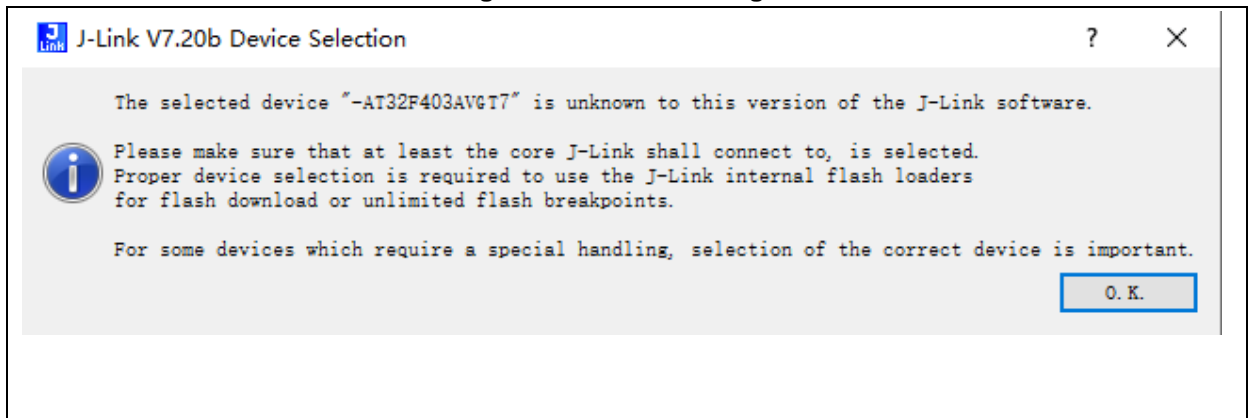


Figure 34. Error warning 2

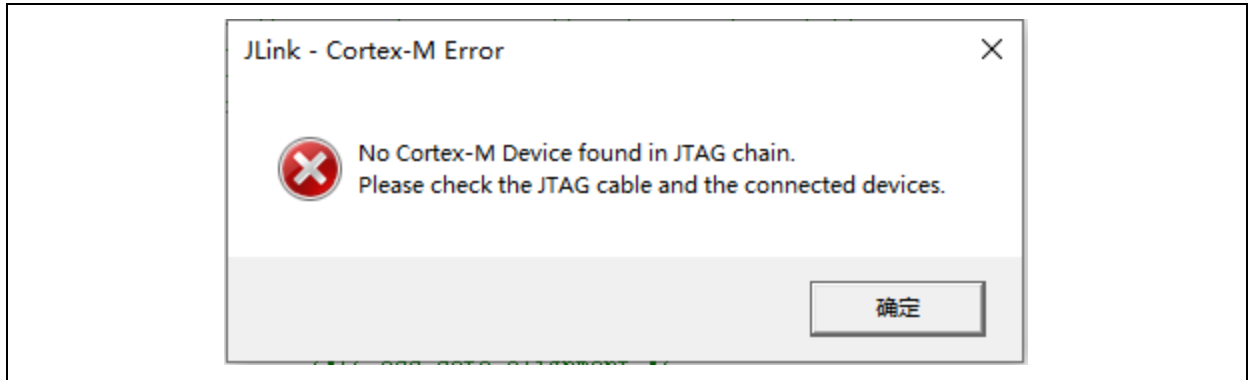
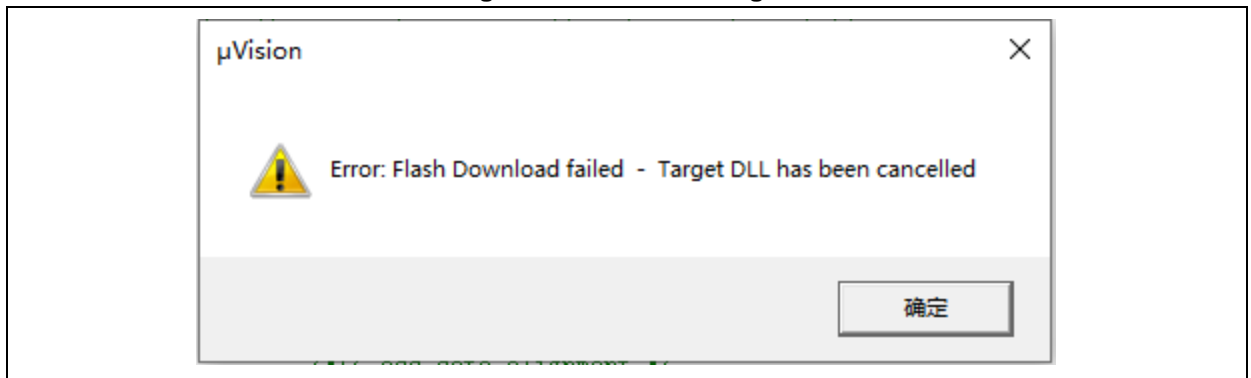


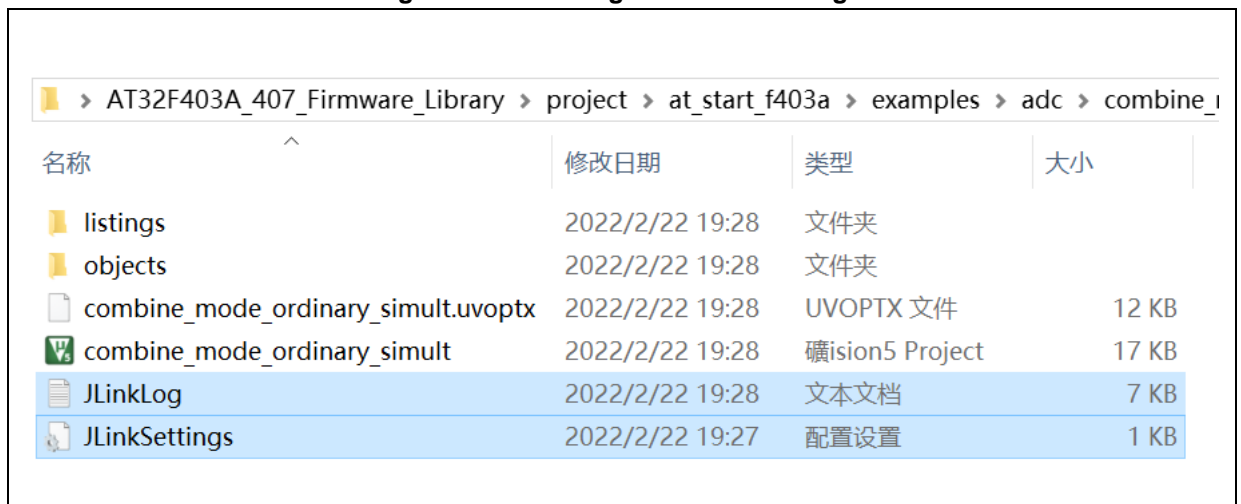
Figure 35. Error warning 3



### How to solve this problem?

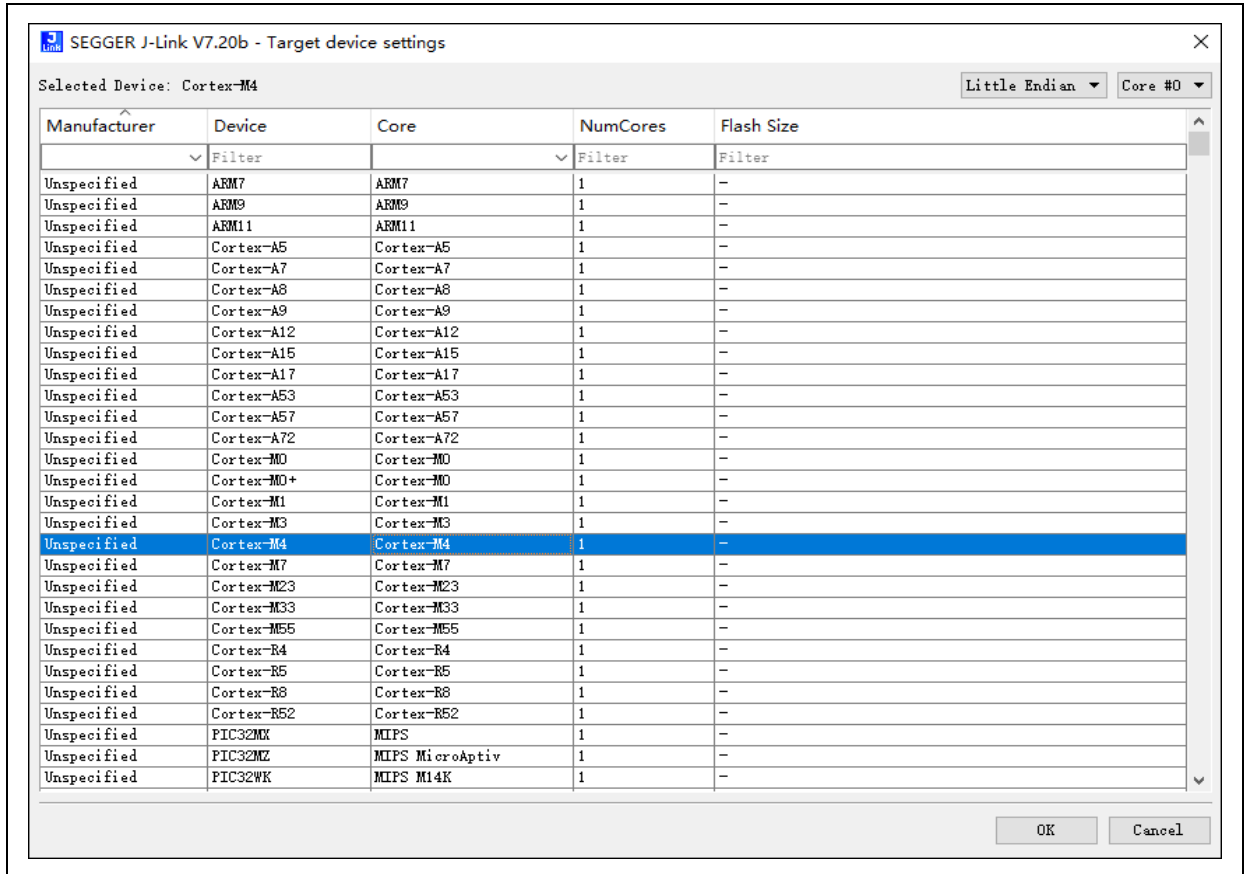
Step 1: Find “JLinkLog” and “JLinkSettings” files according to project path, and delete them

Figure 36. JLinkLog and JLinkSettings



Step 2: Click on magic wand, go to “Debug”, select “Unspecified Cortex-M4”

Figure 37. Unspecified Cortex-M4



## 6.3 How to change HEXT crystal

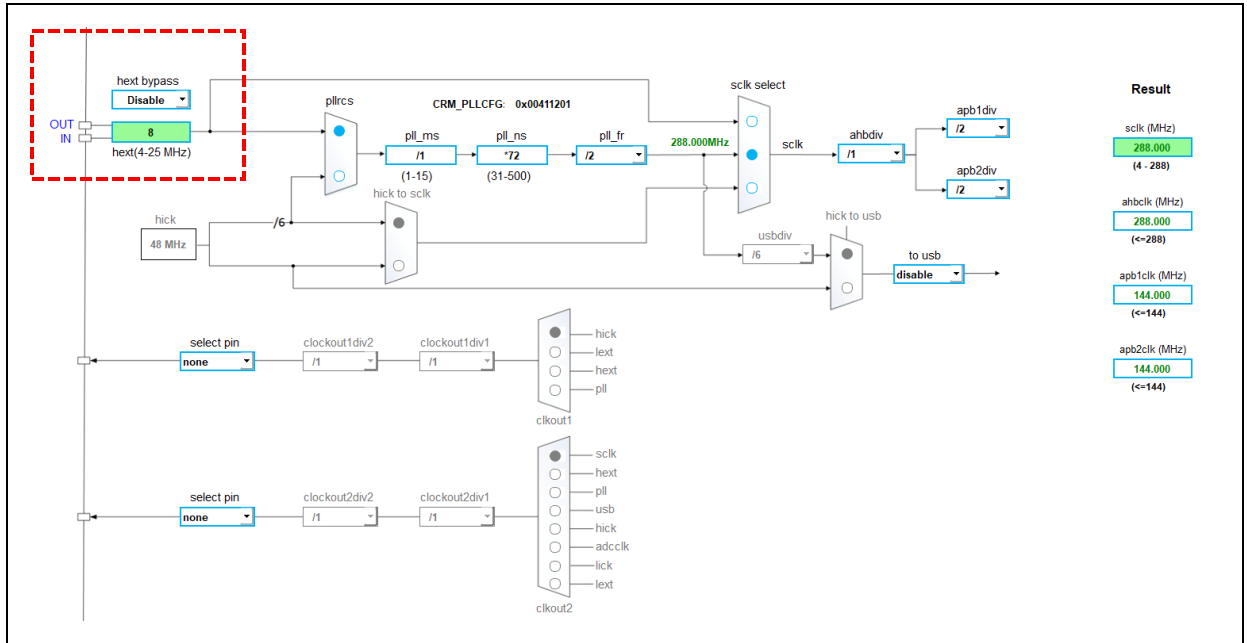
All examples used in BSP implements frequency multiplication based on 8 MHz external highspeed crystal oscillator on the evaluation board. If a non-8 MHz external crystal is used in actual scenarios, it is necessary to modify clock configuration in BSP to allow for accurate and stable clock frequency.

Therefore, the “AT32\_New\_Clock\_Configuration” tool is specially developed by Artery to generate the desired BSP system clock code file, including external clock source, frequency division factor, frequency multiplication factor, clock source selection and other parameters, marked in red in Figure 38. After the completion of parameter configuration, it is ready to generate code file, avoiding complicated operations involved in code modification.

The users simply need to replace the original one in BSP demo with the newly generated clock code file (at32f4xx\_clock.c/ at32f4xx\_clock.h/ at32f4xx\_conf.h) and call the function system\_clock\_config in main function.

Also, it is necessary to replace the macro definition HEXT\_VALUE in the at32f4xx\_conf.h. Taking the AT32F403A as an example, the HEXT\_VALUE of the at32f403a\_407\_conf.h is defined as:  
`#define HEXT_VALUE ((uint32_t)8000000) /*!< value of the high speed external crystal in hz */`  
 Figure 38 shows the window of AT32\_New\_Clock\_Configuration tool.

Figure 38. AT32\_New\_Clock\_Configuration window



For more information on the AT32\_New\_Clock\_Configuration, please refer to the corresponding Application Note shown in the table below, which are all available from the official website of Artery.

Table 728. Clock configuration guideline

| Part number                       | Application Note |
|-----------------------------------|------------------|
| AT32F403A/407 clock configuration | AN0082           |
| AT32F435/437 clock configuration  | AN0084           |
| AT32F421 clock configuration      | AN0116           |
| AT32F415 clock configuration      | AN0117           |
| AT32F413 clock configuration      | AN0118           |
| AT32F425 clock configuration      | AN0121           |

## 7 Revision history

**Table 729. Document revision history**

| Date       | Version | Revision note   |
|------------|---------|---|
| 2021.09.06 | 2.0.0   | Initial release   |
| 2021.11.19 | 2.0.1   | Updated screenshots and descriptions in the Pack installation section |
| 2022.05.09 | 2.0.2   | Added Section 6 Precautions   |
| 2022.06.15 | 2.0.3   | Added descriptions of peripheral library functions                    |
| 2022.11.15 | 2.0.4   | Modified descriptions of I2C in “abbreviations of peripherals”        |



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